

Unifying occupancy-detection and local frequency scaling (Frescalo) models

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Abstract

Frescalo’s “local frequency scaling” and classical occupancy-detection models both seek to recover true species-occurrence signals from imperfect data. In this paper, we show that the two approaches rest on the same underlying detection mathematics. Occupancy models treat each site’s repeat visits as independent detection trials and separately estimate occupancy probability and per-visit detectability. Frescalo, by contrast, pools data across ecologically defined neighbourhoods and infers a single combined detection rate and a temporal “time-factor” to capture trends. We demonstrate that the Bernoulli-trial formulation of occupancy-detection converges to Frescalo’s Poisson-process framework, with occupancy and detectability collapsing into a single rate parameter. This equivalence clarifies how Frescalo’s neighbourhood and time corrections function as a coarser-scale analogue of repeat-visit models. By casting Frescalo in occupancy modelling terms, we hope to promote further investigation into the adoption of occupancy-model diagnostics, extensions and covariate tests within Frescalo analyses, improving transparency and rigour when working with less structured biodiversity data.

Keywords: occupancy models, sampling effort, effort correction, citizen science, unstructured data, Frescalo

1. Introduction

Occupancy-detection models [9] and the Frescalo “local frequency scaling” method [6] both aim to correct raw biological records (i.e. species occurrence) data for imperfect sampling. Classical occupancy models do this at the scale of repeated visits to individual sites, explicitly estimating true presence probabilities (ψ) and detectability (p) via a hierarchical likelihood. Frescalo was designed to work at larger spatio-temporal scales, exploiting emergent patterns of relative frequency in “neighbourhoods” to derive Poisson-process-based scaling factors (α) and species’ relative “time factors” indexing true fluctuations in site occupancy. Given that many datasets lack repeat-visit structure, and/or may exhibit variation in the detection process that is unmodellable due to a

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18 lack of knowledge of its determinants [11], understanding how Frescalo recovers
 19 effort-adjusted trends from aggregated data can broaden the toolkit of ecologists.

20 Although the two models can appear quite different, Pescott et al. [11]
 21 informally suggested that Frescalo could be seen as a type of occupancy-detection
 22 model “where an adjustment for overlooked species is made in relation to spatial
 23 rather than temporal replication, whilst simultaneously adjusting for variable
 24 regional effort”. We here show that this suggestion can be formalised due to
 25 the two model types’ reliance on the same core mathematics of Bernoulli versus
 26 Poisson detections. Below we (1) recall each framework, (2) write down their
 27 key equations, and (3) algebraically map one onto the other, demonstrating that
 28 Frescalo time trends are based on an implicit occupancy-detection model whose
 29 “visits” and “occupancy” are folded into a single site/species discoverability rate
 30 parameter λ and standardised neighbourhood effort index.

31 **2. Occupancy-detection models**

32 *2.1. Basic single-season model*

33 Following MacKenzie et al. [9], at each site i for species j assume a latent
 34 occupancy indicator

$$z_{ij} \sim \text{Bernoulli}(\psi_{ij}).$$

35 Conditional on presence, v total survey visits indexed by k produce

$$y_{ij1}, \dots, y_{ijv} \mid z_{ij} = 1 \sim \text{Bernoulli}(p_{ij})$$

36 where p is detectability. If $z_{ij} = 0$ (i.e. species absent), then all $y_{ijk} = 0$.
 37 Marginalising out z_{ij} , it is well-known that the probability of at least one
 38 detection across v visits is

$$P(\max_k y_{ijk} = 1) = \psi_{ij}[1 - (1 - p_{ij})^v].$$

39 Thus the model simultaneously estimates

$$\psi_{ij} = \text{Pr}(\text{occupied}), \quad p_{ij} = \text{Pr}(\text{detect} \mid \text{occupied}),$$

40 and inference proceeds via the full likelihood over all sites and detection histories.

41 **3. Frequency scaling using local occupancy (Frescalo)**

42 *3.1. Neighbourhood frequencies*

43 Frescalo [6] pools presence-only data across a neighbourhood around target
 44 site i . We denote the observed proportion of neighbourhood sites in which
 45 species j was recorded by f_{ij} (in practice this frequency may relate to a weighted
 46 neighbourhood as per Hill [6], but this detail is not crucial for what follows).
 47 Under a Poisson-process model of species discovery with rate λ_{ij} and unknown
 48 total neighbourhood-level sampling effort $s_{i(N)}$, one has

$$f_{ij} = 1 - \exp(-\lambda_{ij}s_{i(N)}).$$

49 Subsequently, a frequency-weighted neighbourhood index

$$\phi_i = \frac{\sum_j f_{ij}^2}{\sum_j f_{ij}}$$

50 is then “standardised” to a target value Φ by solving for a site-specific effort
51 multiplier α_i such that

$$\phi_i(\alpha_i) = \frac{\sum_j [1 - (1 - f_{ij})^{\alpha_i}]^2}{\sum_j [1 - (1 - f_{ij})^{\alpha_i}]} = \Phi.$$

52 Mathematically, Φ is chosen so that every neighbourhood’s weighted-mean
53 frequency $\phi_i = \sum_j f_{ij}^2 / \sum_j f_{ij}$ equals Φ . Hill [6] showed that ϕ_i is the ratio of
54 the mean species richness to the ‘effective number of common species’ (often
55 called N_2 , the reciprocal of Simpson’s index; Hill [5]), which means that ϕ_i
56 isolates sampling intensity from true differences in richness and evenness. By
57 fixing $\phi_i = \Phi$, we therefore align all neighbourhoods to the same effort scale
58 without erasing real ecological differences.

59 This process yields the standardised neighbourhood frequencies

$$\tilde{f}_{ij} = 1 - (1 - f_{ij})^{\alpha_i}$$

60 which are independent of time (i.e. they are calculated with respect to the
61 entire time period under consideration, rather than any subdivisions of this used
62 for trend calculations), and serve as a proxy for the “true” discoverability- or
63 effort-standardised neighbourhood species rank-frequency curve.

64 3.2. Temporal correction

65 Within each time period t , one chooses a set of “benchmark” species [8] and
66 computes the proportion recorded per site and time period (Hill’s s_{it}) as an index
67 of site-level recording effort. (Note that there are potentially many ways to choose
68 ones’ neighbourhood benchmarks, but Hill [6] proposed a fixed proportion R^* of
69 the standardised species rank-frequency curve after an additional normalisation
70 step involving the division of species’ ranks by the expected species count $\sum_j \tilde{f}_{ij}$;
71 however, the precise method of choosing benchmarks does not affect what follows).
72 For each species j in period t , Hill then defines a Poisson-link intensity

$$Q_{ijt} = -\ln[1 - s_{it}\tilde{f}_{ij}],$$

73 The modelled “discovery” probability is then

$$P_{ijt}(x_{jt}) = 1 - \exp(-Q_{ijt}x_{jt}).$$

74 Hill [6] estimates the time-factor x_{jt} by matching the *total* modelled to *total*
75 observed presences y_{ijt} :

$$\sum_i y_{ijt} = \sum_i P_{ijt}(x_{jt}).$$

76 In practice one iterates x_{jt} in the exact Poisson form above until those
77 sums coincide (e.g. see the *R* code of Pescott [10]). The difference between
78 the (summed) observed presences y_{ijt} and the model's baseline expectation
79 after standardising time-independent neighbourhood effort α_i and adjusting for
80 site/time specific effort s_{it} is therefore captured by the time factor x_{jt} . Frescalo
81 can thus deliver detection-corrected trends from unstructured data when its core
82 assumptions are met.

83 4. Bridging the gap

84 4.1. Static occupancy and detection

85 We can compare the static (i.e. single season) single-species occupancy-
86 detection model probability of at least one detection in v visits

$$\psi[1 - (1 - p)^v]$$

87 with the Poisson-process discovery rate (conditional on the all-time frequency
88 curve) used in Frescalo

$$1 - e^{-\lambda s_{i(N)}}.$$

89 For small pv , $(1 - p)^v \approx e^{-pv}$, hence $\psi[1 - \exp(-pv)] \approx 1 - \exp(-\psi pv)$; now
90 identifying $\lambda = \psi p$ and $v = s_{i(N)}$ recovers the approximate Frescalo detection
91 probability $1 - \exp(-\lambda s_{i(N)})$. For any value of p , exact equivalence can be found
92 by solving

$$1 - e^{-\lambda v} = \psi[1 - (1 - p)^v] \tag{1}$$

93 for

$$\lambda = -\frac{1}{v} \ln[1 - \psi(1 - (1 - p)^v)], \tag{2}$$

94 but this only reduces to ψp in the limit $pv \rightarrow 0$. Frescalo's Poisson rate λ is
95 therefore exactly the function of occupancy, detectability and (latent) visit count
96 that makes equation (1) true. Whilst in Frescalo we never observe v directly,
97 we can infer it via the continuous neighbourhood effort index $s_{i(N)}$, which is
98 aligned across all neighbourhoods by the spatial scaler α_i . Frescalo can therefore
99 be interpreted as an occupancy-detection analogue at the neighbourhood scale:
100 it replaces the two-parameters (ψ, p) and discrete v with a Poisson rate λ and
101 a continuous effort-multiplier α equalising variable survey effort s_i (inferred by
102 the neighbourhood level $s_{i(N)}$) across sites.

103 A key step in recognising the equivalent elements of these models is to
104 appreciate that Frescalo applies its discoverability standardisation at a large scale:
105 not only is the adjustment done with respect to the multi-site neighbourhood and
106 across all species, but it is also calculated across all time periods in the analysis.
107 The standardised neighbourhood frequencies f_{ij} and the species rank-frequency
108 curve they form is estimated once, independently of time, before temporal change
109 is examined.

110 *4.2. Time trend interpretation*

111 A time trend in occupancy derived from a classical occupancy-detection
112 model is modelled simply by letting ψ_{ij} vary linearly or non-linearly over time,
113 conditional on both model-specific [16, 17] and other standard survey sampling
114 assumptions [3] being reasonable. Frescalo, by contrast, posits a single time-
115 independent set of discoverability-adjusted baseline frequencies \tilde{f}_{ij} , and then uses
116 benchmarks and the site/period effort index s_{it} to compute expected frequencies
117 under an assumption of stasis, subsequently letting the time factors x_{jt} absorb
118 any residual differences as true ecological change.

119 This underscores a key difference in how effort-adjustment processes func-
120 tion in each model type. Occupancy-detection models assume that true site
121 occupancies, and so trends in these, are directly recoverable from visit-level
122 information. Frescalo assumes that fine-scale visit data is generally unavailable
123 and/or uninformative for all or part of the time series of interest, and so models
124 species' discoverability at a much larger scale. The main aim of this adjustment
125 is to ensure a common scale across which neighbourhoods, and therefore sites,
126 can be compared: without the harmonisation of effort across neighbourhoods,
127 the time factors estimated for each site for a species would not be comparable,
128 making average time factors and trends in these meaningless.

129 Another fundamental difference is the meaning of the site occupancy values
130 produced. As noted, ψ_i has the simple meaning of predicted site occupancy under
131 the classical model (notwithstanding debates around usage versus occupancy
132 when these types of models are applied at different scales; [14]). The Frescalo
133 time factor x_{jt} is, however, defined by the benchmark average, and values >1 or
134 <1 indicate that a species is at a higher or lower average frequency relative to the
135 common species where it occurs, rather than in absolute occupancy probability.
136 This may be an important limitation to inferring effort via observable recording
137 outcomes, rather than having knowledge of those factors that directly map onto
138 effort, such as the actual number of visits and covariates that are known to explain
139 an important portion of observed variance in species' visit-level detectability
140 [6, 15, 7].

141 One way around this issue is the observation of Bijlsma [1] that site occupancy
142 probabilities can actually be derived from Frescalo via the combination of the
143 standardised species' frequencies \tilde{f}_{ij} and the time-factors x_{jt} , and this has been
144 exploited in at least one published analysis [4]. However, this requires a note of
145 caution: whilst sensitivity analyses published in Hill [6] suggested that the trends
146 in time-factors estimated by Frescalo can be relatively insensitive to the choice of
147 R^* , the benchmark threshold (variation in this parameter changing the intercept
148 of estimated trends but not their slope), the same is not true of back-calculated
149 site occupancy probabilities. Because the relationship between time-factors and
150 species frequencies is non-linear, the shifts in time trend intercept seen using
151 different values of R^* will not translate into the same proportional changes
152 in predicted site occupancies over time (Pescott, pers. obs.) This may be
153 particularly important when these trends are used to classify species' into risk
154 categories, as for example happens in Red Listing exercises [e.g. 12].

155 5. Conclusions

156 Unstructured species occurrence data are too valuable to ignore, especially
157 for historical periods where no information about the visit-level data collection
158 process survives [11]. Hill’s “frequency scaling using local occupancy” or Frescalo
159 method allows the careful analyst to infer a large-scale detectability or effort
160 metric that can subsequently be used to place neighbourhoods on a common
161 footing for the estimation of distribution trends. The large-scale formulation of
162 this approach not only allows for the potential inclusion of more data sources
163 (e.g. records extracted from Atlases or museums), but may also act to reduce
164 the actual error in species’ trends intrinsically [2, 13].

165 By demonstrating how Frescalo collapses the classical occupancy-detection
166 model’s ψ and p into λ , and how it infers visit-related effort via an emergent
167 community-level mean rate, the approach performs an occupancy-detection-
168 type correction even when explicit or informative temporal repeat-visit data
169 are lacking. By highlighting this link, we hope to promote the development of
170 additional diagnostics, extensions and more rigorous uncertainty quantification
171 for the frequency scaling using local occupancy method.

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