

1 **The Puzzle of Leadership: The Interplay between Individual Traits and Coordination Mechanisms**

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11 **Abstract**

12 In social systems, movement of individual group members scales up to spatiotemporal dynamics of the group.
13 However, the level of influence on group movement dynamics can be variable among group members. The influence
14 of an individual is often referred to as their leadership potential. However, despite the common occurrence of leader-
15 follower patterns across various taxa, little is known whether leadership relates to certain traits of the leader or whether
16 it emerges from the behavioural coordination of leader and followers. Furthermore, leadership can also emerge as a
17 by-product of group coordination mechanisms. This review highlights the variability of leadership across individuals,
18 social groups, and populations emphasizing the need for an interdisciplinary research approach. By combining theory,
19 observations, and novel technologies, we can explore the relationships between social responsiveness, movement
20 characteristics, and coordination processes, advancing our understanding of leadership's ecological and evolutionary
21 implications.

22 **Introduction**

23 Social species exist across all major taxa, and, within groups, coordination processes emerge as an outcome of
24 interactions among individual group members. These processes include for instance collective movement, behavioural
25 synchronisation and social information transmission, which have been shown to affect individual fitness (Fryxell and
26 Berdahl, 2018). Importantly, the level of influence that an individual has within a group can vary among its members
27 (Delgado et al., 2018). But we have a limited understanding of the *proximate* mechanisms and *ultimate* consequences
28 of this variable influence. A dichotomous approach, that classifies individuals into leaders or followers has provided
29 some important insights on leader-follower dynamics. An important question is whether leadership is an *intrinsic* trait
30 that is selected for and hence that evolves. Or whether leadership is an *emergent* trait arising from certain group
31 properties and across varying environmental scenarios. Often, we observe that a few individuals (“followers”) follow
32 an animal that moved away from the group or location. This can cascade through the whole group causing everyone
33 to move. If a particular individual consistently initiates group movement and successfully recruits other group
34 members, we call it a “leader” (Krause et al., 2000). A broader definition states that leaders consistently influence,
35 either directly or hierarchically, the behaviour of conspecifics (Strandburg-Peshkin et al., 2018). Leaders often show
36 increased travel speed and directionality as well as a characteristic frontal or peripheral position within the group
37 (Gueron et al., 1996; Couzin et al., 2005; Conradt and List, 2009; Bode et al., 2012; Pettit et al., 2015). Furthermore,
38 empirical studies indicate that leader-follower dynamics are often influenced both by cues of the social and ecological
39 environment (Strandburg-Peshkin et al., 2017; Stutz et al., 2018). However, whether leadership itself or these traits
40 have any fitness benefits and hence are favoured by natural selection remains unclear (Pettit et al., 2015; Strandburg-
41 Peshkin et al., 2018). In this review, we aim to explore the literature on social evolution and leadership and point out

42 knowledge gaps within the field. Addressing those gaps would improve our understanding of the *proximate* and
43 *ultimate* properties of leadership in a social context.

44 Social behaviour evolved independently in several different taxa (Krause and Ruxton, 2002; Ward and Webster, 2016),
45 with parental care representing an early stage of sociality (Clutton-Brock and Scott, 1991). Sociality offers advantages
46 such as increased protection from predation (Clutton-Brock and Scott, 1991; Couzin et al., 2002; Ebensperger et al.,
47 2014), and enhanced foraging success in heterogeneous environments (Hamilton, 1964; Rubenstein, 2011).
48 Furthermore, harsh environmental conditions have been found to favour the evolution of social behaviour, particularly
49 cooperative behaviour, such as in helper systems. Helpers significantly contribute to the reproductive success of the
50 usually related breeding pair which otherwise would be hard to achieve in such conditions (Rubenstein, 2011;
51 Ebensperger et al., 2014). Nonetheless, other selection pressures aside from kinship have been identified to drive the
52 evolution of sociality (Hamilton, 1964).

53 An important challenge of group living is to maintain group cohesion. To maintain it, animals combine environmental
54 stimuli and monitor the movement of other group members (Kappeler, 2019). Several behavioural rules have been
55 identified to facilitate group cohesion and within-group synchronisation (Couzin et al., 2002; Couzin and Krause,
56 2003; Sumpter et al., 2008; Klamser et al., 2021). In some cases, the behavioural rules can be very simple and only
57 involve very minimal sensory and cognitive processes (Camazine et al., 2001; Sumpter, 2010). Overall, these rules
58 relate to the attraction, alignment and/or repulsion with one another (Sumpter, 2010), but even the variability in
59 individual speed itself can have an impact on the synchronisation dynamics (Klamser et al., 2021). Furthermore, these
60 rules can be modulated based on individuals' internal state, such as satiation level (Hansen et al., 2015b), perceived
61 risk of predation (Krause and Godin, 1995), and phenotypic assortment (Couzin et al., 2002). Animals also reach
62 consensus through simple quorum rules which strongly correlate with group size (Sumpter et al., 2008). However,
63 how these behavioural rules are modulated by different environmental contexts remains an open question. Valuable
64 insights can be gained by examining social systems that depend on regular and frequent interactions among individuals
65 in diverse environmental settings, where individuals frequently encounter each other (Freeberg et al., 2012). For
66 instance, investigating social groups with fission-fusion societies, characterized by frequent changes in group size and
67 spatiotemporal cohesion, can greatly contribute to achieving this research objective (Sueur et al., 2011; Silk et al.,
68 2014).

69 **Collective decision making**

70 Group living species benefit from using social information and social learning (Conradt and Roper, 2003;
71 Dunbar and Shultz, 2007; Ward and Webster, 2016). Social information is acquired through observing or
72 communicating with informed or experienced conspecifics (Lesmerises et al., 2018). It can be acquired more quickly
73 than personal information which is acquired through exploring and interacting with the environment (Sigaud et al.,
74 2017). However, social information can be unreliable if it does not represent the actual environmental conditions.
75 Therefore, using social information can either be cheaper or more costly than personal information depending on the
76 level of reliability (Guttal and Couzin, 2010). In situations where the acquisition of personal information and socially
77 transferred information cannot occur simultaneously, relying solely on socially acquired information can occasionally
78 result in sub-optimal behaviours (Giraldeau et al., 2002; Couzin, 2009; Donaldson et al., 2012). For example, birds
79 may choose a night roost site based on an informational cascade, disregarding the survival benefits of communal
80 roosting. Similarly, individuals may ignore their personal preferences in mate choice due to maladaptive copying
81 behaviour, or they may mistakenly employ socially transmitted information in the context of false rapid escape
82 behaviours (Giraldeau et al., 2002). In addition, the efficient transfer of social information among individuals of the
83 same species typically relies on the stability and cohesiveness of a group (Krause and Ruxton, 2002). Consequently,
84 group members should coordinate their movements in both space and time to increase the likelihood of interactions
85 within the group, thereby enhancing social transmission.

86 Such behavioural coordination is particularly crucial in the context of fission-fusion societies (Aureli et al., 2008),
87 which are characterized by frequent changes in group size and composition, with individuals frequently joining and
88 leaving the group. This dynamic nature often leads to an assumption that fission-fusion societies are less stable and
89 less cohesive compared to other types of social systems. However, it is precisely because of this dynamic nature that

90 the coordination of movement and timing becomes essential between the fissioned individuals to maintain the social
91 relationships within the group (Lerch et al., 2021). As the group members continually join and leave the group, the
92 ability to effectively transmit social information is paramount (Sueur et al., 2011). Mechanisms driving behavioural
93 coordination increase the likelihood of intragroup interactions, allowing for the exchange and transmission of valuable
94 social information between subgroups (Fryxell and Berdahl, 2018). Therefore, in fission-fusion societies,
95 spatiotemporal movement coordination between all group members becomes critical for enhancing social
96 transmission.

97 Nevertheless, in dynamic and unpredictable natural environments, the transmission of socially acquired maladaptive
98 information can result in fitness loss for group members, particularly if the initial assessment of environmental quality
99 was flawed (Sigaud et al., 2017) or if it hinders the learning of optimal behavioural patterns when acquired from
100 misinformed individuals (Laland and Williams, 1998). This phenomenon, known as "ecological traps," occurs when
101 animals select habitats that appear to be of high quality based on cues but are actually of poor quality (Schlaepfer et
102 al., 2002). For instance, a population of plains bison (*Bison bison bison*) ventured out from a protected area to forage
103 on agricultural land that had higher-quality resources compared to natural meadows. However, this resulted in
104 increased mortality (due to hunting) and no discernible increase in reproduction (Sigaud et al., 2017). Interestingly,
105 researchers found that naïve bison were more likely to forage on the cultivated land when accompanied by at least one
106 informed individual, potentially acting as a leader, thus indicating the maladaptive transmission of information (Sigaud
107 et al., 2017). A similar sub-optimal interaction between social learning and the use of anthropogenic food sources was
108 observed in a study on bottlenose dolphins (*Tursiops aduncus*). Pods led by misinformed individuals that fed on
109 bycatch experienced a higher risk of mortality due to collisions with boats (Donaldson et al., 2012).

110 **Group cohesion and behavioural synchronisation**

111 The mechanisms that govern behavioural synchronization among group members, promoting their proximity
112 and maintaining sensory communication range, are crucial for the evolution and persistence of group living
113 (Michelena et al., 2005; Gautrais et al., 2007; Michelena et al., 2008; King and Cowlshaw, 2009; O'Bryan et al.,
114 2019). Animals within a group tend to coordinate their movements in both space and time, ensuring the cohesion of
115 the group for varying durations (Michelena et al., 2008; Nathan et al., 2008; Ginelli et al., 2015; Westley et al., 2018).
116 Group cohesion can be achieved through allelomimetic interactions (Camazine et al., 2001; Gautrais et al., 2007),
117 wherein individuals are more likely to adopt the behaviour of their neighbouring group members. Furthermore,
118 context-specific group cohesion may be attained through a balancing effect, considering the trade-off between
119 increasing the distance to reduce scramble competition while remaining in proximity to enhance anti-predator benefits
120 (Ginelli et al., 2015).

121 Synchronization among group members can be achieved through simple interaction rules, including attraction, short-
122 range repulsion, alignment, and behavioural amplification among neighbouring individuals (Couzin, 2009; Sumpter,
123 2010; Delgado et al., 2018). These interaction rules can be further influenced by past experiences, the local
124 environment, and social cues (King and Cowlshaw, 2009; Michelena et al., 2009). To enhance the effectiveness of
125 behavioural synchronization, individuals are likely to select specific interaction partners based on their identity and
126 shared history and adjust their actions accordingly (Gascuel et al., 2021). In this way, moving group members respond
127 to local changes in the movement and position of their neighbours, leading to "interaction neighbourhoods" resulting
128 in coordinated movement among conspecifics in close proximity (Rosenthal et al., 2015; Herbert-Read, 2016; Jiang
129 et al., 2017; Gascuel et al., 2021). Therefore, group cohesion relies on the spatiotemporal synchrony of activities
130 among group members, rather than being dependent on a particular type of behaviour (Gautrais et al., 2007; King and
131 Cowlshaw, 2009).

132 When the costs associated with maintaining cohesion outweigh the benefits, behavioural asynchrony among group
133 members can increase. In fission-fusion societies, this may lead to a fission event, reducing the costs of cohesion
134 (Gautrais et al., 2007; Aureli et al., 2008; Sueur et al., 2011; Silk et al., 2014; Senior et al., 2016). In more stable
135 societies, this process helps regulate optimal group size (Markham et al., 2015).

136 **Within-group heterogeneity**

137 Sociality, although ubiquitous, is not a uniform trait. Instead, taxon-specific life history traits (Arnold and
138 Owens, 1998; Griesser and Suzuki, 2016; Griesser et al., 2017; Shell and Rehan, 2018; Beery, 2019; Kappeler, 2019)
139 in interaction with ecological conditions influence the evolution and maintenance of sociality leading to a spectrum
140 of sociability. The evolutionary mechanisms shaping sociality lead to species-specific differences in the fundamental
141 aspects of group living, including variations in social unit size, composition, and spatiotemporal stability. On one end
142 of the spectrum, sociality may confer advantages to species in harsh environmental conditions, favouring the formation
143 of stable social groups. On the other end, species with weaker social systems may benefit from social behaviours to
144 counter demographic challenges but form temporary and less stable associations. It is important to note that this
145 example is not meant to imply a fixed order within the spectrum, as the dynamics can vary. It is worth considering
146 that the reverse could also be true. It is conceivable that fission-fusion societies, which exhibit flexibility in adjusting
147 group size and other aspects of sociability, may be better adapted to harsh and unpredictable conditions (Silk et al.,
148 2014). This flexibility might allow them to maximize the benefits of sociality in a given context, highlighting the
149 importance of considering different strategies along the sociability spectrum in relation to environmental conditions
150 and specific circumstances.

151 Group size is variable and suggested as a key factor that determines many facets of social living, ranging from
152 maintaining group cohesion (Michelena et al., 2008) to influencing group demography (Grueter et al., 2012). Variation
153 in group size may also alter social preferences among group members (Michelena et al., 2009), their travelling speed
154 (Jang et al., 2019; Klamser et al., 2021) and spatiotemporal patterns (Boissy and Dumont, 2002; Michelena et al.,
155 2010). Moreover, group size may be of principal importance for the transfer of social information and the evolution
156 of collective decision-making (Conradt and Roper, 2003; 2009). If all group members have the same access to noisy
157 environmental information but respond to it in slightly different ways, the average behavioural response is more
158 accurate (Couzin, 2009). Thus, with increasing group size selection should lead to better decisions, known as the
159 many-wrongs hypothesis (Simons, 2004; Sumpter, 2006).

160 However, not all group members have access to the same information, for example, due to its spatiotemporal
161 occurrence or individuals' varying internal states (King and Cowlishaw, 2007). Such within-group heterogeneities can
162 alter group decision-making leading to the evolution of mechanisms that resolve within-group conflict such as quorum
163 responses (Conradt and List, 2009; Papageorgiou and Farine, 2020) or voting (Ramos et al., 2015). Once a critical
164 number of group members show a certain behavioural response, for instance, leave a foraging patch, then all group
165 members join and show the same behaviour (Sumpter and Pratt, 2009; Ward et al., 2012; Marshall et al., 2019).

166 Nonetheless, if individuals differ consistently in the expression of movement patterns, e.g., due to varying aspects of
167 foraging behaviour (activity, risk-taking, physiological drivers, specific social roles in foraging groups), or preferences
168 for social and/or habitat features, we would expect assortativity among conspecifics based on those traits or
169 preferences (Toscano et al., 2016). Moreover, it is hypothesised that intraspecific variation in personality, movement
170 and space-use preferences can impact population dynamics and promote coexistence by influencing intra- and inter-
171 specific interactions (Milles et al., 2020). For instance, repeatability in among-individual variation in movement speed
172 across a foraging gradient indicates how the distribution of fast- and slow-moving caribous, in different habitats, may
173 alter group dynamics (Webber et al., 2020). Crucially, a recent meta-analysis of 200 home range estimates, movement
174 metrics and habitat uses across all main animal taxa, indicated generalizability and high repeatability of among-
175 individual variation in movement behaviour (Stuber et al., 2022).

176 Among-individual heterogeneity in movement can also influence other aspects of spatiotemporal group dynamics by
177 affecting individually-expressed boldness resulting in variation in spatial distribution (Michelena et al., 2008;
178 Michelena et al., 2010; Briard et al., 2021), exploratory behaviour (Michelangeli et al., 2020), foraging (Patrick et al.,
179 2017), learning (Pettit et al., 2015), anti-predator response (Brodin et al., 2019), social structure (Bonnell et al., 2017),
180 social affinity (Briard et al., 2015) and social ranking (Sasaki et al., 2018).

181 **Leader-follower relationship**

182 In social systems characterized by quorum decision-making, all individuals have equal influence on the group.
183 However, leadership can still emerge in many other social systems, even though it may not be a prerequisite for group

184 coordination processes (Couzin et al., 2005). In these systems, certain individuals consistently exhibit marked
185 differences in their influence on the group (Krause et al., 2000; Conradt and Roper, 2005; Couzin et al., 2005; Conradt
186 and List, 2009; Pillot et al., 2010; King and Sueur, 2011; Nakayama et al., 2013; Briard et al., 2015; Sasaki et al.,
187 2018). For example, individuals with disproportionate influence, known as leaders, can recruit and influence other
188 group members to follow their lead (King, 2010). Leadership offers several benefits, such as reducing free-riding
189 behaviour and coordination errors within a group (Frank, 2003; Hooper et al., 2010). Additionally, leaders facilitate
190 the initiation of group activities.

191 Leader-follower dynamics can be more complex when individuals vary in the propensity and plasticity to lead or
192 follow conspecifics (Harcourt et al., 2009), with followers being less likely to co-opt leadership roles (Nakayama et
193 al., 2013). For example, in guineafowl (*Acryllium vulturinum*), when dominant leaders monopolize resources, some
194 subordinate individuals choose to move away. Once the number of subordinates that move away reaches a critical
195 threshold, it triggers group movement, compelling the dominant leader to abandon the monopolized food patch and
196 catch up with the departing group (Papageorgiou and Farine, 2020). This behavioural flexibility aligns with the
197 conditional strategies hypothesis (Tomkins and Hazel, 2007). Depending on specific environmental and/or social cues,
198 it can be more advantageous to act as a leader in certain situations, while in others, it may be more beneficial to be a
199 follower. This example highlights the complex interplay between resource acquisition, group dynamics, and individual
200 decisions, which may involve a nuanced understanding of the leader-follower relationship and its fluidity.

201 **Contrasts between leaders and followers**

202 Social attraction and responsiveness vary among conspecifics (Ward et al., 2004; Kurvers et al., 2009;
203 Michelena et al., 2010; Briard et al., 2015; Jolles et al., 2015; Sih et al., 2018; Sumpter et al., 2018). Socially responsive
204 individuals prioritise social interactions and proximity to others and are often followers. Whereas leaders are
205 characterised by decreased social responsiveness, preferentially choosing environmental cues and their preferences
206 over maintaining cohesiveness of the social group (Lamprecht, 1996; Wolf et al., 2008; Johnstone and Manica, 2011;
207 Pettit et al., 2015). A mix of followers and leaders within a single population is hypothesised to be maintained through
208 negative frequency-dependent selection, as the benefits of social responsiveness might be high for some individuals,
209 but not for all of them at the same time (Wolf et al., 2008; Wolf and McNamara, 2013). In particular, when group size
210 and/or population density increase, individuals are more likely to encounter conspecifics, which negatively affects
211 individuals with lower sociability, such as leaders. Importantly, theoretical models indicate that even in large groups,
212 only a small proportion of leaders is needed to achieve high accuracy of coordination (Couzin et al., 2005). Hence,
213 the frequency-dependent coexistence of leader-follower strategies remains evolutionarily stable even in large groups
214 (Guttal and Couzin, 2010). Perhaps, a socially responsive cohort that pays attention to socially transmitted cues within
215 a heterogenous group can act as a social glue preserving cohesiveness, while a socially unresponsive cohort determines
216 group movement and influences decision-making (Harcourt et al., 2009; Pettit et al., 2015).

217 The value of leadership in social systems is not solely determined by the resources a leader possesses or can obtain,
218 but rather by the likelihood of making resources available to others (Lamprecht, 1996). When an individual seeks a
219 resource and subsequently increases its critical distance from conspecifics, it can become a leader if others choose to
220 follow (Lamprecht, 1996). However, natural selection acts on the individual, thus there must be a net benefit for
221 leaders themselves. Yet, this perspective holds if leadership is an *inherent* individual trait, as natural selection would
222 then favour specific leadership traits. In contrast, if leadership *emerges* solely as an outcome of coordination processes
223 among group members, it becomes less clear how net fitness gains are distinctly different between individuals. The
224 emergence of leadership through coordination processes blurs the line between individual fitness benefits and the
225 overall benefits of group coordination. In this view, the value of leadership is intertwined with the benefits gained by
226 followers, indicating that leadership is not solely driven by individual fitness gains, but rather by the cumulative
227 advantages of collective behaviours. For instance, in a scenario where knowledgeable individuals lead naïve
228 individuals to known food patches (Merkle et al., 2015), leadership is beneficial for the leaders as they access first and
229 forage more than followers, while simultaneously benefit from the dilution effect (Hamilton, 1971). At the same time,
230 following is beneficial for naïve individuals, as they discover food patches faster than if they had to forage on their
231 own. However, it is important to note that leadership can also be driven by other factors, such as variation in
232 exploratory propensities among individuals (Wolf and McNamara, 2013). In this view, leaders being characterized by

233 lower sociability and a higher propensity to forage farther away from conspecifics, increase their chances of
234 discovering new food patches, regardless of their initial knowledge state. Followers, on the other hand, by being more
235 socially responsive, move towards departing individuals to maintain group cohesion and consequently benefit from
236 the newly discovered food patches. This highlights the complexity of leader-follower dynamics and suggests that
237 leadership can have multiple underlying mechanisms and benefits for both leaders and followers. For example, Rands
238 and colleagues (2003) introduced a state-dependent game-theoretical model that demonstrated the emergence of
239 leaders in foraging dyads when individuals have different energetic requirements, allowing them to coordinate their
240 foraging activities (Rands et al., 2003; Rands et al., 2006; Rands et al., 2008). Empirically, this effect has been
241 observed in food-deprived fish occupying front positions in shoals more frequently and influencing the movement
242 preferences of others (Krause, 1993; Hansen et al., 2015b). Additionally, lactating zebras, due to their elevated
243 nutritional needs, initiate group movement more frequently, showcasing the dynamic relationship between individual
244 needs and the emergence of leadership within the group (Fischhoff et al., 2007).

245 Behavioural coordination, such as the dilution effect (Hamilton, 1971) and shared vigilance (Krause and Ruxton,
246 2002), benefits all members of a group, including leaders and followers. However, the magnitude of these benefits
247 can be modulated by the spatial position of individuals within the group. For example, the dilution effect, which
248 reduces individual predation risk through group size, provides greater benefits to individuals positioned more centrally
249 within the group, while those occupying frontal and peripheral positions face increased mortality risk (Bumann et al.,
250 1997). It is noteworthy that leaders often occupy these frontal and peripheral positions, potentially diminishing their
251 net benefit from the dilution effect compared to other group members positioned more inward. This spatial distribution
252 of risk highlights an intriguing aspect of leadership dynamics. Leaders, driven by their own goals, may deliberately
253 sway the group towards their selfish objectives using various strategies such as vocalizations, explicit motions, or
254 coercion (Garland et al., 2018). In doing so, leaders can exploit the benefits of behavioural coordination, such as the
255 dilution effect and shared vigilance, to their advantage. By encouraging followers to adopt their actions, leaders
256 increase the likelihood of achieving their goals while potentially gaining personal advantages. This scenario
257 underscores how leaders may benefit when others in the group, particularly followers, adopt or co-opt their behaviours.

258 Leadership dynamics encompass a range of complexities, involving both costs and benefits for individuals taking on
259 leadership roles depending on ecological and social conditions. While leadership may impose unequal costs on
260 individuals assuming the leadership role (Gillet et al., 2011), theoretical models suggest that the maintenance of
261 followership can be driven by voluntary propensity to follow, rather than coercive dominance and exploitation, if
262 leadership enhances group productivity (Hooper et al., 2010; Powers and Lehmann, 2014). It is crucial to consider
263 both within-group and between-group effects to fully grasp the net benefits of leader-follower dynamics. Within-group
264 analysis might suggest that followers receive greater benefits compared to leaders (Koykka and Wild, 2015). However,
265 when we incorporate between-group effects, a more nuanced perspective emerges. Leaders can benefit from the
266 presence of followers during inter-group conflicts and competition with leaders from other groups (Gavrilets and
267 Fortunato, 2014). Indeed, empirical observations from a range of species engaged in between-group conflicts align
268 with this prediction demonstrating unequal energetic expenditures of high-rank individuals. This was observed in
269 chimpanzees during territorial border patrols (Amsler, 2010), and in blue monkeys when defending communal feeding
270 territories (Cords, 2007). These findings highlight the role of individuals likely occupying leadership roles in resource
271 defence. Furthermore, studies on grey wolf packs demonstrate how older and more aggressive males assess opponents
272 from competing groups and adjust their behaviour based on relative pack size. The more a grey wolf pack outnumbers
273 their opponent, the more likely an individual will participate in an aggressive in-between group interaction (Cassidy
274 et al., 2017). As such, the net benefits of leader-follower interactions may extend beyond the immediate group
275 dynamics and encompass the broader context of group competition and self-interest. Therefore, understanding leader-
276 follower dynamics requires a comprehensive examination of both within-group and between-group effects. By
277 considering the impact on group productivity, and the potential costs and benefits for leaders and followers, we can
278 develop a clearer and more comprehensive understanding of the complexities and nuances underlying leadership
279 dynamics.

280 However, gregarious species are often engaged in a producer-scrounger game, where individuals employ different
281 foraging strategies. The scrounging tactic tends to spread within these populations (Dumke et al., 2016). Drawing
282 parallels to leader-follower dynamics, leaders can be likened to producers, while followers can be likened to

283 scroungers. The decision to lead or follow is influenced by the perceived payoffs associated with each strategy, and
284 individuals rely on social learning rules to make these decisions. In this context, individuals that forage effectively
285 alone without relying on social information act as producers/leaders and likely benefit other group members (Morand-
286 Ferron and Giraldeau, 2010). While theoretical insights shed light on these dynamics, the generalizability of these
287 findings is limited due to a current lack of empirical data. Therefore, further research is needed to better understand
288 the similarities between producer-scrounger and leader-follower patterns.

289 **Leadership in socially stratified systems**

290 In gregarious species, we often observe a social stratification and the development of hierarchies which
291 reduces instances of free-riding and aggression within the group (Issa and Edwards, 2006). The most dominant
292 individuals are characterised by the tendency to monopolise resources and occupy the best and safest relative positions
293 within the group (Ward and Webster, 2016). Even though leadership can be correlated with high dominance status
294 (Squires and Daws, 1975; Robbins, 1995; Peterson et al., 2002; King et al., 2008; Sueur and Petit, 2010; Krueger et
295 al., 2014; Tokuyama and Furuichi, 2017; Ramos et al., 2018; Papageorgiou and Farine, 2020), the effect of social
296 hierarchy is hard to evaluate because it is intertwined with other factors, such as age (Tokuyama and Furuichi, 2017;
297 Ramos et al., 2018), sex (Squires and Daws, 1975), degree of kinship (Sueur and Petit, 2010) or reproductive status
298 (Robbins, 1995; Peterson et al., 2002; King et al., 2008; Krueger et al., 2014). Moreover, in some systems with
299 dominance-driven leadership, the most dominant individual was not the sole leader, but instead, leadership was
300 distributed among several high-ranking group members (Peterson et al., 2002; King et al., 2008; Papageorgiou and
301 Farine, 2020). Dominance also plays an important role in within- and between-group interactions and conflict
302 mediation (Smith et al., 2016). However, dominant individuals may simply induce followership by acting more
303 independently and being less socially responsive (King et al., 2009) or individuals that are strongly connected and
304 occupy important positions within their social network may have a disproportionate influence on their group (King,
305 2010; Briard et al., 2015; Tokuyama and Furuichi, 2017; Strandburg-Peshkin et al., 2018).

306 Most animal social networks are non-random and individuals are connected with a different number of conspecifics
307 or their ties are of different strength. Hence, we may expect that individuals also differ in their importance within the
308 social network (Wey et al., 2008). An advantage of studying leadership from a social network perspective is its direct
309 insight into inter- and intra-individual variability in social responsiveness underlying leader-follower dynamics. Some
310 advances have been made in this area, with theoretical research indicating the importance of centralised leadership
311 positions within the social network (Krause et al., 2007; Bode et al., 2011; Bode et al., 2012; Clemson and Evans,
312 2012; Sueur et al., 2012; Strandburg-Peshkin et al., 2018). However, empirical studies are lacking which would greatly
313 improve our limited understanding of the role of leaders in the network (Briard et al., 2015; Lerch et al., 2021).

314 **The puzzle of leadership**

315 Researchers are successively broadening the list of individual characteristics associated with leadership, such
316 as more directional and faster movement (Gueron et al., 1996; Couzin et al., 2005; Conradt and List, 2009; Sasaki et
317 al., 2018), elevated nutritional requirements (Fischhoff et al., 2007; Hansen et al., 2015b; a), age (Tokuyama and
318 Furuichi, 2017; Allen et al., 2020), learning abilities (Pettit et al., 2015), personal knowledge (Pillot et al., 2010;
319 Mueller et al., 2013; Berdahl et al., 2018; Allen et al., 2020), social responsiveness (Briard et al., 2015) and a high
320 degree of kinship with followers (Sueur and Petit, 2010; Ramos et al., 2018). Despite this suite of identified
321 characteristics, a question that remains open is whether these traits led to the evolution of leadership or vice versa.
322 One argument proposes that leaders may have evolved dominance as a means to secure an unequal proportion of
323 resources (Koykka and Wild, 2015). In this view, dominance and the associated traits may have emerged as a strategy
324 for leaders to gain an advantage in resource acquisition. However, it is important to note that the relationship between
325 these traits and leadership is complex and multifaceted. It is possible that a combination of factors, including genetic
326 predispositions, environmental conditions, and social dynamics, have shaped the evolution of leadership and its
327 associated traits. Further research is needed to unravel the causal relationships and understand the evolutionary origins
328 of leadership in different species.

329 A noteworthy challenge when studying leader-follower relationships is the need to simultaneously monitor many
330 potential decision-makers in a group, as leadership might be distributed among several individuals, rather than being
331 monopolised by a single individual (Bourjade and Sueur, 2010; Taylor et al., 2011; Bourjade et al., 2015; Ramos et
332 al., 2015; Ramos et al., 2018; Sasaki et al., 2018). Hence, to examine whether and how group members influence each
333 other, particularly in initiating movement, it is paramount to monitor whether the speed or direction of a focal
334 individual is adopted by its neighbours across the entire group (Ramseyer et al., 2009; Nagy et al., 2010; Herbert-
335 Read, 2016).

336 A significant challenge awaiting to be addressed is whether leadership is *inherent* or *emergent* (Garland et al., 2018;
337 Strandburg-Peshkin et al., 2018). In other words, whether it is linked with certain semi-persistent individual traits such
338 as size, sex, personality, or social status? Or whether leadership emerges as a consequence of group coordination
339 combined with variation in travel velocity and spatial position within the group? This topic is even more complex, as
340 these two scenarios are not necessarily mutually exclusive. It seems plausible that movement initiation and successful
341 recruitment might be driven by the interaction of leader characteristics (Ramseyer et al., 2009) and allelomimetic
342 processes (Taylor et al., 2011), thus carefully designed experiments are needed to disentangle these phenomena.
343 Additionally, exploration of how individual traits interact with group coordination processes can provide insights into
344 the evolutionary origins and the relative importance of intrinsic traits and social dynamics in shaping leadership.

345 Another question is the consistency of leadership. Does the same individual or group of individuals repeatedly assume
346 leadership roles, or does leadership change between movement events? Examining the repeatability and/or context-
347 dependence of leadership can deepen our understanding of social dynamics and help to identify patterns of stability
348 and variability of leader-follower relationship. The consistency of leadership may also depend on socio-ecological
349 factors and potentially have a heritable component. Exploring the influence of these factors on leadership can provide
350 insights into its adaptive value and contribute to our understanding of the evolutionary processes shaping social
351 systems.

352 Furthermore, investigating how leadership differs between species, populations, and different social groups within the
353 context of social responsiveness across the sociability spectrum can provide valuable insights. Understanding leader-
354 follower relationships in groups with varying levels of social complexity can shed light on the implications of the
355 sociability spectrum for movement coordination, decision-making, and social organization.

356 Lastly, we should explore how we can leverage leadership dynamics to improve agricultural and/or nature
357 conservation practices and enhance animal welfare. Understanding how to utilise leader-follower relationships can
358 optimize agricultural practices, inform conservation strategies, contribute to animal welfare and bridge the gap
359 between scientific research and practical applications, benefiting both human and animal well-being.

360 **Concluding Remarks**

361 In conclusion, leadership plays a crucial role in the functioning of complex animal social systems. However, it
362 is important to acknowledge that the nature of leadership can vary significantly depending on the specific context in
363 which it occurs. For instance, the characteristics and mechanisms associated with leadership may differ between
364 species, populations, and even within different social groups of the same species. To further advance our understanding
365 of leader-follower dynamics, we propose a more interdisciplinary approach. For example, social network analysis, as
366 discussed by Makagon et al. (2012), can contribute valuable tools for investigating social interactions in applied
367 ethology. Moreover, the assimilation of novel technologies offers exciting opportunities to study spatiotemporal
368 dynamics simultaneously among all group members. High fidelity and resolution biologgers, as well as unmanned
369 aerial vehicles (drones), as highlighted by Hughey et al. (2018), enable us to capture at the same time detailed
370 information about all individual movements, group coordination, and collective behaviours in the wild. By leveraging
371 these advanced technologies, we can gain a more comprehensive understanding of how leader-follower dynamics
372 manifest across species in different socio-ecological contexts. To address key questions concerning the fitness costs
373 and benefits of leadership and its generality across social systems and species, it is essential to integrate theory,
374 behavioural observations, and well-designed experiments. By combining these approaches, we can explore the causal
375 relationships between inter- and intra-individual heterogeneity in social responsiveness, movement characteristics,

376 and coordination processes. This integrative approach holds great promise for advancing our knowledge of leadership
377 dynamics and its ecological and evolutionary implications.

378 **Author Contributions**

379 KF Hlebowicz: conceptualisation, investigation, writing - original draft, writing - review & editing; J Buhl,
380 and ST Leu: conceptualisation, writing - review & editing, supervision. All authors contributed to the article and
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386 **Conflict of Interest**

387 The authors declare that the research was conducted in the absence of any commercial or financial
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