1	EcoEvoRxiv
2	Smartphones as a new tool for biodiversity research
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4	Peter Dietrich <sup>1,2+</sup> , Jan Bumberger <sup>2,3,4</sup> , Stanley Harpole <sup>2,3,0</sup> , Christiane Roscher <sup>2,3</sup> , Peter
5	Dietrich <sup>2,3,7</sup>
6	
7	<sup>1</sup> Geobotany and Botanical Garden, Martin Luther University Halle-Wittenberg, Halle, Germany
8	<sup>2</sup> German Centre of Integrative Biodiversity Research (iDiv) Halle-Jena-Leipzig, Leipzig, Germany
9	<sup>3</sup> Department of Monitoring and Exploration Technologies, Helmholtz Centre for Environmental Research (UFZ),
10	Leipzig, Germany
11	<sup>4</sup> Research Data Management - RDM, Helmholtz Center for Environmental Research (UFZ), Leipzig, Germany
12	<sup>5</sup> Department Physiological Diversity, Helmholtz Centre for Environmental Research (UFZ), Leipzig, Germany
13	<sup>6</sup> Martin Luther University Halle-Wittenberg, am Kirchtor 1, 06108 Halle (Saale), Germany.
14	<sup>7</sup> University of Tübingen, Geo- and Environmental Sciences, Tübingen, Germany
15 16 17 18 19 20 21 21 22 23	*Corresponding Author: peter.dietrich@idiv.de (alternative: peter.dietrich@botanik.uni-halle.de) ORCID Peter Dietrich (MLU) 0000-0002-7742-6064 Jan Bumberger 0000-0003-3780-8663 Stanley Harpole 0000-0002-3404-9174 Christiane Roscher 0000-0001-9301-7909 Peter Dietrich (UFZ) 0000-0003-2699-2354
24	Biodiversity is declining dramatically due to the effects of global change, with unknown
25	consequences for human life on Earth <sup>1</sup> . In recent years, more and more research has been carried
26	out on this topic, in the form of field, pot and long-term biodiversity experiments, in order to
27	better predict the consequences of biodiversity loss and to understand its underlying processes.
28	However, most of the methods used are either destructive, very costly, time consuming or
29	cumbersome. Here we highlight the use of smartphones to acquire novel biodiversity and
30	ecosystem function data, leveraging recent technological developments in terms of
31	photogrammetry and image recognition. Smartphones can allow us to carry out modern non-
32	destructive analysis, such as 3-dimensional (3D) vegetation analysis, with relatively low effort
33	and cost.
34	One application we see is focused on the relationships between plant species diversity and
35	ecosystem functioning. Examples of studies that would benefit include long-term experiments

such as Nutrient Network<sup>2</sup>, field studies with natural diversity or land-use gradients<sup>3</sup> and 36 research infrastructures such as eLTER<sup>4</sup>. A shared measured variable for all of these is above-37 ground plant biomass as a proxy for plant production, an essential component of ecosystem 38 functioning (next to other structural characteristics, e.g. cover or growth height). The most 39 common way to determine above-ground biomass is to harvest the plants (there are also 40 alternative non-destructive methods, which are, however, error-prone if used incorrectly<sup>5</sup>). 41 42 Actual estimates of productivity-measuring rates of biomass change vs. standing pool size requires longer time-series of biomass over the seasons than is possible with destructive 43 harvesting. In addition to its coarse time resolution, destructive sampling also is very coarse in 44 45 terms of capturing spatial variation of vegetation structure. Newer, more modern techniques allow finer-scale temporal and spatial measurements using 3D scans and computationally 46 processing the resulting digital point clouds (e.g., terrestrial laser scanning [TLS])<sup>6</sup>. The 47 48 disadvantage is that the equipment and software are very expensive and the work in the field is cumbersome and time consuming. 49

A middle way that combines the positive aspects of both methods (i.e., cheap and fast, easy to 50 implement, non-destructive) is to use smartphones and freely available 3D scanning apps 51 (without special fields of application). Almost everyone nowadays has a smartphone, and the 52 53 technology has improved enormously in recent years. Cameras with at least 40 megapixels, multiple lenses, image stabilisers and autofocus are standard for modern smartphones, and take 54 high-resolution photos that rival those of SLR cameras. Some models even have a LiDaR (Light 55 56 Detection and Ranging) sensor that can measure infrared light reflected from surfaces to create 3D images. As well as the hardware, software and apps have also developed significantly. There 57 are now freely available apps such as Scaniverse<sup>7</sup> (completely free), Polycam, or 3d Scanner 58  $App^{TM}$ , which allow 3D scans of above-ground vegetation. The applications are simple to use: 59 one opens the app, scans the plot (takes about 20 seconds, depending on the size), then the app 60 61 processes the captured images/videos (takes about 0.5-1 minute, depending on the size) and

finally outputs a 3D animation, as shown in figure 1 and 2, as well as under 62 https://doi.org/10.5281/zenodo.10610071. In this way, it is possible to easily scan the above-63 ground vegetation at daily, weekly, or monthly intervals, convert it into biomass, and thus get 64 an even more accurate picture of the plant communities without high cost and disturbance of 65 the system. This approach has many advantages, even beyond the simple determination of 66 biomass: repeated or even automated sampling over the growing season allows for estimates of 67 the rates of biomass production; the 3D point clouds allow the quantification of the structure 68 and spatial variation of vegetation; captured wavelengths can be decomposed to quantify 69 phenological patterns based on the colour changes; spectral data can be used to directly estimate 70 71 species composition and diversity (with suitable ML/AI methods). Moreover, this method opens up numerous possibilities for citizen science, i.e., people can collect data and provide 72 important additional quantitative and qualitative information<sup>8,9</sup>. Another conceivable use would 73 74 be for teaching, in order to better explain structural interrelationships.

Of course, the use of smartphones for biodiversity research is in its early stages and requires 75 "ground-truthing" to calibrate 3D images into accurate biomass estimates, and to test 76 reproducibility and comparisons to traditional methods, as well as scaling opportunities to 77 various more remotely-sensed imaging methods. Other challenges include the fact that only 78 79 small areas can be scanned at the moment (e.g., no forests) and that the resolution of the 3D scans is not very high; thus, it is necessary to further develop apps. In particular, software is 80 needed that allows virtual sampling of plants/leaves, automatic quantification of leaf 81 82 distributions and other individual/species-based analysis methods.

Because of the growing necessity for more and higher-quality biodiversity data, we see that harnessing these emerging technologies as an opportunity to meet the challenges of monitoring biodiversity change, opening up new questions and novel data to old questions, as well as a way to increase inclusion and access to biodiversity science. Biodiversity research needs to evolve and open up, establishing state-of-the-art methods as the standard that everyone can use.

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## Figures

- Fig. 1) Result of scanning a research plot with smartphone and the app Scaniverse. The
- photography (a) and the scan (b) were taken in the *DivResource* experiment<sup>10</sup> at the UFZ
- research station in Bad Lauchstädt (Germany). 3D animations can be found in Fig. 2 and under
- https://doi.org/10.5281/zenodo.10610071.



Fig. 2) 3D animations of scanned research plots with smartphone and the app *Scaniverse*.
The scans were taken in the *DivResource* experiment<sup>10</sup> at the UFZ research station in Bad
Lauchstädt (Germany). Note: trust the document to see the 3D animation (yellow bar at the top
of the PDF).

