

# Density dependence impacts our understanding of population resilience

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**Data availability statement** The data that support the findings of this study are openly available at [www.compadre-db.org](http://www.compadre-db.org). Code will be archived in Zenodo and available at the time of publication in a peer-reviewed journal.

## Abstract

Current metrics of demographic resilience (e.g., resistance, recovery) summarize the potential responses of populations to the frequent, varied disturbances that ecological systems experience. Much of the application of these metrics has focused on the potential response of time-invariant, density-independent structured population models to hypothetical disturbances. Here, we examine such resilience measures in a flexible structured model with five vital rate parameters. Making one vital rate density-dependent at a time, we show that density dependence has profound and complex impacts on our understanding of resilience. Depending on which vital rate was subject to density effects, existing measures of demographic resilience (compensation, resistance, and recovery time) either increased or decreased with population density. Moreover, the density-independent model under-predicted the recovery time of the corresponding density-dependent model, with a greater offset for species with longer generation times and higher iteroparity. Our findings demonstrate the importance of underlying non-linear processes when examining demographic resilience.

# 1 Introduction

Ecological systems are exposed to a variety of disturbances. In the broadest sense, a disturbance is any a/biotic impact that causes a temporary change in the underlying biological processes of a system, potentially pushing it away from its equilibrium. Examples of disturbances include a hurricane knocking down adult trees in a stand (Horvitz et al., 1995), pollutants decreasing fertility (Levin et al., 1996), or the introduction of an invader that leads to the decline of endemic species (Doody et al., 2009). As a result of frequent disturbances in natural systems (Turner, 2010), ecological systems may spend little time at equilibrium (Coulson, 2021; Hastings, 2010; Hastings et al., 2018). Consequently, a major focus of ecology is to understand how ecological systems respond to these myriad disturbances (e.g., Horvitz et al., 1995; McLauchlan et al., 2020; Paniw et al., 2017). As human-induced impacts on biodiversity continue (Butchart et al., 2010; Jaureguiberry et al., 2022) and the frequency of disturbances increases (Turner, 2010), there is an urgent need to identify which species are most likely to persist (Hare et al., 2016; Hernández-Yáñez et al., 2022; Urban, 2015). The study of ‘resilience’ holds promise for addressing this urgent need (Capdevila et al., 2020; Ingrisch and Bahn, 2018; Scheffer et al., 2015). At its core, resilience is related to concepts of stability: when perturbed, does the system return to its previous (equilibrium) state –and how quickly does it return– or do the dynamics change dramatically in such a way that the system is attracted to a new equilibrium (Hastings et al., 2018)?

In natural populations, the demographic resilience framework (Capdevila et al., 2020; Stott et al., 2011) describes how populations are expected to respond to perturbations to population structure. Population structure is the relative distribution of individuals in a population across different size, stage, or age classes. Perturbations to population structure might arise from, for example, fires (Sah et al., 2010), hurricanes (Horvitz et al., 1995),

26 or changes in hunting pressure (Coulson et al., 2004). This framework of demographic  
27 resilience (Capdevila et al., 2020; Stott et al., 2011) is based on matrix population models,  
28 where the fates and reproductive contributions of individuals that are classified by their  
29 age, size, and/or developmental stage are followed in discrete time (Caswell, 2001). In  
30 these models, the long-term deterministic behaviour of the population is growth at the  
31 rate  $r = \log \lambda$ , where  $\lambda$  is the leading eigenvalue of the population projection matrix. If  $\lambda$   
32 is greater than 1, the population is predicted to grow in the long term, and if  $\lambda$  is less than  
33 1, to decline. When the population follows this deterministic behaviour, the population  
34 maintains a stable distribution across classes: the relative size of each (st)age class is  
35 constant, while the total population size grows or declines. When the relative size of the  
36 (st)age classes changes, the short-term growth rate can vary dramatically from  $\lambda$  (Stott  
37 et al., 2011). Natural populations are generally near, but not at, their stable distributions  
38 (Williams et al., 2011), leading to mismatches between the expected and realized population  
39 growth rate over the short term. An important assumption in this demographic resilience  
40 framework is that the vital rates (e.g., survival, maturation, reproduction) that define the  
41 matrix population model are density-independent (Stott et al., 2011).

42 Vital rates are commonly affected by population density, with important implications  
43 for population and community dynamics. At the population level, negative density depen-  
44 dence can lead the population size to be stable, to cycle, or to follow chaotic dynamics;  
45 the outcome typically depends on the life history of the species (Neubert and Caswell,  
46 2000). In Soay sheep (*Ovis aries*), interactions between climate and population density  
47 cause population size to cycle between increases and crashes (Coulson et al., 2001). When  
48 reproductive output is subject to negative density dependence, adult survival is more im-  
49 portant to population dynamics and reproduction less important as population density  
50 increases (Layton-Matthews et al., 2019). At low population densities, low encounter rates

51 between individuals can significantly inhibit reproduction, driving small populations to  
52 extinction (“Allee effects” Courchamp et al. 1999). Meanwhile, at the community level,  
53 density-dependent regulation is crucial to our understanding of species diversity. The-  
54 ory predicts that coexisting species should exhibit stronger intra-specific competition (i.e.,  
55 within-population negative density dependence) than inter-specific competition (Chesson,  
56 2000). This theoretical expectation is strongly supported by empirical evidence from plant  
57 communities, which overwhelmingly exhibit stronger intra- than inter-specific competition  
58 (Adler et al., 2018; Metz et al., 2010; Wills et al., 1997).

59 Matrix population models are generally evaluated at a particular density, rather than  
60 being constructed as explicitly density-dependent models (Crone et al., 2011). Even when  
61 density has been manipulated as part of the experimental design, these models are often  
62 constructed as ‘high-density’ and ‘low-density’ populations (Meekins and McCarthy, 2002;  
63 Oli et al., 2001). As a result, the vast majority of models archived in the COMADRE  
64 and COMPADRE databases (Salguero-Gómez et al., 2015; Salguero-Gómez et al., 2016a),  
65 which are among the largest repositories of published population models, do not explicitly  
66 include density effects. Since there is currently limited access to density-dependent ma-  
67 trix population models, past work on demographic resilience (Capdevila et al., 2022; Stott  
68 et al., 2011; Stott et al., 2012) has not taken density effects into account. This aspect  
69 is especially important since demographic resilience usually examines population change  
70 relative to disturbances in population structure and/or size. Currently, the implicit as-  
71 sumption is that a population’s resilience is the same given a certain structure, regardless  
72 of overall population size. Under density dependence, this assumption is likely not to hold.  
73 Even given the same population structure and size, resilience could be different if density  
74 dependence operates differently through time in terms of life cycle stages and vital rates  
75 affected.

76 Here, we explore the implications of density-dependent vital rates on the study of de-  
77 mographic resilience. We take a virtual species approach by simulating density-dependent  
78 effects on the vital rates of a two-stage matrix population model. By varying the com-  
79 bination of vital rate values, we explore a wide range of possible life history strategies.  
80 With these models, we ask the following questions: (i) How would the unobserved effects  
81 of density change our interpretation of population resilience?, (ii) How do the effects of  
82 density on resilience depend on life history strategy? Finally, we investigate the difference  
83 in transient behaviour of the density-independent and density-dependent models to (iii)  
84 assess whether the density-independent models currently in use could predict qualitative  
85 behaviour of the density-dependent models. We conclude by suggesting that the discipline  
86 is insufficiently equipped to study demographic resilience in non-linear systems, and offer  
87 suggestions to expand our toolbox to examine populations in their natural settings.

## 88 **2 Methods**

89 To examine the role of density dependence on demographic resilience across a wide vari-  
90 ety of life history strategies, we defined a two-stage population model following Neubert  
91 and Caswell (2000). The two stages of this model are non-reproductive and reproduc-  
92 tive individuals, with new offspring being placed into the non-reproductive class. An  
93 important addition to the Neubert-Caswell model here is the potential for individuals to  
94 retrogress (i.e., move ‘backwards’ in their development) from the reproductive class to the  
95 non-reproductive class. Including retrogression is important for accurately representing  
96 the life cycles of many plants (Salguero-Gómez and Casper, 2010) and some animals (Cant  
97 et al., 2023; Wikelski and Thom, 2000) that have the ability to drastically decrease in size.  
98 For simplicity of language from this point on, we refer to the non-reproductive class as  
99 “juveniles” and the reproductive class as “adults.” Since some life cycles are best under-

100 stood in terms of size, here we note that our framework also applies to size-based models,  
 101 in which case readers might want to think of the classes as “small” and “large” individuals.  
 102 The transition probabilities that link them would then be growth (instead of progression)  
 103 and shrinkage (instead of retrogression).

$$104 \quad \begin{bmatrix} n_j(t+1) \\ n_a(t+1) \end{bmatrix} = \begin{bmatrix} \sigma_j * (1 - \gamma) & \phi + \sigma_a \rho \\ \sigma_j * \gamma & \sigma_a * (1 - \rho) \end{bmatrix} * \begin{bmatrix} n_j(t) \\ n_a(t) \end{bmatrix} \quad (1)$$

105 The resulting model has five vital rates: juvenile survival probability ( $\sigma_j$ ), juvenile  
 106 progression probability ( $\gamma$ ), adult survival probability ( $\sigma_a$ ), adult retrogression probability  
 107 ( $\rho$ ) and adult per-capita reproductive output ( $\phi$ ). The population is projected forward in  
 108 time by multiplying the population vector, composed of the current number of juveniles  
 109 ( $n_j$ ) and adults ( $n_a$ ), by the projection matrix.

## 110 2.1 Density dependence in demographic parameters

111 To explore the effects of density on population resilience, we made each vital rate density  
 112 dependent, such that individual performance decreases with increasing density (Bonen-  
 113 fant et al., 2009; Layton-Matthews et al., 2019; Shepherd and Cushing, 1980; Takada and  
 114 Nakashizuka, 1996). For survival, progression, and reproductive output, we used an expo-  
 115 nential form of negative density dependence (Eq. 2). We chose this form because Neubert  
 116 and Caswell (2000) found that their matrix population models had a stable equilibrium (at  
 117 certain vital rate combinations/ranges) for density dependence on any of the vital rates.  
 118 The general form is

$$119 \quad \alpha(N) = \alpha_{max} e^{-N}, \quad (2)$$

120 where  $\alpha_{max}$  is the maximum value that a given vital rate can take, and  $\alpha(N)$  is that vital  
 121 rate’s value at a given value of population density ( $N = n_a + n_j$ ).

122 The only vital rate that did not follow this functional form in our model framework  
123 was retrogression ( $\rho$ ). In plant systems, the optimal size decreases when resource avail-  
124 ability or habitat suitability decreases (Csergő et al., 2017; Salguero-Gómez and Casper,  
125 2011); the same occurs in some animals (Cant et al., 2023; Wikelski and Thom, 2000).  
126 Since a higher density implies lower per-capita resource availability, we would expect the  
127 mean size of individuals to decrease with increasing density. Therefore, when retrogression  
128 is density-dependent, we would expect retrogression probability to increase with higher  
129 population density. Rather than the exponential form in Equation 2, here we used a satu-  
130 rating functional form, where retrogression probability is 0 at very low densities ( $N \approx 0$ )  
131 and increases up to a selected maximum value (asymptotically):

$$132 \quad \rho(N) = \rho_{max} \ln(N + 1) \quad (3)$$

133 To ensure that  $\rho(1)$  would have a pre-determined value, we set  $\rho_{max}$  to  $\frac{\rho(1)}{\ln 2}$ . This value is  
134 the result of re-arranging Equation 2 to solve for  $\rho_{max}$ .

135 To compare the response to population density across a wide range of life history  
136 strategies, we re-scaled our models. The population densities of, for example, elephants  
137 and mice in a given unit of habitat area are on different orders of magnitude (Santini  
138 et al., 2018). Rather than being concerned with the absolute population densities, we  
139 examined demographic resilience when populations were ‘far from carrying capacity’ vs.  
140 ‘near carrying capacity.’ So, we scaled our models to a carrying capacity of 1, enabling us  
141 to examine the resilience of all life history strategies across the same range of population  
142 density values, from  $N = 0$  to  $N = 1$ .

143 We carried out our scaling as follows. For each density-dependent vital rate ‘case’, we  
144 selected all parameters except for reproductive output ( $\phi$ , or  $\phi_{max}$  in the case of density-  
145 dependent reproductive output). Then, we solved for the value of reproductive output that



146 would cause the population to be at a stable equilibrium point at  $N = 1$ . The equations  
147 for reproductive output as a function of the other vital rates, for each density-dependent  
148 case, are given in Appendix Section S1. This scaling caused  $\phi_{max}$  to be rather high for  
149 life history strategies with low survival. Indeed, to successfully invade, a species with low  
150 survival would have to produce a high number of propagules (Stearns, 1977). As  $\sigma_j$ ,  $\sigma_a$ ,  
151 and  $\gamma$  increased, the required  $\phi_{max}$  decreased (Figure S1). This relationship also caused  
152 the population growth rate ( $\lambda$ ) at low density to vary across life history strategies, with  
153 higher  $\lambda$  in shorter-lived life history strategies (Figure S2). Meanwhile, regardless of life  
154 history strategy, our scaling for a carrying capacity of 1 means that  $\lambda$  always equals 1 at a  
155 density of 1 (Figure S2).

## 156 **2.2 Selecting virtual species**

157 When all five vital rates can vary due to density dependence, the possible population  
158 models represent a large five-dimensional space. This would make it difficult to visualize  
159 how resilience and its response to density vary across life history strategies. To overcome  
160 this challenge, we selected a subset of 16 vital rate combinations that represent the ‘space’  
161 of life history strategies as archived in the COMADRE (Salguero-Gómez et al., 2016a)  
162 and COMPADRE (Salguero-Gómez et al., 2015) databases. In their versions 4.23.3.1 and  
163 6.23.5.0, these databases comprise 3,448 and 8,994 matrix population models for animals  
164 and plants, respectively. The majority of these models (>95%) have been digitized from  
165 the published literature. Here, we give a brief overview of how we used these databases to  
166 select our virtual species models. For the full details, see Appendix Section S2.

167 We first defined a subset of high-quality models from the COMADRE and COMPADRE  
168 databases that represent wild populations under control (“unmanipulated”) conditions.  
169 Next, we collapsed each of those selected models to the same  $2 \times 2$  matrix form given in

170 Equation 1 following (Salguero-Gómez and Plotkin, 2010), using the `mpm_collapse` function  
171 in the `Rage` package (Jones et al., 2022). Finally, we performed a principal component  
172 analysis (PCA) on the collapsed empirical matrix population models to project the five  
173 vital rates into a reduced dimensional space (Figure S3). We retained the first two principal  
174 component (PC) axes because together they captured 70% of the variation among models  
175 from COMADRE and COMPADRE (PC1: 43.83%; PC2: 26.25%). PC1 was primarily  
176 explained by variation in survival ( $\sigma_j, \sigma_a$ ) and progression ( $\gamma$ ), such that longer-lived and  
177 late-maturing species score positively on PC1, while short-lived and fast-maturing species  
178 score negatively. PC2 was primarily influenced by reproductive output ( $\phi$ ), such that  
179 species with high reproductive output score positively on PC2 (Supplemental Table S1).  
180 As such, we refer to virtual species that fall in the upper left quadrant (low scores on PC1  
181 and high scores on PC2) as exhibiting fast life histories, and we refer to those that fall in  
182 the lower right quadrant (high scores on PC1 and low scores on PC2) as exhibiting slow  
183 life histories.

184 To define our virtual species, we inspected the distribution of empirical values of vital  
185 rates in our final set of 1,285 collapsed two-stage models. Based on these distributions, we  
186 selected a high and low value for juvenile survival ( $\sigma_j$ ), juvenile progression ( $\gamma$ ), and adult  
187 survival ( $\sigma_a$ ) (Table S2). For retrogression ( $\rho$ ), we set the low value as 0 (no retrogression  
188 at all), and we set our high value near the mean of empirical values in models from the  
189 databases where retrogression was greater than 0 (Table S2). We then projected our  
190 virtual species models across density-dependent scenarios onto the PC axes as defined by  
191 the empirical models. Our virtual species models cover the space of naturally observed  
192 populations reasonably well (Supplemental Figure S3). Based on our model scaling, for  
193 some virtual species and density-dependent vital rate scenarios, the virtual species plotted  
194 at much higher values of PC2 than seen in the empirical models (Supplemental Figure S4).

195 For plotting and analyses, we restricted the virtual species to combinations of vital rates  
196 and density-dependent scenarios that had a score on PC2 of  $\leq 5.1$  for population densities  
197 between 0 and 1.

### 198 **2.3 Density-independent resilience metrics**

199 We explored how population density, via effects on individual vital rates, would impact  
200 previously-studied metrics of demographic resilience (Capdevila et al., 2020; Stott et al.,  
201 2011). These previously-studied metrics are density-independent, but we can calculate  
202 them for a population projection matrix built at a particular density. In essence, we an-  
203 alyzed how our understanding of resilience would change if demographers had measured  
204 vital rates when the population was at low density vs. high density. To do so, we calcu-  
205 lated *compensation*, *resistance*, and *recovery time* for the (density-independent) population  
206 projection matrix built from vital rates at various values of density between  $N = 0$  and  
207  $N = 1$  (Figure 1A).

208 Compensation is the propensity for a population to ‘boom’ after a disturbance. Com-  
209 pensation is calculated as the largest possible population size, relative to a population  
210 growing at a rate  $\lambda$ , in the first time step after a disturbance (Capdevila et al., 2022). In  
211 general, this maximum one-time-step population growth rate would occur when the entire  
212 population is concentrated in the most fecund stage class. In our two-stage model, this  
213 situation corresponds to a scenario where only adults remain after a disturbance.

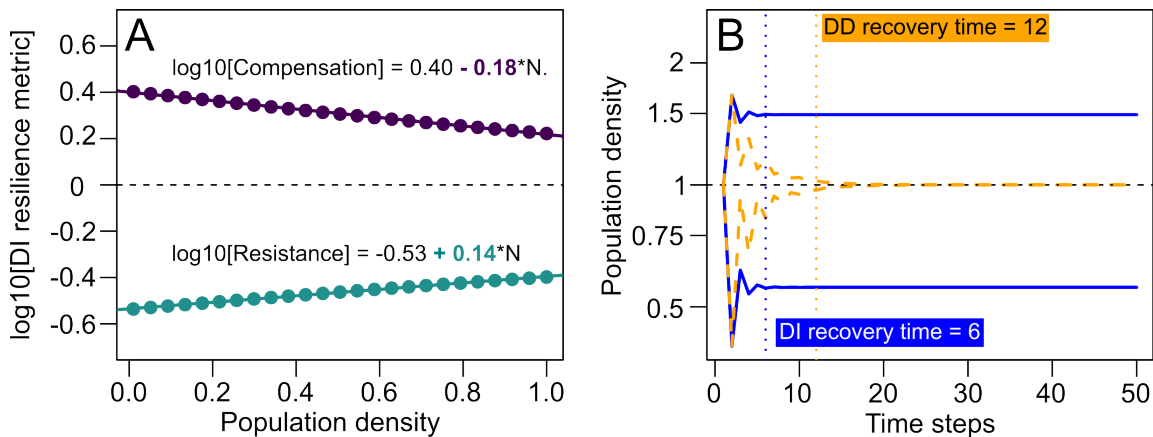
214 Resistance is the ability of a population to prevent further losses after a disturbance.  
215 Resistance is calculated as the smallest possible relative population size in the first time step  
216 after a disturbance (Stott et al., 2011). In general, this minimum one-time-step population  
217 growth rate would be achieved if the entire population were concentrated in the most  
218 vulnerable and least fecund stage class (e.g., juveniles in our two-stage model). Populations

219 can vary greatly in their degree of resistance from those whose abundance changes little  
220 following a disturbance even when individuals are concentrated in the most vulnerable and  
221 least fecund class (high resistance, metric close to 1) to those whose abundance crashes  
222 (low resistance, metric close to 0).

223 Recovery time is here defined as the number of time steps until all possible stage-  
224 biased trajectories converged back to asymptotic dynamics. A stage-biased trajectory  
225 has an initial condition (i.e., following a disturbance) where all remaining individuals are  
226 in a single stage class. For each possible stage-biased initial condition, we iterated the  
227 population model until the one-step-ahead population growth converges to  $\lambda$  using the  
228 `convt()` function in the `popdemo` package (Stott et al., 2012). We then measured recovery  
229 time as the maximum time across the possible initial conditions. In our model, there are  
230 two possible stage-biased initial conditions: only adults, and only juveniles. Note that this  
231 definition of recovery time is a change from recent publications on demographic resilience  
232 which used a definition of recovery time closely based on the damping ratio (e.g., Capdevila  
233 et al., 2020; Capdevila et al., 2022). Past analyses have indicated that the damping ratio  
234 is a poor measure of time to convergence (Stott et al., 2011). All density-independent  
235 resilience metrics were calculated using the `popdemo` package in R (Stott et al., 2012).

236 We analyzed the relationships between vital rates and resilience metrics in our virtual  
237 species using linear regression models in R (R Core Team, 2023). For each resilience  
238 metric, we fit two separate regression models. First, we fit a linear regression with strictly  
239 additive terms for all five vital rates. Second, we fit a linear regression for the first two  
240 principal component axes including additive terms and their interaction. We used these  
241 models to interpret the importance of different vital rates and the PC axes in driving the  
242 values of compensation, resistance, and recovery time by focusing on the effect sizes (i.e.,  
243 regression coefficients). However, we do not report p-values because statistical power is

244 artificial in virtual species approaches (White et al., 2014), such as the one presented here.  
 245 In essence, any desired p-value could be achieved by modulating the sample size and the  
 246 level of replication of each virtual species across multiple density values for multiple vital  
 247 rate scenarios.



**Figure 1:** Examples for some key calculations regarding demographic responses to disturbances using transient dynamics. In both examples, reproduction decreases with increasing population density, and the vital rates are juvenile survival  $\sigma_j = 0.4$ , juvenile progression  $\gamma=0.9$ , adult survival  $\sigma_a = 0.6$ , and adult retrogression probability  $\rho=0$ . (A) At each value of population density (the plotted points), we calculated the density-independent resilience metrics (compensation in purple, resistance in green) from the density-independent matrix population model evaluated at the corresponding value of population density. We then fit a line to the  $\log_{10}$ -transformed resilience metrics, finding in this example that compensation decreased with population density (negative slope), while resistance increased with population density (positive slope). Note that we also calculated the slope of density-independent recovery time in the same way. (B) The recovery process of a density-independent and density-dependent model are distinct, even when they start from the same initial conditions. For this combination of vital rates, the density-independent model requires six time steps to recover back to asymptotic dynamics. Meanwhile, the density-dependent model requires 12 time steps to recover back to the carrying capacity.

248 We also explored how life history strategy interacted with density-dependent effects on  
 249 resilience metrics. To do so, we calculated the slopes of  $\log_{10}$ -transformed compensation,  
 250 resistance, and recovery time with population density using the `lm` function in R v.4.3.2  
 251 (R Core Team, 2023) (Figure 1A). We calculated these slopes for each combination of  
 252 juvenile survival, progression, adult survival, and retrogression across the full range of

253 possible values for those vital rates. To examine broad differences across density-dependent  
254 scenarios, we plotted the distributions of slopes for each resilience metric as histograms for  
255 each density-dependent scenario. To relate these slopes to life history strategy, we focused  
256 on how slopes changed across the full range of possible values of adult survival ( $\sigma_a$ ) and  
257 progression ( $\gamma$ ). For a subset of virtual species across the full range of adult survival  
258 and progression but with a single value of juvenile survival ( $\sigma_j = 0.6$ ) and retrogression  
259 ( $\rho = 0.3$ ), we plotted the slopes as colour contours using the `levelplot` function from  
260 the `lattice` package (Sarkar, 2008). We chose these two vital rates because of their clear  
261 mathematical connection with generation time (Gaillard et al., 2005), which is itself an  
262 important proxy for life history speed (Healy et al., 2019; Paniw et al., 2018; Salguero-  
263 Gómez et al., 2016b). When progression rate is high and adult survival is low, species would  
264 exhibit precocious maturation and short mature life span, leading to a short generation  
265 time—we refer to this type of life history as ‘fast.’ Conversely, when progression rate is low  
266 and adult survival is high, species would have delayed maturation and long mature life  
267 span, leading to a long generation time—therefore this would be a ‘slow’ life history.

## 268 **2.4 Analysis of transient envelopes**

269 The addition of density-dependence to vital rates in the population models we explored  
270 here fundamentally changed the transient dynamics of those models. Not only did the  
271 density-independent metrics of resilience change with population density, but the process  
272 of recovery itself changed. This is because the density-dependent model will be attracted  
273 back to its equilibrium population size (a single point), while the density-independent  
274 model will be attracted to the asymptotic growth rate (a curve) (Figure 1B). Following  
275 Stott et al. (2011), we projected our virtual species forward in time from an all-juvenile  
276 or all-adult post-disturbance distribution, starting from a population density of 1. For

277 the first time step, the density-dependent and density-independent models are the same  
278 (Figure 1B). However, the entries of the density-dependent matrix model vary through  
279 time as density affects its target parameter: one of the five vital rates in our two-stage  
280 matrix population model (Eq. 1).

281 We examined whether the density-independent transient period is predictive of the  
282 density-dependent transient period. To that end, we calculated the recovery time in both  
283 models, and compared them. In the density-independent model, the recovery time is (as  
284 explained above) the elapsed time before both the upper and lower transient bounds return  
285 to following asymptotic dynamics (Stott et al., 2012). Because the transient bounds are  
286 calculated by iterating the standardised model ( $\hat{\mathbf{A}} = \mathbf{A}/\lambda$ ; Stott et al. 2011), population  
287 size in the standardised model stops changing when the model converges (solid blue line  
288 in Fig. 1B). In the density-dependent model, the transient bounds will both eventually  
289 return to a population size of 1, the carrying capacity we pre-defined for our density-  
290 dependent models (dashed orange line in Fig. 1B). We defined the density-dependent  
291 recovery time as the time until the distance between the upper and lower bound was  
292 smaller than 0.1; this distance could be achieved when both bounds cross within 5% of  
293 the carrying capacity, or when one of the bounds has reached carrying capacity and the  
294 other is 0.1 population size units away. To compare these two values of recovery time, we  
295 defined the difference in recovery time ( $\Delta RecoveryTime$ ) as the difference between the  
296 density-independent definition of recovery time (`convt()` from the `popdemo` package; Stott  
297 et al. 2011) and the density-dependent definition of recovery time (as defined here).

298 We also investigated how life history traits relate to the convergence time of the density-  
299 dependent model. We focused on generation time as a proxy for the position of the species  
300 along the fast-slow continuum (Gaillard et al., 2005), and the degree of parity as a measure  
301 of reproductive strategy (Salguero-Gómez et al., 2016b). For generation time, we calculated

302 the average age difference between parents and offspring (Bienvenu and Legendre, 2015).  
303 For degree of parity, we calculated Demetrius' entropy, which measures how spread out  
304 reproduction is across an individual's lifespan (Demetrius, 1977). Previous research has  
305 shown that both life history traits adequately capture a species' life history strategy (Healy  
306 et al., 2019; Paniw et al., 2018; Salguero-Gómez et al., 2016b). For both life history traits,  
307 we used the functions `gen_time` and `entropy_d`, respectively, from the `Rage` package (Jones  
308 et al., 2022).

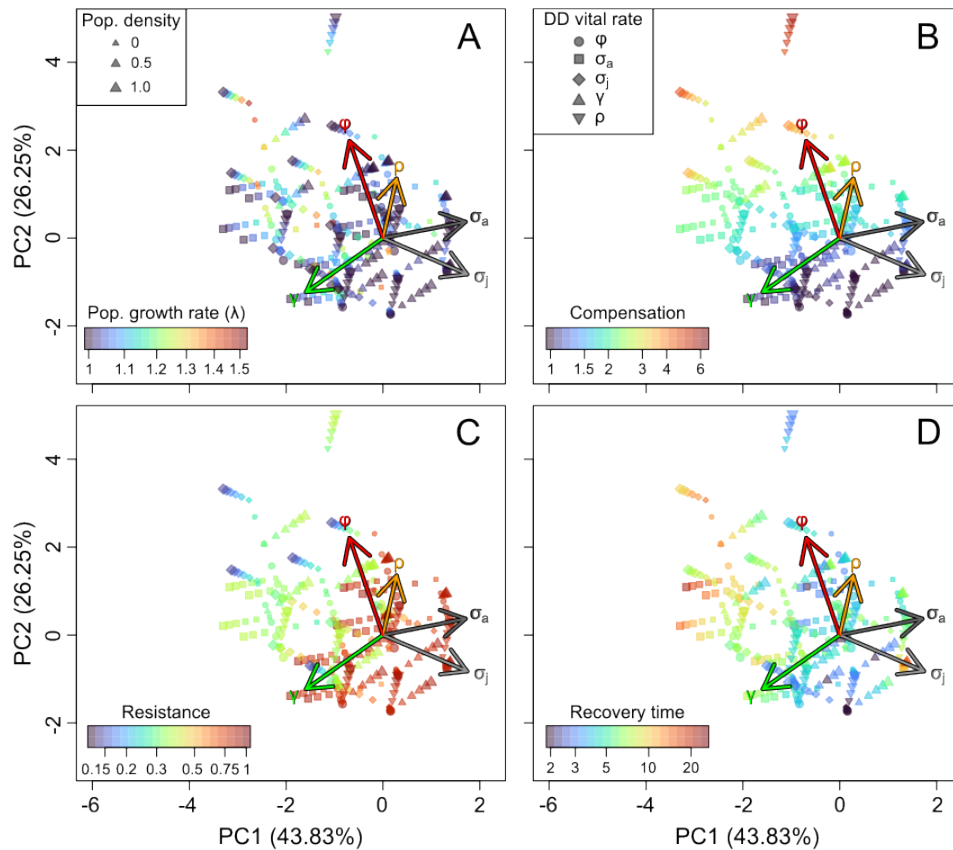
309 We note that, in our comparisons of density-dependent and density-independent mea-  
310 sures of convergence time, we present p-values for correlation coefficients and an ANOVA  
311 analysis. In this section, each combination of a virtual species and density dependence  
312 scenario occurs at most once, for a sample size of 54 models. We acknowledge that the  
313 p-values are a tenuous measure of significance (see White et al. 2014), but we argue that  
314 the p-values provide a useful benchmark for examining the patterns resulting from our  
315 analyses.

### 316 **3 Results**

317 Density dependence affected our interpretation of demographic resilience. The strength  
318 and direction of the impact of density dependence on resilience metrics depended on both  
319 life history strategy and the specific vital rate target of density dependence. Because of  
320 our model scaling, faster life histories exhibited stronger density-dependent effects on their  
321 overall population growth rate (Figure 2A). Indeed, because we scaled the reproductive  
322 output ( $\phi$ ) so that all virtual species would have a carrying capacity of 1, fast life histories  
323 have high reproductive output and high values of population growth rate ( $\lambda$ ) at low density,  
324 as evidenced by red colour (low  $\lambda$ ) being associated with small points (low density), in  
325 the top-left area of Figure 2A (fast life history space). Equivalent patterns are not as



326 pronounced in the bottom right of the figure (slow life history space).



**Figure 2:** Resilience metrics in virtual species models change across life history strategies and density-dependent scenarios for (A) population growth rate, (B) compensation, (C) resistance, and (D) recovery time. The vital rates are: juvenile survival ( $\sigma_j$ ), adult survival ( $\sigma_a$ ), juvenile progression ( $\gamma$ ), adult retrogression ( $\rho$ ), and reproductive output ( $\phi$ ). The principal component (PC) axes were defined by the matrix population models parameterised with data from natural/wild populations under control conditions from 1,285 populations of animals and plants (see Figure S3). The virtual species have then been projected onto the PC axes. Life history speed generally increases with PC2 (increasing reproductive output), and decreases with PC1 (increasing survival), such that slow life histories are located towards the bottom-right of the PCA space and fast life histories are located towards the top-left. Each virtual species was modelled with density-dependence on each of the five vital rates (see top-right insert in panel B). For each density-dependent scenario, the virtual species model was calculated for six values of density between 0 and 1 (plot symbols sized according to population density).

327 In our virtual species models, compensation was most strongly influenced by repro-

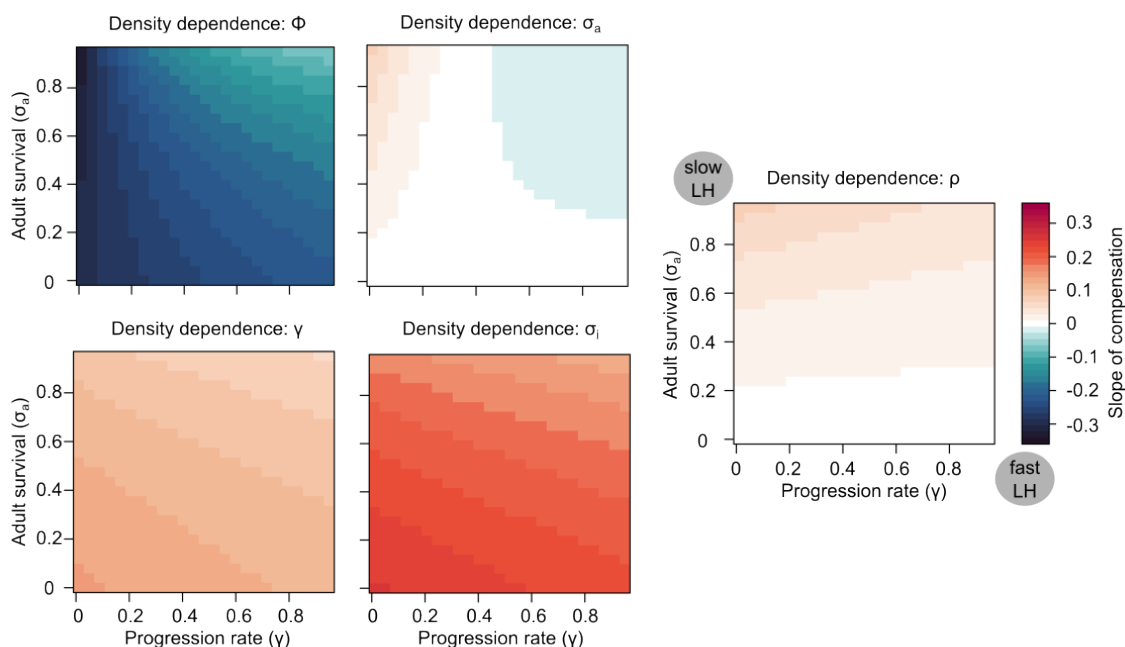
328 ductive output (Figure 2B, Supplemental Table S3). Although most vital rates influenced  
329 compensation, the coefficients were both positive and negative (Supplemental Table S3).  
330 As a result, the effect of PC1 on compensation was much smaller than the effect of PC2  
331 (Supplemental Table S3). As such, virtual species with higher reproductive output and  
332 faster life histories exhibited higher compensation (redder colours in the upper left of Figure  
333 2B). Conversely, resistance was highest in species with slow life histories (redder colours  
334 to the lower right of Figure 2C). Resistance was most strongly influenced by juvenile sur-  
335 vival, with limited influence from other vital rates (Supplemental Table S3). Recovery  
336 time decreased with adult survival and juvenile survival, but increased with retrogression  
337 (Supplemental Table S3). As a result, recovery time was longest in virtual species with  
338 low survival and high retrogression (redder colours to the far left in Figure 2D).

339 Compensation either increased or decreased with population density, depending on  
340 the vital rate that was affected by density dependence (Figure 3). Compensation always  
341 decreased at higher population density (negative slope) when reproductive output was den-  
342 sity dependent, and always increased at higher population density (positive slope) when  
343 density-dependence acted via juvenile survival (Figure S5). When density dependence op-  
344 erated via adult survival, the response of compensation to density was rather weak (Figure  
345 3), with the distribution of slope values centered on 0 (Figure S5). For progression and  
346 retrogression, compensation tended to increase with density (positive slopes; Figure 3), al-  
347 though the distribution crossed 0 (Figure S5). The response to density was clearly stronger  
348 when reproductive output or juvenile survival were density-dependent (absolute value of  
349 mean slope  $\approx 0.2$ , Supplemental Figure histograms), in agreement with our results in Fig-  
350 ure 2B that compensation was most closely related to reproductive output and juvenile  
351 survival.

352 In general, fast and slow life histories exhibited similar slopes of compensation across

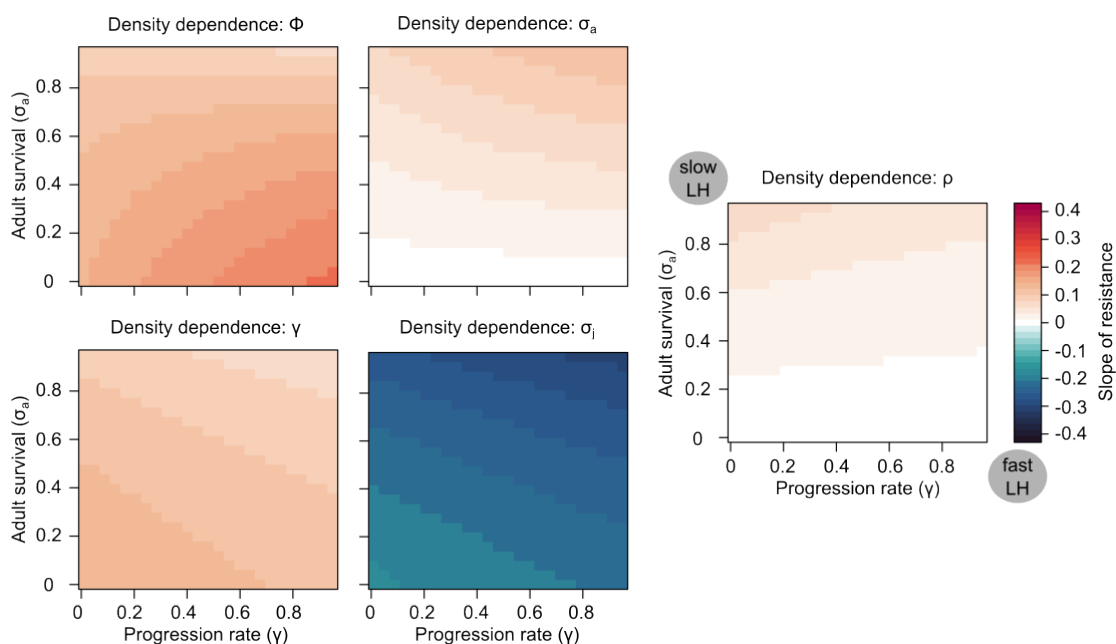
353 densities (Figure 3). In other words, moving from a fast to a slow life history did not indicate  
 354 a change in how strongly compensation would respond to density when reproductive output,  
 355 progression, and juvenile survival were density dependent (see how the color contours  
 356 in Figure 3 connect the upper left and lower right corners of the panels for  $\phi$ ,  $\gamma$ , and  
 357  $\sigma_j$ ). However, when retrogression was density-dependent, then the strongest response  
 358 of compensation to population density was in species with a slow life history (delayed  
 359 progression and high adult survival).

360 Resistance tended to increase with population density in all scenarios except for density-



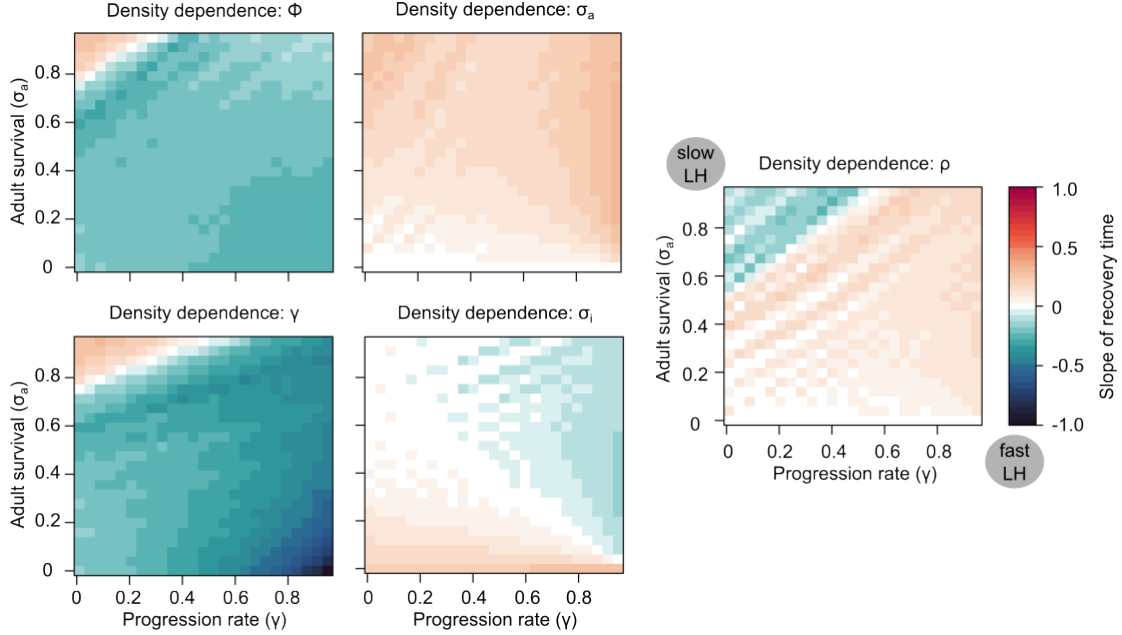
**Figure 3:** Strength of density effects on compensation varies with both life history strategy and density-dependence scenarios. The color contours indicate the slope of compensation as a function of population density. Redder colors indicate that compensation increased with increasing population density, while bluer colors indicate that compensation decreased with increasing population density. Slow life histories are in the upper left of each panel, and fast life histories are in the lower right. These slope surfaces are shown for models with intermediate juvenile survival  $\sigma_j = 0.6$  and with retrogression rate  $\rho = 0.3$ . To see how slope changed across juvenile survival  $\sigma_j$  and adult retrogression  $\rho$  values within each scenario, see Figures S10-S9.

361 dependent juvenile survival (Figure 4 and S11). Like for compensation, the strongest  
 362 response to population density was observed for the density-dependent reproductive output  
 363 and juvenile survival cases. When reproductive output was density-dependent, resistance  
 364 increased with population density most strongly in fast life histories, and the response  
 365 was weaker in slow life histories. When juvenile survival was density-dependent, changes  
 366 in slope were not related to life history speed; instead, the steepest slope emerged when  
 367 individuals matured early and had high adult survival (Figure 4).



**Figure 4:** Strength of density effects on resistance varies with both life history speed and density-dependence scenarios. The color contours indicate the slope of resistance as a function of population density. Figure details are the same as in Figure 3. To see how slope changed across  $\sigma_j$  and  $\rho$  values within each scenario, see Figures S16-S15.

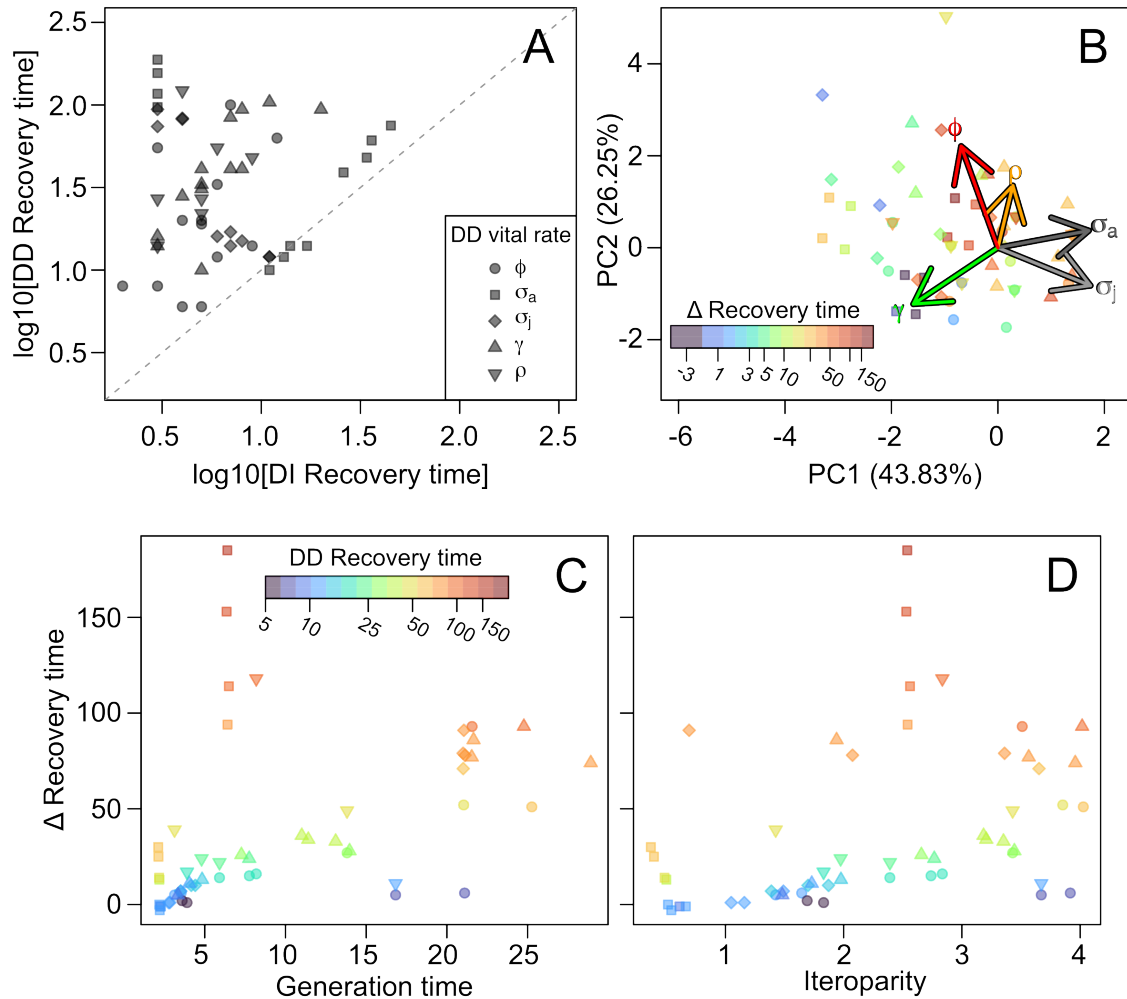
368 Responses of recovery time to changes in population density were highly variable (Fig-  
 369 ure 5). The steepest slopes of recovery time with density were seen when progression or  
 370 reproductive output were density-dependent. When progression or reproductive output



**Figure 5:** Strength of density effects on recovery time varies with both life history strategy and density-dependence scenarios. The color contours indicate the slope of recovery time as a function of population density. Figure details are the same as in Figure 3. To see how slope changed across juvenile survival  $\sigma_j$  and adult retrogression  $\rho$  values within each scenario, see Figures S22-S21.

371 were density-dependent, recovery time decreased at higher population densities for slow  
 372 life histories, and recovery time increased at higher population densities for fast life histo-  
 373 ries (Figure 5). In the other vital rate cases, the response of recovery time to changes in  
 374 density did not follow any consistent patterns.

375 Adding density dependence to our demographic models fundamentally changed the pro-  
 376 cess of recovery, as shown in Figure 1B. Because we tuned our models such that the carrying  
 377 capacity is at a population size/density of 1, we can compare the transient envelopes from  
 378 the density-independent and density-dependent cases. We show one example in Figure 1B,  
 379 but note that the shapes of the transient envelopes can vary dramatically across our vir-  
 380 tual species and depending on which vital rate is density-dependent (Supplemental Figures



**Figure 6:** The density-independent (DI) model under-predicts recovery time compared with the density-dependent (DD) model. Panel A shows the relationship between density-independent recovery time and density-dependent recovery time for the virtual species models. Panel B shows the same virtual species on the PCA space as in Figure 2, colored according to  $\Delta \text{RecoveryTime}$ . Panels C and D show how  $\Delta \text{RecoveryTime}$  relates to the generation time (C) and degree of iteroparity (D). The different shapes, across all panels, indicate the different density-dependent vital rate scenarios. The color scale shown in panel C applies to panel D as well.

382 The recovery time of the density-independent model nearly always under-predicted the

383 recovery time of the density-dependent model, without a significant relationship between  
384 the two recovery time measures ( $r = 0.03, p = 0.80$ ; Figure 6A). There was no pattern to  
385 the offset between recovery time in the density-dependent and density-independent models  
386 ( $\Delta RecoveryTime$ ) based on which vital rate was the target of density dependence (ANOVA  
387  $F_{4,49} = 0.787, p = 0.54$ ). In the vital rate PCA space,  $\Delta RecoveryTime$  increased along  
388 PC1 ( $\Delta RecoveryTime = \beta_1 * PC1 + \beta_2 * PC2$ :  $\beta_1 = 11.8, p=0.01$ ;  $\beta_2 = 8.1, p=0.12$ ),  
389 indicating that species with greater survival and delayed progression should take longer  
390 to recover (Figure 6B). Moreover, we found a significant correlation of  $\Delta RecoveryTime$   
391 with both generation time ( $r = 0.44, p < 0.001$ ) and iteroparity ( $r = 0.37, p = 0.005$ ). In  
392 other words, as generation time increased or species became more iteroparous, the density-  
393 independent model was worse at predicting recovery time of the density-dependent model.  
394 If adult survival was density-dependent, then the density-independent model performed  
395 particularly poorly (Figure 6C and D).

## 396 4 Discussion

397 In the face of myriad disturbances that characterise the Anthropocene, the study of re-  
398 silience promises to help ecologists and managers identify the species and ecosystems most  
399 likely to persist (Enquist et al., 2024). Resilience is closely related to concepts of sta-  
400 bility (Hastings et al., 2018) and, in demographic models, long-term asymptotic system  
401 behavior (Capdevila et al., 2020; Stott et al., 2011). Although population density has  
402 important impacts on individual and population performance (e.g., Bonenfant et al., 2009;  
403 Layton-Matthews et al., 2019; Takada and Nakashizuka, 1996), density-dependence has  
404 been neglected in past studies of demographic resilience. Here, we show that density  
405 dependence has profound and complex impacts on our understanding of demographic re-  
406 silience. Depending on which vital rate (e.g., survival, reproduction) is subject to density

407 effects, existing measures of demographic resilience (compensation, resistance, and recov-  
408 ery time sensu Capdevila et al. 2022; Stott et al. 2011) can either increase or decrease  
409 with population density. Importantly, the strength of density-dependence in our resilience  
410 metrics was often uncorrelated with life history speed: the apparent resilience of fast and  
411 slow life histories often responded the same way to density-dependence. We also found that  
412 the recovery time of a density-independent model did not predict the recovery time of the  
413 corresponding density-dependent model. In fact, the offset between the density-dependent  
414 and density-independent definitions of recovery time were correlated with life history: in  
415 species with longer generation time and greater iteroparity, the density-independent model  
416 is even worse at predicting recovery time of the underlying density-dependent dynamics.

417 Our results generally agree with past examinations linking metrics of demographic re-  
418 siliance and life history traits. For instance, using 162 populations of 69 animal species  
419 from COMADRE and 748 populations of 232 plant species from COMPADRE, all explicitly  
420 density-independent, Capdevila et al. (2024) showed that species with high reproductive  
421 output compensate more, resist less and tend to take longer to recover. Here, we found the  
422 effects of reproductive output on compensation, resistance, and recovery time to be in the  
423 same direction as previously reported, but the effect of reproductive output was only domi-  
424 nant over other vital rates in the relationship with demographic compensation. Generation  
425 time, a strong marker of life history speed (Gaillard et al., 2005), was found to influence  
426 the transient dynamics across 111 mammal species (Gamelon et al., 2014). Additionally,  
427 Capdevila et al. (2022) found that slow life histories take longer to recover following a  
428 disturbance. In agreement with this finding, here we report longer recovery times for  
429 slow life histories, as well as more severe under-estimation of recovery time in the density-  
430 independent compared with density-dependent model ( $\Delta RecoveryTime$ ). These authors  
431 also found kingdom-specific responses for resistance: resistance increases with generation



432 time in animals but decreases in plants (Capdevila et al., 2024). These kingdom-specific  
433 responses may be linked via the more frequent ability of plants to shrink (Salguero-Gómez  
434 and Casper, 2010) than in animals (but see Wikelski and Thom 2000), an aspect that can  
435 be explicitly explored in future steps via our flexible structured population model. Regard-  
436 less, the general agreement between both studies and ours, despite their lack of explicit  
437 consideration of density dependence, may be due to their strict data selection criteria,  
438 which might have implicitly incorporated self-regulation effects in the matrix models.

439 In some cases, we found counter-intuitive relationships between resilience and density.  
440 For example, when juvenile survival was density-dependent, compensation increased with  
441 population density. This counter-intuitive result arises from an indirect effect of density on  
442 compensation, via the direct effect of density on population growth rate ( $\lambda$ ). Compensation  
443 is calculated as the maximum column sum of the standardized population matrix ( $\hat{\mathbf{A}}$ ).  
444 Given that survival rates are bounded between 0 and 1, while fertility rates are often greater  
445 than 1 (Salguero-Gómez et al., 2015; Salguero-Gómez et al., 2016a), compensation is often  
446 determined by the fertility entries. Therefore, in our two-stage model, compensation is  
447 determined by the second column sum of  $\hat{\mathbf{A}}$ . So how does the density effect on juvenile  
448 survival, which appears only in the first column, impact compensation? The change in  
449 compensation arises because of the standardization ( $\hat{\mathbf{A}} = \mathbf{A}/\lambda$ ). As juvenile survival  
450 decreases with density,  $\lambda$  decreases, and so the sum of the second column of  $\hat{\mathbf{A}}$  actually  
451 increases. The same general principle applies for each of the vital rate scenarios where  
452 resistance increased with increasing density. This indirect effect of vital rates on resilience  
453 via a change in  $\lambda$  is both striking and easily interpreted in our two-stage model, but we may  
454 expect different results in larger, more complex life cycles and their resulting structured  
455 population models. Unlike the  $2 \times 2$  model that we used here, most (93%) matrix population  
456 models archived in COMADRE and COMPADRE have more than two stages. In fact, 89%

457 of the models that we used for selecting our virtual species model were  $3 \times 3$  or larger, and  
458 53% of them were  $5 \times 5$  or larger (Supplemental Figure S28).

459 Our findings have important implications for the study of invasive species. Amplifica-  
460 tion (here referred to as compensation), one of the three key components of demographic  
461 resilience (Capdevila et al., 2020), has recently been reported to be a strong predictor of in-  
462 vasiveness (Iles et al., 2016; Jelbert et al., 2019). However, neither of these two works dealt  
463 with models that explicitly incorporated density dependence - although we did find here  
464 that compensation and reproductive output are correlated in density-dependent models.  
465 Early in the invasion of a species, logically population size (and thus density) tends to be  
466 low, a feature that has attracted much attention via the so-called ‘paradox of invasion’ (Sax  
467 and Brown, 2000). However, the extent to which amplification remains a good predictor  
468 of performance of invasive populations as they become established, and how amplification  
469 may clarify the paradox of invasion, are promising next steps of research.

470 Our findings clearly highlight the need for more research aimed at understanding the  
471 role of density dependence in populations at risk of extinction. We found that the currently-  
472 available density-independent demographic models underestimate recovery time if the un-  
473 derlying vital rates are density-dependent. The underestimation of recovery time was most  
474 severe when species have long generation times and/or high iteroparity. Because animal  
475 species with long generation times are also more vulnerable to extinction under climate  
476 change (Pearson et al., 2014), understanding how these species respond to changes in pop-  
477 ulation density may be most urgent. Interestingly, generation time does not appear to be  
478 a strong predictor of extinction risk in plants (Hernández-Yáñez et al., 2022; Salguero-  
479 Gómez, 2017), suggesting that different processes may be most important. In vertebrates,  
480 the vital rates with the strongest evidence of density dependence are age or size of maturity  
481 (e.g. progression in our model) and reproductive output (Bassar et al., 2010). Meanwhile,

482 we found that resilience was most impacted by density-dependent effects when either repro-  
483 ductive output or juvenile survival were the targets of density dependence. Taken together,  
484 this suggests that density effects on reproductive output may be the best place to start  
485 integrating density-dependence into demographic models.

486 The existing framework of demographic resilience is insufficient to examine the tra-  
487 jectory of a density-dependent model after a disturbance. Instead of analysing the de-  
488 mographic resilience of a fully-specified density-dependent matrix population model, we  
489 built a series of hypothetical density-independent models by calculating the vital rates  
490 that a population would have at each population density. We were constrained to this  
491 approach because the framework of demographic resilience relies on analysis of population  
492 size relative to the asymptotic population growth and requires that populations start from  
493 a population size/density that is standardised to 1 following a one-off (i.e., pulse) distur-  
494 bance (Stott et al., 2011; Stott et al., 2012). These generalisations make less sense in a  
495 density-dependent scenario where the model has an asymptotic population growth rate  
496 ( $\lambda$ ) of 1 (no net growth once the population reaches equilibrium). Instead, for density-  
497 dependent models, measuring relative to carrying capacity is more relevant and encom-  
498 passes elements of both population size and asymptotic stability. Indeed, in our models  
499 we set carrying capacity, rather than initial population size, to equal 1. As a result, our  
500 density-dependent transient analyses measure the recovery time back to the equilibrium  
501 population size and structure (see example in Figure 1B). Past work examining the dynam-  
502 ics of density-dependent structured population models has focused on the local stability  
503 of the carrying capacity, defining reactivity as the propensity of perturbations from equi-  
504 librium to grow before decaying back to the stable equilibrium (Caswell, 2019; Caswell  
505 and Neubert, 2005; Neubert and Caswell, 1997). This approach, like what we have done  
506 here, focuses on perturbations to the system when it is at equilibrium. However, Caswell

507 (Caswell, 2019, p. 207) notes that the local stability approach is based on the inherent  
508 system dynamics, while the indices put forward by Stott and colleagues (Capdevila et al.,  
509 2020; Stott et al., 2011) are based on the transient responses to a particular initial condi-  
510 tion. Further work will be needed to analyse the transient responses of density-dependent  
511 models to perturbations that cause a particular initial condition. Still, we have shown  
512 that there is one resilience metric that can be generalised to both density-dependent and  
513 density-independent models: recovery time. We found that density-dependent recovery  
514 time was nearly always longer than density-independent recovery time, indicating that the  
515 non-linear model has a greater probability of long transient periods (Hastings et al., 2018).

516 In our modelling framework, density dependence and disturbance are separate pro-  
517 cesses, but it is likely that they interact in natural systems. In a perennial plant population,  
518 the impact of density on both vital rates and population growth rate depended on whether  
519 the plot had experienced a fire that year or not (Gornish, 2013). For red deer (*Cervus*  
520 *elaphus*) in Scotland, the cessation of culling led to both changes in population density and  
521 population structure, resulting in long-term transient dynamics and density-dependent os-  
522 cillations (Coulson et al., 2004). Transient life table response experiment (LTRE) analysis  
523 holds the potential to disentangle the effects of variation in vital rates and variation in  
524 population structure (Knape et al., 2023; Koons et al., 2016), such as could result from the  
525 interacting effects of density-dependence and disturbance. However, transient LTREs have  
526 so far been underutilized, perhaps because fewer than 40% of the publications archived in  
527 the COMADRE and COMPADRE databases (a representative sample of published matrix  
528 population models) include data on observed population distributions (Gascoigne et al.,  
529 2023).

530 In spite of the idiosyncratic patterns of resilience across densities and life history strate-  
531 gies, a few patterns with life history strategy remain reliable. Specifically, compensation

532 is greatest and resistance lowest in fast life histories, and vice versa in slow life histories.  
533 Additionally, we found that recovery time estimates from the density-independent frame-  
534 work were furthest from the recovery time of the true underlying density-dependent model  
535 in virtual species with long generation times and high iteroparity. Therefore, identifying  
536 density-dependent effects in more slow-living species, where there are already more conser-  
537 vation concerns (Lande 1998; Purvis et al. 2000, but see Paniw et al. 2018) may be most  
538 urgent for predicting responses to disturbance and management intervention. Finally, to  
539 truly understand the resilience of natural populations of plants and animals, then we must  
540 update transient dynamics methods and the demographic resilience framework to accom-  
541 modate time-varying vital rates. These advances will substantially improve our ability to  
542 predict the responses of species to the myriad and increasingly frequent disturbances they  
543 face.

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## Section S1 Model tuning for density dependence

For each scenario, we solved analytically for per-capita reproductive output ( $\phi$ ) or maximum per-capita reproductive output ( $\phi_{max}$ ) value that corresponds to the population model having its equilibrium population size ('carrying capacity') at a density of 1. Density is calculated as a simple sum of the number of juveniles and adults ( $N(t) = n_j(t) + n_a(t)$ ).

The method for solving for  $\phi$  or  $\phi_{max}$  is as follows:

- A. Write the population projection matrix with one vital rate as a function of density, following the form  $r(N) = r_{max}e^{-bN}$ .
- B. Solve for the equilibrium population distribution for juveniles  $\hat{n}_j$  and adults  $\hat{n}_a$  that are unchanged by projection to the next time step.
- C. Set  $\hat{n}_j + \hat{n}_a = 1$  and solve for  $\phi$  (or  $\phi_{max}$  in the case where  $\phi$  is the density-dependent vital rate).

The analytical solutions are as follows:

### Density-dependent juvenile survival

$$\phi = \frac{[1 - (1 - \gamma)\sigma_{j,max}e^{-b}] [(1 - \gamma) - \sigma_a(1 - \rho)(1 - \gamma)]}{\gamma(1 - \gamma)\sigma_{j,max}e^{-b}} - \sigma_a\rho \quad (S1)$$

### Density-dependent progression

$$\phi = \frac{-1}{\sigma_j\gamma_{max}e^{-b}} \left[ \sigma_a\rho(\sigma_j - 1) + (\sigma_a - 1) \left( 1 - \sigma_j(1 - \gamma_{max}e^{-b}) \right) \right] \quad (S2)$$



### Density-dependent adult survival

$$\phi = \frac{1 - \sigma_j(1 - \gamma) - \sigma_{a,max}e^{-b} [\sigma_j\gamma\rho + (1 - \rho)(1 - \sigma_j(1 - \gamma))]}{\sigma_j\gamma} \quad (\text{S3})$$

### Density-dependent retrogression

$$\phi = \frac{1}{\sigma_j\gamma} [(1 - \sigma_a)(1 - \sigma_j(1 - \gamma)) - \sigma_a\rho_{max} \ln 2(\sigma_j - 1)] \quad (\text{S4})$$

### Density-dependent reproductive output

$$\phi_{max} = e^b \left( \frac{[1 - \sigma_j(1 - \gamma)][1 - \sigma_a(1 - \rho)]}{\sigma_j\gamma} - \sigma_a\rho \right) \quad (\text{S5})$$

## Section S2 Selecting virtual species

We subsetted the COMADRE Animal Matrix Database (Salguero-Gómez et al., 2016) and the COMPADRE Plant Matrix Database (Salguero-Gómez et al., 2015) to matrix population models that are ergodic, irreducible, and primitive. Doing so guarantees the existence of a single dominant eigenvalue (Caswell, 2001, pp. 83-85). We imposed a series of selection criteria on the 3,488 matrix population models available in COMADRE (v. 4.23.3.1) and 8,994 models in COMPADRE (v. 6.23.5.0) to ensure fair comparisons. The criteria are as follows: We retained only models (1) built from demographic data on *both* survival and reproduction, so complete life-cycle information was available; (2) collected in observational (“wild”, *i.e.*, non-laboratory) settings without experimental manipulations so the models would reflect the dynamics of natural populations; and (3) published and digitized such that survival and reproduction are separable (*i.e.*, there are separate  $\mathbf{F}$  and  $\mathbf{U}$  matrices). The latter criterion is particularly necessary here to separate the proportion of the matrix element  $a_{1,2}$  that corresponds to reproductive output *vs.* to (potentially)

retrogression. Finally, (5) we excluded models with clonal reproduction because permitting fair comparisons between studies with and without clonal reproduction requires careful consideration of ramet *vs.* genet dynamics (Janovský and Herben, 2020) and their emergent vital rates (Salguero-Gómez, 2018). As such, in our virtual species model, we also do not include clonal reproduction.

For each matrix population model that met our criteria, we coerced it into the same model formulation as Equation 1, that is, a two stage model. When models are digitized for the databases, each stage of the model is identified as a propagule, an active member of the population, or a dormant member of the population. Based on the non-zero columns of the fertility ( $\mathbf{F}$ ) matrix, we can also identify each life stage as reproductive or non-reproductive. With the columns of the fertility ( $\mathbf{F}$ ) and survival-growth ( $\mathbf{U}$ ) matrices correctly identified, we can collapse the models down into a  $2 \times 2$  matrix model matching Equation 1 (Salguero-Gómez and Plotkin, 2010). This last step was performed using the `mpm_collapse` function in the `Rage` package (Jones et al., 2022) in the R programming language.

We then eliminated any collapsed models with incorrect survival values ( $\sigma_j$  or  $\sigma_a > 1$ ). Finally, we restricted our set of observed models to those with a population growth rate ( $\lambda$ , the dominant eigenvalue of the projection matrix) between 1.0 and 1.6. We chose this range as a realistic comparison with our density-dependent models: at equilibrium (“carrying capacity”), our virtual species models will have  $\lambda = 1$  and in early tests of the density-dependent reproductive output case, the highest population growth (at  $N \rightarrow 0$ ) was  $\lambda \approx 1.6$ . Finally, we removed models with extremely high or extremely low reproductive output, with outliers defined as values for  $\phi$  that fall outside of the interval  $[LQ - 1.5 * IQR, UQ + 1.5 * IQR]$ , where  $LQ$  is the lower quartile,  $UQ$  is the upper quartile, and  $IQR$  is the interquartile range. This final step resulted in a matrix population model for 410 animal, 872 plant, and three fungi populations, representing 100, 204, and one species,

respectively (Supplemental Materials Table S4).

With our final filtered set of collapsed population models, we used a principal components analysis (PCA) to define the space of ‘observed life history strategies’ (Figure S3). This two-dimensional space captured 70% of the variation among models from COMADRE and COMPADRE (PC1: 43.83%; PC2: 26.25%). PC1 was primarily explained by variation in survival ( $\sigma_j, \sigma_a$ ) and progression ( $\gamma$ ), such that longer-lived and late-maturing species score positively on PC1, while short-lived and fast-maturing species score negatively. PC2 was primarily influenced by reproductive output ( $\phi$ ), such that species with high reproductive output score positively on PC2 (Supplemental Table S1). As such, we refer to virtual species that fall in the upper left quadrant (low scores on PC1 and high scores on PC2) as exhibiting fast life histories, and we refer to those that fall in the lower right quadrant (high scores on PC1 and low scores on PC2) as exhibiting slow life histories.

To define our virtual species, we inspected the distribution of empirical values of vital rates in our final set of 1,285 collapsed two-stage models. Based on these distributions, we selected a high and low value for adult survival ( $\sigma_a$ ), juvenile survival ( $\sigma_j$ ), and progression ( $\gamma$ ) (Table S2). For retrogression ( $\rho$ ), we set the low value as 0 (no retrogression at all), and we set our high value near the mean of empirical values in models from the databases where retrogression was greater than 0 (Table S2). We then projected our virtual species models across density-dependent scenarios onto the PC axes as defined by the empirical models. Our virtual species models cover the space of naturally observed populations reasonably well (Supplemental Figure S3). Based on our model scaling, for some virtual species and density-dependent vital rate scenarios, the virtual species plotted at much higher values of PC2 than seen in the empirical models (Supplemental Figure S4). For plotting and analyses, we restricted the virtual species to combinations of vital rates and density-dependent scenarios that had a score on PC2 of  $\leq 5.1$  for population densities

between 0 and 1.

As these two axes together explain a sufficient amount of variation (>70%), we used these two components to visualize the space occupied by the different life history strategies, as well as to describe how the resilience components of our virtual species are influenced by vital rates and the PC axes (Supplemental Table S3).

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## Section S3 Supplemental Figures and Tables

**Table S1:** The contribution of each vital rate to the first two principal component axes (PC1 and PC2). Loadings in bold indicate a high contribution (greater than  $\pm 0.50$ ) of the life-history trait to the PC axis.

Vital rate	Symbol	PC1	PC2
Juvenile survival	$\sigma_j$	<b>0.579</b>	0.269
Progression	$\gamma$	<b>-0.529</b>	-0.408
Adult survival	$\sigma_a$	<b>0.569</b>	0.123
Retrogression	$\rho$	0.094	0.450
Reproductive output	$\phi$	-0.230	<b>0.735</b>
Proportion of variance		0.438	0.263
Cumulative proportion of variance		0.438	0.701

**Table S2:** Empirical and modelled values of vital rates. Empirical values come from the matrix population models from the COMADRE and COMPADRE databases (model selection and vital rate estimation is described in Appendix Section S2). Based on inspection of the distribution of empirical values, we selected the high and low values for each vital rate as seen here.

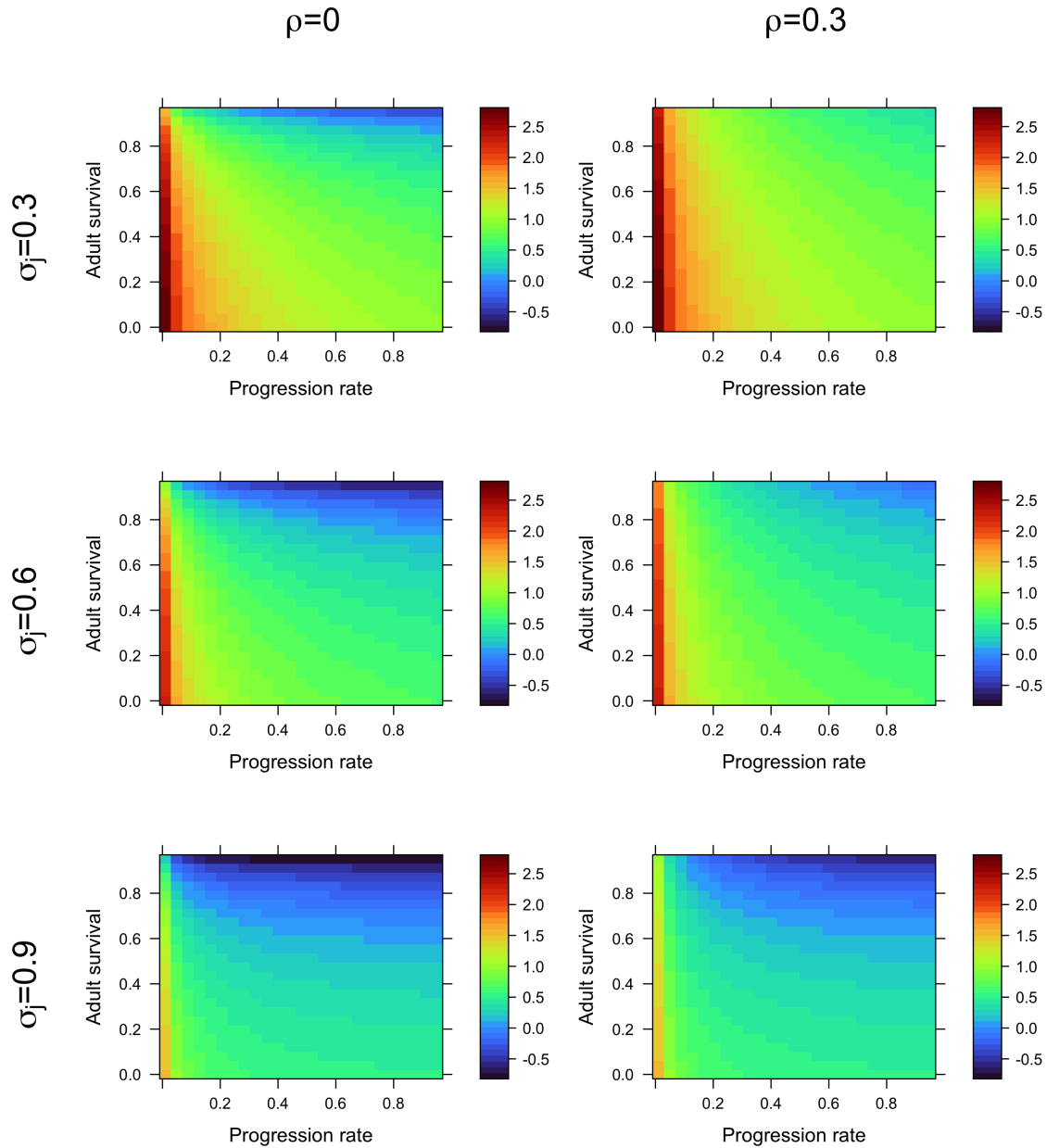
Parameter	Empirical models		Virtual species	
	Mean	Std. dev.	Low value	High value
$\sigma_j$	0.66	0.28	0.4	0.9
$\gamma^*$	0.34	0.35	0.1	0.9
$\sigma_a$	0.84	0.23	0.6	0.95
$\rho^{**}$	0.23	0.25	0	0.3

\* The empirical distribution of values for  $\gamma$  was bimodal with values close to 0 and 1 being more common than intermediate values.

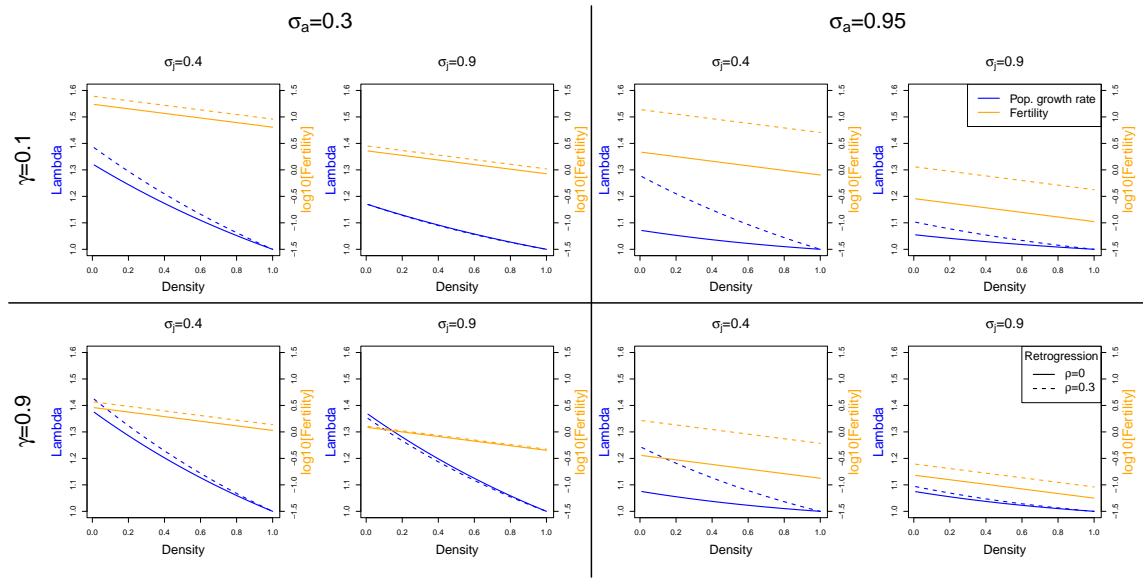
\*\* The empirical mean and standard deviation for  $\rho$  were calculated for only models where some retrogression was observed ( $\rho > 0$ ).

**Table S3:** The effects of vital rates and principal component axes on the resilience metrics of compensation, resistance, and recovery time in our virtual species. For each resilience metric, we fit two separate regression models. First, we fit a linear regression with strictly additive terms for each vital rate. Second, we fit a linear regression for the principal component axes including additive terms and their interaction.

Vital rate	Symbol	Regression coefficient		
		Compensation	Resistance	Recovery Time
Juvenile survival	$\sigma_j$	-0.402	0.838	-3.679
Progression	$\gamma$	-0.351	-0.085	0.588
Adult survival	$\sigma_a$	0.626	-0.076	-4.689
Retrogression	$\rho$	0.152	0.048	2.687
Reproductive output	$\phi$	0.771	-0.036	0.201
PC axis 1		-0.094	0.135	-0.805
PC axis 2		0.604	-0.060	-0.383
Interaction PC1 and PC2		-0.023	0.002	-0.705

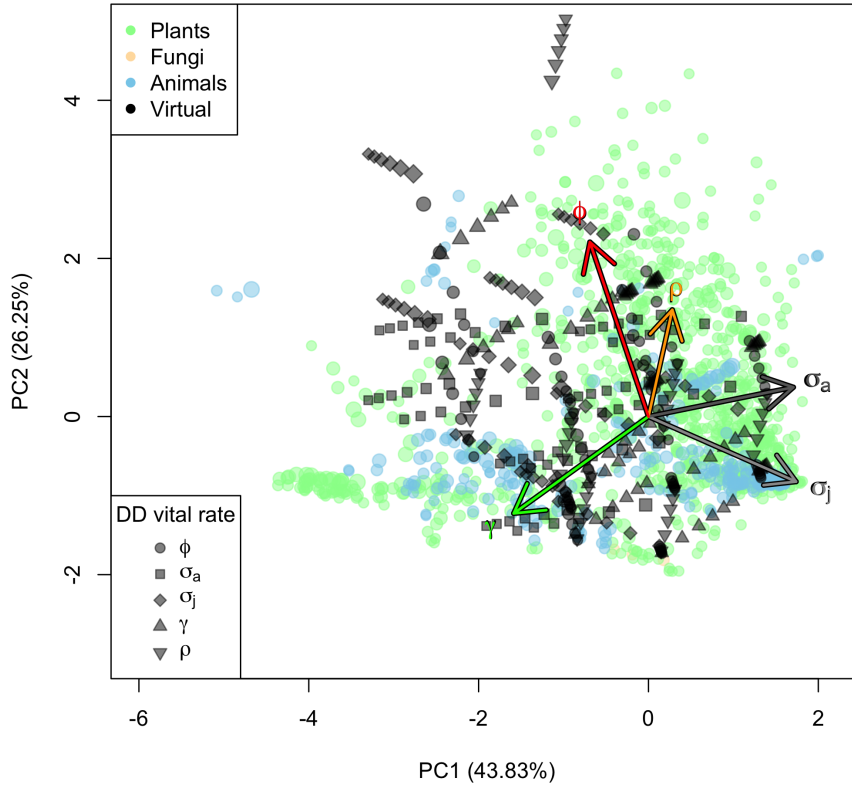


**Figure S1:** An example of how our model scaling affects maximum reproductive output ( $\phi_{max}$ ) across other vital rates. In this case, reproductive output is density-dependent, and the model is scaled such that the population is at its carrying capacity ( $\lambda = 1$ ) when population density ( $n_a + n_j$ ) is equal to 1. In each panel, we show how  $\phi_{max}$  varies across progression ( $\gamma$ ) and adult survival ( $\sigma_a$ ) for a given value of juvenile survival ( $\sigma_j$ ) and retrogression ( $\rho$ ). The color scales are  $\log_{10}(\phi_{max})$ .

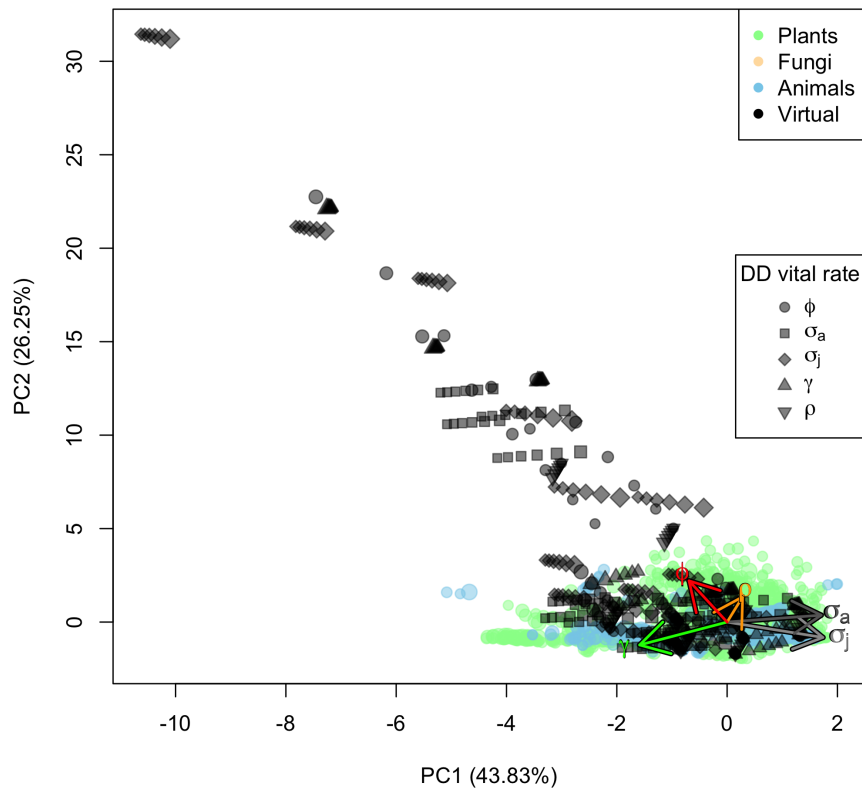


**Figure S2:** Population growth rate ( $\lambda$ ) and per-capita reproductive output ( $\phi$ ) across population density for 16 virtual species models.

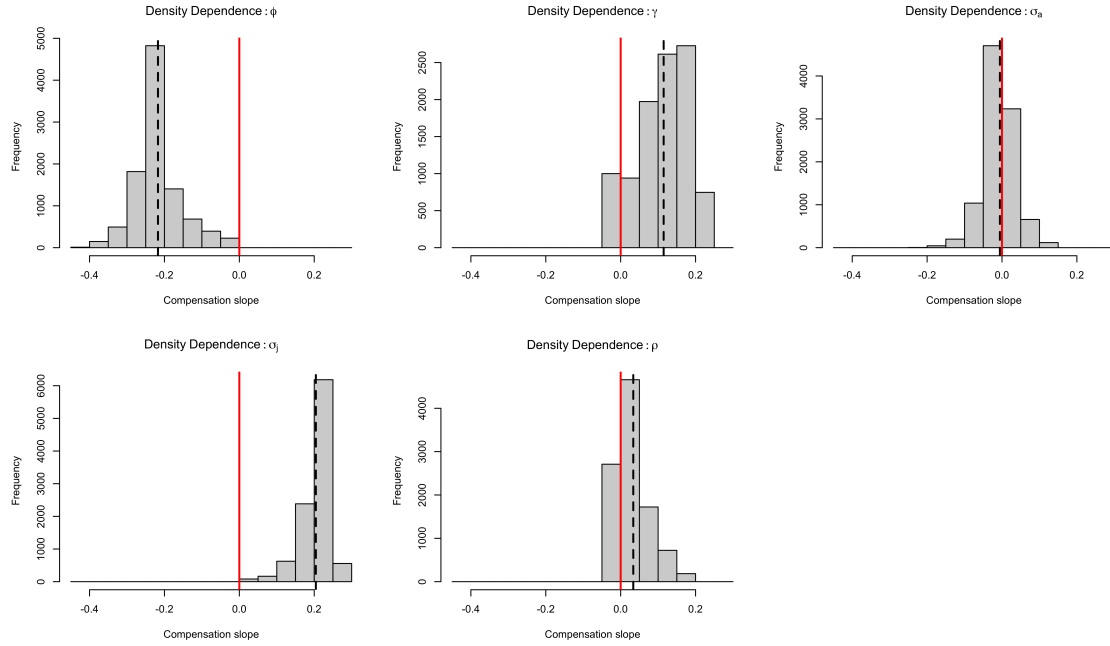




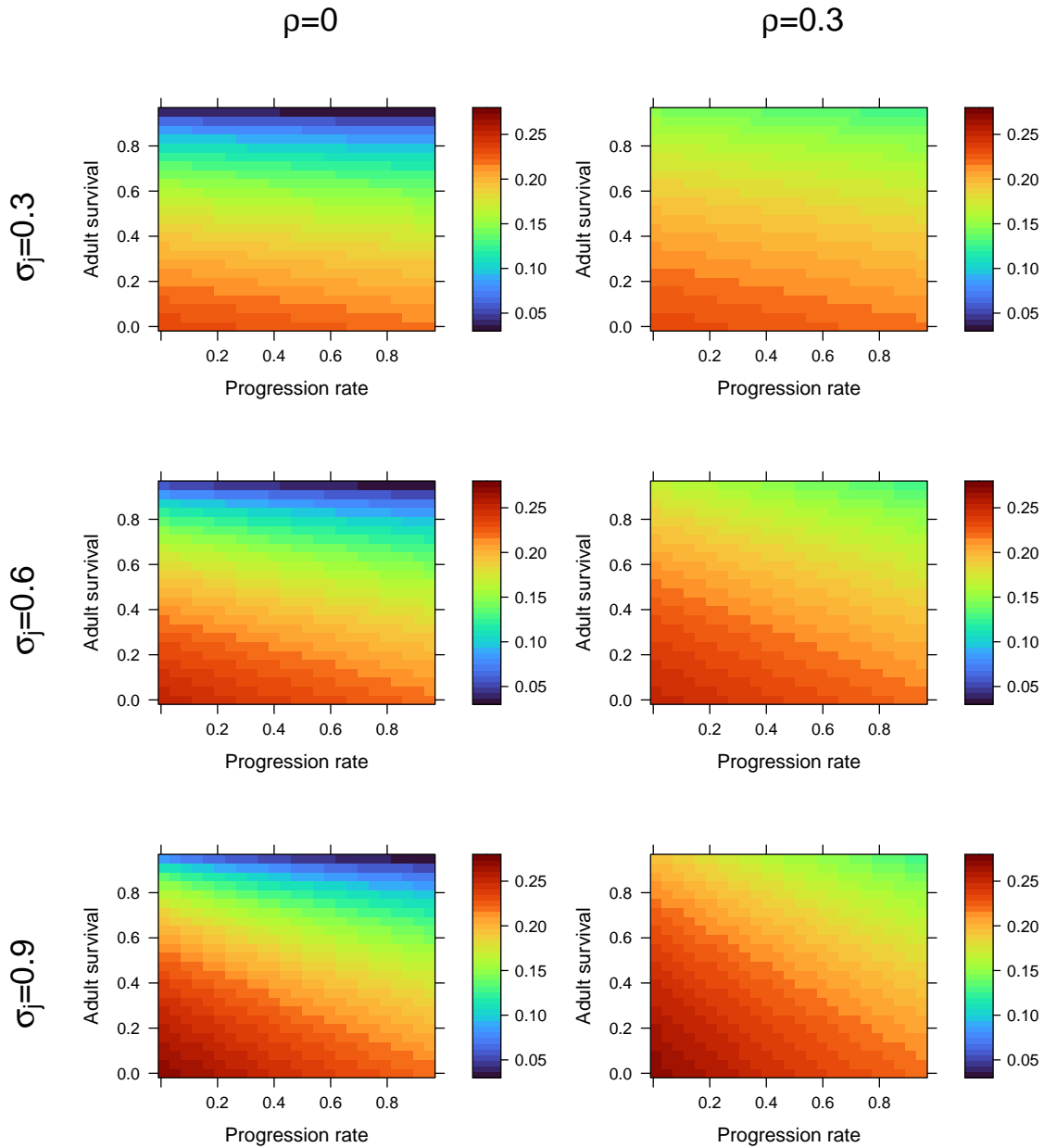
**Figure S3:** Principal component analysis (PCA) of life history strategies based on the two-stage population model given in Equation 1. The parameters are: juvenile survival ( $\sigma_j$ ), juvenile progression ( $\gamma$ ), adult survival ( $\sigma_a$ ), adult retrogression ( $\rho$ ), and reproductive output ( $\phi$ ). The PCA space is defined by the observed models (colored circles, sized according to their asymptotic population growth rate,  $\lambda$ ). The virtual species, shown in black, were then projected onto the PCA space. Each virtual species was modelled with density-dependence on each of the five vital rates (shown with different shapes), and each density-dependent scenario was plotted for six values of density between 0 and 1, sized according to  $\lambda$ . Note that this figure excludes values of PC2 >5.1.



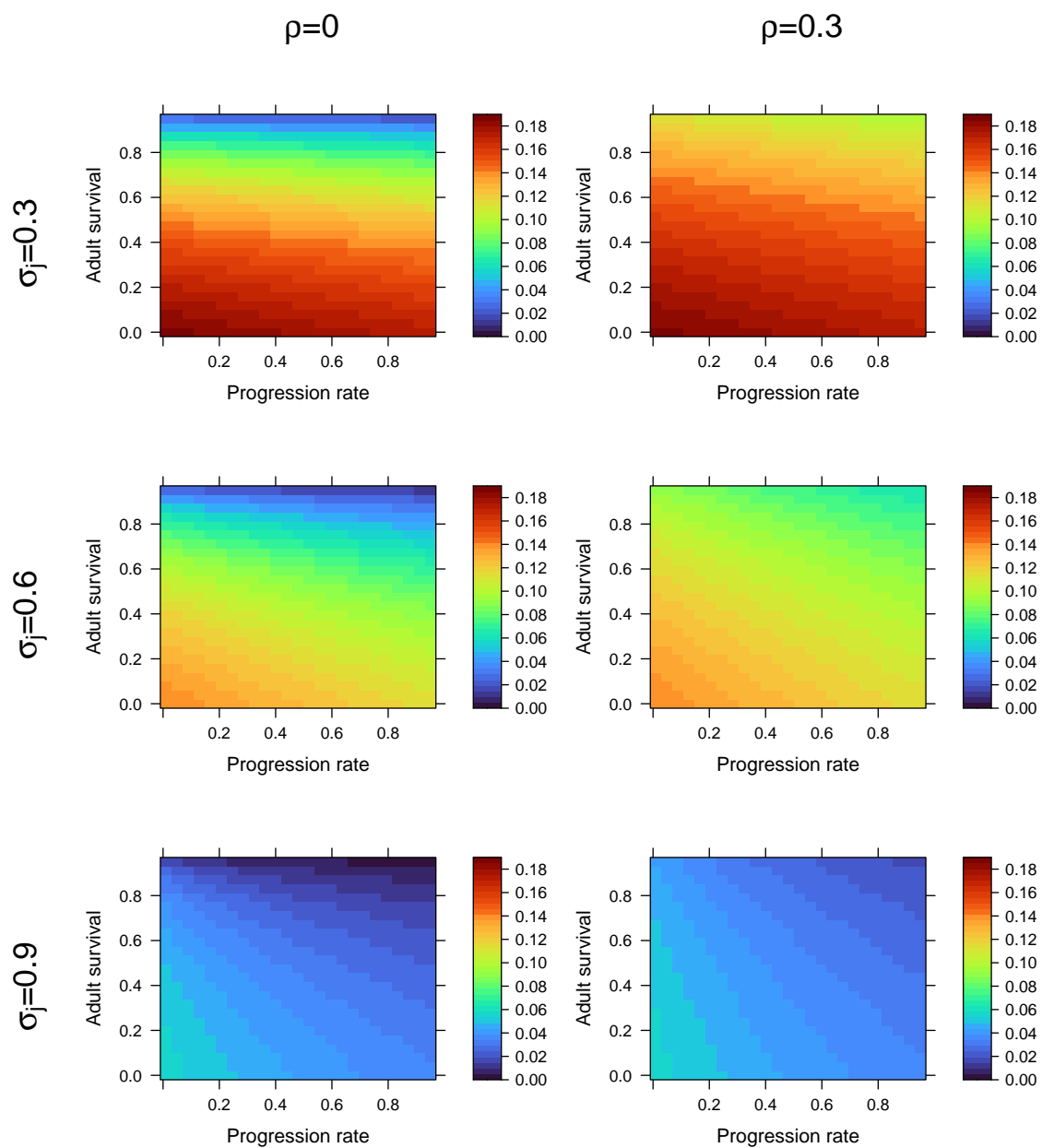
**Figure S4:** Some of the virtual species and density-dependent vital rate scenarios corresponded to extreme values of PC2, falling far from the space defined by empirical models. Figure details are the same as in Figure S3.



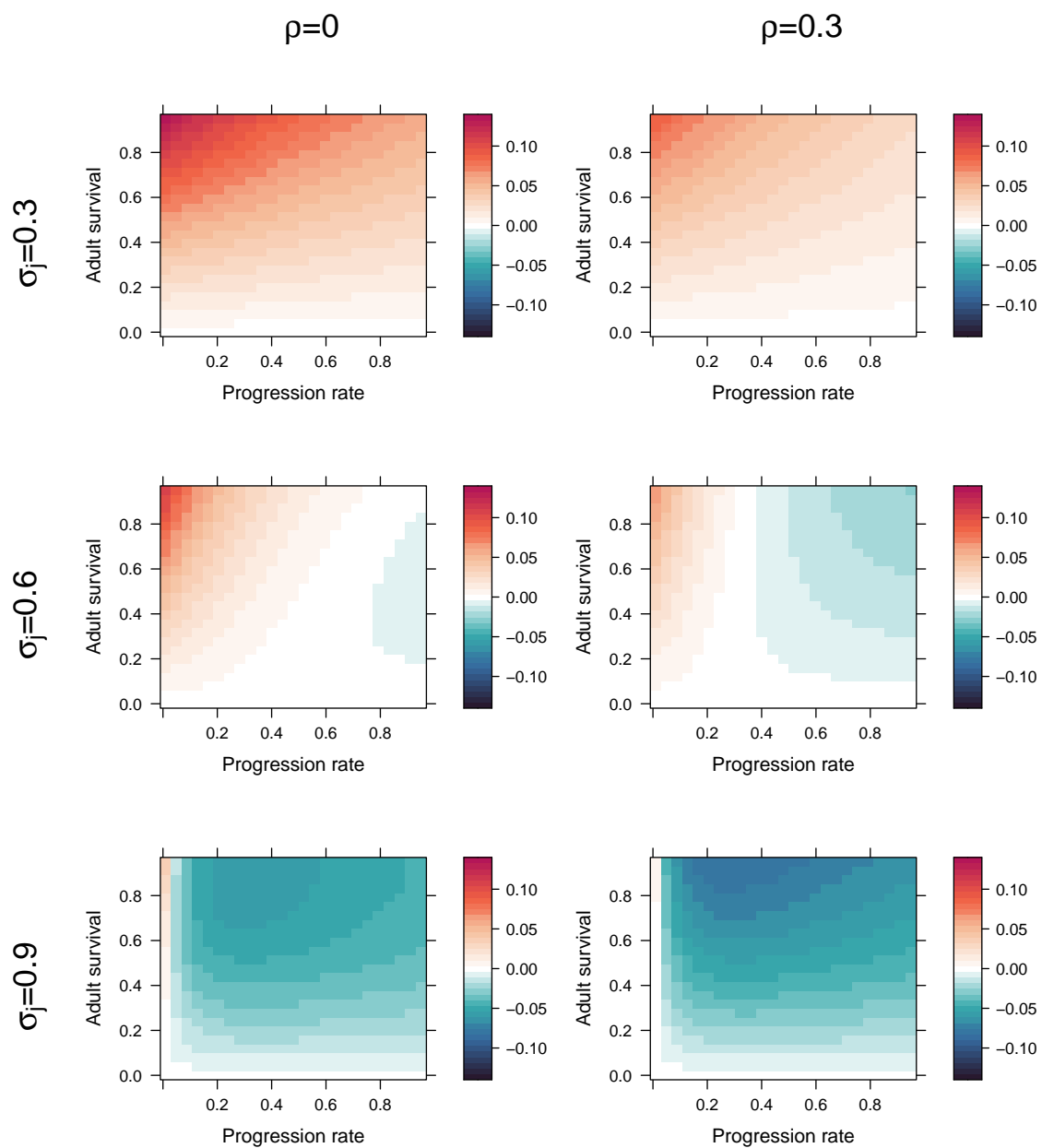
**Figure S5:** The distribution of compensation slope values depends on which vital rate is the target of density dependence. For each density-dependence scenario, we calculated the slope of compensation across densities (*i.e.*,  $a$  in  $\log_{10}(C) = a * N + b$ , where  $N$  is population density and  $C$  is the compensation of the population projection matrix calculated at each value of  $N$ ) for the full range of possible vital rates:  $\sigma_j \in [0.01, 1]$ ;  $\gamma \in [0.01, 0.95]$ ;  $\sigma_a \in [0, 0.95]$ ; and  $\rho \in [0, 1]$ . For each vital rate, we calculated slopes at 10 values, yielding a total of  $10^4$  vital rate combinations for each density-dependence scenario. In each panel, a slope of 0 is highlighted with a solid red line, and the mean value of slopes across all tested vital rate combinations is shown with a thick vertical dashed line.



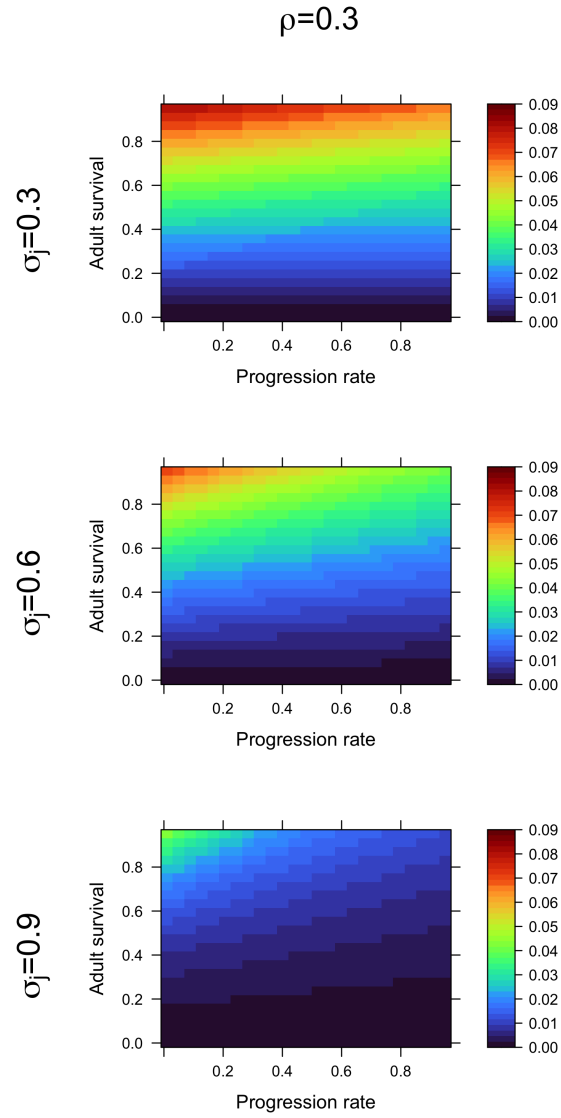
**Figure S6:** Strength of density effects on compensation when juvenile survival is density-dependent. We calculated the slope of compensation across population densities ( $\log C \sim N_t$ ) for many possible parameter combinations across:  $\sigma_a \in [0, 0.95]$ ,  $\gamma \in [0.01, 0.95]$ ,  $\sigma_j = 0.3, 0.6, 0.9$ , and  $\rho = 0, 0.3$ . A single color scale is used for all panels. Slow life histories are in the upper left of each panel, and fast life histories are in the lower right.



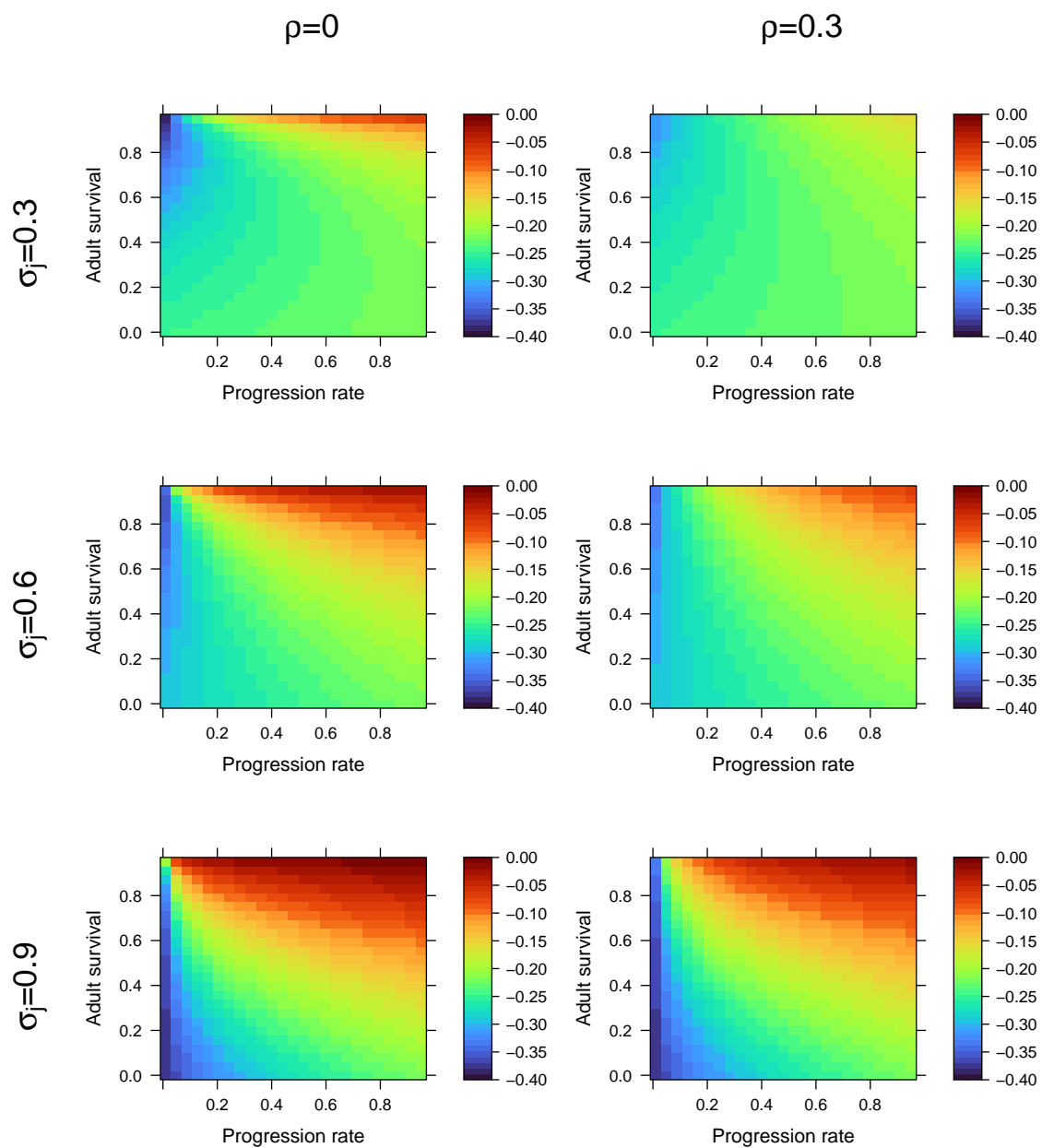
**Figure S7:** Strength of density effects on compensation when juvenile progression rate is density-dependent. Details are the same as Figure S6.



**Figure S8:** Strength of density effects on compensation when adult survival is density-dependent. Details are the same as Figure S6.

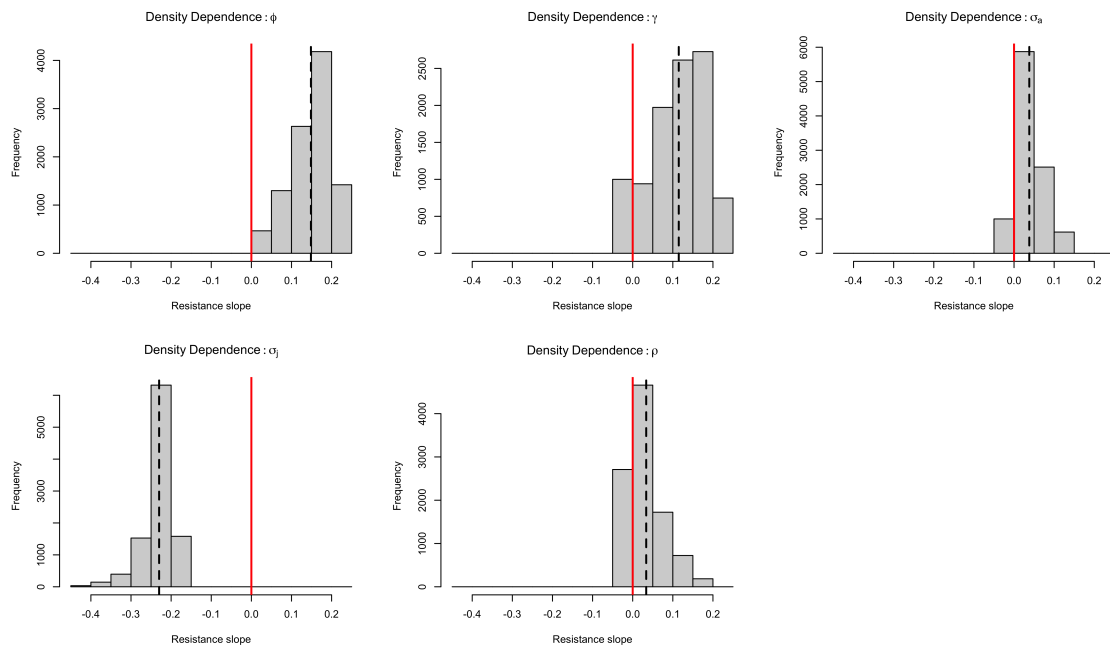


**Figure S9:** Strength of density effects on compensation when retrogression rate is density-dependent. Details are the same as Figure S6.

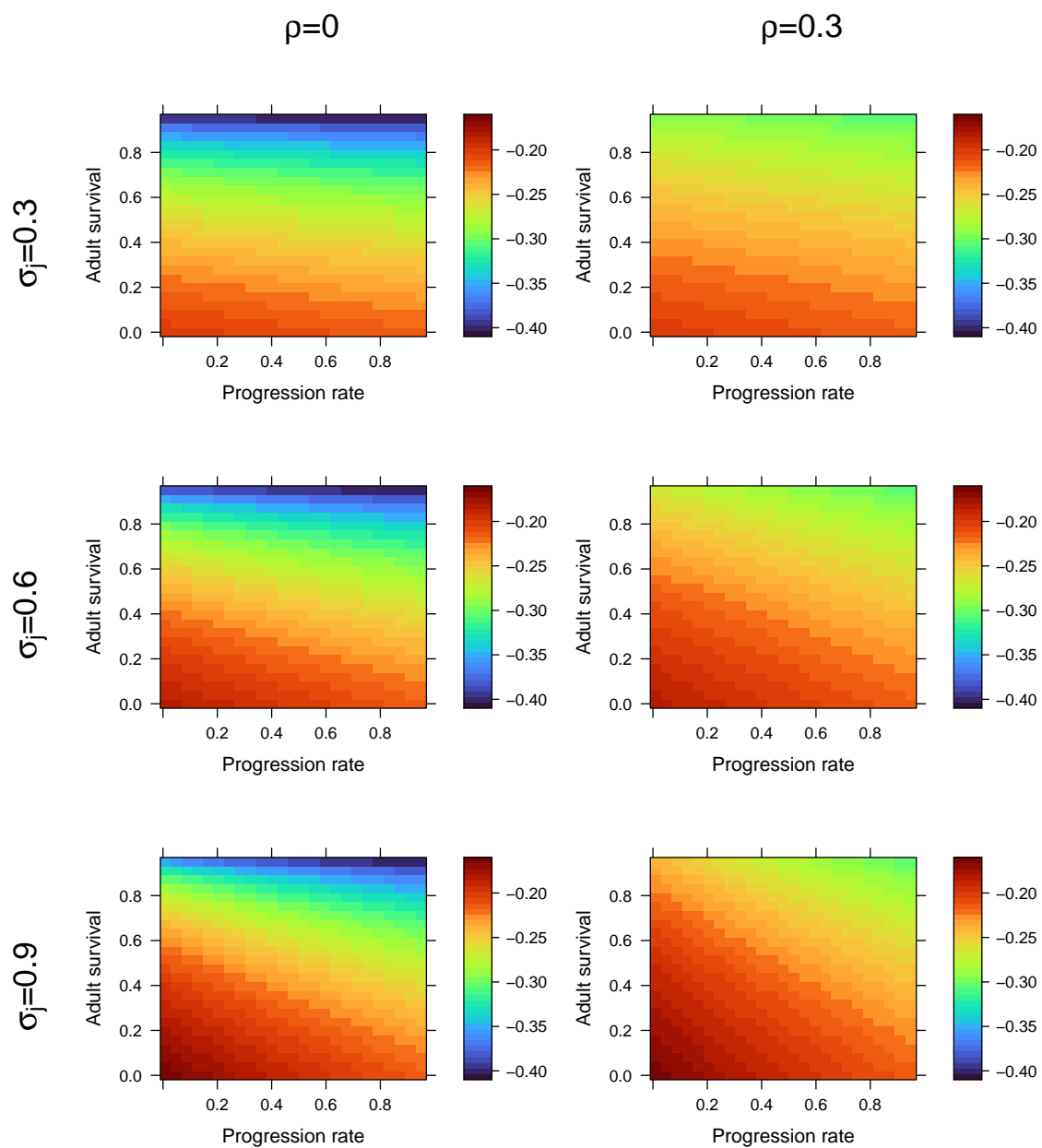


**Figure S10:** Strength of density effects on compensation when reproductive output is density-dependent. Details are the same as Figure S6.

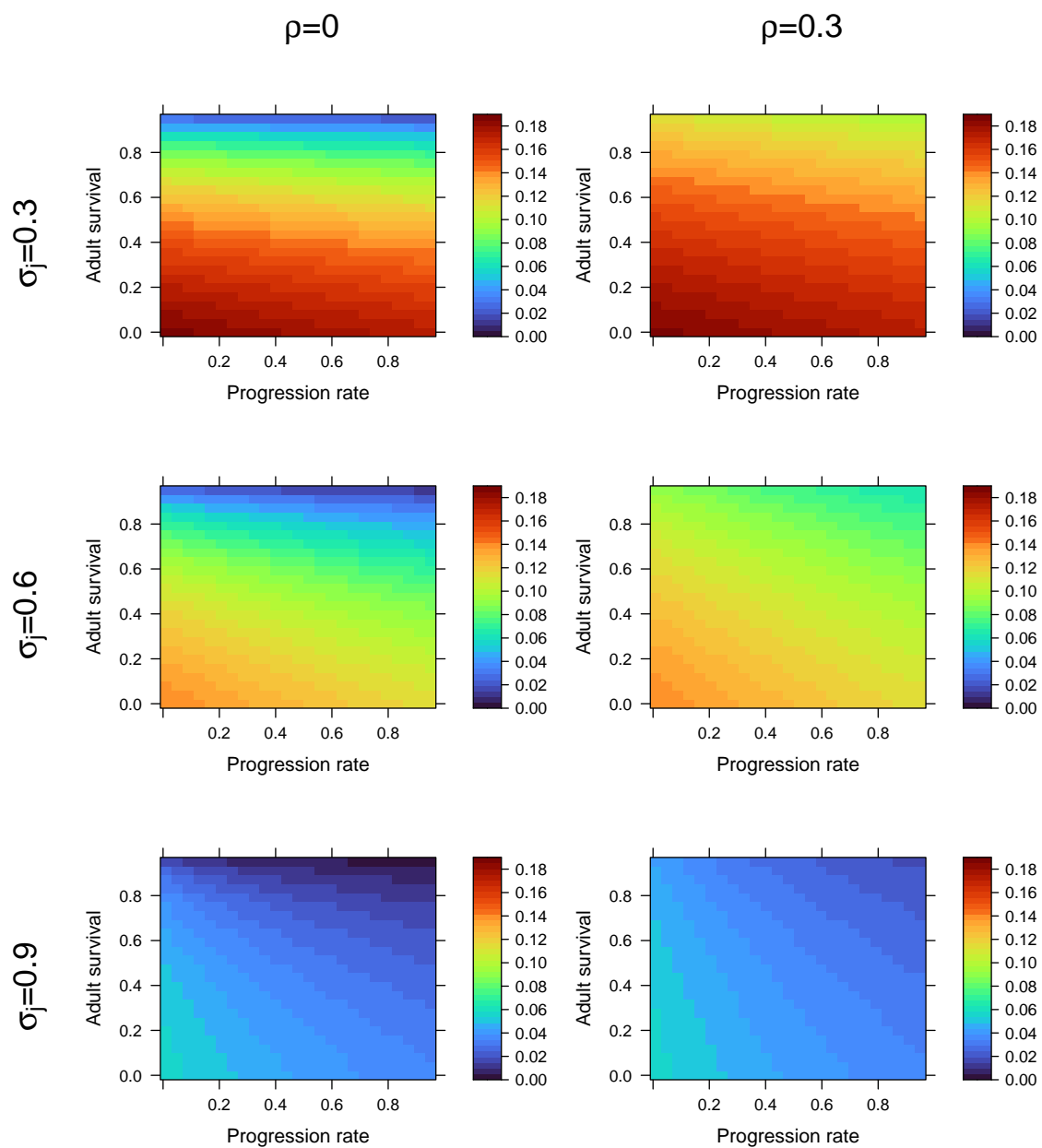




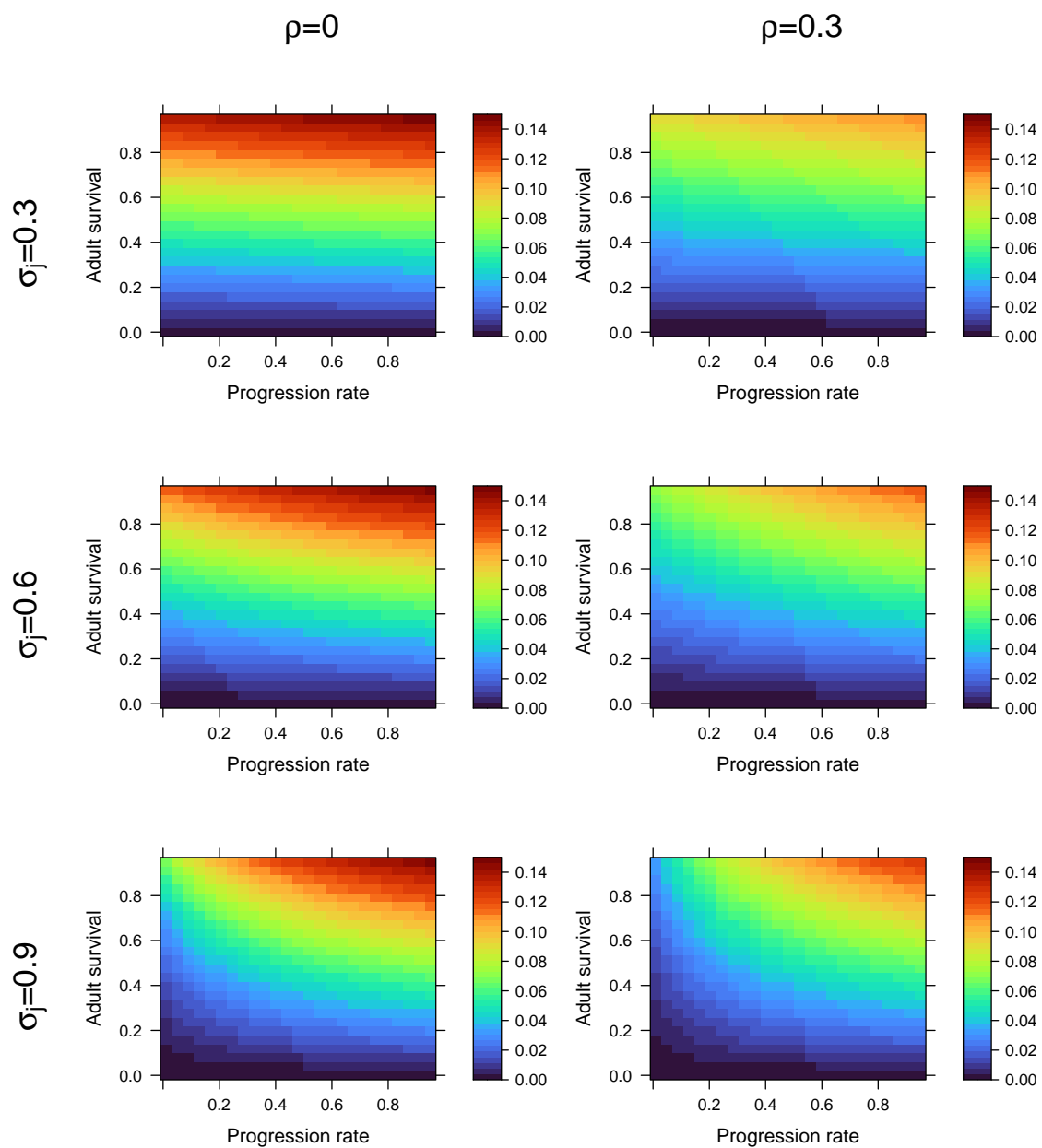
**Figure S11:** The distribution of resistance slope values depends on which vital rate is the target of density dependence. Details are the same as in Figure S5.



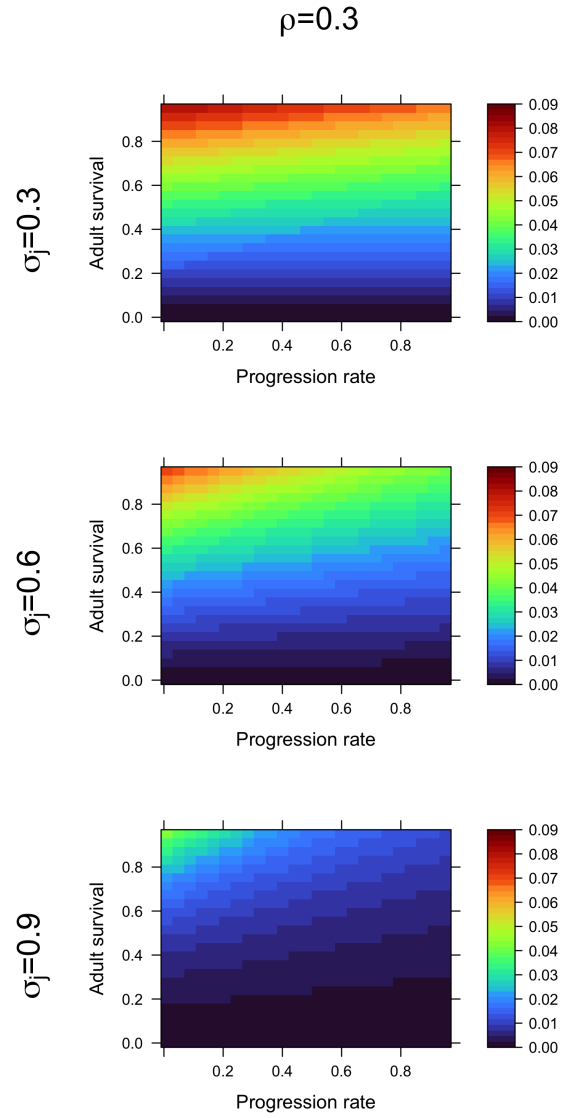
**Figure S12:** Strength of density effects on resistance when juvenile survival is density-dependent. Details are the same as Figure S6.



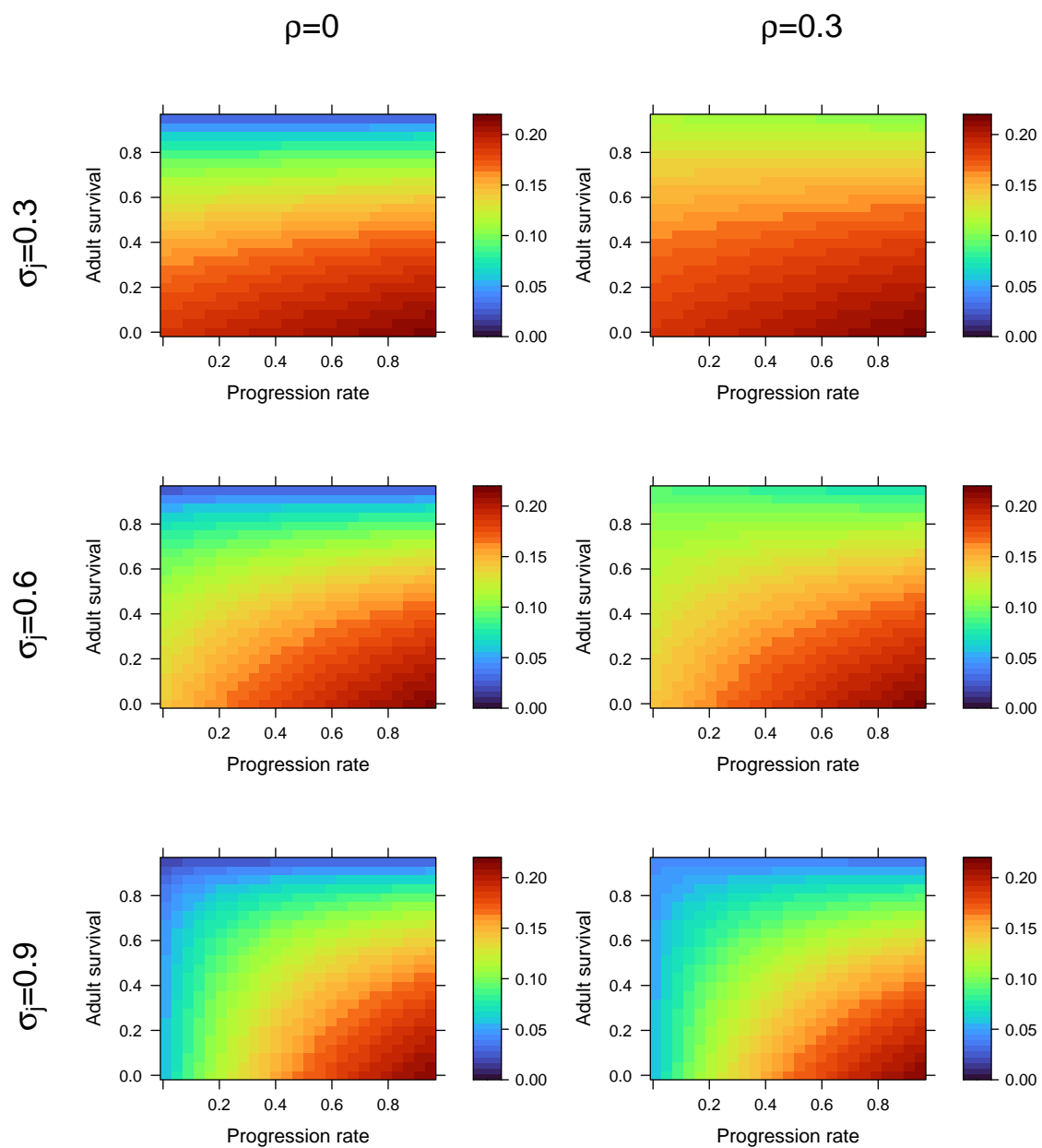
**Figure S13:** Strength of density effects on resistance when juvenile progression rate is density-dependent. Details are the same as Figure S6.



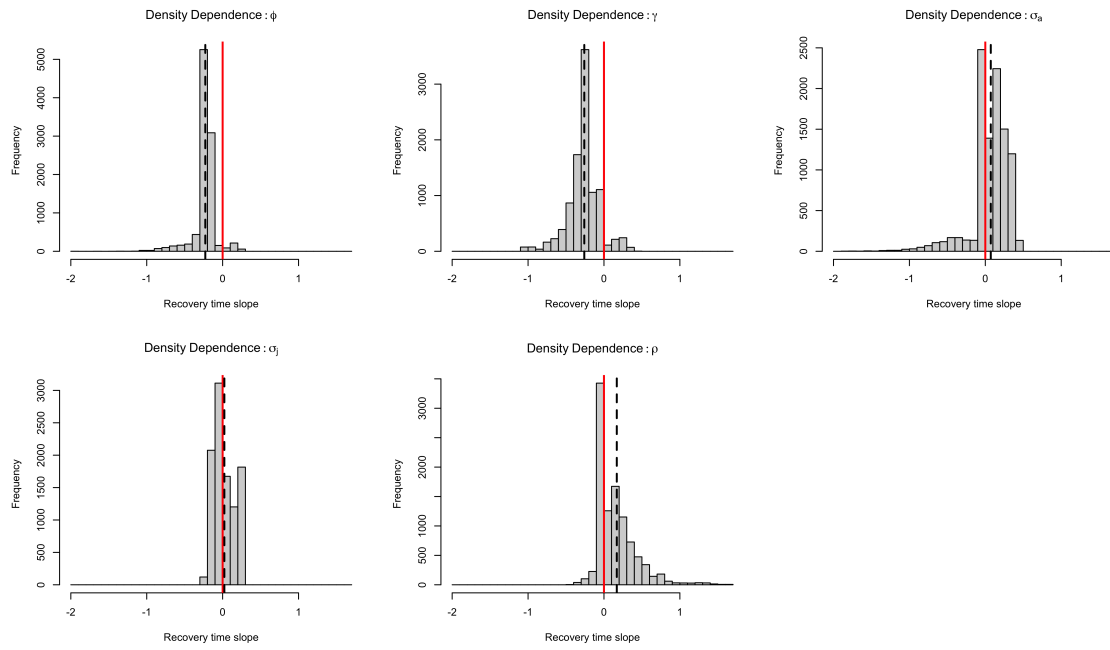
**Figure S14:** Strength of density effects on resistance when adult survival is density-dependent. Details are the same as Figure S6.



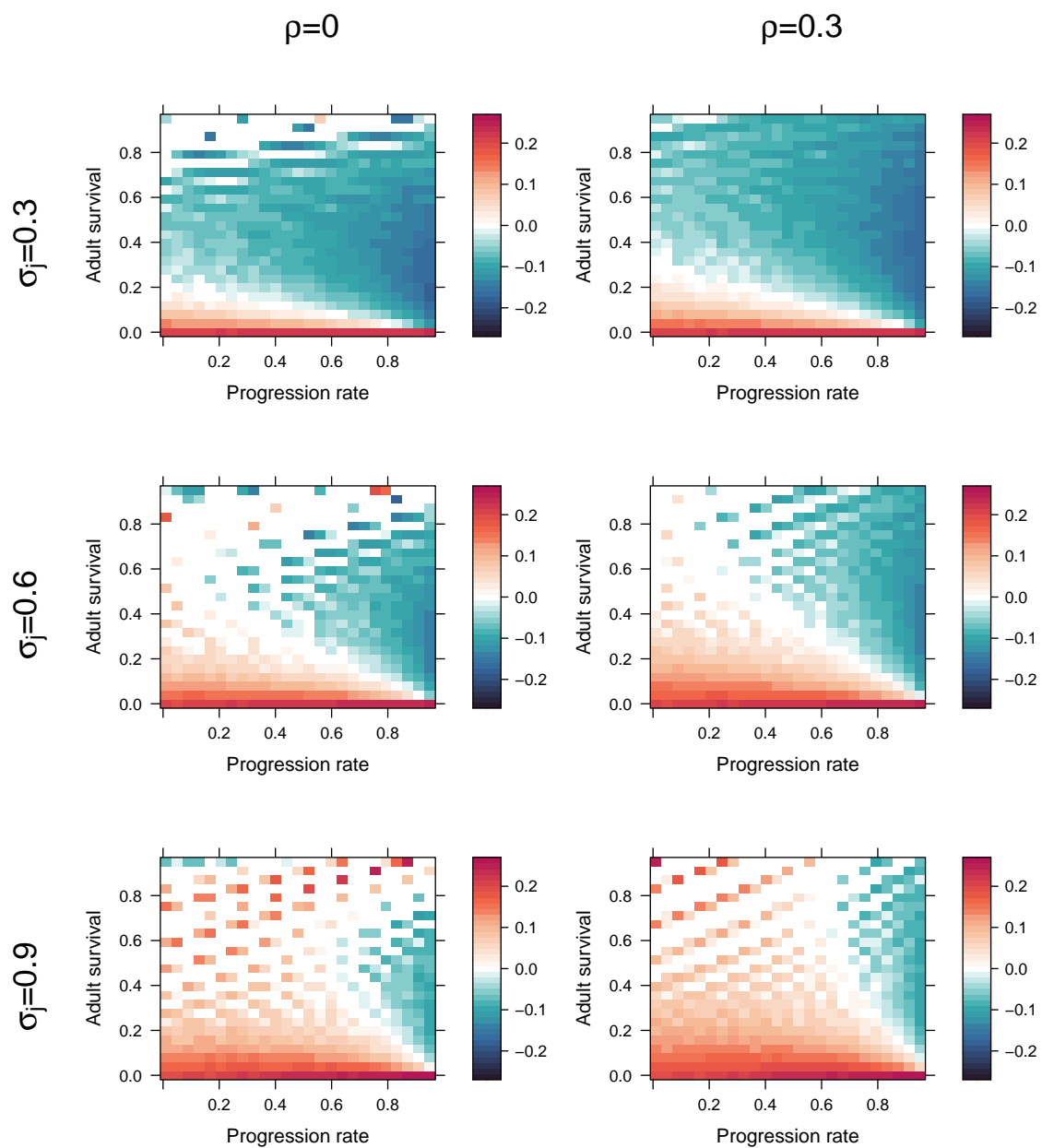
**Figure S15:** Strength of density effects on resistance when retrogression rate is density-dependent. Details are the same as Figure S6.



**Figure S16:** Strength of density effects on resistance when reproductive output is density-dependent. Details are the same as Figure S6.

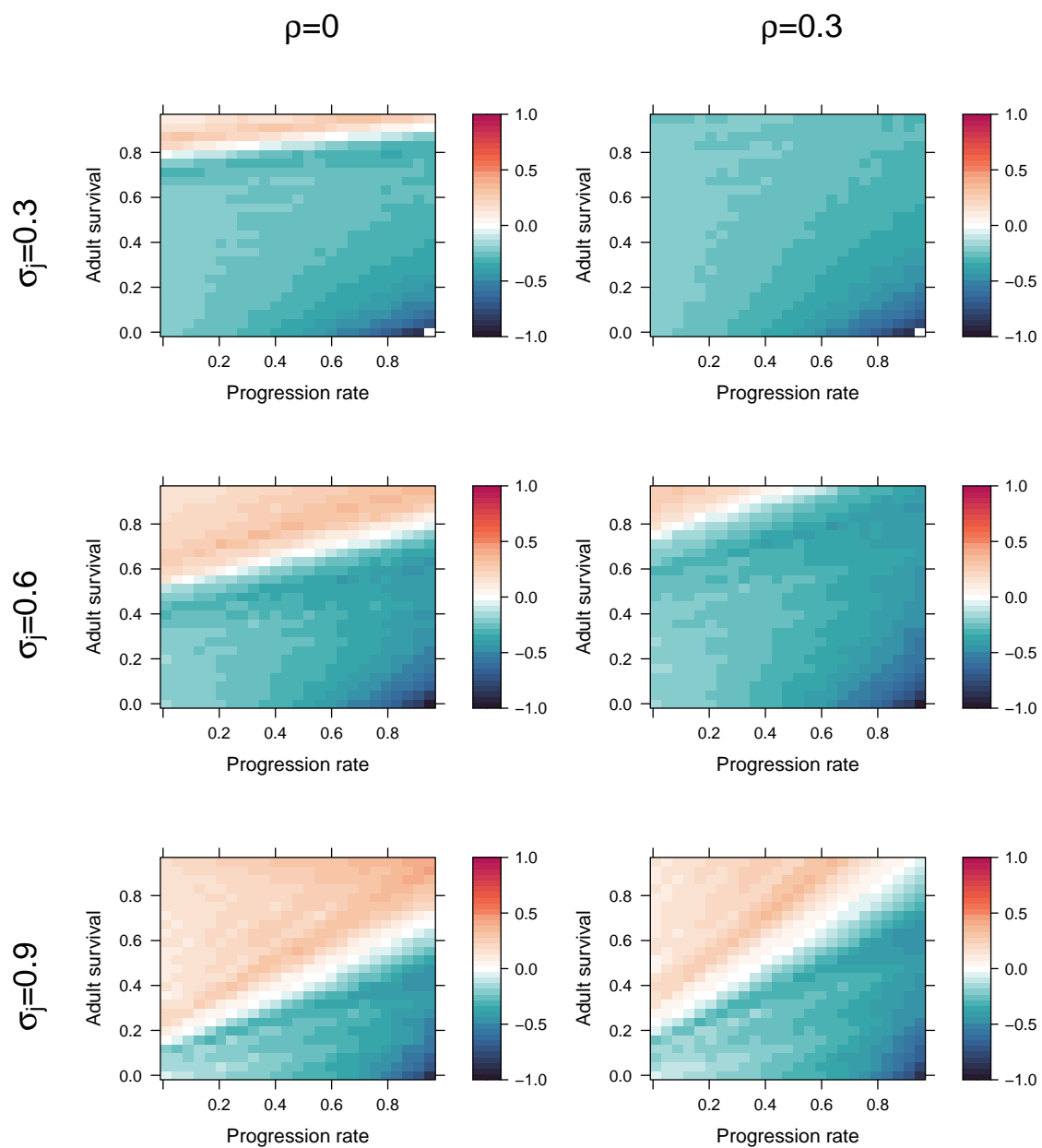


**Figure S17:** The distribution of recovery time slope values depends on which vital rate is the target of density dependence. Details are the same as in Figure S5.

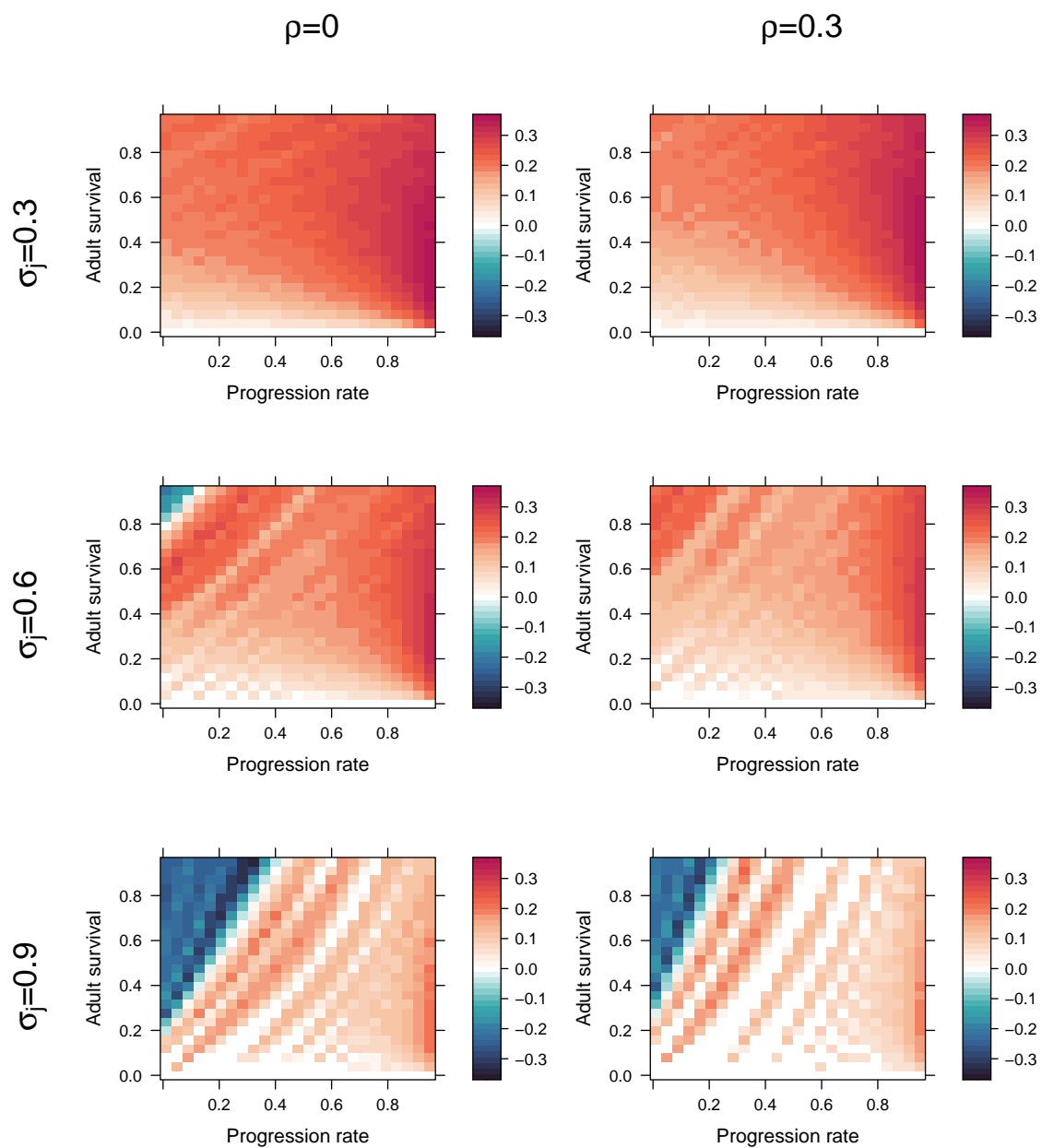


**Figure S18:** Strength of density effects on recovery time when juvenile survival is density-dependent. Details are the same as Figure S6.

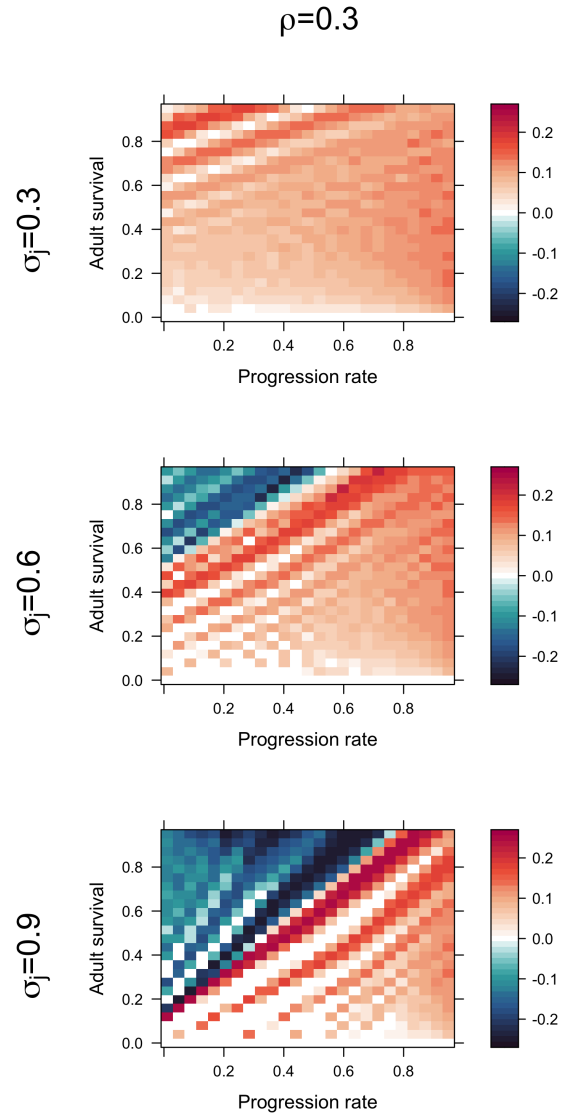




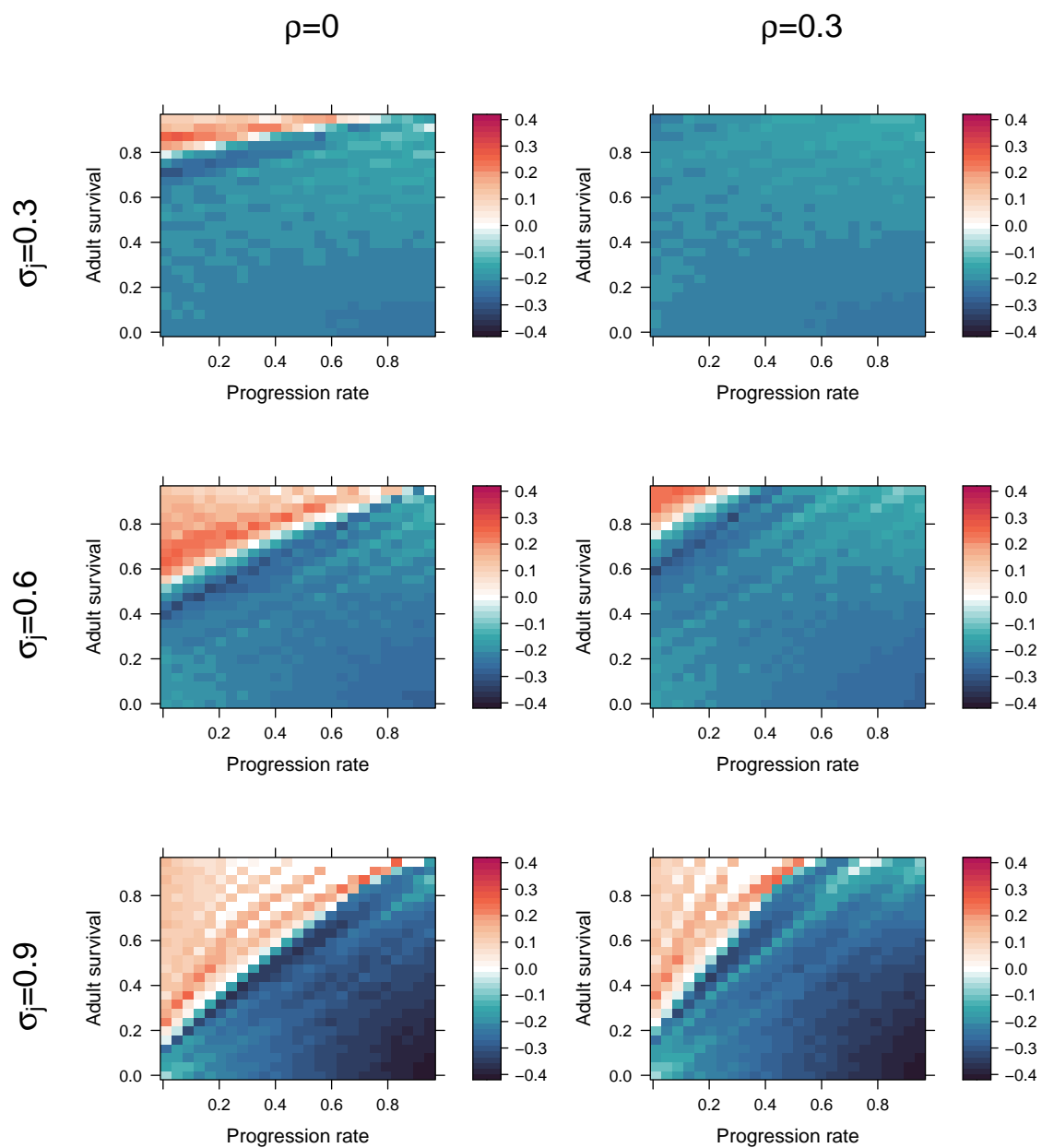
**Figure S19:** Strength of density effects on recovery time when juvenile progression rate is density-dependent. Details are the same as Figure S6.



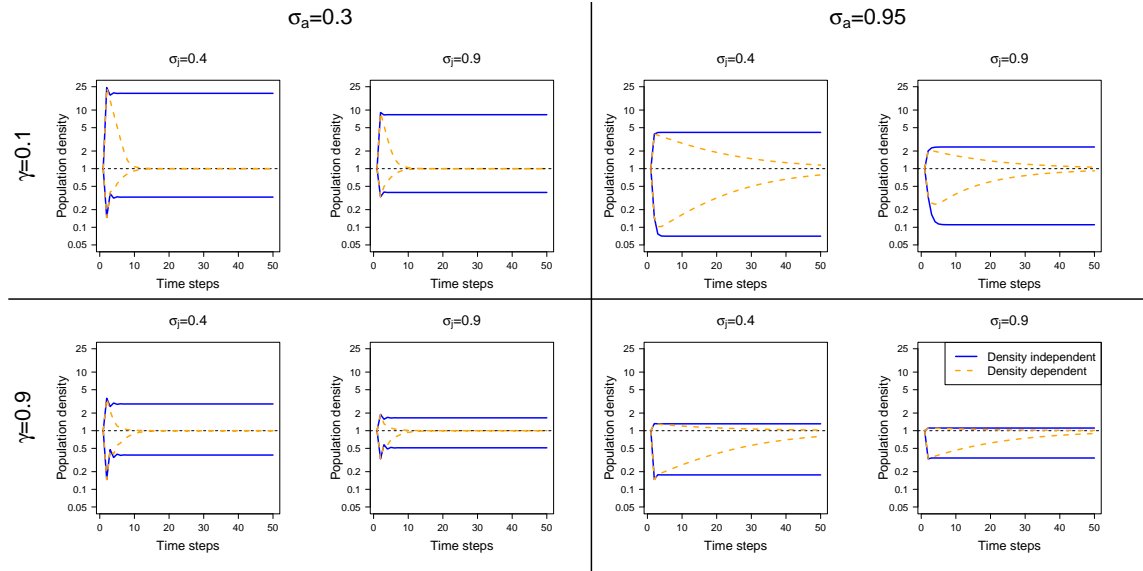
**Figure S20:** Strength of density effects on recovery time when adult survival is density-dependent. Details are the same as Figure S6.



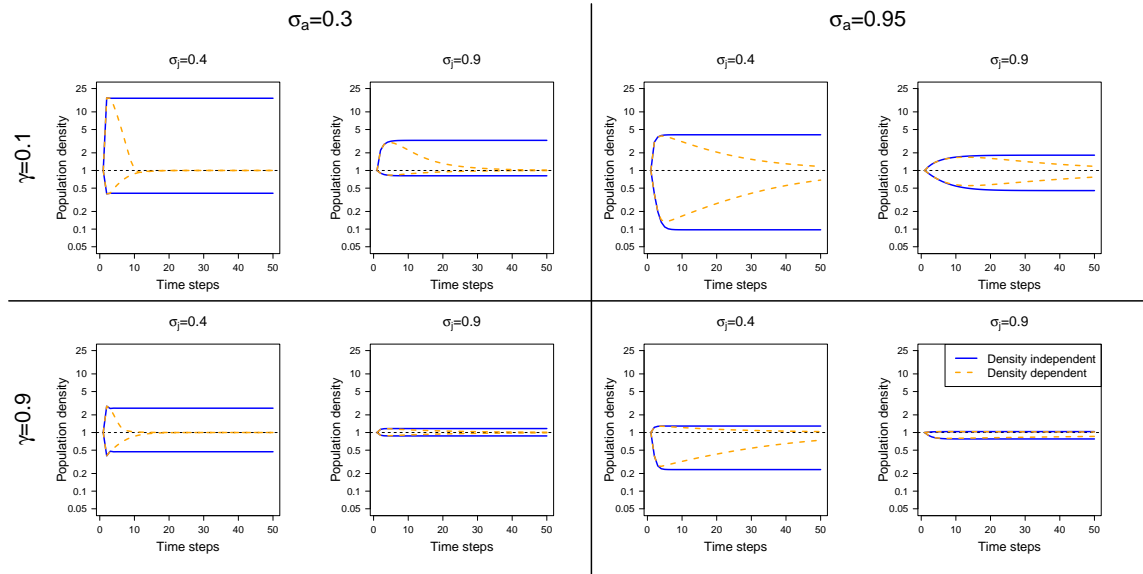
**Figure S21:** Strength of density effects on recovery time when retrogression rate is density-dependent. Details are the same as Figure S6.



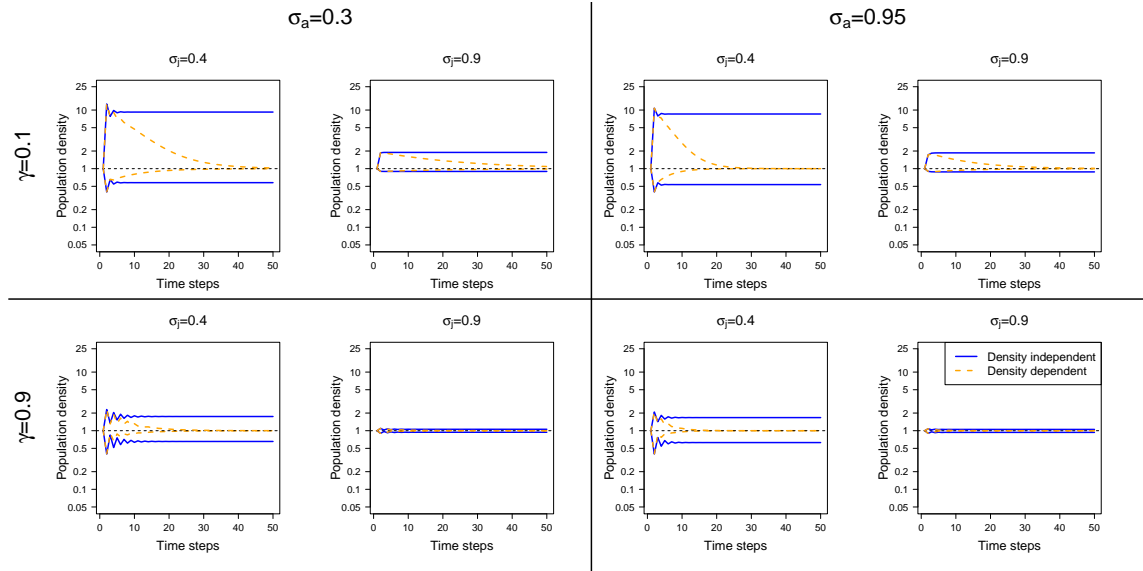
**Figure S22:** Strength of density effects on recovery time when reproductive output is density-dependent. Details are the same as Figure S6.



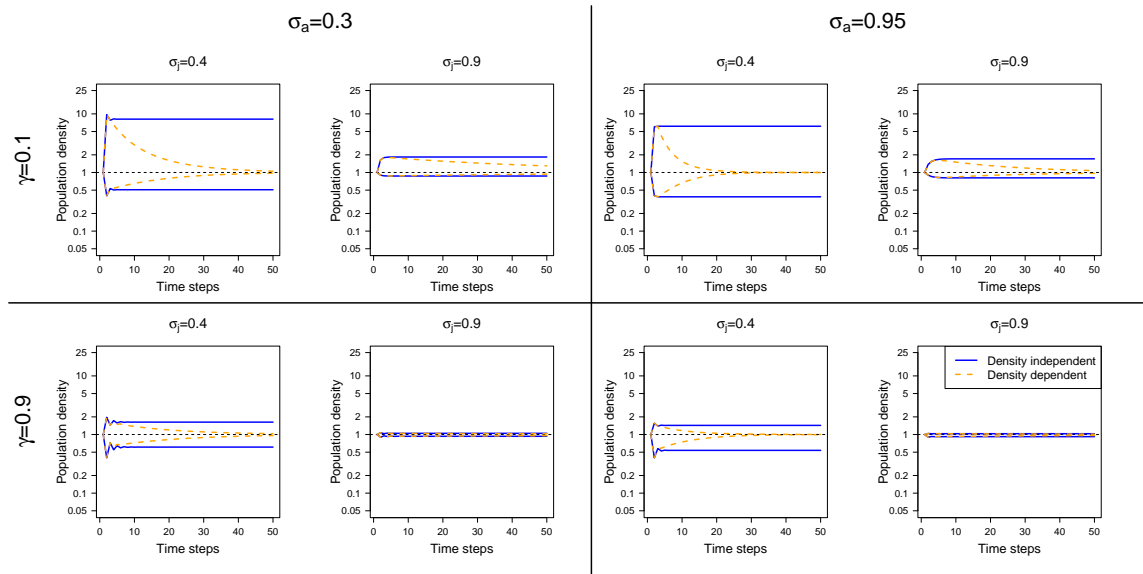
**Figure S23:** Variation in transient envelope patterns across our set of virtual species and between density-dependent and density-independent models. In this case, density dependence operates on juvenile survival ( $\sigma_j$ ).



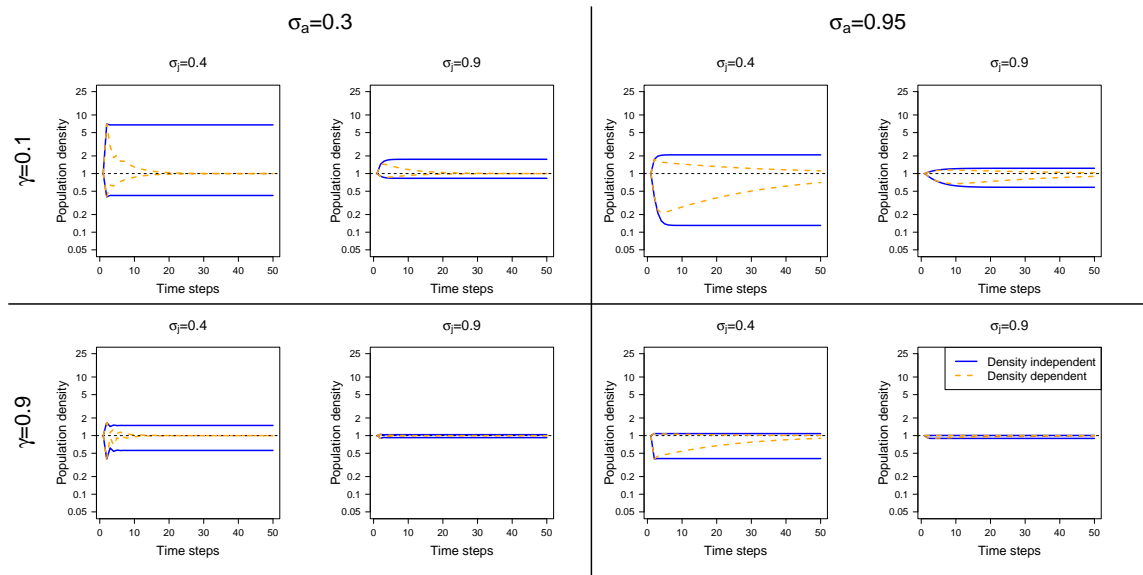
**Figure S24:** Variation in transient envelope patterns across our set of virtual species and between density-dependent and density-independent models. In this case, density dependence operates on progression rate ( $\gamma$ ).



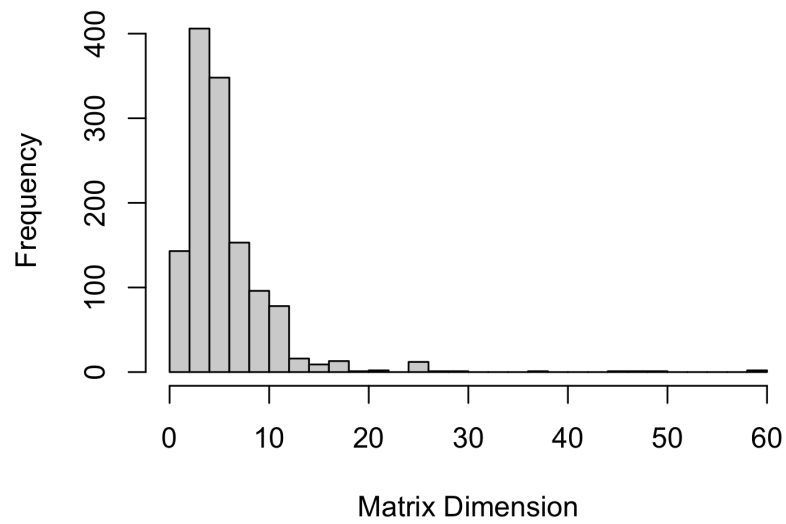
**Figure S25:** Variation in transient envelope patterns across our set of virtual species and between density-dependent and density-independent models. In this case, density dependence operates on adult survival ( $\sigma_a$ ).



**Figure S26:** Variation in transient envelope patterns across our set of virtual species and between density-dependent and density-independent models. In this case, density dependence operates on retrogression rate ( $\rho$ ).



**Figure S27:** Variation in transient envelope patterns across our set of virtual species and between density-dependent and density-independent models. In this case, density dependence operates on reproductive output ( $\phi$ ).



**Figure S28:** The matrix dimensions for empirical models used in selecting virtual species models. The matrix dimension is the number of classes included in the projection matrix. Before collapsing all the models to  $2 \times 2$ , most of the models were larger, representing more complex life cycles than represented by our two-stage model (Supplemental Materials Table S4).