

1 **Improving our understanding of adaptive evolution by addressing**  
2 **multi-generational non-genetic responses**

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5 Giacomo Zilio<sup>1</sup>, Stéphanie Bedhomme<sup>1</sup>, Emanuel A. Fronhofer<sup>2</sup>, Staffan Jacob<sup>3</sup>, Delphine  
6 Legrand<sup>3</sup>, Hervé Philippe<sup>3</sup>, Luis-Miguel Chevin<sup>1</sup>

7  
8 <sup>1</sup> CEFE, University de Montpellier, CNRS, EPHE, IRD, Montpellier, France

9 <sup>2</sup> ISEM, University of Montpellier, CNRS, EPHE, IRD, Montpellier, France.

10 <sup>3</sup> Station d'Ecologie Théorique et Expérimentale, CNRS, UAR 2029, Moulis 09200, France

11  
12  
13 Giacomo Zilio<sup>1</sup>, giacomo.zilio@cefe.cnrs.fr, ORCID ID: [https://orcid.org/0000-0002-4448-](https://orcid.org/0000-0002-4448-3118)  
14 3118

15  
16 Stéphanie Bedhomme<sup>1</sup>, stephanie.bedhomme@cefe.cnrs.fr, ORCID ID:  
17 <https://orcid.org/0000-0001-8075-0968>

18  
19 Emanuel A. Fronhofer<sup>2</sup>, emanuel.fronhofer@umontpellier.fr, ORCID ID:  
20 <https://orcid.org/0000-0002-2219-11784X>

21  
22 Staffan Jacob<sup>3</sup>, staffan.jacob@sete.cnrs.fr, ORCID: <https://orcid.org/0000-0003-1956-9646>

23  
24 Delphine Legrand<sup>3</sup>, delphine.legrand@sete.cnrs.fr, ORCID ID: [https://orcid.org/0000-0002-](https://orcid.org/0000-0002-5186-2909)  
25 5186-2909

26  
27 Hervé Philippe<sup>3</sup>, herve.philippe@sete.cnrs.fr, ORCID ID: [https://orcid.org/0000-0002-1335-](https://orcid.org/0000-0002-1335-8015)  
28 8015

29  
30 Luis-Miguel Chevin<sup>1</sup>, luis-miguel.chevin@cefe.cnrs.fr, ORCID ID: [https://orcid.org/0000-](https://orcid.org/0000-0003-4188-4618)  
31 0003-4188-4618

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41 **Abstract**

42 Populations that face abrupt environmental change reducing their fitness can recover by  
43 adaptive genetic evolution over tens to hundreds of generations, but their immediate  
44 responses often involve non-genetic mechanisms. When such non-genetic responses span  
45 multiple generations, their dynamics may be difficult to distinguish from those of genetic  
46 evolution. We here argue that focusing research on such multi-generational non-genetic  
47 responses (MGNGR) should be crucial to better understand and predict eco-evolutionary  
48 responses to environmental stress. We survey the most salient forms of MGNGR (delayed  
49 impact of stress, transgenerational plasticity, and priming), with a focus on how they may  
50 impact the dynamics of observed phenotypic change across multiple generations. Analysing  
51 the rate, stability, and reversibility of MGNGR, as well as their relative contributions to overall  
52 phenotypic responses, and their interactions with genetic changes, should be particularly  
53 fruitful towards a more comprehensive deciphering of evolutionary responses to novel or  
54 changing environments.

## 55 **1) Population responses to stressful environments**

56 Understanding how populations respond to environmental change with detrimental impacts  
57 on biological function and fitness is a critical goal of basic research in ecology and evolution  
58 (Côté *et al.*, 2016; Orr *et al.*, 2020; Taborsky *et al.*, 2021), with important applied  
59 consequences for conservation, global change research, human health and agriculture (Urban  
60 *et al.*, 2024). The two main processes allowing organisms to cope with environmental  
61 challenges *in situ* (i.e., without dispersing) are phenotypic plasticity, the expression by one  
62 genotype of different phenotypes in different environments (Pigliucci, 2005), and genetic  
63 evolution, the increase in frequency of beneficial mutations in a population through natural  
64 selection. These processes are usually thought to occur over clearly distinguishable  
65 timescales, with plasticity taking place within generations, while genetic evolution unfolds  
66 across generations. This assumed timescale separation has consequences for predicted  
67 population responses to environmental stress at the phenotypic and demographic levels. On  
68 the one hand, an immediate plastic response, if adaptive, can limit the initial reduction of  
69 fitness - and potentially population size - in a novel, stressful environment. On the other hand,  
70 adaptive genetic evolution acting on new mutations, standing genetic variation, or a mixture  
71 of both (Orr & Unckless, 2008, 2014), leads to gradual change in traits and fitness that accrues  
72 over generations, and might even prevent extinction of a declining population if sufficiently  
73 fast (Gonzalez *et al.*, 2013), a phenomenon known as evolutionary rescue (reviewed by Bell,  
74 2017). Such a clear-cut timescale difference between plasticity and evolution, if true, would  
75 not preclude interactions among them. For instance, adaptive plasticity may shield  
76 phenotypes from selection, reducing the efficiency of the following adaptive genetic  
77 evolution (Ghalambor *et al.*, 2007). Conversely, non-adaptive or maladaptive plasticity can be  
78 the main driver of compensatory evolutionary changes (Grether, 2005; Ghalambor *et al.*,  
79 2015). Other effects involve interactions of evolution with demography. For instance,  
80 adaptive plasticity can allow populations to persist over the first few generations of exposure  
81 to environmental stress, until natural selection “takes over” to rescue the population, a  
82 phenomenon often described as the Baldwin effect (Simpson, 1953; Crispo, 2007).

83 Nevertheless, this timescale separation between plasticity and genetic evolution, although  
84 conceptually useful, remains a simplified representation of an organism's set of responses to  
85 environmental changes. Non-genetic inheritance (NGI, Bonduriansky *et al.*, 2012;  
86 Bonduriansky & Day, 2018), defined as any form of inheritance that does not rely on DNA,  
87 blurs this separation line, by allowing phenotypic variation (including that induced by the  
88 environment) to spill-over from one generation to the next. Transgenerational plasticity  
89 (TGP), whereby trait expression depends on the environments experienced by the previous  
90 generations, is also increasingly recognized as an important biological phenomenon. Bell &  
91 Hellmann (2019) recently proposed a useful framework to study such responses, reporting  
92 evidence for six different patterns, including bounce-back (visible only in F1 generations) or  
93 persistent effects (still visible several generations after stress exposure; Table 1 in Bell &  
94 Hellman 2019). Using a more systematic approach, (Yin *et al.*, 2019) conducted a meta-

95 analysis on TGP, showing their potentially fundamental role in responses to changing  
96 environmental conditions across a diversity of taxa (see also Herman *et al.* 2014 for a more  
97 adaptive perspective).

98 While NGI and TGP are now well-accepted phenomena, their prevalence and contribution to  
99 the dynamics of environmental stress responses remain underappreciated. There is  
100 accumulating evidence that a diversity of mechanisms can transmit effects of environmental  
101 stress across generations in plants, unicellular eukaryotes, and animals (Quadrana & Colot,  
102 2016; Pilling *et al.*, 2017; Sengupta *et al.*, 2023). Histone modification, patterns of DNA  
103 methylation, and the transmission of non-coding RNAs, are some of the well-elucidated  
104 mechanisms (Bošković & Rando, 2018; Adrian-Kalchhauser *et al.*, 2020). But NGI may be even  
105 more diverse for unicellular organism, where the lack of a soma/germline divide (at the  
106 notable exception of ciliates, see below) means that many aspects of their phenotype,  
107 including proteins, gene regulatory factors and epigenetic modifications, are indeed directly  
108 transmitted to their descendants over multiple generations (Sengupta *et al.*, 2023). In  
109 *Escherichia coli* for instance, the average protein's half-life (~20 hours) is much longer than  
110 its generation time of ~20 minutes under ideal conditions (Moran *et al.*, 2013), and even that  
111 estimated under natural conditions (Gibson *et al.*, 2018). Similarly, the half-life of mRNAs is  
112 often on a similar order of magnitude as the generation time in ideal conditions (Mohanty &  
113 Kushner, 2016).

114 Non-genetic responses to environmental stress can thus span multiple generations, during  
115 which they can accumulate gradually, or decay/revert, depending on their mechanism. In  
116 other words, they can exhibit dynamics similar to those of rapid genetic evolution (Fig. 1),  
117 making these alternatives difficult to distinguish based solely on observations of changes in  
118 phenotypes and fitness. To emphasize this similarity of timescale with evolutionary change,  
119 we describe as multi-generational non-genetic responses (MGNGR) any form of NGI and TGP  
120 with dynamics that span multiple generations. We argue that dismissing the temporal  
121 dynamics of such MGNGR (whether adaptive or not) and their contribution to fitness, and not  
122 clearly distinguishing them from genetic change, is likely to limit our ability to infer and predict  
123 population responses to changing environments, especially in long-term experimental  
124 evolution and common garden experiments. We therefore suggest that making MGNGR a  
125 study object of their own, by considering them explicitly while designing experiments,  
126 deciphering how they interact with adaptive genetic evolution, and how they themselves  
127 evolve, will improve our understanding of eco-evolutionary dynamics in changing  
128 environments.

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## 130 **2) Major types of multi-generational non-genetic responses (MGNGR)**

131 We are interested in population responses to an environmental change that initial causes  
132 substantial maladaptation, manifested by a decrease in fitness. Unless explicitly stated, we  
133 are considering constant conditions following this initial environmental change. The standard

134 scenario for adaptive genetic evolution to such abrupt environmental changes posits that  
135 fitness first declines sharply, then slowly increases again (Fig. 1 middle), through the  
136 establishment and rise in frequency of beneficial mutations (Fig. 1 top). However, different  
137 forms of MGNCR might alter the dynamics of adaptive evolution while closely resembling the  
138 genetic mechanisms. We focus below on three main categories that are particularly relevant  
139 in this context.

## 140 **2.1 Delayed impact of stress: time-to-response**

141 The detrimental impact of environmental change on fitness may be delayed, and only  
142 manifest some generations after exposure to the stressor(s). Delayed impact of stress may be  
143 largely passive, due to purely mechanical or physical reasons that do not involve any  
144 specifically evolved response; or in contrast, an organism may have evolved specific  
145 mechanisms for coping with the stressor. An example of essentially passive delayed impact is  
146 the accumulation of toxic or harmful molecules (*e.g.*, pesticides) that slowly permeate into  
147 cells, and only start to have measurable detrimental impacts once a tolerance threshold is  
148 crossed for the affected cellular functions (*e.g.*, DNA replication, protein synthesis/folding,  
149 cell metabolism or structure). For instance, exposing *Drosophila melanogaster* to silver  
150 nanoparticles induced reproductive costs only from generation F2 onwards, and these costs  
151 increased in the following generations (Panacek *et al.*, 2011). This was due to the  
152 accumulation of oxidative stress and the upregulation of heat shock protein 70, which  
153 reduced flies' investment in reproduction, and thereby fecundity. Similarly, nanoparticle  
154 exposure of *Caenorhabditis elegans* impaired germ cells, leading to reproductive  
155 abnormalities and fecundity reduction only in the F2 generation (Kim *et al.*, 2013). Another  
156 possible cause of passive delay is when a stressor only acts at a specific stage in the life cycle.  
157 For instance, some antibiotics only target newly formed cell membranes (Kohanski *et al.*,  
158 2010), such that they cannot express their detrimental effect until cell division occurs.

159 On the more active side, delayed detrimental impacts of stress could also occur because the  
160 mechanisms for coping against stressors cannot be sustained for long, eventually affecting an  
161 organism survival or reproduction. For instance, specific enzymes, from heat shock proteins  
162 to molecular pumps, have intrinsic biophysical and biochemical limits, beyond which they  
163 cannot operate. This could also be mediated by the resources needed to maintain the coping  
164 machinery. In other words, delays in the onset of stress impacts may be tightly related to the  
165 permanency and stability of immediate stress response mechanisms (which we address  
166 below). The dynamics of this form of MGNCR will resemble baseline expectations for a fitness  
167 decline following environmental changes, but the manifestation of detrimental effects will  
168 only start sometime after the stressor exposure (Fig. 2A, yellow line).

## 169 **2.2 Speed and reversibility of TGP**

170 There is increasing evidence for the importance of TGP in the context of environmental  
171 change (Donelson *et al.*, 2018), both abiotic (Donelan *et al.*, 2020; Castano-Sanz *et al.*, 2022)  
172 and biotic (Tariel *et al.*, 2020; Shahmohamadloo *et al.*, 2024). Despite attempts to

173 conceptualise TGP and its underlying mechanisms (Bell & Hellmann, 2019), a key aspect that  
174 remains understudied is its dynamics over multiple generations. Extending recent arguments  
175 about within-generation plasticity (Burton *et al.*, 2022; Dupont *et al.*, 2024), we suggest that  
176 it would be useful to quantify the whole temporal dynamics of TGP, both within the first F1  
177 generation and in the following ones.

178 An important temporal aspect to consider is the speed of trait change over generations after  
179 exposure to environmental change, that is, the rate of TGP. This rate is likely to affect short-  
180 and long-term responses to stress (fitness), and is thus critical to understand and predict  
181 when the dynamics of MGNGR is likely to mimic those of adaptation through genetic  
182 evolution (Fig. 2B orange line). In a simple scenario, we can envisage that following  
183 environmental change, the trait changes over generations, until reaching a plateau of  
184 stationary trait expression (Fig.3A-B grey line). Populations with a faster rate of TGP (before  
185 the plateau) should have faster fitness increase in face of the stressors, and recover more  
186 quickly from the initial detrimental impacts of environmental stress, without any genetic  
187 evolution. The maximum magnitude of transgenerational plasticity (at the phenotypic  
188 plateau), or TGP capacity, in turn determines to what extent genetic evolution is needed at  
189 all for adaptation.

190 Another important aspect of TGP is the stability (or stationarity) and reversibility of responses.  
191 Most work to date assumes a permanent stress exposure in all generations following the  
192 initial environmental change, as illustrated in our baseline scenario in Fig. 3A (E1). In this  
193 context, a critical question is whether the phenotypic response can be sustained at a  
194 phenotypic plateau (stable response), or instead is only transient, and eventually reverts back  
195 towards its initial value after some generations of exposure. There are several reasons for  
196 which TGP may not be sustained after many generations of exposure. First, responses might  
197 be costly to sustain, for instance because they lead to accumulating defects over generations  
198 (as discussed for the delayed impacts of stress), or because they require important metabolic  
199 investments that trade off against other functions of the organism. Alternatively, TGP could  
200 act as a more emergency mechanism lasting a few generations, such as for heat shock  
201 response to thermal stress (Richter *et al.*, 2010), before it is replaced by more specific and  
202 durable physiological responses. The stability of TGP was empirically investigated in a plant  
203 system. The yellow monkeyflower plant (*Mimulus guttatus*) increased trichome production in  
204 response to wounding that simulated insect damage. This response was stable for 3  
205 generations in the absence of subsequent damage, before starting to decrease to the level of  
206 control unwounded plants in generation 4 and 5 (Akkerman *et al.*, 2016). Interestingly, the  
207 results also suggested that both parents contributed to the TGP responses additively, but via  
208 different mechanism (maternal methylation vs. paternal histone modifications).

209 In scenarios where the environment is changed again after a few generations, such as going  
210 back to its pre-stress value, the crucial question becomes whether - and how fast - the  
211 phenotype can go back to its initial state, *i.e.* how reversible it is (Fig.3B). Differences in the

212 speed of induction vs. reversibility for TGP of osmotolerance were found in the unicellular  
213 alga *Dunaliella salina* (Rescan *et al.*, 2020). Transferring populations across salinity levels  
214 showed that increasing glycerol content (when going from low to high salinity) was much  
215 slower than decreasing it (from high to low salinity), because the mechanisms involved are  
216 completely different: increasing glycerol level requires synthesizing it through metabolism,  
217 whereas decreasing it can be simply achieved by excretion. The asymmetry between synthesis  
218 of molecule and excretion could be a rather common mechanism. Environmental  
219 perturbations can also cause non-genetic changes in gene regulatory networks that are poorly  
220 reversible, as shown in *Escherichia coli* by Zhao *et al.* (2024). Beyond these examples, little is  
221 still known about how reversibility unfolds across generations. Maintaining the machinery to  
222 sense the environment and revert the phenotype is likely to have significant costs, as  
223 emphasized for within-generation plasticity by Hoffmann & Bridle (2022), but  
224 multigenerational reversibility also depends on how the mechanisms of NGI are affected by  
225 patterns of environmental fluctuations among generations.

### 226 **2.3 Trans-generational priming: memory of past responses**

227 Another major class of MGNR is trans-generational priming, whereby prior exposure of an  
228 organism to a stressor (priming) can prepare its descendants to better respond to the same  
229 or different stressors upon later exposure (triggering). Trans-generational priming therefore  
230 occurs across cycles of stress/non-stress. For instance, the descendants of *Escherichia coli*  
231 cells primed with antimicrobial peptides (AMP) exhibited both increased tolerance and  
232 persistence when re-exposed to AMP after some generations (Rodríguez-Rojas *et al.*, 2021).  
233 Similarly, the four- and five-generation descendants of *Saccharomyces cerevisiae* originally  
234 primed with salt exhibited increased resistance to hydrogen peroxide and faster gene  
235 expression. The salt priming in the parental generation activated the synthesis of the long-  
236 lived cytosolic catalase Ctt1p, which was then propagated through generations by NGI (Guan  
237 *et al.*, 2012). Exposure of *Arabidopsis thaliana* to caterpillar herbivory primed the  
238 descendants for enhanced insect resistance for two generations, due to the production of  
239 interfering RNAs (Rasmann *et al.*, 2012). Stress exposure can also prime *E. coli* and/or rewire  
240 the regulatory network for several generations (Zhao *et al.*, 2024) without any immediate  
241 costs. In their extensive review, which included both within- and trans-generational priming,  
242 Hilker *et al.* (2016) briefly proposed some temporal scenarios for primed stress responses (Fig.  
243 2 in Hilker *et al.* 2016). For example, the primed organisms can respond faster or earlier, or  
244 even produce a stronger response with higher amplitude than the non-primed counterparts  
245 upon triggering. Wesener & Tietjen (2019) explored some of these temporal aspects, by  
246 modelling population performance under different (trans-generational) priming and stress  
247 conditions associated with different costs. Faster and earlier responses were favoured under  
248 short and severe/lethal stress, whereas stronger responses were favoured for stress of longer  
249 durations. Nonetheless, empirical studies are still limited, especially those with an  
250 evolutionary perspective. Understanding whether trans-generational priming reduces the  
251 immediate impact of stress upon next exposure (light green line in Fig 2C), or instead leads to

252 faster TGP in subsequent generations (dark green line in Fig 2C), is of central importance to  
253 fully unravel the implications of this process for population dynamics, fitness and evolutionary  
254 trajectories. In addition, it would be necessary to measure for how many generations the  
255 trans-generational priming could last in the absence of re-exposure to stress.

### 256 **3) Empirical approach to disentangle MGNGR from genetic responses**

257 Because they lead to changes in fitness that unfold over multiple generations, the described  
258 MGNGR can phenomenologically resemble genetically-based evolution. To avoid reaching  
259 misleading conclusions about eco-evolutionary processes, it is therefore crucial to identify  
260 MGNGR and measure their dynamics. We suggest below some approaches and ideas to  
261 measure MGNGR while conducting preliminary assays, experimental evolution, and common  
262 garden experiments.

#### 263 **3.1 Establishment of experimental protocol**

264 Preliminary assays and pilot experiments are fundamental steps to optimise protocols,  
265 laboratory conditions, and reduce undesirable technical noise or variation. In experiments on  
266 stress responses, preliminary tests often serve to identify the level of stressor (*e.g.*, dose  
267 concentration or exposure time) that yields sufficiently strong detrimental effects to be  
268 clearly detectable, without leading to rapid extinction of the population. Although it is of  
269 course part of the scientific approach, this step may in some cases lead to discarding (and  
270 potentially biasing) relevant biological information and variation. For instance, a treatment  
271 level leading to rapid population decline might be discarded because the stressor would be  
272 deemed too strong for the envisaged protocol. However, longer observations (*e.g.*, over more  
273 cycles of batch culture in a microbe) might show fitness recovery through MGNGR (Fig. 2B-C),  
274 such that the treatment is actually compatible with long-term evolution. Conversely, a  
275 presumably permissive treatment during a short preliminary test could turn out to represent  
276 stressful conditions over the longer run because of delayed impacts of the stressor (Fig. 2A).  
277 In both cases, performing preliminary assays for a longer time (*i.e.*, over several cycles of  
278 batch culture, or more generations), could allow thoroughly describing a stressor effect on  
279 fitness.

280 From a more applied perspective, these considerations are particularly relevant for  
281 (eco)toxicological studies. Although it is well-known that chemicals and synthetic components  
282 can cause transgenerational effects affecting the basal levels of a pathway and/or molecular  
283 modifications (Oziolor *et al.*, 2017), this is rarely considered in conventional ecotoxicology  
284 tests, which might produce misleading results. Typically, most assays are of short duration  
285 (often stopping when any visible effect is observed), and thereby ignore the temporal and  
286 transgenerational components of stress responses (Brevik *et al.*, 2018; Nilsson *et al.*, 2022).  
287 For instance, descendants from primed populations might have stronger or faster responses  
288 upon exposure to the same or another stressor. Another shortcoming is that these tests often  
289 focus on survival without measuring sublethal effects, or other fundamental fitness  
290 components such as growth and reproduction over generations (Straub *et al.* 2020). Overall,

291 considering non-genetic aspects by (i) implementing longer assays (including across  
292 generations), (ii) sampling at regular intervals to tackle short-term dynamics, and (iii)  
293 measuring additional traits, might directly improve risk assessment and policy making in such  
294 eco-toxicological studies.

### 295 **3.2 Experimental evolution**

296 Experimental evolution is a powerful and versatile research approach to test predictions and  
297 study eco-evolutionary dynamics and their underlying mechanisms in real time under  
298 controlled conditions (Kawecki *et al.*, 2012). Repeated phenotypic assays and measurements  
299 over generations allow tracking the dynamics of change in fitness and other traits of interest.  
300 However, how the MGNGR described above might act during these long-term experiments  
301 and influence their outcomes is still too rarely considered.

302 A first step towards better inclusion of MGNGR involves using order of magnitude  
303 computations to assess whether the timescale of observed changes is consistent with genetic  
304 evolution in the considered biological system. Beyond differences between model systems,  
305 expectations will differ depending on specificities of the experiment, for instance whether  
306 genetic evolution has to involve *de novo* mutations (when starting from isogenic populations),  
307 or can occur via standing genetic variation. Very rapid fitness dynamics taking place over a  
308 few generations are more likely to involve MGNGR than genetic evolution, unless selection is  
309 extremely strong and acts on a genetically diverse population (for instance when the  
310 population of wild types is rapidly depleted and replaced by an initially rare mutant). Making  
311 these arguments more quantitative requires reliable knowledge about mutation rates, levels  
312 of standing genetic variation, and distribution of fitness effects in the studied organism in  
313 response to this particular stressor.

314 Another quantitative aspect to consider is the repeatability of observed responses. Because  
315 of stochasticity in the origin of mutations and random genetic drift, genetic responses to  
316 selection are not expected to occur exactly at the same time and with identical effects (*e.g.*  
317 speed of fitness recovery) in different replicated lines, such that high repeatability of  
318 responses is more consistent with MGNGR. However, this argument should be used with  
319 caution. Highly polygenic traits could have highly repeatable evolutionary responses at the  
320 phenotypic level, despite being underlain by very unpredictable genetic changes because of  
321 high redundancy in their genetic architecture (Ridenhour & Nuismer, 2007; Barghi *et al.*,  
322 2019). Furthermore, the (possibly transient) presence of hypermutator strains, mutation  
323 hotspots, or any other sources of mutation bias, could increase the repeatability of  
324 evolutionary outcomes even at the molecular level (Cano *et al.*, 2023; Sane *et al.*, 2023).

325 The relative contributions of MGNGR vs. allele frequency changes to phenotypic changes at  
326 different timescales can be investigated by using a combination of omics analyses (*e.g.*,  
327 transcriptomics vs. genomics) with phenotypic assays over time. In practice, this would  
328 require assessing the genetic and epigenetic composition of the population at many

329 timesteps, to track the relative frequencies of genomes and epigenomes, together with  
330 phenotypic traits and/or fitness. Nevertheless, even when simultaneous genomic and  
331 phenotypic change is observed, showing that the former explains the latter is challenging  
332 when only using population-based measurements. More progress can be achieved by  
333 isolating genotypes, for instance by creating clonal populations for microbes, before  
334 phenotyping them. However even when this is feasible, deciphering the genotype-phenotype  
335 map remains extremely difficult (Wagner & Zhang, 2011; Aguilar-Rodríguez *et al.*, 2018), as it  
336 requires more resolution (low linkage disequilibrium) than is typically available in  
337 experimental evolution designs. Introducing a mutation of interest in the ancestral  
338 background to isolate its effect (reverse genetics) is another possible approach with model  
339 bacteria. Yet, this remains labour intensive and the dynamics are untraceable without  
340 reducing and precisely controlling the number of mutations to test.

341 In addition to jointly tracking genetic and phenotypic change over time, more insights on the  
342 role of MGNGR in experimental evolution can be achieved by performing more complete  
343 assays, beyond the conditions from the evolution experiment. In particular, sampling lines at  
344 several points during experimental evolution, and exposing them to transfers from control to  
345 stress conditions, would help identify whether the initial response in the experiment was  
346 mediated by genetic or non-genetic mechanisms. Nonetheless, this approach would already  
347 require somewhat precise knowledge about the speed of reversibility (see above) of the  
348 response of interest in the model system. This would also imply some underlying knowledge  
349 of how many generations the study organisms should be maintained in control before  
350 switching back to stress conditions.

### 351 **3.3 Common-garden experiments**

352 Common garden and transplant experiments are standard protocols to evaluate whether  
353 populations from different experimental or natural origins show patterns of local genetic  
354 adaptation. They consist of placing individuals from different origins in the same  
355 environmental condition(s), to remove environmental and non-genetic effects, and thus  
356 quantify the genetic basis and trait variation. Typically, this procedure allows controlling for  
357 the potential misleading outcomes due to parental effects (maternal and paternal), which  
358 have been recognised for a long time (Mousseau *et al.*, 2009; Marshall, 2024). However,  
359 controlling for one generation (parental) might not be enough. As emphasised above,  
360 transgenerational effects are common, and they might lead to wrong inference even for well-  
361 designed studies that only control for parental effects. The extent to which MGNGR have to  
362 be accounted for, and consequently the required number of generations of common garden,  
363 depend on the question asked and the organism. The duration of the common garden should  
364 account for the possibility of long MGNGR when these are suspected, while limiting the  
365 opportunity for *de novo* mutations to arise.

366 A productive way forward would be to systematically measure the dynamics of traits during  
367 the common garden phase. In particular, transferring an organism to standardised laboratory

368 conditions might represent a complex set of changing environmental conditions *per se*, which  
369 could trigger undesired MGNGR. In fact, due to historical contingency, individuals or lines  
370 from different localities or treatments might react differently to the common garden, leading  
371 to a confusion between genetic adaptation and transgenerational effects. Priming might be  
372 the most problematic MGNGR in this context, as it could lead to phenotypic effects in  
373 responses to environments that differ from those where populations have been sampled.  
374 Priming could be particularly difficult to distinguish from the consequences of recent  
375 evolutionary history of stress exposure, *i.e.*, the “ghost of selection past” (Connell, 1980;  
376 Samani & Bell, 2016), making the explicit study of the timing of adaptation through multiple  
377 generations particularly important in eco-evolutionary studies.

378 Here again, more progress can be made by explicitly addressing MGNGR. For instance,  
379 samples can be transferred from different natural environments (or evolutionary treatments)  
380 to control condition / common garden, and then back from control to treatment, to measure  
381 the rate of phenotypic change in response to these environmental changes. Additionally,  
382 changing the environment gradually *vs.* abruptly (or modifying stress intensity and duration)  
383 could highlight differences in transient dynamics and potential costs.

#### 384 **4) The evolution of transgenerational effects**

385 Although the main accepted mechanism of adaptive evolution (at least in the long run) is  
386 change in allele frequency by natural selection (Charlesworth *et al.*, 2017), MGNGR can lead  
387 to dynamics of phenotypic change over generations that may mimic patterns thereof. In  
388 addition, MGNGR can produce variation on which selection may act, and they may themselves  
389 vary genetically, and thus evolve. We propose some promising basic research questions on  
390 this topic, to hopefully motivate more theoretical and empirical studies and stimulate further  
391 discussion.

392 A first critical question towards understanding evolution of MGNGR is how selection operates  
393 on them. We still know little about which pattern of environmental change favours each type  
394 of response and why, but theory has started exploring this problem as reviewed by  
395 Bonduriansky & Day (2009) for NGI and recently discussed their book (Bonduriansky & Day,  
396 2018). Furrow & Feldman (2014) found that slow temporal environmental fluctuations can  
397 lead to the evolution of more faithfully transmitted transgenerational effects (and  
398 conversely), providing that their underlying mechanisms entail little costs (see also Rivoire &  
399 Leibler, 2014). More recently, a population-genetic model of two habitats interconnected by  
400 dispersal found that adaptive transgenerational effects were likely to evolve under moderate  
401 dispersal, and when the direction of selection differed between habitats (Greenspoon &  
402 Spencer, 2018). However, to our knowledge little attention has still been given to the  
403 evolution of dynamic aspects of MGNGR, such as the rate of TGP, the stability and reversibility  
404 of responses across generations, or the duration of priming.

405 Another fundamental question is the genetic basis and heritability of these processes. This is  
406 mostly an empirical question, which likely depends on the mechanisms of non-genetic  
407 inheritance. Field studies have shown the contribution of transgenerational mechanisms in  
408 generating phenotypic variation in natural populations (Husby, 2022). Supporting the idea  
409 that transgenerational effects can evolve by natural selection, laboratory experiments  
410 demonstrated the presence of genetic variation for such processes. For instance, Alvarez *et*  
411 *al.* (2021) showed genotypic-specific TGP responses to temperature for several phenotypic  
412 traits in *Arabidopsis thaliana*. Similarly, Cayuela *et al.*, (2022) found that in the ciliate  
413 *Tetrahymena thermophila* the TGP of traits related to dispersal was determined by their  
414 genotypes.

415 Beyond the evolution of transgenerational effects, a key question is how they influence  
416 genetic evolution. First, heritable non-genetic phenotypic changes can mask genotypic  
417 variation from selection, thereby modifying evolutionary trajectories (Sengupta *et al.*, 2023).  
418 In addition, some mechanisms of non-genetic inheritance can interact with the origination of  
419 genetic variation. In particular DNA methylation, by influencing mutation rate and transposon  
420 insertion, can affect genome stability, and therefore directly contribute to DNA sequence  
421 evolution (Ashe *et al.*, 2021; Yi & Goodisman, 2021). These combined influences of epigenetics  
422 on selection and mutation could lead to potentially strong positive effects on adaptive  
423 evolution, opposite to the abovementioned buffering hypothesis. Such interactions between  
424 transgenerational effects and genetic evolution have been investigated in a few experimental  
425 studies. An evolutionary experiment with an engineered strain of *Saccharomyces cerevisiae*  
426 showed that transgenerational effects can modify rates of evolutionary adaptation (Stajic *et*  
427 *al.*, 2019). Intermediate levels of transgenerational gene silencing of the URA3 gene locus,  
428 responsible for the production of uracil (an essential component for cell growth), enabled  
429 better survival and faster adaptation to a novel environment (Stajic *et al.*, 2019). This occurred  
430 because transgenerational silencing increased the effective population size, thereby  
431 facilitating the appearance of new mutational targets and alleles that could accelerate  
432 adaptation. Further, the transgenerational gene silencing interacted with the novel alleles,  
433 rendering the transgenerational gene silencing itself more stable and strongly heritable. Using  
434 the same strains, the authors additionally showed that transgenerational gene silencing  
435 provided an adaptive advantage under fluctuation regimes (Stajic *et al.*, 2022). In another  
436 study, Kronholm *et al.*, (2017) evolved populations of the unicellular green alga  
437 *Chlamydomonas reinhardtii* for two hundred asexual generations in three different  
438 environments (high salt, low phosphate, and high CO<sub>2</sub>). The populations genetically adapted  
439 in all environments and increased their fitness. The authors additionally evolved algal  
440 populations in parallel treatments (same environmental conditions and time period), but they  
441 genetically and chemically reduced the amount of non-genetic variation produced and  
442 transmitted. Decreasing non-genetic variation reduced or impeded adaptation to the high salt  
443 and CO<sub>2</sub> environments. In contrast, lower levels of non-genetic variation had little role in  
444 adaptation to low phosphate. Overall, these results highlight the role of transgenerational

445 effects in adaptive evolution, and how this might depend on the environmental context.  
446 Smith *et al.* (2016) even found that transgenerational effects might explain behavioural  
447 isolation and divergence between fish of the genus *Etheostoma*, with potential consequences  
448 for speciation, thus scaling up to macro-evolutionary scale.

449 Interestingly, differences between MGNGR and genetic adaptation might sometimes not be  
450 fundamentally clearcut, even conceptually (not only experimentally), and cases exist where  
451 MGNGR and genetic adaptation mechanistically cross each other. Ciliates, unicellular  
452 eukaryotes characterised by nuclear dimorphism (germline and somatic), are an  
453 extraordinary example in which TGP might actually occur through genetic mechanisms. In  
454 brief, genetic mutations can occur in both their nuclei, but during sexual reproduction the  
455 somatic nucleus is lost, with (almost) no transfer to descendent cells. Thus, genetic evolution  
456 in the somatic nucleus can be considered a form of TGP at the scale of their sexual generations  
457 (Verdonck *et al.*, 2021).

458 We suggest that a productive future line of research would be to investigate how the  
459 dynamics of MGNGR influence their effects on genetic evolution. For instance, MGNGR that  
460 are both rapidly induced and stable through time could be expected to have more long-lasting  
461 influences on genetic evolution. This could be investigated by manipulating the dynamics of  
462 MGNGR through engineering where feasible, as done by (Kronholm *et al.*, 2017). The  
463 development of new theoretical work could help refine predictions and expectations to  
464 empirically demonstrate a direct relationship between non-genetic and genetic responses,  
465 suggest experimental design strategies, and inform on specific ecological conditions favouring  
466 each of these phenomena.

## 467 **5) Concluding remarks**

468 Although their relevance for adaptation is still being debated (Charlesworth *et al.*, 2017), NGI  
469 and TGP are an integral part of population responses to environmental change (Bonduriansky  
470 & Day, 2018; Donelson *et al.*, 2018; Sengupta *et al.*, 2023). Evidence is mounting that such  
471 responses are not only repeatable and widespread, but can also span multiple generations  
472 (which we describe as MGNGR), and thus take place over similar timescales as rapid genetic  
473 evolutionary responses. Modern techniques allowing for precise in-depth investigations of  
474 the underlying mechanisms are now available to go a step further in our comprehension of  
475 the many forms of MGNGR, provided we make them an object of study rather than a mere  
476 nuisance parameter. Here, we highlighted some major types of MGNGR, and proposed  
477 empirical assays that could help identify such effects and understand their consequences.  
478 Critical insights could be gained by jointly tracking changes in genotypes frequencies and  
479 within-genotypes phenotypic changes, in common gardens (see also de Villemereuil *et al.*,  
480 2016), evolutionary experiments, or natural populations. This would provide precious  
481 information on the extent of these effects, and on their relative contributions to short- and  
482 long-term responses to environmental change. In the current context of global changes,

483 explicitly considering the contribution of MGNGR to population responses to environmental  
484 changes, and potentially of adaptation, may prove particularly important.

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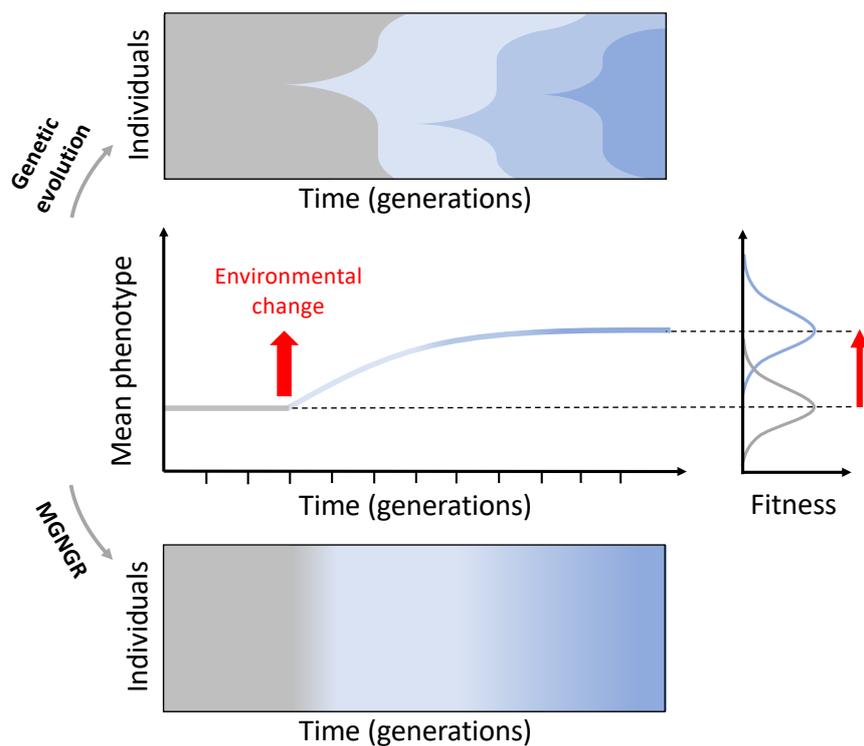
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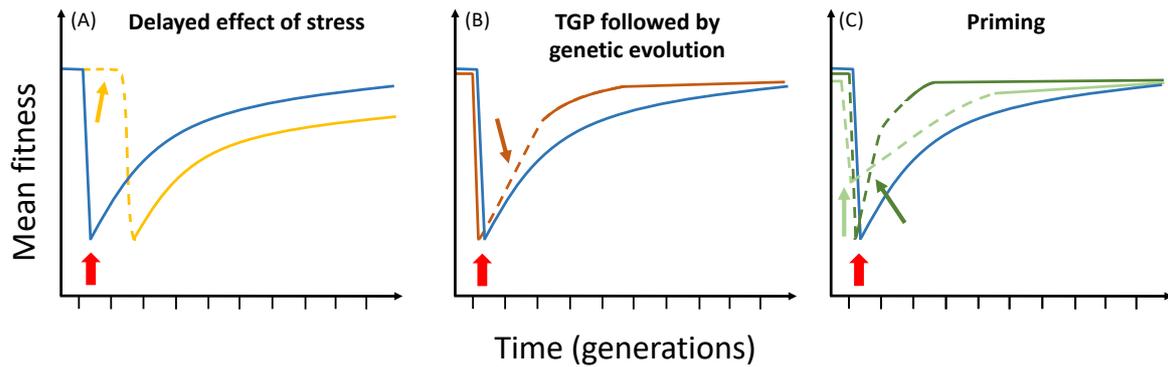
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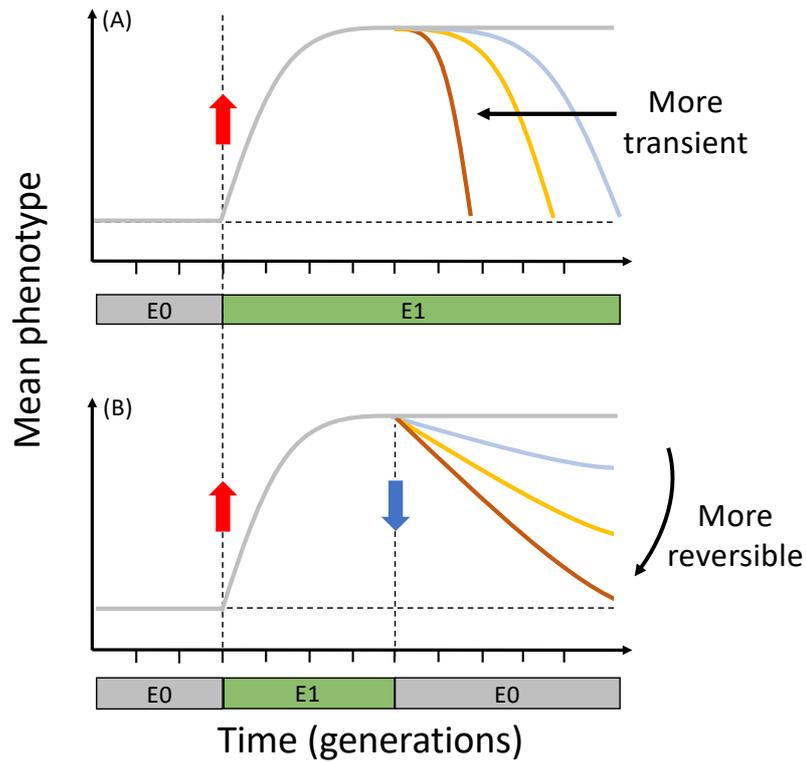
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679  
 680 **Figure 1** Phenotypic response to environmental change can result from either genetic evolution (top panel) or  
 681 multi-generational non-genetic response (MGNGR, bottom panel). The line in the middle panel represents the  
 682 dynamics of the mean value of a phenotypic trait, following an environmental change (red arrow). The curves  
 683 on the right depict the fitness landscape before and after environmental change, with an optimum phenotype  
 684 shifted upwards (grey to blue fitness landscape). The Muller plot in the top panel represents the canonical case  
 685 of genetic evolution caused by changes in the genetic composition of the population, with an appearing colour  
 686 denoting a new mutation/genotype. The bottom panel illustrates MGNGR, in which the environment  
 687 experienced by one generation gradually impacts the phenotype of the following generations (from light grey  
 688 to dark blue), homogeneously in the population.  
 689



690  
 691 **Figure 2** Examples of dynamics of mean population fitness over time after an environmental change (bottom  
 692 red arrow), under different mechanisms of MGNGR. The blue line in all panels illustrates the baseline scenario,  
 693 with an instantaneous effect of stress reducing mean fitness, followed by adaptation via genetic evolution. The  
 694 coloured lines illustrate different forms of MGNGR mechanisms. Their effects are shown with dashed lines, and  
 695 are followed by genetic evolution in full lines. (A) Delayed effect of stress (yellow). (B) Dynamic TGP (orange).  
 696 (C) Priming effect of previous stress exposure on initial fitness drop (light green), or on rate of fitness recovery  
 697 by dynamic TGP (dark green).  
 698



699

700

701 **Figure 3.** Stability and reversibility of phenotypic responses across generations. (A) Transient dynamics occur

702 when the phenotypic trait goes back to its initial state, even though the environment has remained unchanged

703 following the initial environmental shift (from E0 to E1), indicated by the red arrow. The grey line is a non-

704 transient phenotypic response, while coloured lines show increasingly transient responses from light blue to

705 orange. (B) Reversibility is the tendency of a phenotype to go back to the initial state after the environment has

706 changed back (from E1 to E0), as indicated by the blue arrow. The grey line shows an irreversible phenotype,

while coloured lines show increasingly reversible responses from light blue to orange.