- 1 Title: A pattern-oriented simulation for forecasting species spread through time and space: A
- 2 case study on an ecosystem engineer on the move
- 3 Authors
- 4
- 5 Rahil J. Amin<sup>a\*</sup>, Jessie C. Buettel<sup>a,b</sup>, Matthew W. Fielding<sup>a,b</sup>, Peter M. Vaughan<sup>c</sup>, and Barry W.
- 6 Brook<sup>a,b</sup>
- 7

## 8 Authors affiliations

- 9 <sup>a</sup> School of Natural Sciences, University of Tasmania, Private Bag 55, Hobart, Tasmania 7001,
  10 Australia
- 11 bARC Centre of Excellence for Australian Biodiversity and Heritage (CABAH), Australia
- 12 School of Biological Sciences, Monash University, Melbourne, Victoria 3800, Australia
- 13
- Author contributions: R.J.A, J.C.B., and B.W.B. conceived and designed the research; B.W.B
- and J.C.B. established the camera network; R.J.A., J.C.B, and B.W.B collected the data; R.J.A and
- B.W.B. analysed the data and interpreted results; R.J.A. drafted the manuscript, and all co-authors
   participated in producing the final manuscript version.
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## **19 Corresponding author**

- 20 Name: Rahil Jasminkumar Amin
- 21 Email: <u>rahiljasminkumar.amin@utas.edu.au</u>
- 22 ORCID: <u>https://orcid.org/0000-0002-6936-5732</u>
- 23

# 24 **Co-author ORCID**:

- 25 Jessie C. Buettel: https://orcid.org/0000-0001-6737-7468
- 26 Matthew W. Fielding: https://orcid.org/0000-0003-4536-0192
- 27 Peter M. Vaughan: https://orcid.org/0000-0002-1202-1963
- 28 Barry W. Brook: https://orcid.org/0000-0002-2491-1517

#### 29 Abstract

Modelling the spread of introduced ecosystem engineers is a conservation priority due to 30 their potential to cause irreversible ecosystem-level changes. Existing models predict 31 potential distributions and spread capacities, but new approaches that simulate the trajectory 32 of a species' spread over time are needed. We have developed novel simulations that predict 33 spatial and temporal spread, capturing continuous diffusion-dispersal with occasional long-34 distance leaps. We focused on the introduced population of Superb Lyrebird (Menura 35 36 novaehollandiae) in Tasmania, Australia. Initially introduced as an insurance population, lyrebirds have become novel bioturbators, spreading across key natural areas and becoming 37 38 "unwanted but challenging to eradicate". Using multi-scale ecological data, our research (1) 39 identified broad and fine-scale correlates of lyrebird occupation and (2) developed a spread simulation guided by a pattern-oriented framework. This occurrence-based modelling 40 framework is useful when demographic data are scarce. We found that the cool, wet forests 41 of western Tasmania, with dense leaf litter and open understories, offer well-connected 42 habitats for lyrebird foraging and nesting. By 2023, lyrebirds had reached quasi-equilibrium 43 within a core range in southern Tasmania, and were expanding northwest, with the frontier 44 reaching the western coast. Our model forecasts that by 2085, lyrebirds will have spread 45 widely across suitable regions of western Tasmania. By pinpointing current and future areas 46 47 of lyrebird occupation, we provide land managers with targeted locations to monitor the effects of their expansion. Our findings offer an evidence-based approach for future 48 monitoring and provide a framework for understanding the dynamics of other range-49 50 expanding species with invasive potential.

#### 51 Introduction

Introducing species to new areas, whether for conservation or by accident, often results in 52 53 unforeseen ecological effects (Powell et al. 2011, Ricciardi et al. 2013). The invasive potential of such species varies between taxa and ecosystems, and across spatial scales 54 55 (Davies et al. 2005, Guerin et al. 2018), necessitating case-specific assessments and tailored management strategies (Fridley et al. 2007, Januchowski-Hartley et al. 2018). Managing the 56 impacts of rapidly spreading ecosystem engineers can be particularly challenging due to 57 potentially irreversible ecosystem-level changes (i.e., hysteresis) and escalating monitoring 58 59 and control costs as the species expands (e.g., Aschim and Brook 2019, Rodda and Savidge 2007). Effective decision-making thus relies on robust projections of species' distribution and 60 spread across the new terrain. 61

Species are expected to spread and establish in areas where conditions are suitable, biotic 62 pressures are low, and the terrain is accessible for dispersal (Kolar and Lodge 2001, With 63 2002, Guisan and Thuiller 2005). Spatially explicit population dynamics models are ideal for 64 65 capturing detailed spread dynamics as they simulate key demographic processes, such as birth rates, mortality, and dispersal (Dunning Jr et al. 1995, Fordham et al. 2021). However, 66 these models often lack the necessary data on population parameters, which typically require 67 extensive long-term monitoring to obtain (Botterill-James et al. 2024). Occurrence-based 68 spread simulations are employed as an alternative, as presence-absence patterns are 69 70 ultimately the product of underlying demographic processes (Gormley et al. 2011). Occurrence-based spread simulations capture continuous diffusion-dispersal, where 71 individuals at the range edge colonise new areas via corridors of suitable habitats (e.g., Cucco 72 et al. 2021) or where environmental resistance is low (e.g., Lovell et al. 2021). To this end, 73 many models have been developed to predict the potential distribution and likely spread 74

routes of introduced species (Gormley et al. 2011, Barbet-Massin et al. 2018). However, these 75 species often have yet to reach biogeographic equilibrium, posing modelling challenges 76 (Gallien et al. 2010). For example, one risk is underestimating the habitat suitability of new 77 areas, as species may occupy a broader niche in new terrains (Fitzpatrick et al. 2007). 78 79 Another challenge is identifying correlates for successful versus unsuccessful colonisation using presence-absence data, as unoccupied habitats might still be viable given enough time 80 81 for the species to reach them (Gallien et al. 2012, Mainali et al. 2015). Additionally, more mobile species can also undergo jump dispersal or extreme long-distance dispersal-rare 82 83 events where they "leap over" nearby unsuitable areas, bypassing them to reach suitable habitat (Wilson et al. 2009). These challenges are exemplified by the introduced population 84 of the Superb Lyrebird (Menura novaehollandiae) - a prominent soil engineer on the move in 85 Tasmania. 86

Native to the temperate forests of the southeast Australian mainland, the Superb Lyrebird 87 (hereafter 'lyrebird') was translocated to Tasmania in the 1930s to safeguard it from mainland 88 predators such as red foxes (Vulpes vulpes) and dingos (Canis lupus dingo) (Tassell 2014, 89 Stobo-Wilson et al. 2021). Since then, lyrebirds have thrived, and spread across regions of 90 91 high conservation value within the Tasmanian Wilderness and World Heritage Area (Tassell 2014). By raking soil and litter in search of invertebrates, foraging lyrebirds profoundly 92 93 modify the forest floor (Maisey et al. 2021), introducing novel bioturbation to Tasmanian ecosystems that evolved without the process. Although they displace up to 155 tonnes/ha of 94 leaf litter annually (Maisey et al. 2021), the full spectrum of lyrebirds' impacts on Tasmanian 95 ecosystems—from beneficial nutrient cycling to disruptive community disassembly— 96 97 remains poorly understood.

In mainland Australia, lyrebirds occupy wet forests or rainforests near creek lines, areas with
deep leaf litter, and forest patches with complex mid- and high-strata vegetation (Ashton and

Bassett 1997, Maisey et al. 2019). These preferences imply that much of Tasmania, with its 100 diverse forest landscapes, could offer suitable habitats for lyrebirds. However, the absence of 101 biotic pressures such as predation and intra-specific competition (except in areas where the 102 species has already established) on the island raises questions about how well lyrebirds' 103 preferences translate to the Tasmanian environment. Despite being introduced for protection, 104 lyrebirds are now categorised as second priority under the Tasmanian invasive species list 105 106 (nre.tas.gov.au/invasive-species)—unwanted but difficult to eradicate. This scenario presents a conservation dilemma: managers must weigh the conservation value of the refuge 107 108 population against potential impacts on the Tasmanian ecosystem. As such, the growing presence of lyrebirds in Tasmania warrants close monitoring if management is to be 109 implemented. 110

This research uses multi-scale ecological data and advanced simulations to forecast the 111 spread trajectory of the Superb Lyrebird in Tasmania. We draw habitat correlates from the 112 species' native and introduced ranges, integrating data from lyrebirds' established mainland 113 distribution with emerging patterns in Tasmania. Specifically, we ask: (1) What fine-scale 114 habitat features influence the local occupancy of lyrebirds? (2) What regional/landscape 115 factors facilitate the species' spread and distribution? (3) What currently unoccupied areas are 116 most suitable for lyrebirds, and how long would it take to spread there? and (4) When will 117 118 lyrebirds spread to reach an equilibrium within the Tasmanian environment? We build novel simulations that combine continuous diffusion-dispersal with occasional long-distance leaps, 119 reflecting complex movement patterns. To accurately emulate lyrebird spread dynamics, we 120 use a Pattern-Oriented Modelling (POM) approach (Grimm et al. 2005), fine-tuning our 121 simulations to align with observed ecological patterns or 'targets'. By decoding these patterns, 122 POM enables us to accurately parameterise the model, ensuring it represents the ecological 123 processes of the lyrebird's spread. 124

By pinpointing current and future areas of lyrebird occupation, we aim to provide land managers with target locations to investigate the impacts of lyrebird expansion in Tasmania. Beyond the specific case of lyrebirds, this research offers a practical starting point for predicting the potential distributions of introduced species, and simulating future species spread despite limited data on demographic parameters. This approach equips researchers and managers with a predictive tool that can guide early intervention and management strategies.

131 Methods

# 132 Overview of the Modelling Framework

We used a sequential framework to model the fine- and broad-scale habitat preferences of 133 lyrebirds and predict their future spread in Tasmania. We: (I) quantified species activity from 134 135 camera-trap detections to model fine-scale habitat structure preferences within the current core range of lyrebirds in Tasmania (Figure 1a); (II) modelled broad-scale habitat correlates 136 137 and projected habitat suitability maps using Species Distribution Models (SDMs) and citizenscience occurrence data across their mainland range, and camera-trap detections from their 138 Tasmanian range (Figure 1b); and (III) used the habitat-correlate information from these 139 140 models to build a two-phase simulation of lyrebird spread. In the first phase, we developed a Parameter Calibration Model (PCM) to trace the species' spread following the introductions 141 in the 1930s. To validate this model, we anchored the target (presence-absence) predictions to 142 both current observations and habitat models, a key step in parameter search using Pattern-143 Oriented Modelling (POM). Then, the selected parameters from POM were used to project 144 the spread of lyrebirds up to the year 2085. 145



146

Figure 1. Data sources for modelling the habitat preferences and spread of the Superb 147 Lyrebird (Menura novaehollandiae) in Tasmania. Panel (a) shows the distribution of camera-148 trap detections (red crosses) of lyrebirds within Tasmania. The black squares highlight the 149 150 specific field sites where fine-scale habitat-structure data were collected to inform the models of lyrebird habitat preferences within their current core range. The dark grey boundary 151 defines the Tasmanian Wilderness World Heritage Area. Panel (b) shows a map of Australia 152 indicating the lyrebird presence across their native mainland range (from the Atlas of Living 153 Australia database; blue crosses), complemented by camera-trap detections in Tasmania (red 154 crosses). The dark grey boundary delineates the perimeter of all thirty-four of the Interim 155 Biogeographic Regionalisation for Australia (IBRA) regions that were included in the study 156 (full list in Table S1), with the red extent box marking the detailed study area within 157 Tasmania. 158

#### 159 I. Fine-scale Habitat Preferences of the Superb Lyrebird in Tasmania

### 160 Camera Survey and Data Pre-processing

We used lyrebird detections from a camera network set across Tasmania for a large-scale 161 continuous wildlife-monitoring program from 2018 to 2023. These data included 497 unique 162 camera stations within the lyrebird's occupied range (Figure 1a), operating over a total of 163 226,031 camera nights (531 average operational days per camera). The Cuddeback Xchange 164 (model 1279) cameras were unbaited and set 30-40 cm above ground, positioned either on 165 166 trails or in off-trail bushland, and spaced 0.5 to 5 km apart to encapsulate diverse habitat types. To ensure independent observations, we retained one lyrebird detection per 30-minute 167 sampling period. We considered this the appropriate duration to infer lyrebird activity 168 169 patterns considering their usual rate of movement through a landscape while occupying a given area (e.g. while foraging or searching for mates) (Lill 1996). The lyrebird activity index 170 was then calculated as the number of independent observations per operating day for each 171 camera site. 172

### 173 Station-Level Habitat Structure Modelling

Fine-scale habitat structure data was documented from 211 camera sites in Tasmania (Figure 174 1a), concentrating on areas where lyrebirds have been present for decades-indicative of a 175 176 potentially stable equilibrium range. We used the camera-detection rate for lyrebirds across the multi-year sampling period to delineate this range, where camera regions with consistent 177 lyrebird records (i.e., more than two records per camera across the sampling period) were 178 considered viable for fine-scale assessments. At each camera, we quantified litter cover, the 179 abundance of rotting logs, and the density of grasses, herbaceous understorey, woody 180 understorey, and trees. To do this, we photographed four images of the vegetation, one facing 181 each cardinal direction (east, west, north, and south) at each site. Habitat structure was then 182

classified by calculating the proportion of the image covered by each vegetative layer by 183 overlaying a  $3 \times 3$  grid over each image. The images were taken using a camera with a 35 184 mm focal length, and the grid size was adjusted to match the image aspect ratio to ensure 185 coverage from the ground layer to the tree line (see Fig S1). The relative density of each 186 vegetation layer was calculated as the ratio of the number of cells where a layer is present to 187 the available nine cells. The scores for all four images were averaged for each layer and used 188 189 to classify the density of each vegetative layer into dense (average score > 0.5) or sparse (< 0.5). 190

## 191 II. Broad-scale Habitat Preferences and Habitat Suitability Mapping

## 192 Range-wide Species Data Collection and Processing

We sourced lyrebird occurrence data from the Atlas of Living Australia, collected between
194 1970 to 2023, across their mainland equilibrium range (downloaded at:

doi.org/10.26197/ala.4744a2de-99ec-4cfb-9a0d-2a52d0f1dd5e, accessed on 06 April 2023;

196 Figure 1b). To control for data quality, we only included records from quality-controlled

197 sources, such as NSW Wildlife, Victorian Biodiversity Atlas, NSW Bird Atlassers, eBird, and

198 Birdlife Australia. In Tasmania, the long-term camera-trap data (see above) provided a

199 reliable indication of lyrebird absence, but such data were not available for their mainland

200 range. Therefore, we generated effort-controlled pseudo-absence data for the mainland by

201 inferring lyrebird absence in locations where at least three other land-bird species had been

reported (indicating sampling effort for birds) but not lyrebirds. This process was applied to

all land-bird species records from the same sources, collected between 1970-2023

- 204 (downloaded from Atlas of Living Australia: DOIs available in Table S2). To minimise
- duplicates, we converted both presence and pseudo-absence data into 1 km<sup>2</sup> grid presences,
- retaining only one record per grid and filtering out spatial anomalies. We implemented a 2 km

207 buffer zone around presence grids to account for localised movement and positional errors. Pseudo-absence sampling was confined within a 50 km radius from presence grids to avoid 208 ecological irrelevance from locations too distant from known occurrences (VanDerWal et al. 209 2009). To address spatial bias common in citizen-science surveys, we applied spatial thinning 210 based on Nearest-neighbour Minimum Distance NMD (Pearson et al. 2007, Barve et al. 211 2011), adjusted to human activity levels, following Amin et al. (2021). 212 For Tasmania, we prioritised camera-derived presences over citizen-collected data in grids 213 where they overlapped. Given that lyrebirds are still expanding their range in Tasmania; to 214 define their current range, we created an 80% Kernel Density Estimate (KDE) contour around 215 Tasmanian presences. Within this contour, we included only camera-derived absences, thus 216 avoiding potential biases from adding suitable but yet-to-be-reached habitats. Consequently, 217 218 the final dataset comprised 10066 presences and 9762 absences across the entire lyrebird 219 range.

#### 220 Mapping Suitable Habitats and Potential Distribution

We selected 17 environmental-raster layers to predict the broad-scale habitat use and 221 222 distribution of lyrebirds, chosen for their ecological relevance. These included bioclimatic (climate and weather) and landscape (e.g., land-use and vegetation type) rasters (complete list 223 in Table S3). The layers were rescaled to a 1 km<sup>2</sup> resolution to match the species-occurrence 224 grids and cropped to Interim Biogeographic Regionalisation for Australia (IBRA) regions 225 relevant to the lyrebird range across southeast Australia (full list in Table S1; Figure 1b). All 226 continuous raster layers were centred and normalised before analysis. We checked for 227 collinearity among variables and removed highly inter-correlated predictors ( $|\mathbf{r}| > 0.7$ ). To 228 avoid model overfitting due to overly nuanced layer classification, vegetation and land use 229 type were both aggregated into four major categories: rainforests, wet forests, dry woodland, 230 and other (e.g., grasslands) for vegetation; and protected, modified native, plantation, and 231 farmland for land use. 232

For the habitat suitability modelling, we initially explored five different model algorithms: 233 Generalised Linear Models (GLM), Generalised Additive Models (GAM), Random Forests 234 235 (RF), Gradient Boosted Machines (GBM) and an unweighted ensemble (see Table S4). Subsequently, the Random Forest classifier was selected as the final modelling method for its 236 superior performance and was fit using the R package caret (Kuhn et al. 2020). The data 237 were split into a 75% validation set for training and tuning and a 25 % hold-out set for 238 performance evaluation. The Area Under the Curve (AUC) of the Receiver Operating 239 240 Characteristic (ROC) values guided model refinement (variable selection/rejection), with only the most accurate and parsimonious predictor set retained—this step used default tuning 241 parameters (1000 number of trees ntrees; 7 number of randomly drawn candidate variables 242 243 *mtry*). After selecting the most relevant predictor set, we used k-fold cross-validation (k = 25)

and grid search for hyperparameter tuning. The selected tuning parameters and predictor set 244 were then used in the final model to evaluate predictive performance and create response 245 curves. We used the AUC of ROC and True Skill Statistic (TSS) as metrics to assess model 246 performance. While AUC allows threshold-independent assessment of model performance, 247 TSS requires the conversion of probabilities to class predictions (Allouche et al. 2006). To 248 address the slight class imbalance (i.e., unequal representation of presences and absences) in 249 250 our data, we refined our threshold using F1 scores, chosen for their emphasis on the minority class and ability to navigate the trade-off between Precision and Recall. 251

252 Given that our research focuses on the future spread of lyrebirds, modelling their potential

253 distribution under climate change scenarios was crucial. Ideally, this would incorporate

254 forecasts of both climate change and habitat conversion, but only future climate projections

were available. Consequently, to model future change in climatic suitability for lyrebirds, we

used mean projections for 2085 from three Global Climatic Models (GCMs) under

257 Representative Concentration Pathway (RCP) scenario 4.5: GFDK-CM21, MRI-

258 CGCM232A, and UKMO-HADCM3, selected for their robustness in downscale scenarios

259 (accessed via ecocommons.org.au; Di Virgilio et al. 2022).

260 Predicting the Timing of Future Spread

#### 261 Spread Model Concept

262 We developed a raster-based spread model at a 5 km<sup>2</sup> resolution (selected for computational

efficiency) that combines local diffusion to adjacent cells and infrequent leap events. Our

discrete-time grid-cell approach was chosen to avoid the complexities of predicting

265 individual-based spread, which requires detailed mechanistic knowledge about species

266 behaviour. While similar grid-based diffusion models have been successfully applied to

267 model disease spread in the Tasmanian devil (*Sarcophilus harrisii*) (Cunningham et al. 2021),

we have advanced this approach to incorporate more complex mechanisms of local diffusionand leap events, reflecting nuanced spread pathways and species dynamics.

270 At each time step in the simulation, spread probability (Pspread) was calculated for each occupied cell to determine whether spread occurs. Then, for each spreading cell, leap 271 probability  $(P_{leap})$  dictated whether to diffuse to adjacent areas or to perform a long-distance 272 leap (skipping adjacent areas). We used an additional parameter, layer coefficient ( $\lambda$ ), to 273 determine how likely a cell is to successfully leap at different distances. These coefficients 274 are tied to conceptual 'expansion rings' (R2, R3, R4), which represent increasing distances 275 from the occupied cell. The first ring, R1, covers the immediate neighbouring cells, while R2, 276 R3, and R4 cover progressively farther zones. The coefficients for each ring were calculated 277 using a trigonometric function, given the parameter  $\theta$  as (Eq. 1, 2, 3): 278

279 
$$\lambda_{R2} = \frac{1}{2} \times (1 + \sin \theta) \tag{1}$$

280 
$$\lambda_{R3} = \frac{1}{2} \times (1 + \cos \theta)$$
(2)

$$\lambda_{R4} = 1 - \lambda_{R2} - \lambda_{R3}. \tag{3}$$

282 Then, we derived normalised layer coefficients (Eq. 4, 5, 6):

$$\lambda_a = \frac{\lambda_{R_2}}{\lambda_T} \tag{4}$$

284 
$$\lambda_b = \frac{\lambda_{R3}}{\lambda_T} \tag{5}$$

$$\lambda_c = \frac{\lambda_{R4}}{\lambda_T} \tag{6}$$

where  $\lambda_T = \lambda_{R2} + \lambda_{R3} + \lambda_{R4}$ . The normalised coefficients (Eq. 4, 5, 6) effectively adjust the probability of leaping to each ring based on its distance, ensuring distance-based likelihood is appropriately scaled in the model. For the post-diffusion establishment, assuming the cell in which the dispersing lyrebird
arrived was unoccupied, we used logistic regression to calculate the probability of
establishment success (P<sub>establish</sub>): the log odds *Y* following dispersal were calculated as (Eq. 7):

292 
$$\log(Y) = \beta_1 + \beta_2 \times Habitat Suitablity$$
 (7)

where  $\beta_1$  was the intercept, and  $\beta_2$  was the coefficient weighting the influence of habitat 293 suitability at the destination cell. The probability of establishment was estimated by 294 converting log odds into probability using the logistic function  $\exp(Y)/(1+\exp(Y))$ . For leap 295 296 events, a cell was randomly selected from one of the expansion rings (R2, R3, or R4). The probability of a successful establishment in this selected cell is then calculated (using the 297 logistic regression above), adjusting for the distance of the leap. This adjustment is made 298 using the appropriate layer coefficient ( $\lambda$ ) for the selected ring, modifying the base 299 establishment probability as follows:  $P_{\text{leap}} = P_{\text{establish}} \times \lambda$ . This formulation accounts for the 300 301 likelihood of successful establishment with changing leap distance, reflecting the challenges 302 of colonisation at farther ranges.

This process was repeated at each timestep, charting species spread over time. The model's inherently stochastic nature was addressed by running multiple simulations, wherein the median spread timeline was used to predict expansion patterns.

306 Pattern-oriented Parameter Search and Simulation of Future Spread

We applied a pattern-oriented framework to parameterise the spread model. Pattern-oriented
modelling provides a systematic, data-driven approach to calibrate complex simulations
(Grimm et al. 2005, Grimm and Railsback 2012). Using Latin Hypercube Sampling (LHS),
we explored a parameter space encompassing 15,000 combinations of parameter values,
including spread probability (*P<sub>spread</sub>*), leap probability (*P<sub>leap</sub>*), the logistic regression intercept

312  $(\beta_1)$ , the coefficient measuring the weight of habitat suitability  $(\beta_2)$ , and the layer coefficient

control parameter ( $\theta$ ). Then, we employed Approximate Bayesian Computation (ABC) to 313 estimate posterior distributions by comparing the simulated outcomes with target patterns. We 314 configured ABC to the neural network approach to improve the model's ability to learn 315 complex patterns from the data. We implemented this in the abc package in R (Csilléry et al. 316 2012), with 200 neural networks, each with 8 nodes, and allowing a maximum of 1000 317 iterations for network training. Our primary objective for this step was to align the model's 318 predictions with the observed range, using binary entropy loss as a metric for validation using 319 POM. The binary entropy loss was calculated as (Eq 8): 320

321 
$$Loss = -\sum_{i} (T_i \times \log(P_i + \epsilon) + (1 - T_i) \times \log(1 - P_i + \epsilon))$$
(8)

where  $T_i$  represents the presence or absence value in the target raster for a cell, and  $P_i$  is the predicted probability for that cell. We added a small value,  $\varepsilon$  (= 1*e*-15), to the probabilities to avoid numerical issues with *log(0)*. This adjustment ensured that the probabilities remain within valid range for the logarithm function.

326 We applied a Parameter Calibration Model (PCM) to map the spread of lyrebirds in 327 Tasmania, from their introduction at Hastings Caves and Mt. Field in the 1930s through to 2023. The PCM identified the optimal parameter set, aligning the model's predictions with a 328 carefully constructed target raster (Figure S2). This raster used current observational data and 329 habitat preferences at broad and fine scales. Rigorous calibration ensured that the PCM 330 accurately reflected the observed patterns of lyrebird presence, absence, and spread 331 boundaries up to 2023, minimising mean binary entropy loss. We then used the selected 332 parameters to project the species' spread from the 2023 distribution in Tasmania to 2085. 333

### 334 Results

## 335 Fine-scale habitat correlates of the lyrebird

Lyrebirds were more active in areas of Tasmania with dense litter (mean activity index  $(\bar{a}i) =$ 0.17, std. error (se) = 0.03) and many decaying logs ( $\bar{a}i = 0.16$ , se = 0.03). They also preferentially used patches with sparse grass ( $\bar{a}i = 0.12$ , se = 0.02), woody ( $\bar{a}i = 0.13$ , se = 0.02), and herbaceous understoreys ( $\bar{a}i = 0.11$ , se = 0.02; Figure 2). We found no effect of tree density on lyrebird activity, highlighting the importance of understorey composition in their habitat preferences (Figure 2).

342



Figure 2. Change in mean activity index of Superb Lyrebirds (*Menura novaehollandiae*) with
habitat structure. This plot shows the activity index of lyrebirds across six habitat-structure
variables in Tasmania. The variables include relative density (classed as dense or sparse) of
litter cover, woody debris, grass cover, herb cover, woody shrub cover, and tree density. Data

- 348 were gathered from 211 camera-station sites, with the activity index calculated as
- independent observations per number of camera operating days. Error bars represent standard 349
- error generated using bootstrapping with 10,000 iterations. 350
- 351

#### Potential distribution of lyrebird 352

- At the broader scale, lyrebirds were found to prefer lower daily temperatures, and rainforest 353
- and wet forests (Figure 3a, c). Here, tall forest stands with lower photosynthetic activity-354
- indicative of mature ecosystems—provided ideal habitat for the lyrebirds (Figure 3b, c). 355
- Conversely, the widespread conversion of native forests into farmlands and non-native 356

plantations constrained lyrebird occupancy (Figure 3d). 357



Figure 3. The relationship between Superb Lyrebird (*Menura novaehollandiae*) occurrence probability and environmental factors from the Random Forest model: (a) daily temperature, and (b) fraction of Photosynthetically Active Radiation (fPAR) of vegetation canopy, as well as categorical habitat characteristics: (c) vegetation type, and (d) land use type. Continuous variables are standardised (z-transformed), shown on the x-axis, to depict their relative influence on the y-axis probability of occurrence. The bars represent 95% confidence intervals, providing a visual gauge of model's uncertainty.

367

Our habitat suitability model for lyrebirds effectively mapped the species' preference for 368 cool, temperate forests of southeast Australia (Figure 4b). The model had robust predictive 369 370 power, with an AUC of 0.9 (TSS = 0.65 at a threshold of 0.54). The model predicted 371 approximately 33,936 km<sup>2</sup> of the Tasmanian landscape to be conducive to lyrebird occurrence, with extensive availability of suitable habitats across the western and 372 373 northeastern forests of the island (Figure 4a). Our model identified a vast corridor of lyrebird habitat with a high suitability index (> 0.8) extending about 350 km from southwest to 374 northwest Tasmania (Figure 4a). This corridor, free from natural landscape barriers, will be 375 important in facilitating the species' movement. Despite the availability of suitable habitats, 376 lyrebird spread to the northeast is likely to be impeded by the agricultural midlands and drier 377 378 lands of part of the east. In the southwest, large areas predominantly covered by button-grass plains and scrublands were also of low to only moderate suitability (Figure 4a). 379





381

Figure 4. Habitat suitability for the Superb Lyrebird (*Menura novaehollandiae*), modelled using Random Forests (RF). Panel (a) displays the range of suitability within Tasmania, ranging from low (yellow) to high (blue) habitat suitability. Panel (b) shows the modelled habitat suitability across southeastern Australia, demarcating areas supporting the mainland lyrebird populations across its native range. The inset map shows Tasmania's position relative to the identified suitable habitats in the broader region. The magenta boundary defines the Tasmanian Wilderness World Heritage Area.

389

# 390 Timing of future spread

The PCM model, fine-tuned with current lyrebird observations, robustly mapped the species'
expansion range in Tasmania in the year 2023 (mean binary loss = 0.72; Figure 5). The model

- 393 successfully excluded the button-grass regions of the far southwest and the drier, human-
- impacted midlands from lyrebird occupancy, meeting the target exclusion criteria. Notably, it
- successfully captured the northwestern verified detections of lyrebird (Figure 5).





**Figure 5.** Modelled potential timing of the spread of the Superb Lyrebird (*Menura* 

398 *novaehollandiae*) in southern and central Tasmania, from initial introduction to present-day

- 399 (2023) distribution. The spread simulation (illustrated by coloured, time-coded contours) is
- 400 calibrated using pattern-oriented modelling and illustrates the lyrebird's capacity for range

401 expansion over 89 years. Spread started from two introduction sites at Hastings Caves State
402 Reserve (down black triangle) and Mt. Field National Park (up black triangle) in 1934, with
403 magenta crosses marking lyrebird detections by the year 2023. The white boundary defines
404 the Tasmanian Wilderness World Heritage Area.

405

The projected lyrebird distribution forecasts an ongoing expansion in Tasmania, with a bias 406 towards the northwest of the state. By the year 2085, the model predicts that lyrebirds will 407 408 have spread across most of the suitable habitat in the west except the far northwest tip of the island (Figure 6). Despite the presence of suitable habitats in the northeast, their spread to 409 these areas is expected to be limited by unsuitable habitat in the midlands and on the 410 411 southeast coast. In addition, the button-grass regions of the far southwest are predicted to remain uninhabited (Figure 6), reflecting the strong preference of lyrebirds for cool, 412 temperate forests. The eastern, western, and south boundaries of the suitable habitats are 413 expected to remain relatively stable from 2023 to 2085, indicating that these areas may 414 already be saturated. However, within these boundaries, future spread will result in increased 415 416 density and infilling of less densely populated areas, especially towards the northwest (Figures 5 and 6). 417



Figure 6. Simulated ongoing spread of the Superb Lyrebird (*Menura novaehollandiae*)
throughout Tasmania, from their current occurrence in 2023 (black crosses and red shading),
projected at ten-year intervals until 2085 (coloured time-coded contours), as determined by a
habitat-constrained stochastic dispersal-diffusion model. The white boundary outlines the
Tasmanian Wilderness World Heritage Area.

#### 424 Discussion

The projected expansion of Superb Lyrebird (*Menura novaehollandiae*) in Tasmania reveals a critical combination of ecological adaptation and invasive potential, with the species growing in presence through the island's temperate forests. Using advanced spread simulations calibrated with multi-scale ecological data, we project a continued spread towards the western coast by the end of this century, underscoring the need for improved knowledge of the effects of lyrebirds upon Tasmanian ecosystems, and targeted conservation management strategies in these well-connected habitats.

432 The fine-scale habitat models found lyrebird activity to be closely associated with open areas within forests that had abundant leaf litter. This habitat selection in Tasmania mirrors their 433 preferences in their native range on the mainland, suggesting consistent ecological 434 435 requirements across both regions. As ground-foraging insectivores, lyrebirds thrive in 436 environments rich in decomposing logs and leaf litter, home to a variety of invertebrates they feed upon, such as earthworms and insect larvae (Tassell 2014; Maisey et al. 2019). Dense 437 understorey vegetation, in contrast, poses navigational challenges and reduces foraging 438 efficiency, explaining their preference for more open habitats (Maisey et al. 2019). 439 440 Within their native range, lyrebirds prefer habitats with complex mid-stratum vegetation, such as small trees and large shrubs, which provide necessary camouflage from predators and 441 442 facilitate breeding (Lill 1979; Maisey et al. 2019). This preference for vegetative concealment, due to their lower nesting attentiveness compared to other birds, is crucial for 443 their reproductive success (Lill 1979). Similarly, in Tasmania, lyrebirds favour rainforests and 444 wet-eucalypt forests with old-growth trees and dense mid-strata (Buettel et al. 2017), 445 environments that our models confirm as ideal areas of occupancy. Lyrebird's preference for 446

447 cooler climates is likely due to an evolutionary trait for successful egg incubation at lower
448 temperatures (Lill 1979) and a predictable food supply (Maisey et al. 2019).

Based on these habitat preferences, it is clear that the national parks and reserves in western 449 and northeast Tasmania contain extensive areas of habitat conducive to lyrebird spread. The 450 prevalence of lyrebirds throughout south-central Tasmania can be attributed to the wide 451 452 availability of connected habitats, at the sites of lyrebird introduction to the state. The two introduced populations, at Hastings Caves State Reserve and Mt. Field National Park, have 453 now merged, facilitating gene flow and potentially enhancing their adaptability and capacity 454 to spread across the island. The camera data showed high prevalence within these regions, 455 indicating successful long-term establishment. The westward spread of lyrebirds to areas like 456 the Macquarie Harbour region, albeit at a lower density, suggests an early stage of invasion, 457 potentially entering a lag phase of colonisation (Crook 2002). With the Tasmanian Wilderness 458 World Heritage Area and over half of the Tasmanian mainland predicted to be suitable for 459 460 lyrebird habitation in our modelling, the species appears poised for further expansion.

Our spread simulations project an extensive future range expansion of lyrebirds, particularly 461 across western Tasmania's suitable but currently unoccupied habitats. By the end of this 462 century, the species is forecast to colonise the west-central highlands, northern slopes, and 463 northwestern Tasmania. However, the periphery of the northwest is not likely to be reached 464 465 within a century due to the patchy nature of suitable forests there. Human and natural barriers, such as cultivated lands, drier climates, and unsuitable vegetation, will also likely 466 block any expansion to the otherwise highly suitable northeast unless an introduction 467 468 (accidental or malicious) is attempted there. Any detection in the northeast should be rapidly addressed by conservation and management interventions if lyrebirds are to be kept 469 470 permanently out of that region. More broadly, given the projected spread of lyrebirds in Tasmania, especially in the wet, temperate forests of the west, focused ecological monitoring 471

is crucial. We recommend prioritising areas such as the Macquarie Harbour region and
adjacent open-temperate forests near Rosebery, which our models identify as likely frontiers
for future lyrebird spread. Using habitat information and suitability maps from our study,
targeted monitoring should add further on-ground data to investigate the lyrebirds' spread
dynamics and ecological impacts from the invasion front.

477 In this context, what ecological risks does the species pose? Tassell (2014) found no longterm evidence for their impacts on native invertebrate assemblages across spatial scales. One 478 possible biological reason for the apparent lack of lyrebird impacts on their food resource is a 479 time lag between the first introduction and measurable effects (Crooks 2005). Such prolonged 480 lags can result from low initial population density or other stochastic demographic processes 481 (Crooks 2005). Concurrently, systematic studies are needed to assess their influence on soil 482 composition, forest structure, and native species interactions. These studies should aim to 483 understand to what degree lyrebirds, as ecosystem engineers, are facilitating ecological 484 benefits (e.g., nutrient cycling (Maisey et al. 2021) and fire-risk suppression (Nugent et al. 485 2014)) versus posing threats to the Tasmanian fauna and the structuring of its forest 486 communities (e.g., through excessive bioturbation) (Tassel 2014). 487

As the Superb Lyrebird adapts to its new habitats in Tasmania, it is imperative to consider the broader challenges the species faces. Recent catastrophic events, such as the 'Black Summer' mega-fires of 2019-2020, have resulted in loss of crucial lyrebird nesting habitats across mainland Australia (Hughes et al. 2023; Maisey et al. 2023). The early 20th-century relocation to Tasmania has played an important role in safeguarding the lyrebird's future amidst escalating environmental threats. This creates a paradox where the introduced population holds conservation value but may require strategies to limit its future spread.

While our models offer robust predictions, there are limitations, particularly associated with 495 the broad-scale vegetation data. For instance, the absence of detailed understorey 496 characteristics in our habitat suitability predictions may lead to an overestimation of suitable 497 habitats, as lyrebirds require open understorey—a feature not adequately represented in the 498 available datasets. This constraint is particularly important for oligotrophic regions of western 499 Tasmania, which support a dense, complex understorey that makes lyrebird foraging difficult. 500 501 In addition to these data constraints, factors such as climate change, habitat alteration, and unforeseen ecological interactions could influence lyrebird distribution and impacts in ways 502 503 that are not currently understood. Future work could also incorporate population data into spread models, but this will require more detailed spatio-temporal monitoring to better track 504 lyrebird demographics and environmental impact. Additionally, exploring the indirect effects 505 506 of lyrebird activities, such as their influence on fire regimes and nutrient cycling in Tasmanian forests, would provide much-needed insight into the ecological trade-offs they 507 influence. 508

## 509 Conclusion

Our research underscores the Superb Lyrebird's adaptability and potential for range 510 expansion in Tasmania's southern and central temperate forests. The extensive, 511 interconnected habitats in the west and northwest are primed for species' future spread. In the 512 broader context, the stable and growing population in Tasmania is significant, as Hughes et 513 514 al. (2023) argue that lyrebirds face greater risk than their current IUCN status of 'Least Concern' indicates. Despite being introduced for conservation, the species is now listed as 515 unwanted in Tasmania, presenting a conservation dilemma. For managers, this involves a 516 delicate balance between protecting this iconic species in a range-wide context, while also 517 managing their unintended effects on new ecosystems. Key to this is continuous monitoring 518

519 at the expanding range front, ensuring that any interventions are timely and based on current

520 data. Leveraging predictive models, our research equips conservation managers with

521 information to identify options for targeted monitoring and potential interventions. Our

522 findings not only address the specific narrative of the lyrebird in Tasmania, but also offer a

- 523 methodological blueprint, combining detailed habitat analysis and flexible forecasting tools,
- 524 for modelling the future spread of translocated vertebrate species in broader contexts.

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