

1 **Advances in biologging can identify nuanced energetic costs and gains in predators**

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21 **Abstract**

22 Foraging is a key driver of animal movement patterns, with specific challenges for predators
23 which must search for mobile prey. These patterns are increasingly impacted by global
24 changes, principally in land use and climate. Understanding the degree of flexibility in predator
25 foraging and social strategies is pertinent to wildlife conservation under global change,
26 including potential top-down effects on wider ecosystems. Here we propose key future research
27 directions to better understand foraging strategies and social flexibility in predators. In
28 particular, rapid continued advances in biologging technology are helping to record and
29 understand dynamic behavioural and movement responses of animals to environmental
30 changes, and their energetic consequences. Data collection can be optimised by calibrating
31 behavioural interpretation methods in captive settings and strategic tagging decisions within
32 and between social groups. Importantly, many species' social systems are increasingly being
33 found to be more flexible than originally described in the literature, which may be more readily
34 detectable through biologging approaches than behavioural observation. Integrating the effects
35 of the physical landscape and biotic interactions will be key to explaining and predicting animal
36 movements and energetic balance in a changing world.

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38 **Keywords:** predation, energetics, foraging, movement ecology, biologging, GPS,
39 accelerometer, social system

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44 INTRODUCTION

45 **Box 1. Key outstanding questions in predation energetics**

46 Predation is an ecologically critical behaviour, dictating predator energy budgets with
47 cascading effects for prey. Predation can be difficult to observe and study in the wild however,
48 and there remain knowledge gaps which are further complicated by variation between
49 individuals and social systems. Some key outstanding questions may be filled using
50 developments in animal-attached technology.

- 51 • How do environmental factors and within- and between-species interactions affect how
52 prey are located, selected and captured, in both stable and changing habitats?
- 53 • How can we refine detection and quantification of complex, variable predation
54 behaviours, such as those involved in handling prey and feeding?
- 55 • Are key predation dynamics incompletely captured by commonly used data collection
56 strategies? For example, are intra-group interactions and hunting roles missed when
57 few animals within a social group are tagged?
- 58 • How do hunting dynamics change if predators and their prey are unequally affected by
59 climate change and habitat modification?

60

61 Animals adapt their behaviour to optimise gains and minimise losses in an environment, with
62 energetic, ecological and evolutionary consequences [1]. Foraging is a sequence of continuous
63 behavioural decisions made to maximise energetic gains while minimising costs in the search
64 for food and its handling [2, 3]. Animals are faced with multiple foraging decisions, for
65 example whether to target one prey species over another [4] or whether to forage cooperatively
66 with conspecifics [5]. The costs associated with foraging are especially pertinent in predatory
67 animals which must invest energy in the pursuit and handling of prey, often with risk of injury

68 to themselves [6]. Foraging costs for predators are determined by the potential profitability of
69 each prey item, encounter rate and handling time [7]. Whether the predator is social or solitary
70 and the number of individuals in a cooperatively foraging group also affect individual prey
71 selection and energy gain [8].

72 Foraging strategies are shaped by external factors, such as resource availability and
73 environmental conditions [9, 10], leading to considerable variation in foraging strategies within
74 and between individuals, social groups, populations, species and taxa [11–15]. Flexibility in
75 foraging strategy can occur in each of these levels. Individuals may display multiple foraging
76 strategies (i.e., switching between multiple food types which require different handling) in
77 complex or variable environments [16], including dynamic switches regarding the tolerance of
78 satellites by territory owners [17]. Distinct strategies may be associated with particular
79 populations or habitats across temporal scales [18]. For example, bluegill sunfish (*Lepomis*
80 *macrochirus*) modify their foraging search speed between open-water and vegetated habitats
81 [19], and foraging trip duration and rate of chick provisioning can vary between colonies of
82 wedge-tailed shearwaters (*Puffinus pacificus*) [20]. This variation across contexts, the
83 difficulties associated with observing predation events, and the stochasticity inherent in food
84 encounter rates (the role of ‘luck’ in finding food [21]), leave many open questions in our
85 understanding of predator energetics (Box 1).

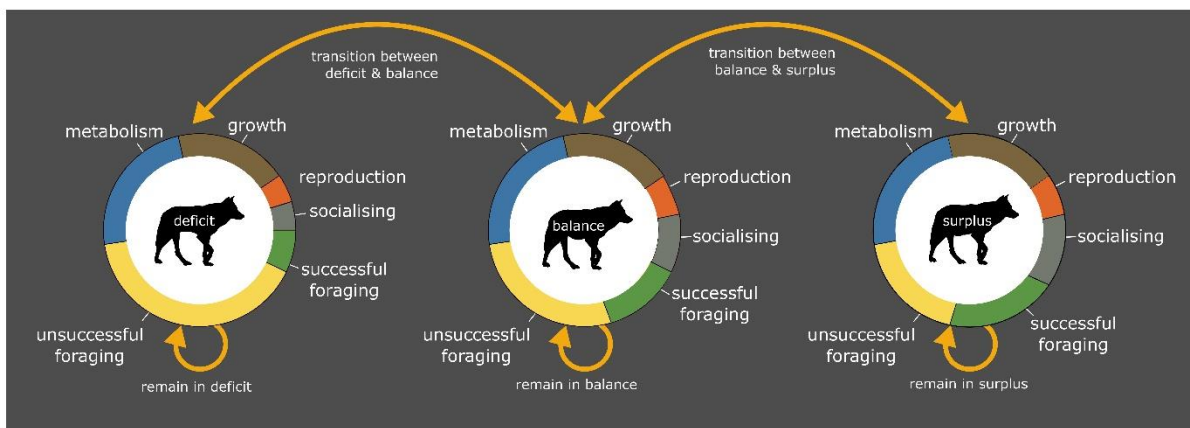
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87 *Predation is costly*

88 Predation typically incurs high energetic costs, either through pursuing and subduing prey, for
89 example in large mammalian predators such as African wild dogs (*Lycaon pictus*) and lions
90 (*Panthera leo*) [22, 23], or through shorter ambushes which require sudden bursts of energy,
91 seen in diverse taxa including mantis shrimp [24] and snakes [25]. Hunting success is a central

92 consideration in predation energetics. Predators must intake enough energy to account for the
93 hunt which has just taken place, but also unsuccessful hunts since the last meal, competition
94 e.g., through kleptoparasitism [26, 27], their basal metabolic rate, and other behaviours
95 required for survival, growth and reproduction (Figure 1). Meeting these diverse demands may
96 promote flexibility in foraging behaviour, with species implementing more diverse suites of
97 predation strategies than can easily be observed and studied using standard methods [27, 28].
98 This can increasingly be rectified with the use of animal-attached technology to reveal out-of-
99 sight animal behaviours across multiple species [29, 30]. Such insights into predator energetics
100 are valuable given the increased demands of predation compared to other foraging methods,
101 related to locating, restraining and handling prey, which we review in full here.

102



103

104 **Figure 1.** Animals can be in energy deficit, energy balance or energy surplus. The arrows here
105 indicate that animals may remain in or transition between these states, mediated by foraging
106 success. Animals in energy deficit incur costs which affect body condition and eventually
107 breeding failure and death will occur if animals cannot regain energy balance. Energy balance
108 allows normal daily functioning, while surplus energy allows investment in growth,
109 reproduction and social behaviours.

110

111

112 *Climate and land use change may cause shifts in predator-prey dynamics*

113 Environmental conditions can add further energetic costs to foraging [31], for example, rising
114 temperatures may subject predators to heat stress during pursuit [32]. Prey species are subject
115 to this pressure as well, but for many predator-prey pairs, it is unclear whether the species are
116 equally (un)affected or whether temperature changes could shift the balance in favour of one
117 species or the other. From the predator perspective, this could shift prey preference, with
118 cascading ecosystem effects [33]. For marine predators, endotherms seem to have a
119 competitive advantage over ectotherms at lower water temperatures, with consequences for
120 species distributions [34]. In terrestrial systems, cursorial predators (which chase prey) are
121 more likely to be adversely affected than stalk and ambush predators, due to the additional
122 energetic costs associated with pursuing prey over large distances [35]. Though disparities in
123 prey *versus* predator responses to rising temperatures may also work in favour of the predator,
124 if prey become more easily exhausted under heat stress. These concepts are understudied at
125 present, especially given the precedence of indirect climate change impacts on ecosystems.
126 Where studies have been carried out, there is disagreement on predator-prey dynamics under
127 rising temperatures, for example in the case of the African wild dog, where there have been
128 contrasting findings on whether the wild dogs themselves or their prey are more impacted by
129 heat stress associated with rising temperatures [36, 37]. These discrepancies may be partially
130 explained by differences in prey preference across populations [32]. Assessing the energetics
131 associated with different hunting and evasion strategies across populations is therefore a key
132 consideration for understanding shifting predator-prey dynamics under climate change.

133 Land use represents another key form of global change with consequences for predator-
134 prey dynamics, often working in tandem with climate change impacts [38]. In some cases, land

135 use change can benefit predators by improving search efficiency as vegetation is thinned or
136 removed [38, 39]. These dynamics can be complex, however, and vary significantly between
137 land use types. For example, pumas (*Puma concolor*) were found to have higher body condition
138 scores in areas of marginal anthropogenic development than in both wilderness and highly
139 developed areas [40]. Socio-ecological phenomena must be considered as habitats are
140 modified; land use change increases human-wildlife conflict, particularly when predators of
141 degraded habitats target livestock [41]. Within increasingly human-dominated landscapes,
142 some prey take advantage of carnivore avoidance of areas of high human activity, a
143 phenomenon known as the human shield [42, 43], while others show stronger avoidance of
144 human activity than their natural predators [44]. Understanding these complex dynamics is a
145 priority under ongoing habitat modification and degradation, particularly given the disparity in
146 observed species' responses across both predators and prey.

147

148 *Energetic landscapes reveal foraging costs*

149 Climate and land use change may cause animal populations to shift in distribution [45] with
150 consequences for how hunting animals locate, select and subdue their prey. Shifting population
151 distributions lead to potential re-arrangement of prey preference and cascading ecosystem
152 effects [43]. These dynamics may be better understood by mapping predation both in the
153 physical landscape and the so-called landscapes of fear, food, disgust and energetics [46–48].
154 The landscape of fear is the spatial and temporal variation seen in prey movements in response
155 to their perceived risk of predation, typically visualised as peaks and valleys, similarly to terrain
156 maps [49]. For example, in Yellowstone, landscape of fear maps computed for elk were
157 strongly affected by the crepuscular activity patterns of wolves (*Canis lupus*) [50]. Similarly,
158 complex changes in diel activity patterns for roe deer across European landscapes were found

159 in response to the threat of both lynx and humans [51]. These dynamics become more
160 complicated in multi-predator systems where prey must contend with predators using different
161 hunting strategies, resulting in complex landscapes of fear with varying levels of risk [52]. The
162 concept of foodscapes, though developed for herbivores navigating immobile foraging
163 resources [46, 53], can also be extended further up the food chain, as prey resource selection
164 will shape the movements and selected hunting strategies of their predators [54]. The landscape
165 of disgust arises from parasite avoidance behaviour, with further consequences for predator-
166 prey interactions and scavenging decisions [48, 55].

167 Energetic landscapes, as revealed through accelerometry (i.e., using on-board
168 accelerometer sensors measuring the rate of change of velocity), represent efforts to put animal
169 behaviour and physiology in the context of wider ecosystems and environments [56]. This
170 concept was introduced by Wilson et al. (2011) assessing varying movement costs associated
171 with foraging in a heterogeneous environment [57]. Specifically, Wilson et al (2011) compared
172 the foraging dives of imperial cormorants (*Phalacrocorax atriceps*) and the travel costs
173 between the foraging area and the breeding site to a model where individuals were evenly
174 spaced. Complexity was added to the energy landscape definition through 1) cost functions and
175 maps visualising areas of different energetic costs, 2) adding speed and tortuosity of animal
176 movement paths and 3) environmental factors such as wind conditions for aerial travel [58].
177 More recent considerations have assumed broader energy requirements, to account for
178 thermoregulation and maintenance of body condition, with quantification of individual
179 foraging strategies highlighted as a future direction in using energetic landscapes for population
180 ecology and global change inferences, considering predator performance [59]. Integrating the
181 landscapes of fear and energetics has been discussed elsewhere [56], but there is still little
182 consideration of how species' social systems factor into this picture.

183

184 *Social interactions influence predation strategies and may be more flexible than originally*
185 *described*

186 Research into how sociality affects animal spatial behaviour and general ecology has grown
187 significantly in recent years, as the social landscape, including the distribution and density of
188 conspecifics, can strongly affect the movements and behavioural decisions of individuals [60],
189 (see also: the social resistance hypothesis [61]). Social network analysis in particular is
190 becoming a dominant approach within behavioural ecology [62–65]. As well as looking at
191 interactions within groups, social networks can be used to represent inter-group interactions
192 such as territorial intrusions related to resource abundance [66] and social dynamics of semi-
193 social conspecifics [67]. Investigating the role of species' social systems, and intraspecific
194 variation in these systems, as a factor influencing energetics requires attention. Conspecifics
195 can affect an individual's foraging behaviour [68]. For example, information transfer pertaining
196 to foraging sites can occur in colonially-breeding species, such as gannets (*Morus bassanus*)
197 [69]. Social eavesdropping has been reported in vultures, as individuals obtain information
198 about thermals from conspecifics, helping them choose energetically efficient foraging search
199 paths [70]. Social information transmission can influence every stage of predation,
200 encompassing encounter, detection, identification, approach, subjugation and consumption of
201 prey [71].

202 Whether an animal is social has profound implications for foraging ecology,
203 particularly if social group members cooperate to obtain food, further compounded by dynamic
204 group size responses by prey [72]. Collective hunting allows the takedown of large prey which
205 individual predators could not manage alone [73, 74]. Other species, such as the Ethiopian wolf
206 (*Canis simensis*), target smaller prey individually, even though these predators live in a social
207 group [75]. Some species that typically forage alone or in pairs can opportunistically adapt to
208 cooperative hunting, such as the black backed-jackal *Canis mesomelas* [76]. Increasingly, there

209 are reports of cooperative hunting in species thought to only forage alone, including harbour
210 porpoises *Phocoena phocoena* [77], goshawks *Accipiter gentilis* [78] and yellow-throated
211 martens *Martes flavigula* [79]. Where cooperative hunting occurs opportunistically, this may
212 be an attempt by individuals to achieve the benefits of cooperative hunting while minimising
213 the costs which can arise through social foraging. Effort expended during cooperative hunting
214 is not necessarily equal between individuals [80] and how food is shared within a group is
215 influenced by intra-group competition, dominance hierarchies and kleptoparasitism [81, 82].
216 This opens research avenues focusing on dynamic behavioural decision-making, investigating
217 spontaneous decisions on whether to cooperate to find food, mediated by internal state and
218 animal personality, as well as environmental conditions [83, 84].

219

220 *Aims*

221 Here we show how biologging technology can be used to provide new insights in predation
222 energetics. First, we review the development of methods for estimating animal energetics and
223 discuss how more recent technological and conceptual advances facilitate finer-scale,
224 multifaceted insights, primarily through approximation of energy expenditure using
225 accelerometry. Next, we briefly outline the importance of accounting for inter-individual
226 variability. In the subsequent section, we discuss the energetics underlying predation in social
227 and solitary contexts, as hunting alone versus with a team has significant implications for both
228 the intake and output of energy, particularly under changing climate and land use scenarios.
229 We conclude with a section on Future Directions, which suggests methods for optimised
230 experimental design, data collection and analysis, aimed at addressing the questions raised at
231 the beginning of this work (Box 1). Specifically, we posit that growing consideration of
232 energetic landscapes and social networks can be combined. Energetic landscapes effectively

233 capture the influence of abiotic factors on individual movement, behaviour and survival, while
234 social networks often lack due consideration of temporal and spatial scales. We recommend
235 calibrating sensors within captive settings prior to setting up experiments in the wild, which
236 will improve our understanding of shifting animal movement patterns and energetics in the
237 Anthropocene. Further suggestions are made outlining which animals to tag, the study design
238 and which variables to include in statistical models.

239

240 **QUANTIFYING PREDATION ENERGETICS**

241 *First investigations of animal energetics: from lab to field*

242 Due to the difficulties associated with studying energetics in wild systems, initial investigations
243 into animal energetics were lab-based. Treadmills were, and continue to be, valuable tools in
244 estimating the energetic costs associated with moving at different gaits across multiple species.
245 The use of treadmills to quantify energetics associated with animal locomotion dates back to
246 the 19th Century [85] and has expanded to include multiple species across diverse taxa
247 including mammals [86], reptiles [87] and birds [88]. In controlled settings (including
248 laboratories and zoos), treadmills combined with oxygen chambers allow measurement of
249 animal speed and oxygen consumption, allowing energy expenditure to be calculated for many
250 species performing multiple gaits. However, this experimental set-up is not possible with free-
251 ranging wild animals; new developments were required.

252 The doubly-labelled water method, developed in the 1950s, allows estimation of an
253 animal's energy expenditure during the window between two blood samples by using
254 isotopically-labelled water to assess carbon dioxide production [89, 90]. With this, research on
255 animal energetics in the wild could commence. It was first used outside the laboratory to assess
256 energy expenditure during rest and flight for homing pigeons *Columba livia domestica* [91]

257 and has since been used extensively across diverse wild species [92–95]. While facilitating
258 inferences across diverse systems, the major limitation of this method is the requirement to
259 recapture animals within a rigid timeframe, as the second blood sample must be taken before
260 the isotopes have been eliminated from the body [96]. Additionally, this method provides
261 energetic estimates from the study period as a whole and extensive behavioural observations
262 are required to estimate the costs associated with specific behaviours [96, 97].

263

264 *The development of animal-borne sensors*

265 Time depth recorders, designed to record the diving depths of marine mammals, represented
266 the first use of archival animal-attached sensors [98, 99]. The development of VHF (Very High
267 Frequency) telemetry allowed triangulation of animal location using an antenna to detect
268 pulsed radio signals emitted from an animal-attached transmitter [100–102]. This allowed
269 studies on movements, home ranges and mortality of wild animals to proliferate, and detection
270 of both predator foraging and prey mortality through VHF telemetry continues to provide
271 important insights into predation [103–105]. Satellite collars were first developed in the early
272 seventies [106, 107], allowing location data to be collected and stored at regular intervals *via*
273 satellite communication. Continued developments expanded options for collecting location
274 information (Figure 2), and the wide adoption of GPS and Argos satellite telemetry has resulted
275 in large, fine-scale datasets of animal movements across space [108, 109]. Beyond movement
276 trajectories, these data provide detailed insights into behavioural states, including foraging
277 [110, 111]. More recent developments have expanded the range of animal-attached sensors and
278 associated insights, known as biologging (Figure 2, [112–115]).

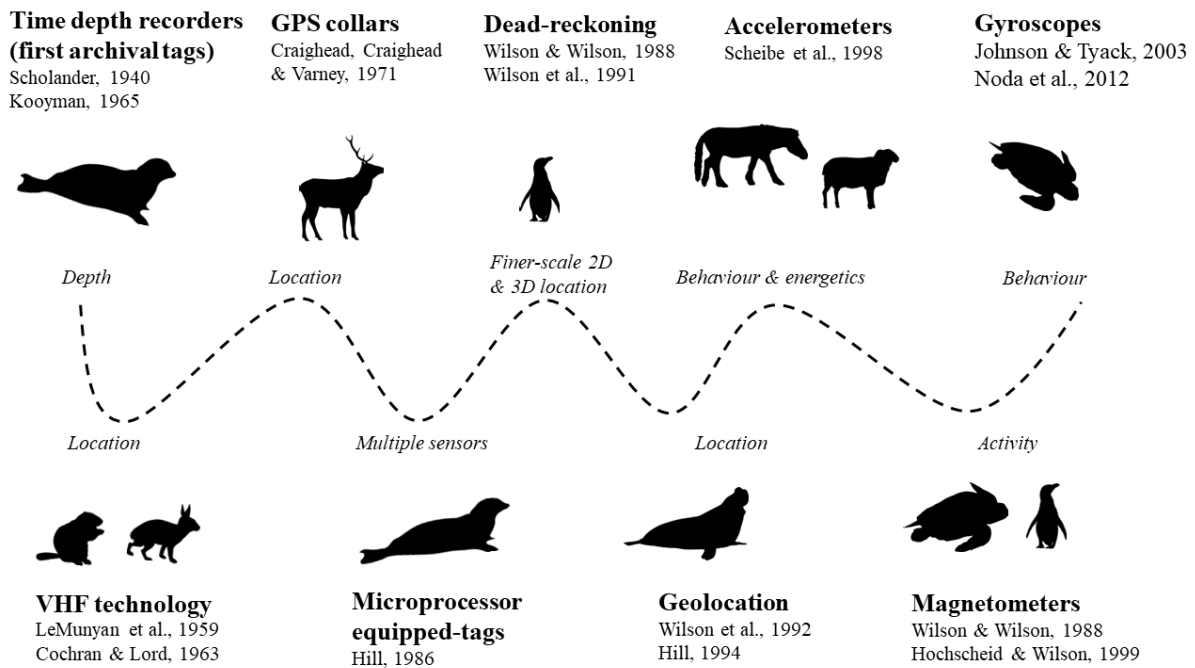
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280 *Additional sensors for finer-scale locations and behaviours*

281 Biologging devices incorporating Inertial Measurement Units (IMUs) such as accelerometers
282 (measuring the rate of change of velocity), magnetometers (measuring Earth's magnetic field,
283 which can be used to give compass-like orientation) and gyroscopes (measuring orientation
284 through angular velocity), allow quantification of fine-scale movement patterns and the
285 relationship between animal behaviour and energetics [116–118]. This is possible as
286 biologging devices allow animal movement to be considered on physiological and
287 biomechanical scales, measuring the individual movements and conditions of the body [119].
288 As such, these additional sensors provide data distinct from those obtained using even high-
289 resolution locational units (such as those collecting data at the scale of seconds or minutes as
290 opposed to hours).

291 Using IMUs in tandem with locational units such as GPS allows fine-scale animal
292 behaviour to be mapped in space. This leads to greater insights than achievable with locational
293 sensors alone. Such multi-sensor techniques can advance our understanding of animal
294 energetics with field-based, sub-second-scale measures of movement costs using dynamic
295 body acceleration metrics derived from tri-axial accelerometer data [120]. Deriving energetic
296 landscapes through mapping energy expenditure in space can be used to test optimal foraging
297 theory, by assessing whether animals maximise energy gain while minimising costs as they
298 navigate their environment [57]. Further, precise animal movement paths can be reconstructed
299 in space through dead-reckoning [121]. Dead-reckoning is a path reconstruction method where
300 location data are combined with heading and speed data derived from IMUs [118, 121, 122].
301 The result is a tortuous, high-resolution path which captures the changes in direction and
302 variable speed of travel undertaken by an animal between subsequent locations. Such highly
303 resolved paths allow more detailed investigations of the precise paths taken by animals and
304 how the costs of moving across different habitat features may shape these.

305 High resolution GPS and IMU sensors offer different yet complementary information.
 306 The behaviour of the species under study and the environment in which it lives dictate the most
 307 appropriate sensor choice and sampling regime [123]. Dead-reckoning can be particularly
 308 valuable in environments where high frequency GPS sampling is prone to errors or high rates
 309 of missed fixes due to habitat composition and/or animal behaviour and posture [123]. High
 310 frequency data have been found to provide additional insights into animal behaviour where
 311 coarser datasets may result in inaccurate or incomplete interpretations. Some examples include
 312 contrasting exploratory movements between bold and shy individuals and detecting multi-
 313 animal interactions with consequences for disease transmission [124].



314

315 **Figure 2.** A timeline of key developments facilitating insights into animal energetics. Note all
 316 references refer to studies of animal ecology, rather than use of these tools in other fields (e.g.,
 317 engineering, physics, robotics). Figure references can be found in the reference list as entries
 318 [98–101, 106, 122, 125–131].

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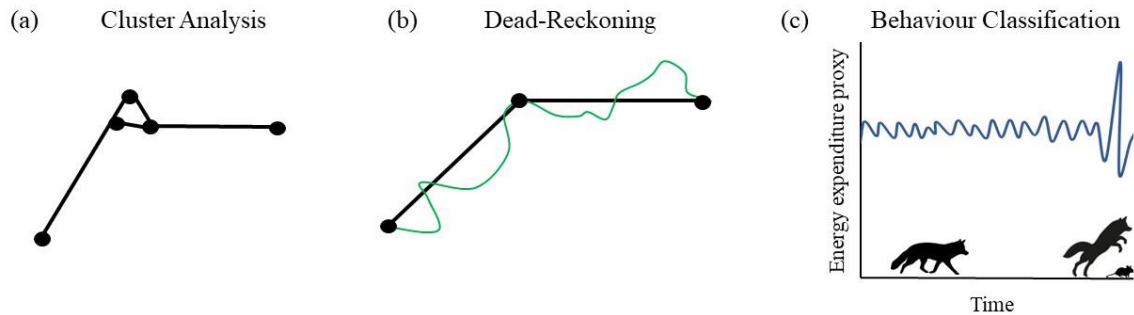
320 *Detecting foraging behaviour*

321 Information about the type and amount of food ingested by animals can answer fundamental
322 ecological questions relating to how animals manage their energy budgets in the wild [132].
323 Inter-mandibular angle sensors (IMASEN), placed on animal jaws, have been used to reliably
324 determine prey ingestion [133]. More commonly, fine-scale movement data are used to
325 reconstruct predation events. Clusters of GPS locations may indicate kill sites, often with field
326 visits for verification [111, 134]. It should be noted that this method is biased towards large
327 predators hunting large prey, with kill sites of small prey typically classified at lower accuracies
328 [134]. Hidden Markov models (HMMs) allow movement data to be categorised into discrete
329 states [135]. Although these states are typically not verified behaviours, kill sites can also be
330 used to confirm HMM-defined predation occurrences [136].

331 Foraging strategies vary depending on the food items targeted, habitat type and whether
332 foraging is cooperative or solitary [79, 137–139]. As different hunting strategies involve
333 different body postures and energetic signatures, it should be possible to extract these separate
334 hunting strategies from biologging data (Table 1). For example, combined tri-axial
335 accelerometer and GPS data have shown promise in elucidating the energetics underlying prey
336 capture by large predators like African leopards *Panthera pardus* [140] and high frequency
337 acceleration data have been used to classify behaviours related to foraging in smaller predators
338 such as the Arctic fox *Vulpes lagopus* [141]. As speed estimates can be derived from both GPS
339 and acceleration data, and magnetometers can capture the tortuosity of animal movement paths
340 [142], these technologies present opportunities to look at speed, pursuit and evasion in hunting
341 predators and fleeing prey (Figure 3; [143]).

342

343



344

345 **Figure 3.** Examples of analysis methods for GPS and Inertial Measurement Unit data with
 346 relevance to predation energetics. (a) Cluster analysis of GPS data allows detection of kill sites
 347 by detecting spatially and temporally clustered locations, indicated by the dots here, e.g. [134,
 348 144]. (b) Dead-reckoning animal movement paths using GPS, accelerometer and
 349 magnetometer data allow the tortuosity of movement paths to be captured and can be used to
 350 reconstruct paths of hunting predators [121]. Here the black line represents the straight-line
 351 distances between subsequent GPS points, while the green line represents a dead-reckoned
 352 path. (c) Behaviour classification of data from IMU sensors such as accelerometers can be used
 353 to distinguish predation from other behaviours e.g., [145]. Note that the proxy for energy
 354 expenditure here can take the form of raw sensor data such as individual acceleration axes or
 355 metrics such as VeDBA or ODBA.

356

357

358 **Table 1.** A list of key sensors linked to behavioural interpretations relevant to predation
 359 energetics.

| Sensor | Behavioural Inferences | Examples |
|---------------------------------------|--|-----------------|
| GPS units | Identify locations visited during foraging trips | [146] |
| | Calculate distances travelled | [147] |
| | Identify kill site clusters | [144] |
| Accelerometers | Identify postures and movements related to pursuing prey | [148, 149] |
| | Quantify predation success rate | [149] |
| | Turns taken during foraging trips | [143] |
| Magnetometers | Identify postures related to foraging | [150] |
| | Turns taken during foraging trips | [151] |
| | Dead-reckoning | [121] |
| Proximity sensors | Social interactions | [152] |
| | Social foraging | [153] |
| Intermandibular Angle Sensor (IMASEN) | Opening/closing mandible during foraging | [154] |
| Camera | Direct footage of all predation-related behaviours | [28] |
| Microphone | Recordings of prey cries | [155] |
| | Recordings of chewing sounds | [156] |
| | Detection of calls associated with foraging | [156] |

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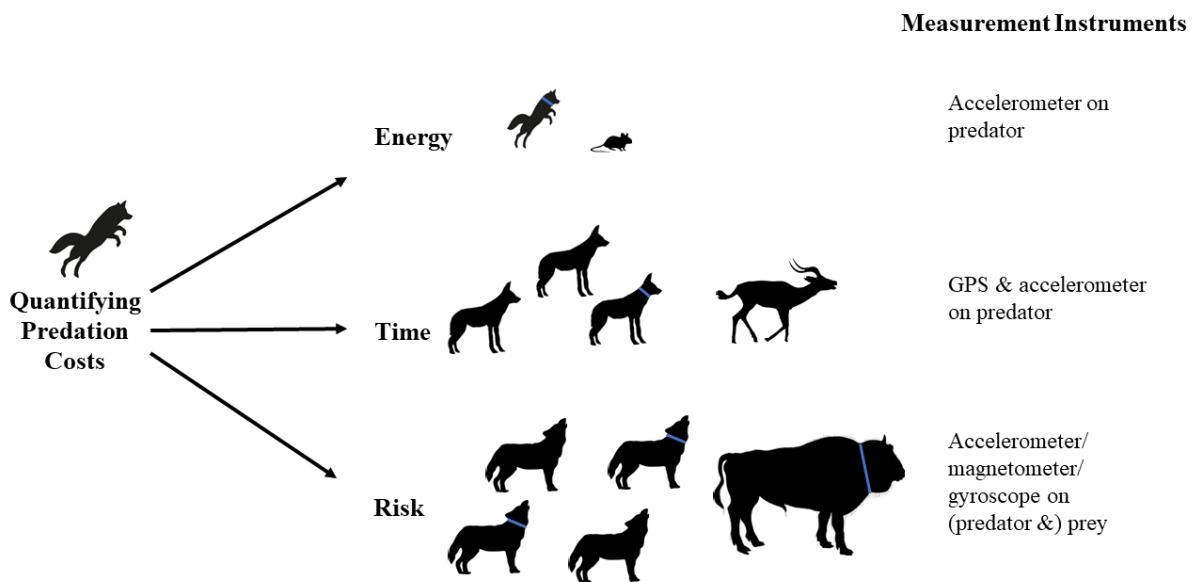
363 *Linking predation theory and biomechanics to sensors*

364 Certain aspects of hunting behaviour should be kept in mind when quantifying predation
365 energetics through biologging given the physiological and biomechanical insights available
366 through such sensors. For example, prey may undertake complex escape manoeuvres as they
367 choose where to flee and predators follow this route. As such, turning dynamics of coursing
368 predators during a chase have been shown to vary with prey species and the mass of both
369 predator and prey [143]. Combining movement data with high resolution habitat data, i.e., those
370 collected using remote sensing and LiDAR methodologies, e.g., [157], represents the highest
371 accuracy framework for assessing turning dynamics in predator-prey chases (see Future
372 Directions). Both pursuit and evasion have important energetic consequences, which ultimately
373 determine hunt outcomes [143, 158].

374 The energetic costs of predation can be split into costs of 1) locating prey, 2) pursuit or
375 ambush and 3) restraining and killing the prey, respectively. More time spent on any of these
376 aspects results in higher energy expenditure, but the costs of each step are unequal and vary
377 between predator-prey dyads. The energy required for separate stages of predation can be
378 estimated through the collection of biologging data (Figure 4). For example, locating prey is
379 less costly than the pursuit per unit time, where terrestrial predators switch from walking or
380 trotting search gaits to running pursuit gaits [159]. Behaviour classification of movement
381 modes can identify and assign approximate costs to such behaviours. Longer search times could
382 involve finding easier prey with shorter pursuit and restraint times [160]. Therefore, time and
383 energy are separate costs, but time spent on a given activity is critical to the total energetic cost
384 of the hunt. Costs incurred by previous unsuccessful hunts and the sum of other behaviours
385 performed by the animal should also be taken into consideration. Failed hunts, scavenging and

386 foraging for smaller food items may also be accounted for through data from accelerometers
 387 and other IMU sensors as behaviour classification methods continue to advance [141, 145].
 388 Developing classification methods for these complex behaviours may be assisted considerably
 389 by the increasing use of animal-attached cameras and microphones, allowing further
 390 verification of IMU sensor outputs [155, 161]. Proximity sensors can be used to detect
 391 cooperative foraging in predators [153], as well as encounters between predators and prey
 392 [162].

393



394

395 **Figure 4.** Predation requires investment of energy and time, while involving significant risks
 396 associated with attacking and subduing prey. Example predator-prey pairs are shown here, with
 397 predation costs linked to sensors which can be used to quantify them. Tagged animals are
 398 indicated with blue collars on the relevant silhouettes. Accelerometers allow the calculation of
 399 Dynamic Body Acceleration proxies which provide estimates of energy expenditure which can
 400 be matched to distinct behavioural states. GPS and accelerometer data allow the start and end
 401 points of predation to be identified so that time spent hunting can be quantified. Inertial

402 Measurement Units can be used to assess animal posture, to detect defensive or aggressive
403 behaviours exhibited by prey and alert postures to be detected in predators. Predator retreat
404 may also be identifiable from dead-reckoned movement paths.

405

406 As well as facilitating fine-scale, behavioural insights, animal-attached technology can
407 also provide important information on broader ecological scales. Understanding the energetics
408 of predation can provide information on trophic cascades and predator-prey dynamics with
409 consequences for whole ecosystems [163]. Integrating biologging data into Dynamic Energy
410 Budget-Individual Population Models (DEB-IPMs) has been identified as a powerful emerging
411 method to link individual level behavioural energetic trade-offs and metabolic processes to
412 population dynamics including survival and reproduction, with due consideration to
413 environmental change [164]. As such, despite the fine-scale nature of biologging data and often
414 short deployment periods, these data can provide important, broader-scale inferences for
415 population ecology [165, 166].

416

417 **INTER-INDIVIDUAL VARIABILITY**

418 There has been relatively little consideration of how consistent inter-individual differences
419 (i.e., animal temperament or animal personality) might affect hunting prowess. Individual
420 variation may lead to specialisation in solitary hunters like octopuses [167] or distinct roles in
421 cooperative hunters, as seen in harbour porpoises [77]. Further, predator and prey personalities
422 may interact in feedback loops [84], with some empirical evidence suggesting both predator
423 and prey personality may interact with consequences for predation attempt outcomes [168].

424 If individuals adopt flexible foraging strategies such as exhibiting prey preference based
425 on prey size and availability, as well as the broader ecological context, then it is reasonable to

426 assume that differences in strategy will arise between individuals. Some differences may be
427 linked to factors such as age and sex [9], though further variation may be attributed to consistent
428 intra-individual variability. This can be measured by considering the repeatability and
429 predictability of behaviours. Protocols for extracting measures of personality from biologging
430 data have recently been developed and are growing in popularity [169]. To date, these methods
431 have largely focused on using parameters extracted from GPS data, including distance moved
432 and activity patterns [170] though there is considerable scope for IMU sensors to yield
433 additional insights into individual variation in activity level and space use as influenced by
434 foraging [171, 172]. Individual variation in activity rhythms and how prey are approached and
435 hunted may affect predation strategies and the roles performed by cooperative hunters, with
436 potential energetic implications. These patterns can be better understood by using movement
437 metrics such as daily travel distances and the amount and timing of activity to detect consistent
438 behavioural differences between individuals (for full review, see [169]). Despite the growing
439 attention given to understanding animal personality in ecology and evolution [83], the role of
440 personality in driving predator behaviour is still far from understood.

441

442 **SOCIAL PREDATORS**

443 An animal's social environment can affect both the costs and benefits associated with finding
444 food, warranting specific considerations for social predators. Social foraging can decrease the
445 time and energy an individual invests in locating and consuming prey [146, 173] and enable
446 access to prey which cannot be obtained by a single predator [74, 174]. Unequal effort invested
447 in securing prey and gained through how food is shared can present new challenges, however
448 [5, 81]. Whether a predator hunts alone or with a team therefore has implications for how
449 animal-attached sensor data should be interpreted and which wider conclusions on predation

450 energetics can be drawn. In this section, we provide a brief overview of challenges and
451 considerations for studies on social predators.

452 Often when studying social species, tags are deployed on one or a few members of
453 multiple social groups, to gain insights into the larger population, though with consequences
454 for our understanding of social group interactions [175]. One of the primary difficulties in
455 interpreting tag data from social foragers is that both the energy expended in acquiring a meal
456 and the energy intake from successful predation may be unequal between group members. This
457 is particularly true where group members perform different roles during a hunt [176, 177]. This
458 makes it difficult to extrapolate energy intake and output from tagged individuals to other group
459 members, and indeed conspecifics more generally. This is particularly complex where social
460 group sizes are unknown or fission-fusion dynamics are at play, leading to variable numbers
461 of predators present at each predation event. The percentage of a social group or population
462 which has been tagged affects how readily social interactions can be detected. Detection of
463 interactions between members of the social group is further influenced by sampling frequency,
464 which must also be taken into consideration when studying group dynamics [175]. The
465 strengths of within-group and between-group social interactions may also vary depending on
466 ecological conditions, e.g., in lions [178]. Thus, an additional complication is estimating the
467 distribution of conspecifics across the landscape. Additional data, such as sightings, combined
468 with tag data, may be used to build a social landscape providing the likely density of
469 conspecifics from different groups [60]. This will likely require intensive sampling and
470 surveying across potentially large areas. Further analysis considerations are required for
471 behaviour classification of IMU sensor data. For example, when some but not all members of
472 a social group have made a kill and an untagged individual does not participate in the hunt but
473 feeds on said kill, it may not be possible to decipher whether this feeding instance represents
474 active predation by the group or opportunistic carcass scavenging.

475 Studies of predation energetics should consider the range of prey species taken by a
476 social predator, as the degree of cooperation may vary with prey size and relative risk to the
477 predator. This is particularly relevant to generalist predators with wide distributions, the range
478 of which may encompass different habitat types and prey species compositions. This is not
479 static, for example larger wolf packs are more cooperative during a hunt when hunting more
480 dangerous prey [74]. Where possible, simultaneous tagging of predators and their prey can
481 improve our knowledge of interactions between groups of predators and dangerous prey
482 (Figure 4).

483 It is important to note that other factors affect the size of animal social groups, including
484 defending vulnerable young and territories. This may explain why social groups are often larger
485 than identified optimum group sizes for cooperative hunting [179, 180] and why some species,
486 like the Ethiopian wolf, occupy shared territories and breed cooperatively but forage alone [75].
487 Even when the hunt itself is cooperative, feeding may still be competitive when groups contain
488 more individuals than are necessary for optimised cooperative hunting [181, 182]. Dominant
489 individuals may limit food access to more subordinate group members [183], though other
490 factors beyond social hierarchies can also affect the roles social group members perform in
491 hunts and the related energy intake and output from a kill. Further studies involving tagging all
492 or most individuals within a social group can shed light on these cooperative hunting dynamics.
493 While this is not practical in all cases, even studies on a single social group can help address
494 these knowledge gaps and aid data interpretation where few or sole individuals in a group have
495 been tagged [184].

496

497

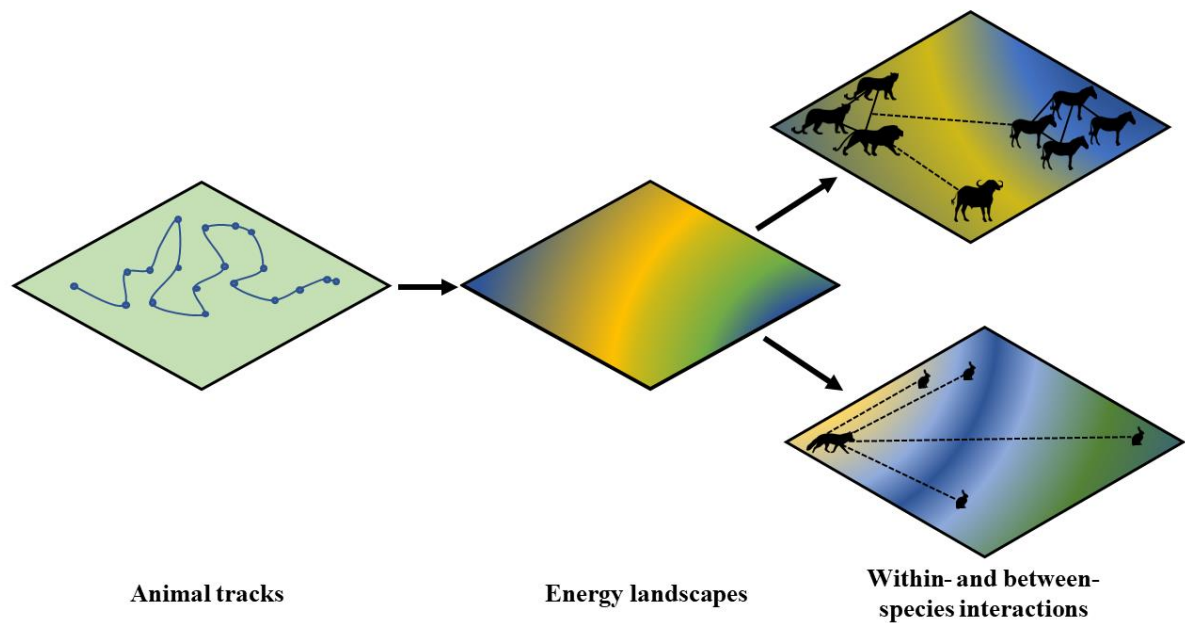
498 **FUTURE DIRECTIONS**

499 In this review, we have summarised key theory in the predation energetics literature, outlined
500 the development of biologging tools for measuring animal energetics and highlighted key
501 considerations which must be accounted for when investigating intra-individual variability or
502 working with social predators. We conclude by proposing future directions in predation
503 energetics research, which will be key in identifying different energetic costs and gains
504 experienced by predators in a changing world.

505 *1. Integrating energetic landscapes and social networks.* Animals navigate a spatial
506 landscape and other animals, including predators and prey, affect movement and
507 energetics in a similar fashion to abiotic landscape factors. These biotic factors have
508 unequal avoidance and attraction effects with consequences for how animals navigate
509 their environment [185]. Attraction to or avoidance of conspecifics and/or
510 heterospecifics may result in suboptimal use of the physical landscape (e.g., expending
511 more energy to traverse through rough terrain to search for prey or avoid competition).
512 Conversely, an animal may choose the least costly path to navigate the local terrain,
513 which then affects its biotic interactions. Studying such interactions within ecological
514 communities is increasingly feasible due to large-scale tracking initiatives such as
515 ICARUS [186] and data-sharing platforms such as Movebank (which also contributes
516 a data standardisation philosophy; [187]). Energetic landscapes, which consider the
517 costs of navigating the physical landscape, and social networks, which define the
518 relative strength of social interactions, can be unified to consider the abiotic and biotic
519 factors shaping animal movement patterns in tandem. For example, integrating these
520 methods could be used across predator and prey communities to investigate how the
521 physical environment influences prey selection. Further, thermal shelters are likely to
522 become more important to many species under climate change [188, 189], which may
523 have knock-on effects for prey detection and predator avoidance strategies.

524 Social network analysis (in both intra- and inter-specific systems) offers an
525 analytical means of assessing the role of social interactions in species ecology [64].
526 Social networks are typically visualised as nodes clustered by interaction frequency,
527 but can be overlaid onto maps to better assess the role of spatial proximity and
528 environmental variables in determining association strength, e.g., [67]. This process can
529 be taken a step further by overlaying social networks onto mapped energy landscapes,
530 where individuals have been tagged with locational units and accelerometers (Figure
531 5). Beyond visualisation, the recently developed R package *aniSNA* can be used to
532 resolve autocorrelation issues encountered in the computation of social network metrics
533 using GPS data [190]. The most robust social network metrics for a given dataset,
534 determined with due consideration to sampling regime and sociality, can then be
535 modelled with measures of energy expenditure derived from mechanistically modelled
536 energetic landscapes, integrating data on species interactions and energy expenditure.
537 This unleashes new opportunities to test specific hypotheses on how social-energetic
538 landscapes vary as a function of, for instance, prey availability or environmental
539 conditions such as temperature, or how individuals modify the strength of their
540 interactions with different prey species across habitats which are more or less costly to
541 traverse. Energetic landscapes under global change scenarios (e.g., [59]) can be adapted
542 to include shifting predator and prey interaction patterns, represented through social
543 network centrality metrics such as mean network strength, to quantify altered
544 ecosystem dynamics. Considering energetic landscapes in conjunction with within- and
545 between-species interactions may expand proposed spatial-social data concepts [191]
546 to provide new insights on how other animals affect how an individual navigates its
547 environment.

548



550

551 **Figure 5.** Infographic contrasting the energetic costs and gains between a social group of
 552 cooperative hunters and a solitary predator, incorporating energetic landscape and social
 553 network concepts. Sensor data on animal location and energetics can be computed into energy
 554 landscapes, which can in turn influence prey selection and encounter rates. The colour gradients
 555 here represent hypothetical energetic landscapes, where movement costs vary across the habitat
 556 in question. Solid black lines indicate interactions between social conspecifics, while dashed
 557 lines indicate directions of interest to predators due to prey presence.

558

559 2. *Refining data collection and analysis procedures using captive and domestic animals.*

560 Pilot studies on captive and domestic animals allow refinements before wild tag
 561 deployments. Zoos provide settings where sensor data can easily be verified for
 562 improved data analysis procedures ahead of wild deployments [172]. Captive studies
 563 can also have welfare benefits by piloting device attachment and deployment methods.
 564 Such studies can also detect potential species-specific considerations required ahead of

565 long-term field deployments e.g., maned wolves *Chrysocyon brachyurus*; English et
566 al., unpublished data. While there are limitations to using surrogates [192], with careful
567 interpretation, data from captive and domestic animals can improve behaviour
568 classification procedures for biologging data [193]. This can be particularly useful
569 when investigating complex postures and motions such as those associated with
570 feeding.

571

572 3. *Tagging multiple or all individuals in a social group.* Simultaneously tagging multiple
573 or all individuals in a single social group is rarely done for multiple reasons. Most
574 studies typically have limited numbers of tags and aim to spread them across multiple
575 social units so that broader population insights can be gained [175]. Deploying tags in
576 discrete social groups can also address statistical assumptions of independence of data
577 points, depending on the analysis methods used. These constraints are valid, but
578 currently limit our fine-scale knowledge of within-group interactions, including distinct
579 roles which may be performed during coordinated hunting behaviour. Studies which
580 target an entire social group can reveal whether a hunt is truly cooperative and quantify
581 the influence of habitat on pursuit predation, with important considerations for how
582 focal species may adapt in changing land-use and climate scenarios [23]. While tackling
583 entire social groups is easier where groups are small, it is becoming increasingly
584 feasible and common to also tag larger social groups (e.g., [194]). While tagging
585 multiple or all members of a social group will lead to advances in our understanding of
586 animal societies, tag burden should be kept in mind and research questions should be
587 well formulated to ensure maximum information gain from studies with potential
588 higher overall tag burden. Researchers can also implement non-invasive technologies
589 to collect empirical data on group size, such as camera traps and drones, for example in

590 scenarios where tagging all members of a social group is not feasible due to economic
591 or logistical constraints, or to verify social bonds where these cannot easily be
592 ascertained by an observer. For example, camera traps have been used to detect high
593 contact rates between red foxes (*Vulpes vulpes*), which are considered solitary foragers,
594 where food availability is high [195].

595

596 4. *Taking social groups as individual units to compare inter-group communication and*
597 *interactions.* Complementary to studies of within-group interactions, there is scope for
598 further consideration of between-group interactions, where territoriality may (at least
599 occasionally) be weaker than first described, as has been found in black-backed jackals
600 [76]. This also applies to solitary species which may interact socially with conspecifics
601 in neighbouring territories more readily than previously thought (e.g., maned wolves
602 [196]). These interactions may be aggressive or affiliative and include communication
603 through scent-marking and vocalisations. These forms of communication also shape
604 how an animal perceives and therefore navigates its environment, with consequences
605 for territoriality and therefore the resources available to the territory holder. Such
606 interactions are more difficult to visualise and frame in a social-energetic landscape
607 context, but mapping instances of scent-marking behaviour classified through IMU
608 sensor data [197] and continued advancements in acoustic recording research [198] may
609 improve our understanding of these non-visual communication channels in shaping
610 how animals move through their environment.

611

612 5. *Simultaneous tagging of predators and their prey.* As well as investigating the within-
613 and between-group interactions of predators, further studies with simultaneous tagging

614 of both predators and their prey are required. Studies where members of a predator and
615 prey species within the same study area are tagged with location sensors can provide
616 valuable information on predator and prey activity rhythms, their degree of spatial
617 overlap and how these may interact with landscapes of fear and energetics [199, 200].
618 Where possible, tagging predators and prey simultaneously with IMU sensors may
619 provide detailed data on individual hunt dynamics. Such data can be used to
620 characterise chase paths, turning dynamics and evasive movements [158]. While the
621 likelihood of a tagged predator hunting tagged prey is still quite small in most systems,
622 any instances where this is recorded is likely to have profound insights into how the
623 pursuit and restraint techniques of the predator and the escape strategies of the prey
624 interact with one another. As well as these tagging approaches, continued advancements
625 in tracking animal locations and postures through drone-collected aerial imagery [201]
626 may hold significant potential in capturing pursuit and evasion dynamics of predators
627 and prey.

628

629 6. *Account for factors such as hunting success rate and relative prey energy value in*
630 *statistical model structures.* Fine-scale biologging data and related behaviour
631 classification can also contribute additional variables to include in models of predation
632 energetics. For example, where hunting can be defined, the approximate energetic costs
633 of distinct prey species and their energy value when obtained (either estimated from
634 time spent feeding if clear from IMU sensor traces or through a proxy derived from
635 prey body size or estimated caloric value) can be included in model structures. Models
636 explaining the likelihood of successful predation of a given prey would benefit from
637 including the approximate energy value of the prey, encounter rate, handling time and

638 individuality. Conversely, failed predation attempts can be an important consideration
639 when considering a more general model of a predator's energetic balance.

640

641 7. *Increasing the diversity of species tagged and included in such studies.* One of the
642 limitations of animal-attached sensors is that tag size and weight can limit the potential
643 for the use of such technology on smaller animals. Considerable advancements have
644 been and continue to be made, however, such as bilogger sensor networks developed
645 for tracking bats [202]. Though the development of smaller tags facilitates deployments
646 on smaller species, these developments should also aim to facilitate the use of reduced
647 mass tags on individuals to minimise potential deleterious effects [203]. Biologging
648 studies are also biased towards mammals, and to a lesser extent fish and birds [204];
649 efforts should be made to increase the diversity of species represented in such studies.

650

651 8. *Sampling designs tackling the influence of climate and habitat modification on foraging*
652 *behaviour.* Predator-prey interactions are key to trophic ecology and it is therefore
653 important to assess energy balance in these relationships in a changing world. Further,
654 robust understanding of energy intake and output is required to understand species
655 responses to climate and habitat change. These questions can be tackled, for example,
656 by comparing energetics across populations with different weather patterns to
657 approximate species responses to climatic shifts [37]. Studies on wildlife in human-
658 dominated landscapes such as urban areas or agricultural land can yield insights for
659 areas undergoing current land-use change.

660

661 The future directions presented here offer a roadmap to further expand our knowledge of
662 predation energetics using animal-attached sensors, accounting for sociality, individual
663 variation and global change. Advances in animal-attached tagging technology have rapidly
664 expanded the ecologist's toolkit for understanding animal energetics. The tools presented here,
665 coupled with thoughtful study designs and integrated analysis concepts, can facilitate
666 substantial advances in our understanding of predation energetics in a changing world.

667

668 **Declarations**

669 *Ethics approval and consent to participate*

670 Not applicable.

671 *Consent for publication*

672 Not applicable.

673 *Availability of data and materials*

674 Not applicable.

675 *Competing interests*

676 The authors declare that they have no competing interests.

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682 **Authors' contributions**

683 HME lead conceptualisation of the review with contribution from SC, LB and AK. HME wrote
684 the original draft. Figures were designed by HME and AK. Supervision was provided by SC
685 and LB. All authors revised the manuscript. All authors approved the submitted version of the
686 manuscript and agree to be accountable for the work.

687

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693

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