Coevolution-induced stabilizing and destabilizing selection shapes species richness in clade co-diversification

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ABSTRACT

Coevolution can occur as a result of species interactions. However, it remains poorly understood how coevolution shapes the accumulation of species richness over macroevolutionary timescales. Assuming speciation occurs in a metacommunity as a result of genetic differentiation across communities due to dispersal limitation, we examine the effects of coevolution-induced stabilizing and destabilizing selection of a single quantitative trait on species diversification. We propose and test two hypotheses. (1) Stabilizing selection within communities enhances species diversification through strengthened dispersal limitation. (2) Destabilizing selection within communities impedes species diversification through weakened dispersal limitation. Here, we simulate clade co-diversification using an individual-based model, considering scenarios where phenotypic evolution is shaped by neutral dynamics, mutualistic coevolution, or antagonistic coevolution, where coevolution operates through trait matching or trait difference, and where the strength of coevolutionary selection is symmetrical or asymmetrical. Our assumption that interactions occur between an independent party (whose individuals can establish or persist in a community independently, e.g. hosts) and a dependent party (whose individuals cannot establish or persist in a community without the independent party, e.g. parasites or obligate mutualists) yields two contrasting results. Stabilizing selection within communities enhances species diversification in the dependent clade but not in the independent clade. Conversely, destabilizing selection within communities impedes species diversification in the independent clade but not in the dependent clade. These results are partially corroborated by empirical dispersal data,

28   suggesting that these mechanisms might explain the diversification of some of the most species-

29   rich clades in the Tree of Life.

30   **Keywords:** Species interaction, symbiosis, coevolution, stabilizing selection, destabilizing

31   selection, dispersal limitation, diversification, metacommunity

32

INTRODUCTION

The natural world is filled with interactions between different species. Many such interactions take the form of a bipartite partnerships in which two interaction parties play two distinct roles, e.g. the interactions between herbivores and plants, parasites and hosts, pollinators and angiosperms, and predators and prey. Bipartite interactions can potentially result in coevolution, that is, reciprocal evolutionary change in two or more interacting lineages driven by natural selection (Thompson 2005). Coevolutionary studies have focused on topics including phenotypic evolution across geographic space (Parchman and Benkman 2002), partnership specificity (Cook and Rasplus 2003), and signatures of coevolution in community assembly (Endara et al. 2017). Two coevolving lineages can co-diversify, i.e. diversify simultaneously, when they are allowed enough time. This has been an active area of research since the "escape-and-radiate" hypothesis, which states that rapid diversification of phytophagous insects or their independent plants often follows a significant shift in interaction partners (Ehrlich and Raven 1964; Cogni, Quental & Guimarães 2022). The ways by which macroevolutionary dynamics can be generated by processes at the local scale can be understood in the light of the geographic mosaic theory of coevolution, which emphasizes that coevolutionary dynamics can occur between geographically connected populations (Thompson 2005). It is therefore plausible that speciation could arise out of coevolutionary mosaics (Hembry, Yoder, and Goodman 2014; Thompson, Segraves, and Althoff 2017). Specifically, local coadaptation could potentially decrease the chance of mating between populations, paving the way for reproductive isolation and consequently speciation (Thompson, Segraves, and Althoff 2017). However, whether speciation is more likely to be enhanced or impeded by coevolution remain unclear (Janz 2011; Harmon et al. 2019; Hembry and Weber 2020).

Coevolution is shaped by the fitness outcomes of species interactions, which can vary in at least three ways. First, species interactions may benefit both parties or benefits one party at the cost of the other, affecting differently the fitness and, consequently, the coevolutionary outcome. Second, coevolution can be characterized by whether they are mediated by trait difference or trait matching (Yoder and Nuismer 2010). Under the trait-difference scenario, a species' fitness is maximized when its trait value is very different from that of its interaction partner. Examples of the trait-difference scenario (in the sense of Yoder and Nuismer 2010) include antagonistic

63   interactions in which predators and prey evolve increasingly strong weaponry and defense

64   against each other (Vermeij 1994) as well as mutualistic arms races in which both partners gain

65   more benefits from their partner when they have a greater trait value than that of their interaction

66   partner, e.g., a longer tongue in moth pollinators and a longer nectary spur in flowers (Whittall

67   and Hodges 2007). Under the trait-matching scenario (in the sense of Yoder and Nuismer 2010),

68   on the other hand, a species' coevolutionary fitness is maximized when its trait value more

69   closely matches that of its interaction partner. Antagonistic examples of this scenario include

70   brood parasitism (Langmore, Hunt, and Kilner 2003) whereas mutualistic examples including

71   obligate pollination mutualisms (Althoff and Segraves 2022). Third, the strength of natural

72   selection imposed by a species interaction is not always symmetrical for the interacting parties,

73   with the selection often being much stronger on one party than on the other (Brodie and Brodie

74   1999; Andreazzi, Thompson, and Guimaraes Jr 2017; Endara et al. 2017).

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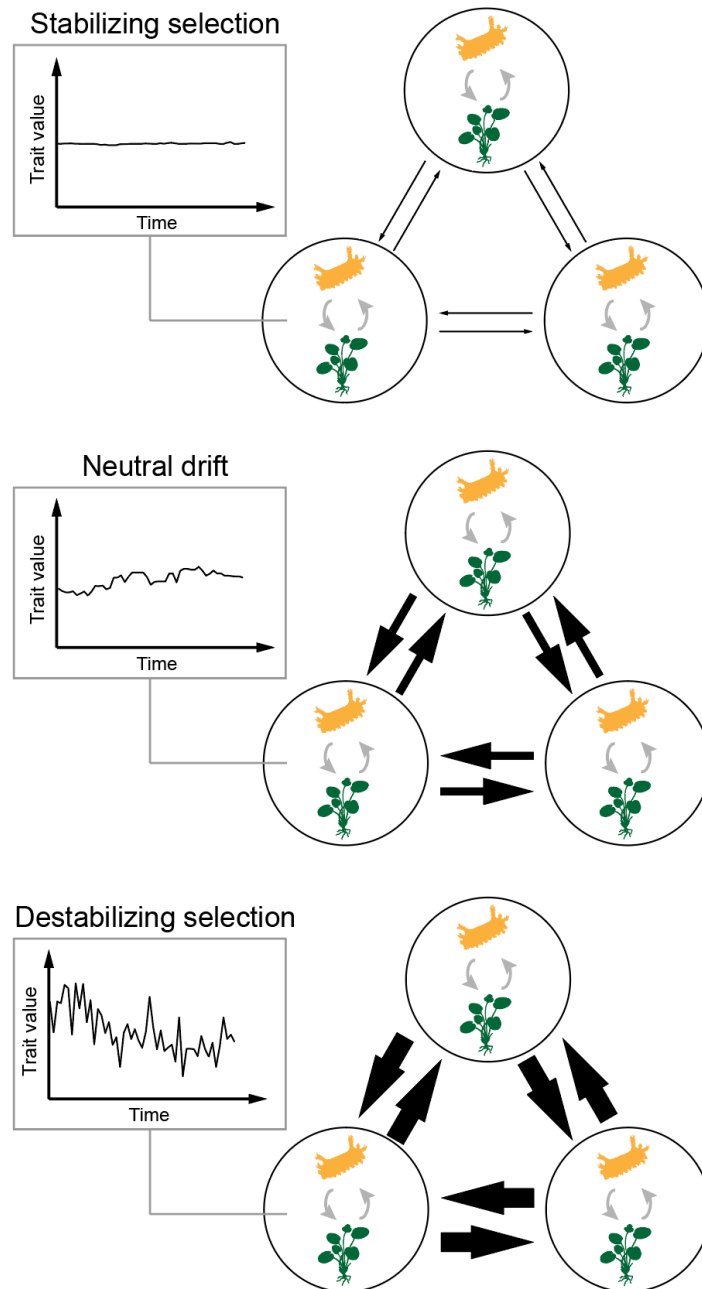
Figure 1. Selective regimes within communities and hypothesized levels of dispersal between communities. A metacommunity is composed of multiple communities (circles) connected through dispersal (straight arrows). Species interactions (curved arrows) occur within each community. The size of a straight arrow indicates the level of dispersal. Compared to neutral drift as the baseline, stabilizing selection is hypothesized to impede dispersal whereas destabilizing selection is hypothesized to enhance dispersal.

84   Different selective regimes (i.e. modes of phenotypic evolution) can potentially arise from the

85   different fitness outcomes of species interactions mentioned above. Prior literature has focused

86   on the microevolutionary effects of different selective regimes on coevolution (Yoder and

87   Nuismer 2010; Hembry et al. 2014). However, a theory is lacking on whether and how different

88   modes of phenotypic selection induced by coevolution drive or impede the accumulation of

89   species richness. The geographic mosaic theory of coevolution points to the possibility of

90   coevolutionary diversification of clades while leaving the exact mechanisms largely unexplored

91   (Thompson 2005). Given that certain types of species interactions are central to the biology of

92   many organisms (e.g. herbivory to the biology of phytophagous insects), a better understanding

93   of how coevolution shapes diversification through phenotypic evolution along this line could

94   potentially explain the diversification of many clades. Here we consider a general mode of

95   speciation where dispersal limitation of both interacting parties causes genetic differentiation

96   across space, eventually leading to speciation (Moran 1962; Etienne & Alonso 2005; Rosindell,

97   Harmon & Etienne 2015; Manceau, Lambert, Morlon 2015; Hubert et al. 2015; Maliet, Loeuille

98   & Morlon 2020). We propose two novel hypotheses regarding how stabilizing and destabilizing

99   selection shape the degree of dispersal limitation (Fig. 1), which in turn shapes the degree of

100   genetic differentiation across space and eventually the species richness accumulation by a clade.

101   Over temporal scales, stabilizing selection is characterized by increased temporal trait stability

102   compared to neutral drift, and destabilizing selection can conversely be defined as a selective

103   regime that decreases temporal trait stability (Gingerich 2019a; Gingerich 2019b). The idea that

104   stabilizing selection selects against immigrant individuals and thus limits dispersal has been

105   supported both empirically and theoretically (Tufto 2000; Tufto 2001; Lopez el al. 2008;

106   Scheepens, Frei & Stöcklin 2010; Yeaman & Whitlock 2011; Huisman and Tufto 2012;

107   Zacchello, Vinyeta, and Ågren 2020). This leads to the intuitive notion that, the stronger

108   temporal trait stability a selective regime causes, the more strongly dispersal is limited – and a

109   stronger degree of dispersal limitation causes stronger genetic differentiation across space and

110   eventually a higher species richness accumulation. Following this intuition, we propose a first

111   hypothesis termed the *stabilizing selection hypothesis*: stabilizing selection impedes dispersal

112   (and thus increases the degree of dispersal limitation), which results in an increase in genetic

113   differentiation across space, eventually resulting in an increase in the species richness

114   accumulation. The same intuition can lead to another hypothesis, which is termed the

115   *destabilizing selection hypothesis*: destabilizing selection enhances dispersal (and thus reduces

116   the degree of dispersal limitation), which results in a reduction in genetic differentiation across

117   space, eventually resulting in a reduction in the species richness accumulation. Given the

118   complexity of coevolutionary systems, these two hypotheses were devised based on a single

119   clade in isolation and later tested in a coevolutionary, metacommunity context.

120   To test these stability hypotheses in the context of two coevolving clades, we built an individual-

121   based model for the coevolutionary accumulation of species richness across two-dimensional

122   space. We considered different coevolutionary scenarios, including those where the interaction is

123   mutualistic versus antagonistic, where the interaction is mediated by trait differences versus trait

124   matching, and where coevolutionary selection is symmetrically versus asymmetrically strong for

125   the interacting parties. In bipartite interactions such as antagonisms and mutualisms, one partner

126   is often more dependent on the other than the other way around. Specifically, many antagonistic

127   interactions occur between antagonistic symbionts (e.g. parasites, pathogens) and their hosts

128   without which they cannot survive (Schmid-Hempel 2013). Even in mutualistic interactions, the

129   mutual dependence of interaction partners can be highly asymmetric (Bascompte, Jordano, and

130   Olesen 2006; Bronstein 2015). Given this, we built into our model the differences between

131   independence and dependence in partnership, assuming that the independent party's individuals,

132   e.g. hosts, can establish or persist in a community independently, whereas a dependent party's

133   individuals cannot establish or persist in a community without the independent party, e.g.

134   parasites or obligate mutualists. Our simulation results suggest mechanisms for the

135   diversification of some of the most species-rich groups in the Tree of Life (Table 1).

136 Table 1. Examples of species interactions that can be described as independent-dependent partnerships and the
137 species richness estimates for the independent and dependent parties.

Interaction	Independent party (species richness)	Dependent party (species richness)	Reference(s)
Host plants and herbivorous insects	Plants (ca. 374,000)	Herbivorous insects (over 500,000)	Bernays (2009); Christenhusz and Byng (2016)
Host and parasites	Hosts (NA)	Parasites (ca. 6,000,000)	Dobson et al. (2008);
Corals and *Symbiodinium*	Corals (ca. 10,661 estimated for Anthozoa)	*Symbiodinium* (NA)	Bánki et al. (2023)
Insects and gut microbes	Insects (ca. 5,500,000)	Gut microbes (NA)	Stork (2018)

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METHODS

Model description

Partnership between independent and dependent individuals

142 In the model, we consider the partnership between independent and dependent individuals. An
143 independent individual can partner with multiple dependent individuals, but a dependent
144 individual can only partner with one independent individual. An independent individual does not
145 need to partner with any dependent individual for survival, but a dependent individual needs the
146 one and only independent individual that it partners with for survival. This is modeled in two
147 separate ways. First, during dispersal, an independent individual could survive where no
148 dependent individuals are present; however, a dependent individual dies where no independent
149 individuals are present. Second, during competition, when an independent individual dies, so do
150 all of its dependent partners; however, when a dependent individual dies, its one and only
151 independent partner does not die. It is important to note that, in nature, the party that interacts
152 with multiple individuals are not necessarily the independent (less dependent) party.

Dispersal

154 The model starts with two populations each belonging to one of the interacting parties (the
155 independent and dependent) placed at the central site of a $n \times n$ grid, where each cell represents
156 a geographic site. Each individual, independent or dependent, has the opportunity to disperse

157   only at birth and moves to one of the four neighboring sites or else remain at the same site (each

158   with an equal probability of 0.2). As previously mentioned, if a dependent individual moves to a

159   site where no independent individuals are present, it dies; however, if it moves to a site where at

160   least one independent individual is present, the dependent individual randomly chooses an

161   independent individual to partner with among the independent individuals available at that site.

162   The entire grid forms a metacommunity composed of $n \times n$ communities (sites) connected

163   through dispersal.

164   **Sexual reproduction and speciation**

165   The genetic model largely follows a previous model built for the diversification of a single clade

166   (Aguilée et al. 2018), but with simplifications. Each independent or dependent individual is

167   diploid and has a given number of L_{dist} loci determining its genetic distance from another

168   individual. A new mutation can arise at any of these loci at a fixed probability μ_{dist}. To

169   determine whether two individuals are genetically incompatible enough to be considered

170   reproductively isolated, we calculated the genetic distance between two individuals based on

171   how many loci carry completely different alleles between the two individuals. The genetic

172   distance is considered sufficient for reproductive isolation if greater than a fixed genetic distance

173   threshold T_{dist}. These features allowed speciation through genetic differentiation across the grid.

174   Both independent and dependent individuals are hermaphrodites and reproduce sexually. For

175   independent individuals or dependent individuals, each mating attempt occurs within each site

176   following these steps: (1) two individuals with the highest fitness are chosen regardless of

177   whether they have reproduced before (see "Fitness outcomes of species interactions" for how

178   fitness is decided; for simplicity, we did not choose a more complicated reproduction model); (2)

179   the two parents successfully reproduce n_{offspr} offspring if they are not reproductively isolated.

180   These steps are repeated until n_{mat} mating attempts are made, regardless of whether mating

181   attempts result in successful reproduction. For each offspring, the genotypes of the genetic

182   distance loci are determined by Mendelian independent assortment of parental alleles. Given that

183   dependent individuals die along with their independent partner but not vice versa, it is necessary

184   for n_{offspr} and n_{mat} to be greater for the dependent individuals than for the independent

185   individuals so that the dependent individuals do not die out.

Genetics of phenotype

Each independent or dependent individual has one locus determining its ecological phenotype which consists of a single quantitative trait. Mutation occurs at each of these loci, with the mutated allele value drawn from a normal distribution with a mean equal to the parent allele value and a standard deviation equal to σ_{eco}. For each offspring, the genotype of the ecological phenotype locus is determined by a Mendelian random segregation of parental alleles.

Competitive death

Many types of antagonisms and mutualisms can occur between a consumer and a resource, such as herbivory, parasitism, or pollination (Bronstein 2015). Given that populations cannot grow infinitely in consumer-resource systems due to resource competition (Abrams 2009), we considered there to be a growth rate of zero when population size reached carrying capacity. In the model, resource competition occurs among dependent individuals partnering with the same independent individual (e.g., parasites on the same host) and among independent individuals within the same site. The number of mutually competing individuals n cannot grow above carrying capacities $K_{independent}$ or $K_{dependent}$. We ensured this by assigning $n_{independent} - K_{independent}$ or $n_{dependent} - K_{dependent}$ individuals to death (where $n_{independent}$ and $n_{dependent}$ are the numbers of mutually competing individuals, for independents and dependents, respectively), on a lowest-fitness-first basis (see "Fitness outcomes of species interactions" for how fitness is decided). Again, when an independent individual dies, so do all of the dependent individuals that partner with it; however, when a dependent individual dies, its one and only independent partner does not die.

Fitness outcomes of species interactions

We allowed different modes of phenotypic evolution to arise from species interactions with different fitness outcomes (Fig. 2). Antagonisms (interactions that benefit one party at the cost of the other) and mutualisms vary in whether each of the two interacting parties receives a benefit or pays a cost (Bronstein 2015). For either antagonisms or mutualisms, the fitness of phenotypes was modeled as the result of either (i) trait difference: how different the two interacting phenotypes were (the direction of phenotypic difference between interacting parties does matter), or (ii) trait matching: how closely two interacting trait values matched each other (the direction of phenotypic difference between interacting parties does not matter). Following Yoder and

216   Nuismer (2010), the fitness of an individual i interacting with an antagonist or mutualist

217   individual j can be expressed as

218
$$w_i\left(z_i, z_{j1}, z_{j2}, \dots, z_{jn}\right) = w_0 + \sum_{k=1}^{n} \frac{\xi}{1 + e^{-\alpha(z_i - z_{jk})}} \tag{1}$$

219   under trait difference, or

220
$$w_i\left(z_i, z_{j1}, z_{j2}, \dots, z_{jn}\right) = w_0 + \sum_{k=1}^{n} \xi e^{-\alpha(z_i - z_{jk})^2} \tag{2}$$

221   under trait matching, where z_i and z_j are phenotypic trait values of interacting individuals, n is

222   the number of partners that individual i has, w_0 is the individual i's fitness in the absence of the

223   interaction, ξ is the cost or benefit to the individual (positive if beneficial, negative if costly), and

224   α determines the sensitivity of the fitness outcome to the difference between interacting trait

225   values (i.e. deviation from fitness neutrality where trait values do not affect fitness). The strength

226   of coevolutionary selection can often be highly asymmetrical, i.e., much weaker on one

227   interacting party than on the other (Brodie and Brodie 1999; Andreazzi, Thompson, and

228   Guimaraes Jr 2017; Endara et al. 2017). Here we considered the extreme case of asymmetrical

229   coevolutionary selection by allowing either the independents' or dependents' individual fitness

230   to be unaffected by trait values (Function II in Fig. 2). A fully factorial design would contain

231   4*4=16 scenarios given the all the combinations of the 4 fitness functions. We simulated a total

232   of 9 possible scenarios (Table 2) to include all possible combinations except 7 combinations of

233   which no or few empirical cases are known, i.e., those where one clade's fitness follows trait

234   difference while the other's follows trait matching (Yoder and Nuismer 2010) or where the

235   interaction is costly for the dependent clade.
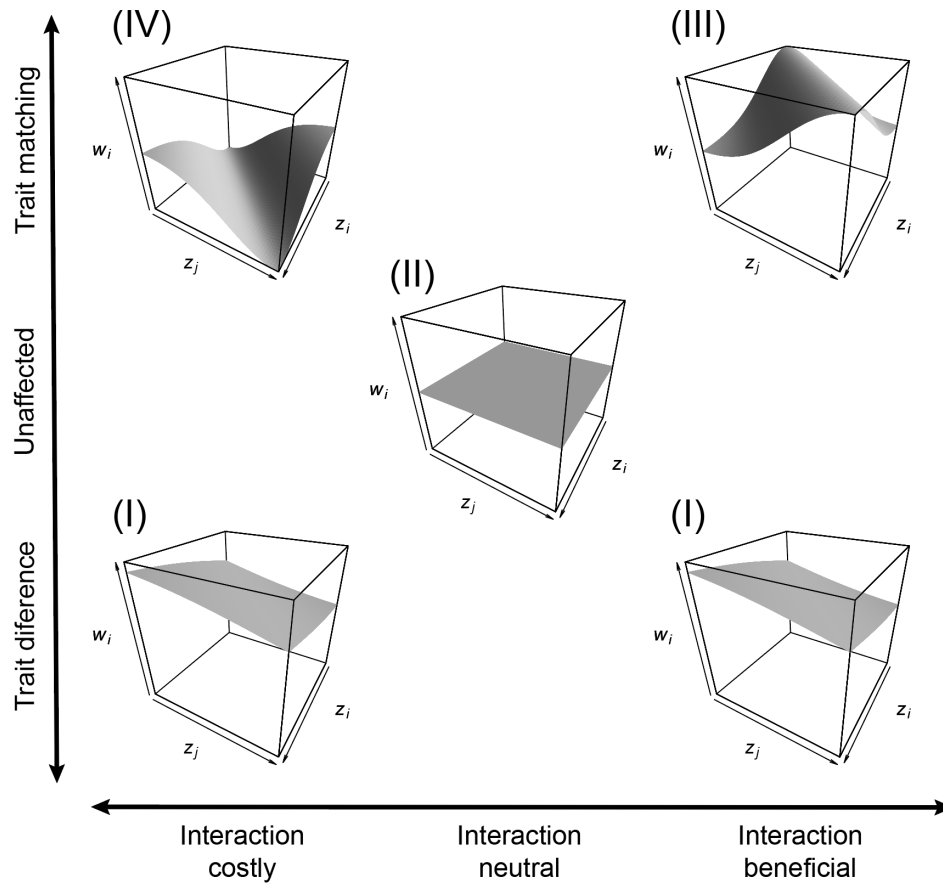
Figure 2. Individual fitness as functions of the traits of interacting individuals. Each surface is the fitness of individual i (w_i) as a function of z_i, which denotes the trait value of individual i itself, and z_j, which denotes the trait value for individual j (individual i's interaction partner). Function I: Equation 1, $\xi = 0.1, \alpha = 1$. Function II: $w_i = 0$. Function III: Equation 2, $\xi = 0.1, \alpha = 1$. Function IV: Equation 2, $\xi = -0.1, \alpha = 1$. For this model, Function II, where individual fitness is held constant and independent from trait values, is equivalent to Equation 1 or 2 when $\alpha = 0$ regardless of the value of ξ. Following Yoder and Nuismer (2010), the fitness function does not dependent on whether the interaction is beneficial or costly when coevolution operates through trait difference (Function I). In all panels, the ranges of the z_i and z_j axes are between 0 and 2 and the range of the w_i axis is between -0.1 and 0.1.

247   Table 2. The 9 scenarios considered in this study and their corresponding fitness functions (Figure 2). 4 fitness
248   functions (I-IV) necessitate a total of 9 combinations after unrealistic combinations are excluded.

Scenario	Trait difference or trait matching	Fitness function for the independent	Fitness function for the dependent	Outcome of interaction
a	Difference	I	I	Mutualism or antagonism
b	Difference	I	II	Mutualism or antagonism
c	Difference	II	I	Mutualism or antagonism
d	Matching	III	III	Mutualism
e	Matching	III	II	Mutualism
f	Matching	II	III	Mutualism or antagonism
g	Matching	IV	III	Antagonism
h	Matching	IV	II	Antagonism
i	Unaffected	II	II	Mutualism or antagonism

249

Simulations

251   The model was implemented and the simulation results were analyzed in the R language (v4.0.0;

252   R Core Team, 2020). All simulations were run on the University of Arizona High-Performance

253   Computing clusters. We ran 96 replicates for each of the 9 scenarios, totaling 864 simulations.

254   The large number of replicate simulations were made possible by custom code that can record

255   the progress of a simulation and resume where that simulation is terminated by the workload

256   manager. Each simulation was run for 1500 generations. For each of the 9 simulated scenarios,

257   t-tests comparing the distributions of mean species richness during the 1401th-1450th generations

258   versus the 1451th-1500th generations found no statistically significant difference ($P > 0.05$, $n = 96$

259   replicates for each of the two distributions being compared). This confirmed that the duration of

260   simulation (1500 generations) was enough for simulations to reach a stationary state in terms of

261   species richness, despite the ongoing fluctuations in species richness near the end of simulation

262   (Fig. S1-S18). The large number of replicate simulations made the analyses computationally

263   intense. This computational challenge was overcome though parallel computation using the R

264 package doParallel (v1.0.17; Microsoft Corporation and Weston). All custom code used in this

265 work is available as a supplementary file (File S1) and on GitHub

266 (https://github.com/Dragonfly4412/Macro_Coevolution). All the constants used in the

267 simulations are provided in Table S1.

Identifying selective regimes based on temporal trait (in)stability

269 To identify the modes of phenotypic evolution for each scenario, we recorded the phenotypic

270 values of all independent and dependent individuals at the central site of the $n \times n$ grid during

271 the entire duration of each simulation (1500 generations). We then quantified the change in mean

272 trait value during each generation, Δz. Δz is conventionally referred to as step difference and is

273 measured in haldanes, i.e., standard deviations per generation on a timescale of one generation

274 (Gingerich 2019a; Gingerich 2019b). For example, a Δz value of 2 haldanes means that the

275 change in mean trait value from Generation 1 to Generation 2 is two times the standard deviation

276 of the trait distribution at Generation 1. We further took the absolute value of Δz to get $|\Delta z|$. We

277 then averaged $|\Delta z|$ across the entire duration of simulation to get the mean step difference $\overline{|\Delta z|}$

278 as a measure of temporal trait instability. We determined the minimum and maximum for the

279 $\overline{|\Delta z|}$ of the entirely neutral scenario (Scenario i, where both the independents' and dependents'

280 fitness are held constant and do not depend on trait values). We treated simulations in which $\overline{|\Delta z|}$

281 is greater than the neutral maximum as destabilizing selection and those in which $\overline{|\Delta z|}$ is less

282 than the neutral minimum as stabilizing selection.

Degree of dispersal limitation, genetic distance between sites, and species richness

284 We quantified the degree of dispersal limitation as the proportion of native individuals among all

285 individuals, with higher proportions of native individuals indicating stronger degrees of dispersal

286 limitation. We define a native individual as an individual that inhabits the same site at which it

287 was born. Specifically, what we measured was realized dispersal rather than dispersal *per se*,

288 because we are interested in the contribution of dispersal to local gene pools, which is contingent

289 on successful establishment of the dispersers following dispersal. The degree of dispersal

290 limitation we refer to is the degree to which dispersal success is limited. Then, we calculated

291 genetic distance between any two sites (i.e., between the two populations inhabiting the two

292 sites) by taking the mean genetic distance between any two individuals from the two sites (i.e.,

293 the two populations). The genetic distance between all sites was then quantified as the mean

294   genetic distance between any two sites. To quantify the species richness that each clade had

295   accumulated at the end of the simulation, we considered populations to belong to a single species

296   if their genetic distance did not exceed the genetic distance threshold for speciation T_{dist} (for

297   details, see "Sexual reproduction and speciation").

298   For the degree of dispersal limitation (the proportion of native individuals), we took the mean

299   over the entire 1500 generations of simulation because it is the cumulative effect of dispersal that

300   is of interest. For genetic distance between sites and species richness accumulation, we took the

301   mean over the last 10 generations of simulation because we were interested in them as the

302   eventual results of multiple generations of dispersal and speciation.

303
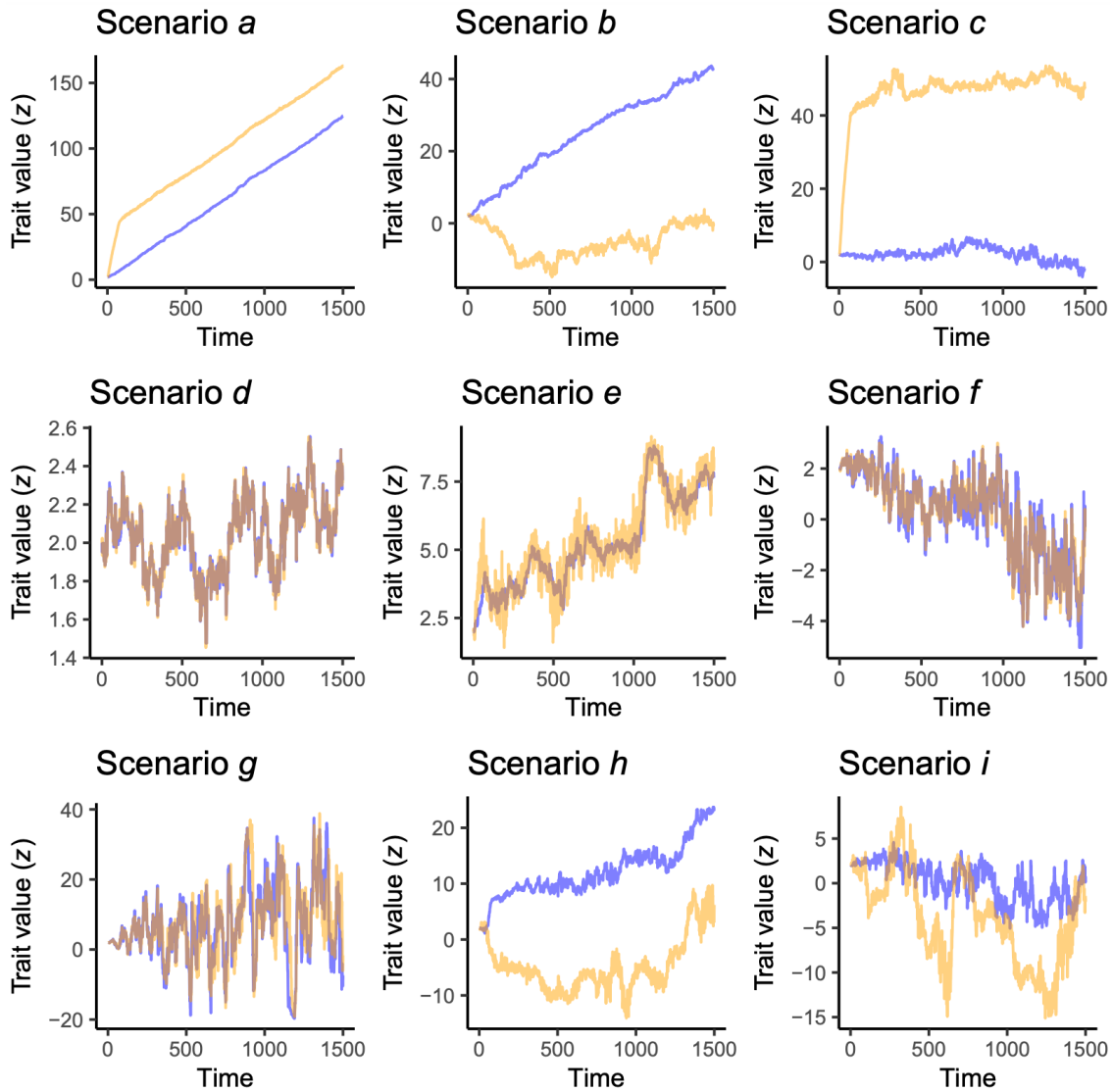
Figure 3. Coevolutionary trajectories within communities in each of the nine simulated scenarios (*a-i*). Solid lines indicate the mean trait value calculated for individuals at the central community (site) of the $n \times n$ grid in one of the 96 replicates for each scenario. Blue and yellow are used to indicate the independent and dependent trait values, respectively.

RESULTS

Each of the 9 simulated scenarios generated a unique coevolutionary trajectory within communities (Fig. 3). The 9 result coevolutionary trajectories were each characterized by rapid and continuous reciprocal escalation of trait values in the two clades characteristic of an arms race (Scenario a; Fig. 3), trait escalation in the independent clade and an initial decrease in trait value followed by a random walk (in the sense that it does not substantially differ from a trajectory typical of the neutral scenario) in the dependent clade (Scenario b; Fig. 3), trait escalation followed by a random walk in the dependent clade and random walk in the independent clade (Scenario c; Fig. 3), varying degrees of temporal trait stationarity in the two clades (Scenarios d-f; Fig. 3), dramatic fluctuation in trait value in both clades characteristic of coevolutionary cycling (Scenario g; Fig. 3), a tendency for the host trait value to not overlap with that of the dependent (Scenario h; Fig. 3), and random walks underlain by neutral dynamics in both clades (Scenario i; Fig. 3).

Analyses of the effects of selective regime on the degree of dispersal limitation, genetic distance between sites, and species richness accumulation revealed the mechanisms by which coevolution shaped species richness (Fig. 4). Quantification of the mean step difference $\overline{|\Delta z|}$ as a measure of temporal trait instability showed that the 9 scenarios generated all three modes of phenotypic evolution, i.e. neutral drift, stabilizing selection, and destabilizing selection in the two clades. For each of the relationships of interest (Fig. 4, A-C), we performed a loess regression to visualize non-linearities, but also two localized simple linear regressions to quantify the average effects of stabilizing and destabilizing selection (Fig. S19).

In the independent clade (Fig. 4, D-F; Fig. S19, D-F), compared to neutral drift, stabilizing selection resulted in relatively weak increases in the degree of dispersal limitation (slope = -1.47 percentage/haldane, $P = 0.0013$, left line in Fig. S19D), genetic distance between sites (slope = -0.1664 loci/haldane, $P = 0.208$, left line in Fig. S19E), and species richness accumulation (slope = -16.4918 species/haldane, $P = 0.00117$, left line in Fig. S19F). However, compared to neutral drift, destabilizing selection resulted in relatively strong reductions in degree of dispersal limitation (slope = -12.11 percentage/haldane, $P < $ 2e-16, right line in Fig. S19D), genetic distance between sites (slope = -7.60415 loci/haldane, $P < $ 2e-16, right line in Fig. S19E), and species richness accumulation (slope = -181.4629 species/haldane, $P < $ 2e-16, right line in Fig.

341   S19F). These results suggest that the predominant mechanism shaping species richness in the

342   independent clade is one where destabilizing selection reduces the degree of dispersal limitation,

343   which reduces genetic distance between sites, eventually resulting in reduced species richness

344   accumulation.

345   In the dependent clade (Fig. 4, G-I; Fig. S19, G-I), compared to neutral drift, stabilizing selection

346   resulted in relatively strong increases in the degree of dispersal limitation (slope = -3.755

347   percentage/haldane, $P < 2e\text{-}16$, left line in Fig. S19G), genetic distance between sites (slope = -

348   1.0355 loci/haldane, $P = 2.87e\text{-}12$, left line in Fig. S19H), and species richness accumulation

349   (slope = -35.7923 species/haldane, $P < 2e\text{-}16$, left line in Fig. S19I). The effect of stabilizing

350   selection showed strong non-linearity, with the highest degree of dispersal limitation, genetic

351   distance between sites, and species richness accumulation being achieved by intermediately

352   rather than extremely strong stabilizing selection (Fig. 4, G-I). However, compared to neutral

353   drift, destabilizing selection resulted in relatively week reductions or even a slight increase in the

354   degree of dispersal limitation (slope = -0.00114 percentage/haldane, $P = 0.993$, right line in Fig.

355   S19G), genetic distance between sites (slope = -0.08698 loci/haldane, $P = 0.853$, right line in

356   Fig. S19H), and species richness accumulation (slope = 6.4800 species/haldane, $P = 0.375$, right

357   line in Fig. S19I). These results suggest that the predominant mechanism shaping species

358   richness in the dependent clade is one where stabilizing selection increased the degree of

359   dispersal limitation, which increases genetic distance between sites, eventually resulting in

360   increased species richness accumulation.

361   Specifically, the destabilizing selection hypothesis explained how species richness accumulation

362   was reduced for the independent clade in the coevolutionary scenarios of mutualistic or

363   antagonistic arms races where selective pressure is comparable between the independent and

364   dependent individuals, i.e., a classical arms race, and in the scenario of antagonistic trait

365   matching where selective pressure is comparable between the independent and dependent

366   individuals (Fig. 4, D-F; Fig. S19, D-F; Scenarios a & g in Fig. 2). The variable $\overline{|\Delta z|}$, as a

367   measure of temporal trait instability, is turned out to be key in shaping species richness

368   accumulation. This is because trait instability is a direct result of coevolution and in turn shapes

369   dispersal and consequently speciation. The stabilizing selection hypothesis explained how

370   species richness was increased for the dependent clade in the coevolutionary scenario of

mutualistic trait matching where selective pressure is comparable between the independent and dependent individuals, the scenario of mutualistic or antagonistic trait matching where selective pressure is weak for independent individuals, and the scenario of antagonistic trait matching where selective pressure is comparable between the independent and dependent individuals (Fig. 4, G-I; Fig. S19, G-I; Scenarios d, f & g in Fig. 2).
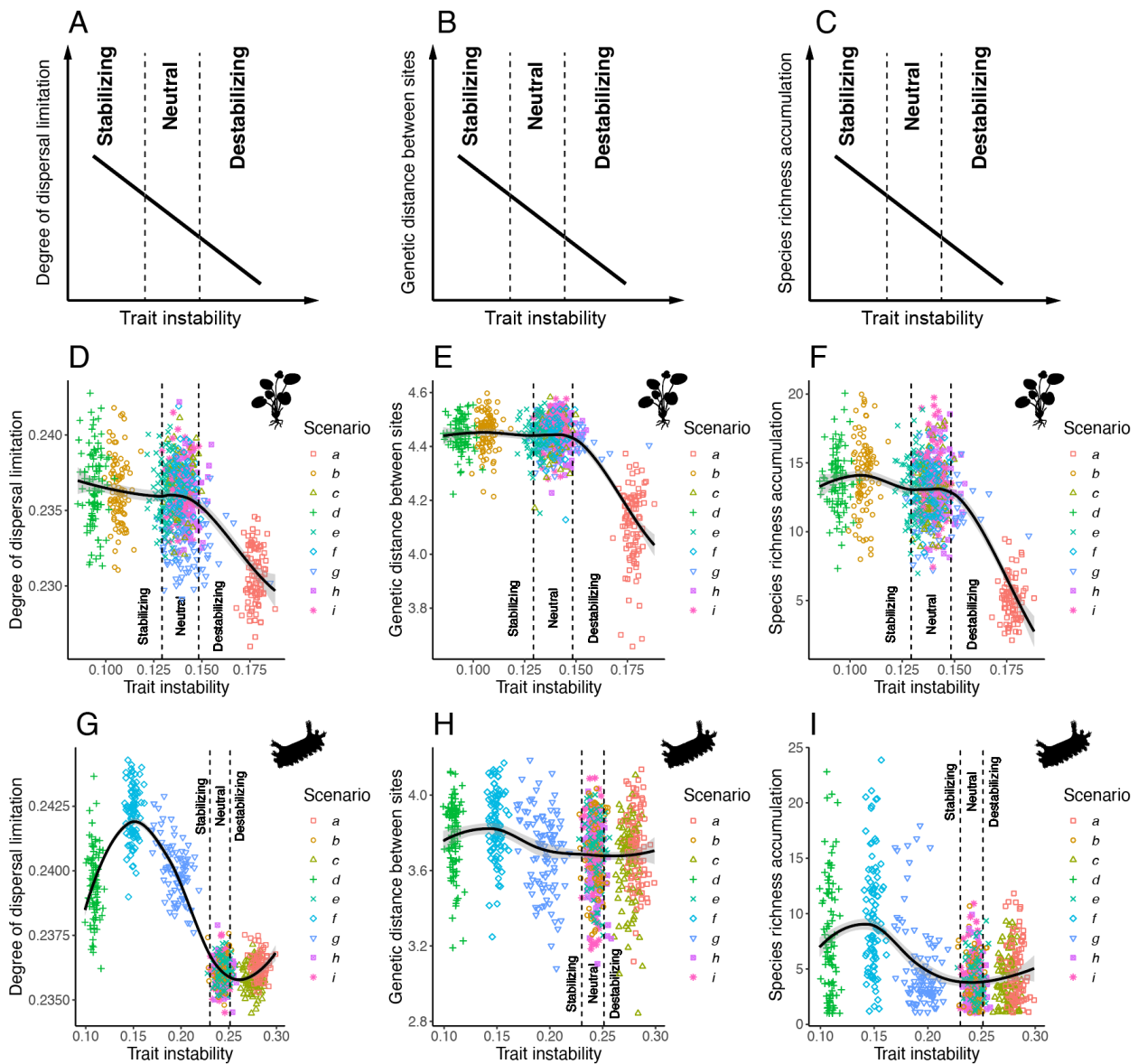
Figure 4. The relationships between selective regime, degree of dispersal limitation, genetic distance between sites, and species richness accumulation. Selective regimes (neutral drift, stabilizing selection, or destabilizing selection) are determined by trait instability measured as the mean step difference $\overline{|\Delta z|}$. (A)-(C): Expected relationships – a significantly negative slope is predicted based on the stabilizing and destabilizing selection hypotheses. (D)-(F): Observed differences between selection regimes in the independent clade. (G)-(I): Observed differences between selection regimes in the dependent clade. In (D)-(I), black lines with gray ribbons show loess regressions with 95% confidence intervals.

DISCUSSION

Here we have shown that coevolution shapes species richness through two different mechanisms depending on whether the clade of interest is independent or dependent. In the independent clade, destabilizing selection enhances dispersal, which results in a reduction in the genetic distance across space, eventually resulting in a reduction in the species richness accumulation (i.e. the destabilizing selection hypothesis). In the dependent clade, stabilizing selection impedes dispersal, which results in an increase in the genetic distance cross space, eventually resulting in an increase in the species richness accumulation (i.e. the stabilizing selection hypothesis). These results arose through two simple rules governing the dynamics of independent-dependent interactions: one independent individual can pair with multiple dependent individuals but not vice versa; a dependent individual dies in the absence of an independent partner but not vice versa. These rules should be applicable to a wide variety of systems including most host-phytophagous-insect interactions, most host-parasite interactions, most host-pathogen interactions, and some obligate interactions between mutualists and their hosts, although exceptions inevitably exist because the biology of species interactions is highly diverse..

Empirical data generally corroborate our results that coevolution-induced stabilizing and destabilizing selection differentially affect the dispersal of independent and dependent individuals, suggesting that our model provides a potential mechanistic explanation for these patterns of dispersal. Previous models have explored the conditions for coevolutionary stable states or strategies to be achieved, yet these model did not consider dispersal or speciation across space (Vasco, Nazarea & Richardson 1987; Gilchrist & Sasaki 2002; Day & Burns 2003). Empirical examples of coevolution-induced destabilizing selection include classical arms race where there is reciprocal escalation of trait values (Dawkins & Krebs 1979; Vermeij 1994; Whittall & Hodges 2007) and coevolutionary cycling where there is persistent alternation between different trait states such between high and low trait values (Prado et al. 2009; Ashby & Gupta 2014; Ashby & Boots 2015). Whether coevolution causes stabilizing or destabilizing selection is usually unknown except in a limited number of empirical systems, but the results of our model tend to match several empirical observations pertaining to ant-plant, ant-bacterium, and plant-fungus mutualisms. First, our model shows that coevolution-induced stabilizing selection impedes the dispersal of dependent individuals only. Although this conclusion is based

414 upon correlation, the direction of causation is inambiguous because the model took a bottom-up

415 approach where dispersal, a between-community process, arose as a result of species interaction

416 and coevlution within communities. This matches large-scale observations that only specialized

417 mutualism (high dependence on mutualistic partners) is associated with a reduced likelihood of

418 successful establishment beyond native ranges (Nathan et al. 2023). Second, our model shows

419 that coevolution-induced destabilizing selection enhances the dispersal of independent

420 individuals only. This matches large-scale observations that only generalized mutualism (low

421 dependence on mutualistic partners) is associated with an increased likelihood of successful

422 establishment beyond native ranges (Nathan et al. 2023). We show that coevolution-induced

423 stabilizing and destabilizing selection can generate these widely observable patterns. This

424 suggests that coevolution-induced stabilizing and destabilizing selection, as well as their

425 macroevolutionary consequences as shown in our model, may be prevalent in nature.

426 It is useful to understand these results in the light of environmental selection and trait multi-

427 dimensionality. Some traits under coevolutionary selection may be simultaneously under

428 environmental selection. Selection imposed by the environment can be either stabilizing or

429 destabilizing – environment-induced stabilizing selection can operate through selection against

430 phenotypes that deviate from a fixed environmental optimum (Kopp & Matuszewski 2014),

431 whereas fluctuating environment can cause potentially destabilizing selection (De Villemereuil

432 2020). Disruptive selection along an environmental gradient has itself been proposed as a

433 mechanism driving speciation (Doebeli & Dieckmann 2003). It would be interesting for future

434 research to explore the interactive effects of coevolutionary selection and environmental

435 selection on co-diversification. In addition, species interactions are sometime better modeled

436 using multi-dimensional traits (Eklöf et al. 2013). The trait difference mechanism can have

437 similar effects on phenotypic evolution to those of the trait matching mechanism when the trait

438 of interest is multidimensional (Yamamichi, Lyberger & Patel 2019). Therefore, destabilizing

439 selection underlain by the trait difference mechanism might be less common in systems with

440 higher trait dimensionalities.

441 These results may provide mechanistic insights into the diversification of some extremely

442 diverse clades that fit the description of a dependent clade. Specifically, explaining the origins of

443 the diversity of phytophagous insects and parasites has long been an active area of research

444   (Ehrlich and Raven 1964; Poulin and Morand 2000; Hardy and Otto 2014; Weinstein and Kuris
445   2016; Kawahara et al. 2023), and our model provided a potential explanation for their staggering
446   diversity: stabilizing selection induced by coevolution selects against immigrants, reducing
447   dispersal success and consequently enhancing genetic differentiation across space that is
448   necessary for speciation under our assumption. This is conceptually similar to the notion that
449   local coadaptation can reduce the chance of mating between populations and this reduction in
450   gene flow can promote reproductive isolation and consequently speciation (Thompson, Segraves
451   & Althoff 2017). However, we furthered this notion by showing that this is likely to be the case
452   only for clades that fit our assumption about dependence such as phytophagous insects, parasites,
453   pathogens, or obligate mutualists that depend on facultative hosts, but is unlikely to be the case
454   for clades that fit our assumption about independence such as various clades of hosts as
455   mutualists or victims of phytophagous insects, parasites, and pathogens. Overall, the mechanisms
456   from this model provide potential mechanisms by which coevolution may have had a profound
457   impact on the diversification of phytophagous insects and parasites, although the prevalence of
458   coevolution in insect herbivory and parasitism has yet to be confirmed by empirical evidence.

459   Our results suggest that the diversity of clades that fit our description of an independent clade
460   (e.g., plants, hosts of parasites and pathogens, or the facultative hosts of obligate mutualists)
461   could also be explained in the light of coevolution. The effect of coevolution on an independent
462   clade's diversity, under our model assumptions, is likely negative for diversification as shown in
463   the destabilizing selection hypothesis. It is interesting in this light that independent clades, e.g.,
464   clades of angiosperms are often more species-poor than their dependent clades, e.g., clades of
465   phytophagous insects (Bernays 2009; Christenhusz & Byng 2016), although many other
466   mechanisms likely contribute to this asymmetry in richness.

467   Comparing our model to previous models provides some additional implications. We show that a
468   classical arms race impedes the accumulation of species richness in the independent clade but
469   has not effect in the dependent clade. Our results focusing on species richness is in contrast with
470   the results of a previous study showing that the classical arms race neither promotes nor inhibits
471   phenotypic diversification (Yoder and Nuismer 2010). We also show that antagonistic trait
472   matching destabilizing selection hypothesis also predicts a decrease in species richness in the
473   independent clade in the scenario of antagonistic trait matching where selective pressure is

474 comparable between the independent and dependent individuals. This also contrasts with the

475 previous model which showed that coevolution promotes phenotypic diversification when trait

476 matching is costly, e.g., as in competition or antagonisms. These contrasts suggest that

477 phenotypic diversification can be decoupled from species diversification during coevolution. The

478 idea that having multiple partners poses a constraint on diversification when the interaction is

479 mutualistic and based on trait matching has been shown in a non-spatially explicit model

480 previously (Raimundo et al. 2014). This agrees with the results of our spatially explicit model

481 and suggests that our results could potentially arise through similar mechanisms. Overall, the

482 new model contributes to an ongoing effort to integrate metacommunity ecology with

483 macroevolution in general (McPeek 2008; Reijenga, Murrell & Pigot 2021) and for independent-

484 dependent systems in particular (Forister & Jenkins 2017).

485 Our model provides an alternative or supportive explanation for some long-standing hypotheses.

486 In the seminal escape-and-radiate hypothesis (Ehrlich & Raven 1964), a lineage, independent or

487 dependent, that acquires a new defense or counter-defense (i.e. key innovations) may then

488 rapidly radiate into a new adaptive zone. We show a different picture here – coevolutionary

489 spatial dynamics can continuously enhance or impede speciation without involving sporadic key

490 innovations. There are also long-standing hypotheses that dependents should be more specialized

491 the more intimate their interactions with their independents are (Ollerton 2006; Thompson 1994).

492 These hypotheses generally predict that dependents should be more species-rich than

493 independents, which is consistent with our results suggesting that coevolution generally impedes

494 diversification for an independent clade and enhances diversification for a dependent clade.

495 However, the intimacy hypotheses are agnostic to the geography of speciation. It is also clear

496 that a single independent can contain a multitude of niches for different dependents (Farrell &

497 Sequeira 2004), so the asymmetry in richness is less surprising regardless of the specific

498 mechanisms of diversification.

499 In conclusion, here we show that there are two general mechanisms of coevolutionary

500 diversification: coevolution-induced stabilizing selection enhances the accumulation of species

501 richness in dependent clades, whereas coevolution-induced destabilizing selection impedes the

502 accumulation of species richness in independent clades. The model provides a new line of

503 thinking in bridging symbiotic biology, coevolution, metacommunity ecology, and

macroevolution. Given that symbiotic relationships between a more dependent party and a less dependent party permeate the natural world (Margulis 1998), these general mechanisms of coevolutionary diversification can potentially explain the diversification of many clades in the Tree of Life.

Authorship statement

Yichao Zeng: Conceptualization, Methodology, Software, Validation, Formal analysis, Investigation, Data cutation, Writing – Original draft, Review & Editing, Visualization. **David H. Hembry**: Writing – Original draft, Review & Editing.

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