

1 **Multi-species dependencies improve forecasts of population dynamics in a long-term monitoring**
2 **study**

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23 **Authorship:**

24 NJC, SKM and EPW designed the study; SKM and GMY oversaw field data collection; HS, JLS and EPW
25 designed cyberinfrastructure to store and access data; NJC and KANKK performed statistical analyses
26 and visualizations; NJC drafted the manuscript and all authors contributed to revisions.

27

28 **Data availability statement:**

29 All data from the Portal Project is publicly archived to Zenodo (Ernest et al. 2023) and is available in
30 processed forms using the *portalr* R package (Christensen et al. 2019b). R code to reproduce
31 analyses is provided in Supplementary materials and in a GitHub repository
32 (https://github.com/nicholasjclark/portal_VAR). R code will be permanently archived on Zenodo on
33 acceptance of the manuscript.

34

35 **ABSTRACT**

36 Forecasts of community dynamics are essential for the management of biodiversity. Theory suggests
37 these predictions can be improved by leveraging multi-species dependencies to improve models, but
38 empirical support for this is lacking. We test whether models that learn from multiple species, both
39 to estimate nonlinear environmental effects and temporal dependence, improve forecasts for a
40 semi-arid rodent community. Using Dynamic Generalized Additive Models, we analyze monthly
41 captures for nine rodents over 25 years. We find strong evidence that multi-species dependencies
42 improve performance, as models that captured these effects gave superior predictions. These
43 models also provide novel insights, in our case by quantifying how changes in abundance for some
44 species can have delayed, nonlinear effects on others while also uncovering important lagged effects
45 of environmental drivers. We show that multivariate models are useful not only to improve
46 ecological forecasts but also to ask targeted questions about community dynamics.

47

48 **KEYWORDS**

49 Biotic interactions, Community dynamics, Ecological forecasting, Generalized additive model, Stan,
50 State-Space model

51 INTRODUCTION

52 Predicting the impacts of environmental change on ecosystems is a global challenge
53 (Intergovernmental Science - Policy Platform on Biodiversity and Ecosystem Services 2019). The
54 need for explicit predictions has sparked a renewed emphasis on ecological forecasting (Lewis et al.
55 2023) including the prediction of population dynamics (Ward et al. 2014, Johnson-Bice et al. 2021).
56 But this is a difficult task, particularly because ecological forecasting is often a multivariate problem.
57 Monitoring studies typically gather data for multiple species, and managers often require
58 community predictions to guide decisions (Clark et al. 2001, Greenville et al. 2016). A major focus of
59 empirical and theoretical research seeks to understand how we can improve predictions using
60 models that leverage data from multiple species (Holmes et al. 2014, Powell-Romero et al. 2023).

61 Forecasting species abundances is inherently difficult because many processes influence
62 population dynamics (Johnson-Bice et al. 2021, Clark and Wells 2023). Population dynamics often
63 exhibit complex responses to drivers (including non-linear responses and lags; Cárdenas et al. 2021),
64 temporal autocorrelation (Ives et al. 2003), and data complexities (e.g., irregular sampling,
65 observation errors, missing samples, and over dispersed counts; Clark and Wells 2023). Species'
66 relationships are also important. The way a species responds to change results from direct influences
67 of the environment on its ability to find resources and reproduce (Heske et al. 1994) and the effects
68 of other species on its abundance and vital rates (Ives et al. 2003). Inference on both processes can
69 be informed using data from multiple species, which should theoretically improve near-term
70 predictions. For example, we expect some species to exhibit shared responses to environmental
71 factors (Christensen et al. 2018), and we gain more precise inferences by learning these responses
72 hierarchically. Importantly, these responses do not need to be assumed to be linear, as Pedersen
73 and colleagues (2019) recently showed how Hierarchical Generalized Additive Models (HGAMs) can
74 estimate multiple non-linear relationships in a single joint model. In addition to shared
75 environmental responses, we also expect direct biotic interactions to play important roles (Heske et

76 al. 1994, Ernest and Brown 2001, Bledsoe and Ernest 2019). Models that impose multispecies
77 temporal dependence offer a solution to explore these interactions and use them to make more
78 informed predictions (Ives et al. 2003, Greenville et al. 2016). However, while we postulate that
79 capturing these sources of multispecies dependence will improve population-level forecasts,
80 empirical tests of this hypothesis are rare.

81 We evaluate whether models that incorporate multi-species relationships can improve near-
82 term population forecasts. Using multi-species data from a long-term monitoring study, we build
83 models that learn species' shared environmental responses and temporal interactions to make
84 inference about factors that relate to community dynamics. Comparisons with simpler models are
85 used to test whether the incorporating biotic dependence structures improves predictions. We show
86 that this approach to modelling population abundances provides a more detailed understanding of
87 the drivers of ecological community change as well as more accurate forecasts.

88

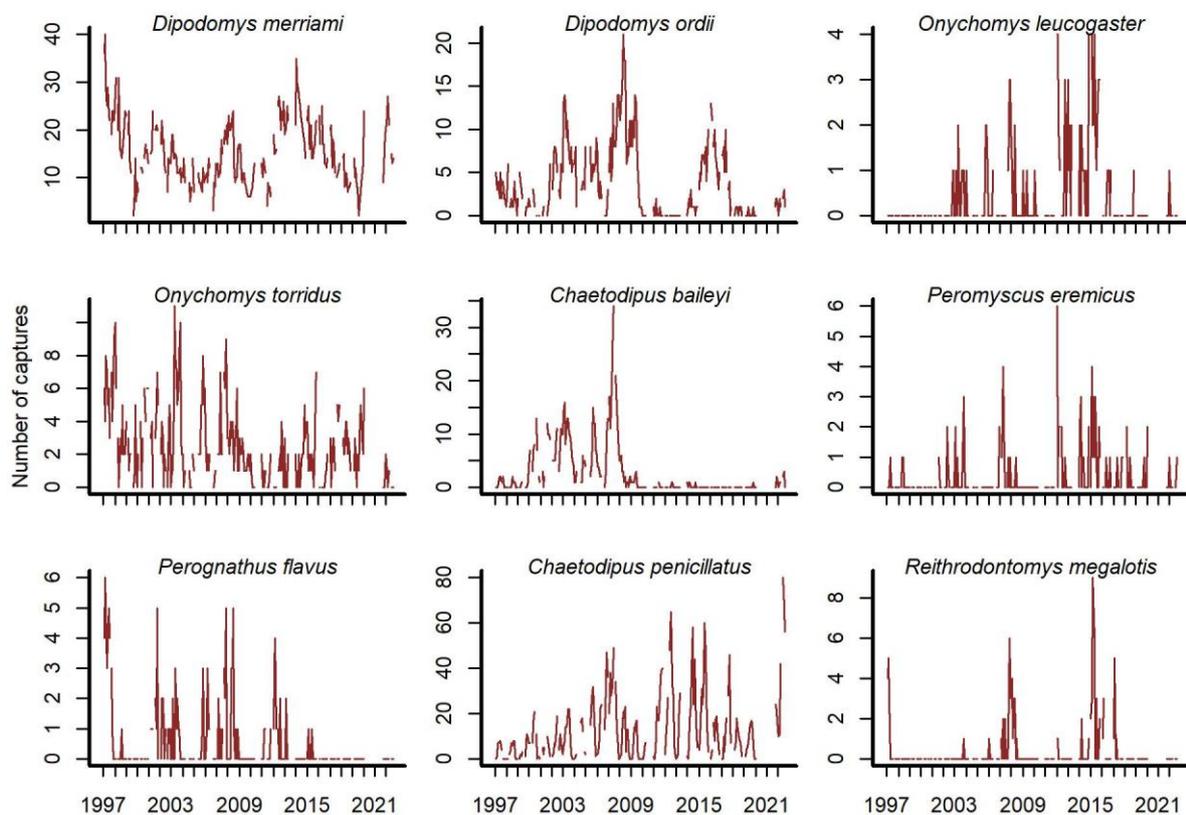
89 **MATERIALS AND METHODS**

90 **Rodent capture data**

91 Our data come from the Portal Project, a long-term monitoring study of a desert rodent community
92 near Portal, Arizona (Brown 1998, Ernest et al. 2020). Sampling covers 24 experimental plots (50m x
93 50m), each containing 49 baited traps that are opened following the lunar monthly cycle (Ernest et
94 al. 2020). The data exhibit many of the complexities that confront population forecasting. These
95 include imperfect detection, missing observations (~5% on average; Dumandan et al. 2023b) and
96 over dispersed discrete counts that include many zeros. Environmental drivers are known to exhibit
97 lagged and nonlinear impacts on rodent population dynamics (Brown and Ernest 2002). The rodents
98 at Portal compete for resources in complex ways, and these biotic interactions are postulated to
99 have important consequences for population dynamics (Lima et al. 2008, Bledsoe and Ernest 2019).

100 We used the *portalr* R package (Christensen et al. 2019) to extract trapping records from the
101 Portal data (version 3.134.0; downloaded October 2022; <https://doi.org/10.5281/zenodo.7255488>).
102 The design uses three experimental treatments with varying levels of rodent exclusion (Ernest et al.
103 2020), but our study focused on long-term control plots (that allow free movement of all rodents)
104 for the period December 1996 – August 2022. We excluded transient species, observed in < 10% of
105 trapping sessions, to focus on species with the most influence on community dynamics (Figure 1).

106



107

108

109 **Figure 1:** Rodent captures from December 1996 to August 2022. Counts are total captures across

110 long-term control plots. Blanks are missing values.

111

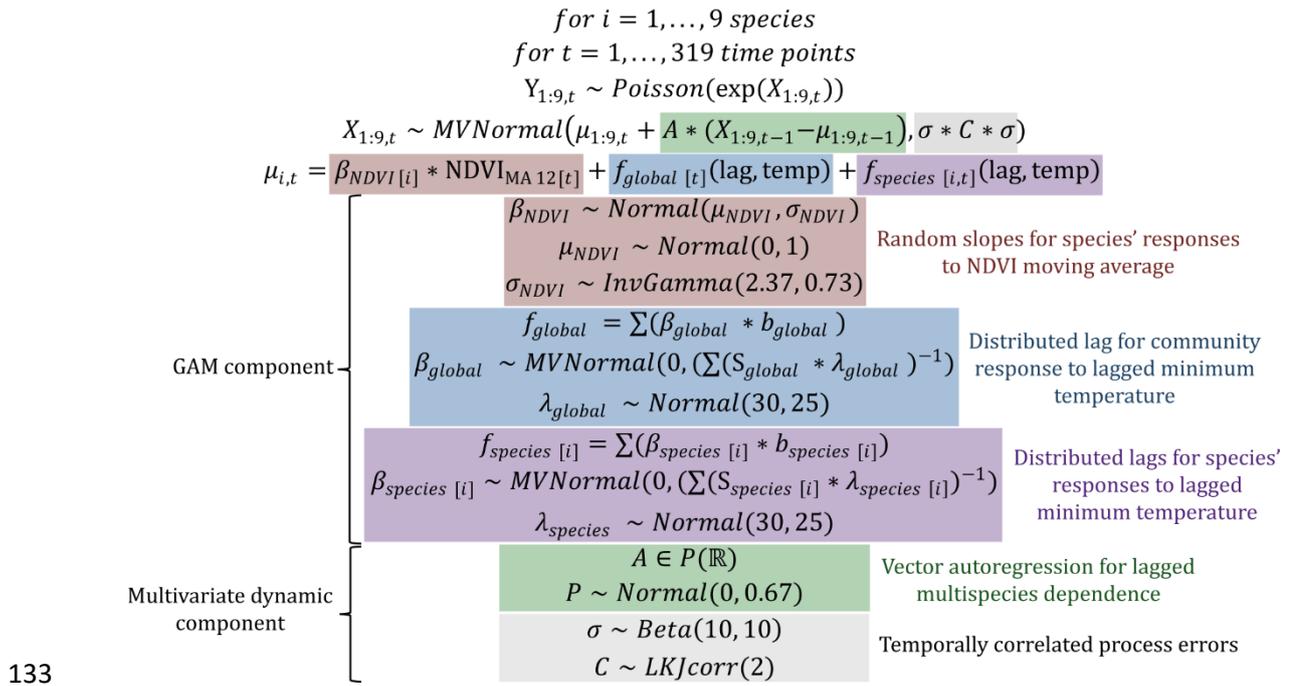
112 **Covariate measurements**

113 Rodents at Portal depend on environmental conditions that reflect resource availability and seasonal
114 breeding signals. We therefore modelled species' responses to environmental variation using
115 minimum temperature and the Normalized Difference Vegetation Index (NDVI) as covariates. Hourly
116 air temperature (°C) is recorded by an automated weather station, while Landsat images are used to
117 calculate NDVI (accessed from the USGS Earth Resources Observation and Science Center;
118 <https://www.usgs.gov/centers/eros>). Measurements were converted to monthly averages and
119 extracted from one year before the start of captures (from January 1995) to calculate lagged and
120 moving average versions.

121

122 **Model description**

123 There were several aspects we needed to consider in our model. Total captures showed both short-
124 and long-term fluctuations (Figure S1). Captures for individual species undulated over multi-annual
125 cycles and were positively autocorrelated at lags up to 20 months (Figures S2 and S3). To test
126 whether multi-species information improves model performance, we needed to model these
127 dynamics using multivariate dependence structures. We also needed to leverage community
128 information to estimate species' time-delayed responses to vegetation and temperature variation.
129 Rodent captures were modelled as *Poisson* observations of a latent state that was composed of a
130 hierarchical GAM component (to capture shared environmental responses) and a multivariate
131 dynamic component to capture multispecies dependence. The full description for this model, which
132 we abbreviate to **GAM-VAR** (Figure 2).



134 **Figure 2:** Definition of the **GAM-VAR** model. Coloured boxes highlight the five main components of
135 the latent state model.

136

137 The GAM component consisted of hierarchical NDVI and minimum temperature effects that
138 were informed by theory and exploration of covariate time series (shown in Figures S4-5). We used a
139 12-month moving average of NDVI ($NDVI_{MA12}$) because we expected rodents to respond gradually
140 to vegetation change. Our model assumed linear effects of $NDVI_{MA12}$, equivalent to hierarchical
141 slopes. Responses to temperature were estimated using hierarchical distributed lags in which
142 nonlinear effects of minimum temperature varied smoothly with increasing lag. To encourage multi-
143 species learning, we included a shared community-level response $f_{global}(Mintemp, lag)$ and
144 species-level deviations $f_{species[i]}(Mintemp, lag)$. These allowed each species to show a different
145 temperature response from the community average, but only if there was information in the data to
146 support such a deviation. We used lags of up to six months in the past.

147 A vector autoregression (VAR) of order 1 captured lagged multispecies dependence, where
148 A was a matrix of autoregressive coefficients. Diagonal entries of A described density-dependence,

149 or the effect of a species' state (at time t) on its own lagged values (at $t - 1$). Off-diagonals
150 represented cross-dependencies that could provide useful biological insights into interspecific
151 interactions. For example, the entry in $A[2,3]$ described the effect of species 3's state at time $t - 1$
152 on the current state for species 2 (at time t). To encourage stability and prevent forecast variance
153 from increasing indefinitely, we enforced stationarity following methods described in Heaps (2023).
154 Briefly, a multistep process mapped the constrained A matrix to unconstrained partial
155 autocorrelations P . Process errors were allowed to be contemporaneously dependent to capture
156 any unmodelled correlations. Priors are shown in Figure 2 and described in the accompanying R
157 code.

158

159 **Do multi-species dependencies improve predictions?**

160 We tested whether learning from multiple species improved our model's predictions using model
161 comparisons. To do so, we estimated a series of benchmark models that acted as natural
162 simplifications of the **GAM-VAR** by eliminating multi-species components in a stepwise manner. The
163 first benchmark model used the same HGAM linear predictor as the **GAM-VAR** but replaced the
164 multi-species VAR(1) dynamics with an AR(1) process. This model (called **GAM-AR** in subsequent
165 sections) eliminated the covariances and temporal cross-dependencies among species' latent states,
166 allowing us to ask whether the multivariate dynamic component was supported for improving model
167 fit. Next, we further simplified the **GAM-AR** by removing the hierarchical environmental response
168 functions from the linear predictor. This forced the model to learn environmental responses for each
169 species without using information from other species in the data (**GAM-AR no pooling**). The final
170 benchmark, referred to as **AR**, also used independent AR(1) states but removed the GAM
171 component entirely. Because this model only learned from past observations, comparisons against it
172 helped us understand how covariates impacted predictions and inferences. Each candidate model
173 was trained on all observations (through August 2022, $N = 319$ timepoints). Models were then

174 compared using Pareto-smoothed importance sampling leave-one-out cross-validation (PSIS-LOO), a
175 method that reweights posterior draws to estimate leave-one-out pointwise prediction accuracy
176 using Estimated Log Predictive Density (ELPD) values (Vehtari et al. 2017).

177 Benchmarking against simpler models is also useful for forecast evaluation (Simonis et al.
178 2021). To evaluate forecasts in a way that respected the temporal nature of our forecasting exercise,
179 we used exact leave-future-out cross-validation in an iterative expanding window framework.
180 Models were re-trained on the first 273 time points (~22 years), with the subsequent 12 time points
181 (through November 2019; selected to avoid a large sampling gap due to the COVID-19 pandemic)
182 used to evaluate forecasts. This allowed us to gauge how models might perform in a forecast
183 scenario, but it only provided a single comparison. To further scrutinize models, we retrained models
184 on the first 75, 115, 154, 194, and 233 observations, and evaluated the subsequent 12 observations
185 in each cross-validation fold. All comparisons used an evenly weighted combination of two proper
186 multivariate scoring rules. We chose the variogram score, which penalizes distributions that do not
187 adequately capture correlations in test observations, and the energy score, which ignores
188 correlations but penalizes forecasts if they are not well-calibrated (Scheuerer and Hamill 2015).

189

190 **Estimation**

191 We estimated posterior distributions with Hamiltonian Monte Carlo in Stan (Carpenter et al. 2017)
192 using the *cmdstanr* interface (Gabry and Češnovar 2021). Stan's superior diagnostics guided us to a
193 model that could be reliably estimated, which included deviation functions for the four most
194 frequently captured species (*D. ordii*, *D. merriami*, *Onychomys torridus* and *C. penicillatus*).
195 Posteriors were processed in R 4.3.1 (R Core Team 2020) with the *mvgam* R package (Clark and Wells
196 2023). Traceplots, rank normalized split- \hat{R} and effective sample sizes interrogated convergence of
197 four parallel chains. Each chain was run for 500 warmup and 1600 sampling iterations. R code to

198 replicate analyses and produce Figures is included in the Supplementary materials and will be
199 permanently archived on Zenodo on acceptance.

200

201 **RESULTS**

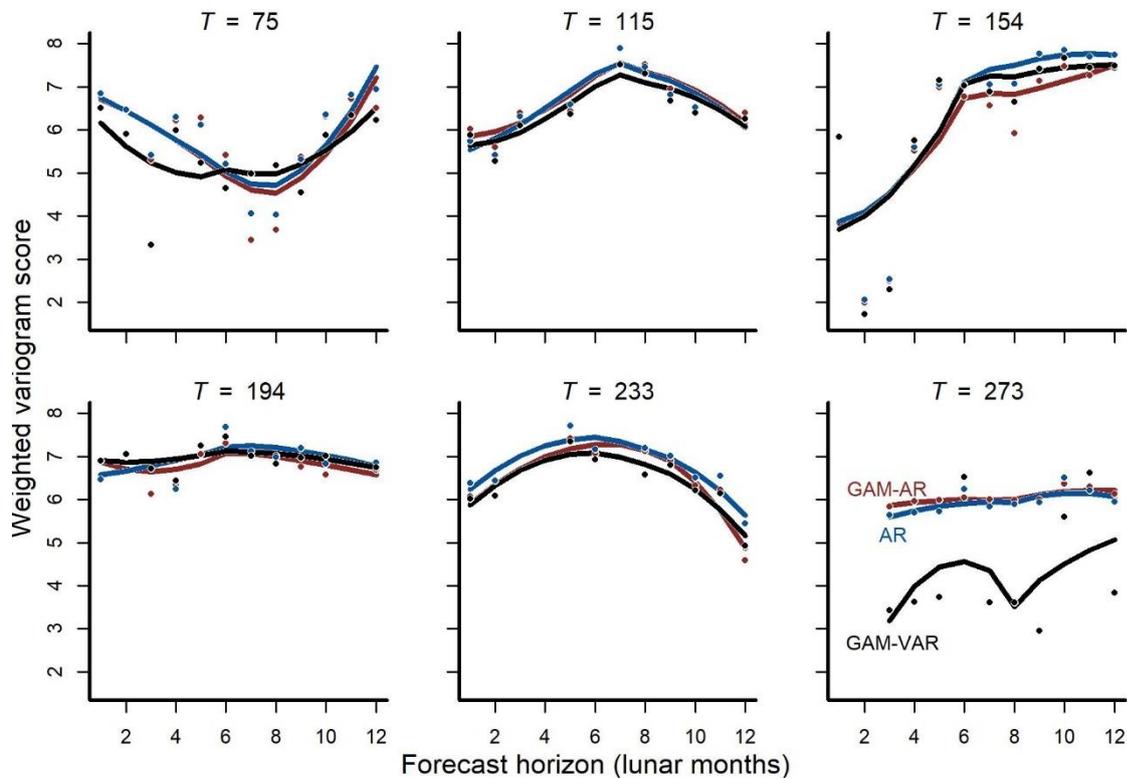
202 **Modeling relationships among species improves prediction performance**

203 Our data included total captures for nine rodent species over 319 time points. All models showed
204 adequate convergence and posterior exploration, and randomized quantile residuals showed no
205 obvious evidence of unmodelled systematic variation (Figures S6 – S7). In-sample performances
206 differed among models, with models that leveraged multi-species information producing higher
207 ELPD's than simpler models (Table 1). This was the case for all stepwise comparisons apart from one:
208 although the **GAM-AR**, which used partial pooling to learn species' environmental responses, was
209 favoured over the simpler **GAM-AR no pooling**, overlapping ELPD standard errors suggested there
210 was large uncertainty about the magnitude of this difference (Table S1).

211 Forecast performance also differed among models, with more complex multi-species models
212 again tending to outperform simpler models. Forecasts from the multi-species **GAM-VAR** were the
213 most accurate when considering all validation points in aggregate and for 4 / 6 cross-validation folds
214 (Figure 3; Figure S8). The **GAM-AR** and **GAM-AR no pooling** models gave similar predictions and
215 effectively tied for second in forecast performance, giving the most accurate forecasts in 2 / 6 cross-
216 validation folds (Figure 3). The simplest **AR** model gave the worst forecasts.

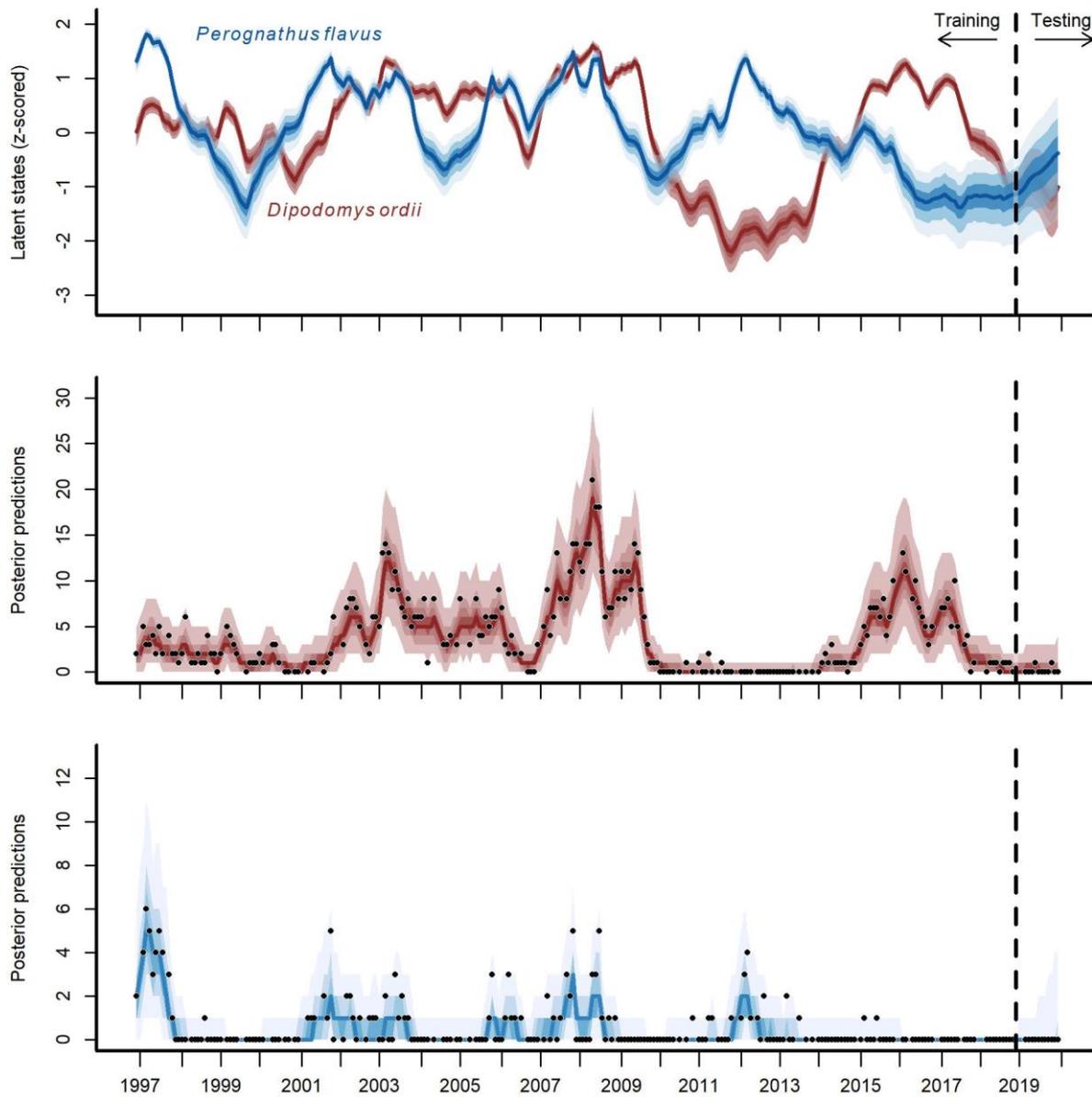
217 The **GAM-VAR** model estimated large, positive autoregressive coefficients for most species
218 (diagonal entries in Figure S9). It also relied strongly on information from multiple species by
219 estimating many non-zero cross-dependence effects (off-diagonal entries in Figure S9) and process
220 error correlations (Figure S10), which provided structure that the model leveraged to accurately
221 simulate historical dynamics. The model recovered multiple notable transitions observed in the

222 time-series including a major shift in community composition around 2000 following the
 223 establishment of Bailey's pocket mouse *C. baileyi*, and a second restructuring that happened
 224 following a drought in 2008 – 09 (Figure S11). It was these multispecies effects that enabled the
 225 **GAM-VAR** to produce more accurate forecasts. For example, Ord's kangaroo rat (*D. ordii*) and silky
 226 pocket mouse (*P. flavus*) had negative cross-dependencies, providing structure that the model used
 227 to make predictions (Figure 4). The benchmarks, which ignored this structure, produced smoother,
 228 less synchronous trends and wider uncertainties (Figure S12). Next, we use simulations to interpret
 229 the multi-species effects that allowed the **GAM-VAR** to outperform simpler models.



230

231 **Figure 3:** Forecast performances for three of the competing models (we do not show metrics for the
 232 **GAM-AR no pooling** model as they were not distinguishable from the **GAM-AR** metrics). Y-axis
 233 shows the log of the weighted variogram score, a scoring rule that penalizes multivariate forecasts if
 234 they are not well calibrated and do not capture inter-series correlations (lower scores preferred). 12-
 235 step ahead predictions were evaluated over six evenly spaced origins. Points show individual scores.
 236 Lines show Loess smoothed trend lines. Missing points indicate a missing observation.



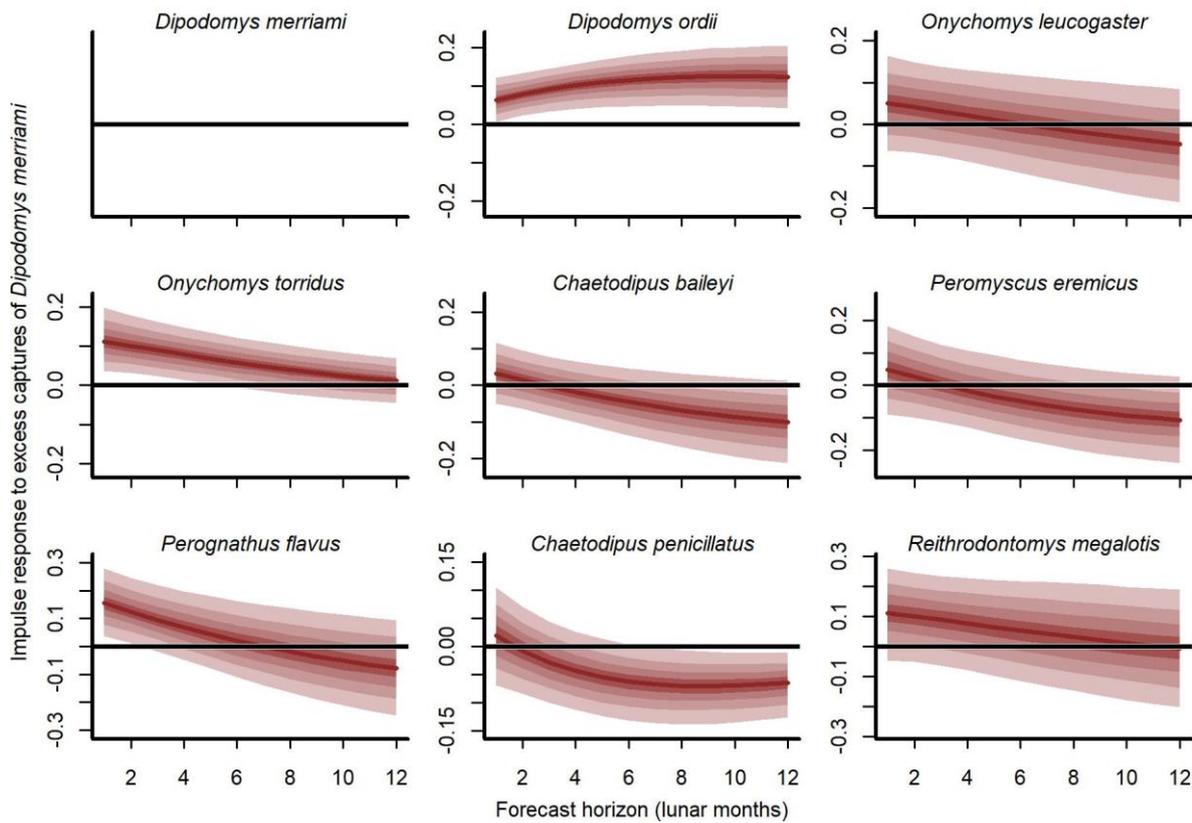
238

239 **Figure 4:** Posterior state estimates (top panel) and posterior predictions (bottom two panels) from
 240 the **GAM-VAR** model for Ord's kangaroo rat (*Dipodomys ordii*; in red) and silky pocket mouse
 241 (*Perognathus flavus*; in blue) for training and testing periods (demarked by the dashed line). State
 242 estimates were standardized for comparisons. Shading shows quantiles (90th, 60th, 40th and 20th).
 243 Dark lines show posterior medians. Points show observations.

244

245 **Species relationships provide new insights into community dynamics**

246 Our cross-validation metrics strongly favoured the **GAM-VAR** and suggested that the multivariate
247 dynamic component was a particularly important driver of increased performance. Estimates of
248 process error were larger for the benchmarks than the **GAM-VAR** for nearly all species (Figure S13).
249 But interpreting this cross-dependence is difficult because VAR effects provide only a marginal view
250 into a complex network of conditional associations. We used impulse response functions (Lütkepohl
251 1990) to better understand the model. These functions involve simulating an ‘impulse’ in captures
252 for one species and then evaluating how predicted captures for other species changed over the next
253 six months (Figure 5). Following a simulated impulse of three extra captures for Merriam’s kangaroo
254 rat (*D. merriami*), the model expected some initial increases (due to the correlated process errors)
255 followed by declines in captures for most of the other species (Figure 5). The shapes of these
256 declines varied by species. Captures for the two pocket mouse species (*C. baileyi* and *C. penicillatus*)
257 showed more immediate declines, while the two grasshopper mouse species (*O. leucogaster* and *O.*
258 *torridus*) declined more gradually (Figure 5). In contrast, the other kangaroo rat species (*D. ordii*) was
259 expected to increase following a *D. merriami* pulse (Figure 5). Different effects were expected when
260 changing the focal species (Figure S14).



261

262 **Figure 5:** Impulse responses showing how mean captures (μ , on the log scale) are expected to
 263 change over the next six months if three additional *D. merriami* individuals are captured. Ribbons
 264 show quantiles (90th, 60th, 40th and 20th). Dark red lines show posterior medians.

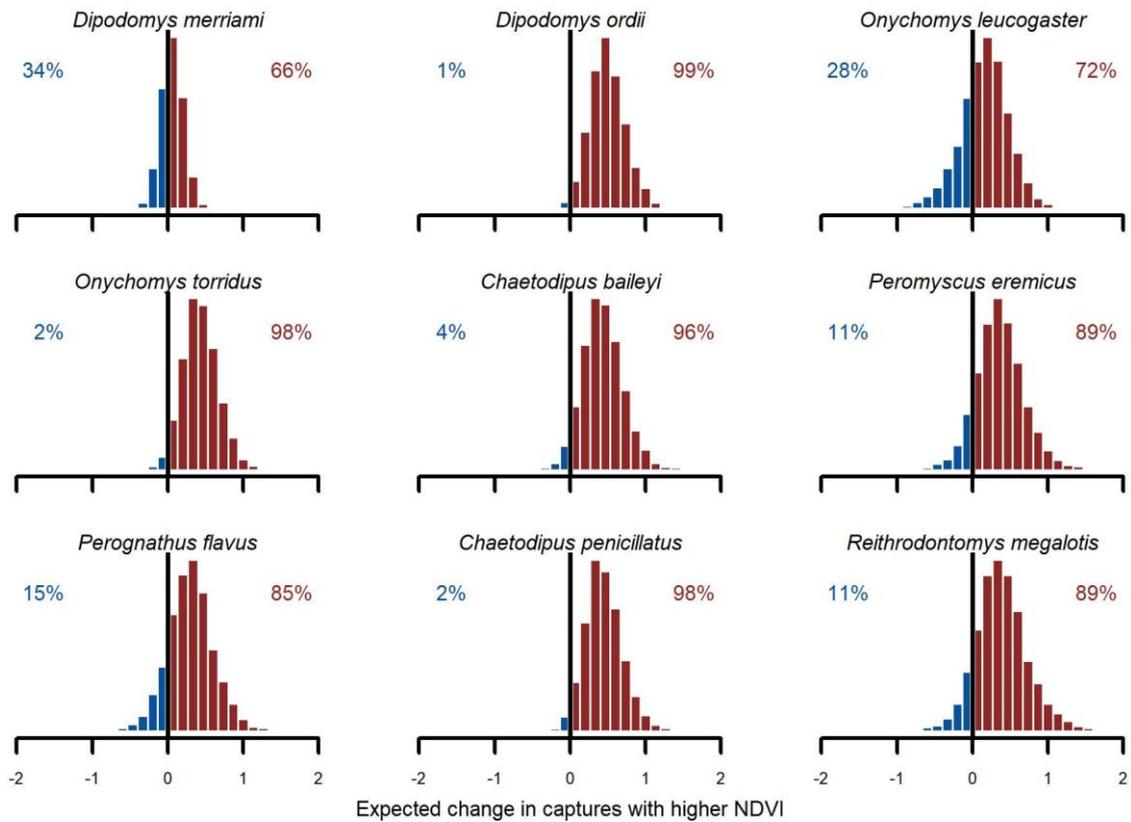
265

266 **Positive NDVI associations and hierarchical minimum temperature effects**

267 We found broad support for positive $NDVI_{MA12}$ associations (Figure 6). Conditional simulations,
 268 which asked how rodents might respond if moved from a relatively dry/brown vegetation state to a
 269 relatively moist/green vegetation state, gave higher probability to increased captures in the
 270 moist/green scenario for all species. But uncertainties varied. Greatest increases were expected for
 271 Ord's kangaroo rat (*D. ordii*), Western harvest mouse (*R. megalotis*) and cactus mouse (*Peromyscus*
 272 *eremicus*). The model was less confident about the direction of effect for Northern grasshopper
 273 mouse (*O. leucogaster*) and for Meriam's kangaroo rat (*D. merriami*). For these species, the model
 274 expected increases in ~70% of simulations and decreases in ~30% (Figure 6). While conclusions were

275 generally similar when using the **GAM-AR no pooling** model, which did not leverage multi-species
 276 learning, estimates were much more variable (Figure S15).

277



278

279 **Figure 6:** Posterior NDVI contrasts from the **GAM-VAR** model. Histograms illustrate how expected
 280 captures would change if the z-scored NDVI 12-month moving average changed from a relatively low
 281 value (-0.50) to a relatively high value (0.50). Numbers indicate the proportion of probability mass at
 282 or below zero (in blue) vs above zero (in red).

283

284 We interpreted minimum temperature distributed lag effects by simulating functions for
 285 each species using temperatures from 1997 (Figure S15). There was uncertainty in function shapes
 286 for all species except desert pocket mouse (*C. penicillatus*). Captures for this species were expected
 287 to increase from May to October and decrease sharply in winter. For seven of the other eight
 288 species, the model expected more captures in spring (March – May) and fewer in late summer /

289 autumn (July – October). But the shapes of these responses varied. Kangaroo rats (*D. merriami* and
290 *D. ordii*) had smoother shapes that decreased gradually from mid-summer to mid-winter, while the
291 Southern grasshopper mouse (*O. torridus*) was expected to show higher captures in late autumn /
292 early winter (Figure S16). The five species that relied solely on the shared function (*O. leucogaster*, *C.*
293 *baileyi*, *P. eremicus*, *P. flavus* and *R. megalotis*) were expected to show tighter spring peaks and
294 autumn troughs. When simulating from the **GAM-AR no pooling** model, the lack of multi-species
295 learning was obvious. There was not enough information to learn nonlinear functions for these
296 species, with the model estimating flat functions centred on zero for all five species (Figure S17).

297

298 **DISCUSSION**

299 Understanding and predicting change in species abundances requires models that capture realistic
300 biotic structure and address data complexities (Hampton et al. 2013, Holmes et al. 2014). Our results
301 show that incorporating relationships between species to estimate temporal dependence, and to
302 learn non-linear associations with environmental drivers, yields better model fits and more accurate
303 predictions. In addition to improved forecasts, incorporating these multi-species complexities
304 provides opportunities for interpretation that are not possible with simpler models. Our dynamic
305 VAR process uncovered biotic structure representing a cascading network of relationships within the
306 community. Captures for all species increased with higher NDVI and responded nonlinearly to
307 temperature change, but the shapes and magnitudes of these responses differed across species.
308 Models that describe biological complexity, both through nonlinear covariate functions and multi-
309 species dependence, are useful for asking targeted questions about drivers of change.

310

311 **Leveraging relationships between species**

312 Our analyses show why models that target multi-species effects should be prioritized to study
313 community dynamics. The **GAM-VAR**'s process variance estimates were smaller than those from the
314 benchmarks because it used more information from the data. By learning relationships between
315 species the model could better capture both shared responses to environmental factors (e.g., a wet
316 year is good for most species) and direct temporal effects (e.g., competition for seeds). Simulations
317 provided deeper insights into multi-species population dynamics. Simulated responses to sudden
318 impulses were often delayed and nonlinear, with cascading impacts lasting up to six months. This
319 type of simulation can have many broad uses in applied ecology, for example by assessing which
320 species have the strongest cascading effects, what changes we can expect from management actions
321 targeting key species, and how these effects relate to regime transitions (Ives et al. 2003).

322

323 **Learning hierarchical nonlinear effects from community data**

324 Our model captured linear, nonlinear, and lagged responses to environmental and climatic
325 covariates that were informed by all species at once. While we cannot interpret these estimates as
326 causal, recovered relationships were consistent with operational models of the system. Positive
327 associations between capture rates and a 12-month moving average of NDVI were expected because
328 rodents at Portal depend on plants for food and resources (Ernest et al. 2000, Brown and Ernest
329 2002). But there were interesting patterns of variation in these effects. The strongest positive
330 association was shown by Ord's kangaroo rat (*D. ordii*), a species that consumes and harvests grasses
331 (Kerley et al. 1997). In contrast, Merriam's kangaroo rat (*D. merriami*) showed weaker associations
332 with NDVI. This species has been predicted to increase in prevalence with more severe droughts, in
333 part due to a preference for foraging habitat with less vegetation (Cárdenas et al. 2021).

334 Our study shows how distributed lag effects can be learned hierarchically and provides
335 useful insights into delayed responses to temperature for rodents at Portal. Most species showed
336 higher captures when temperatures were low 3 – 4 months prior, suggesting increases begin during

337 mid to late spring when resources become available. But others showed increases during cooler
338 months in autumn and winter. Asynchronous phenology, where species show different reproductive
339 timing in the presence of competition, has been reported at Portal (Dumandan et al. 2023b) and
340 may be one reason why seasonal patterns differed among species. Comparing temperature
341 responses on control vs experimental plots may help to determine if these competitive forces play a
342 role in seasonal capture variation.

343 Despite the large number of observations in our data, estimates of environmental responses
344 were more precise when they were learned from all species jointly. This strongly supports the need
345 for hierarchical models in ecology. But while hierarchical intercepts and slopes are common, there
346 has been less emphasis on hierarchical nonlinear functions (but see Pedersen et al. 2019). Open
347 access to software that makes it easy to construct and estimate these types of functions, such as the
348 *mvgam* R package that we used here (Clark and Wells 2023), should improve their uptake in
349 ecological forecasting.

350

351 **Future directions**

352 As ecosystems undergo shifts in species composition (e.g. Dornelas et al. 2014), integrating species
353 relationships into forecasting models may become increasingly important. Recent work leveraging
354 the Portal Project's long-term experimental manipulations shows that single-species models can
355 perform poorly when transferred to novel biotic contexts (i.e., between controls and manipulations
356 Dumandan et al. 2023a). This suggests that in ecosystems undergoing biotic reorganization single-
357 species models may be insufficient for predicting future populations, even if such models perform
358 well under current conditions. By considering species relationships, multi-species models like the
359 **GAM-VAR** have the potential to transfer better into situations where composition is changing – an
360 assumption that can be tested using the experimental plots at Portal.

361 More broadly, we hope that estimating multi-species dependencies will result in more
362 accurate forecasts, inspire new questions, and lead to an improved understanding of the factors that
363 govern ecological community dynamics. The combination of long-term monitoring, manipulative
364 experiments, and models that capture real-world biological complexities provide a framework for
365 advancing both our understanding of ecological systems and our ability to forecast their dynamics.

366

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375 White.

376

377 **SUPPORTING INFORMATION CAPTIONS**

378 **Figure S1:** Total rodent captures from the Portal Project for the period December 1996 to August
379 2022. Counts represent total captures for nine species across long-term control plots, sampled at
380 each cycle of the lunar moon. Blanks represent missing values.

381 **Figure S2:** Autocorrelation functions of rodent capture time series in the Portal Project. Dashed lines
382 show values beyond which the autocorrelations are considered significantly different from zero.

383 **Figure S3:** Histograms of rodent capture time series in the Portal Project. Counts represent total
384 captures across long-term control plots, sampled at each cycle of the lunar moon.

385 **Figure S4:** Seasonal and Trend decomposition using Loess smoothing (STL) applied to observed
386 minimum temperature time series for the period December 1996 – August 2022. The top panel
387 shows the raw time series. The middle plot shows the estimated long-term trend (calculated using a
388 Loess regression to the de-seasoned time series). The bottom plot shows the time-varying estimate
389 of seasonality (calculated using a Loess regression that smooths across years).

390 **Figure S5:** Top panel: observed Normalized Difference Vegetation Index (NDVI) time series for the
391 period December 1996 – August 2022, with obvious seasonal fluctuations. Bottom panel: a 12-
392 month moving average that represents smooth, gradual changes in NDVI at the study site.

393 **Figure S6:** Autocorrelation functions of randomized quantile residuals from the **GAM-VAR** model.
394 Ribbon shading shows posterior empirical quantiles (90th, 60th, 40th and 20th). Dark red lines show
395 posterior medians. Dashed lines show values beyond which the autocorrelations would be
396 considered significantly different from zero in a Frequentist paradigm.

397 **Figure S7:** Normal quantile-quantile plots of randomized quantile residuals from the **GAM-VAR**
398 model. Ribbon shading shows posterior empirical quantiles (90th, 60th, 40th and 20th). Dark lines show
399 posterior medians.

400 **Figure S8:** Posterior predictions from the **GAM-VAR** model for the training and testing periods
401 (demarcated by the vertical dashed line). Latent state estimates were scaled to unit variance for
402 comparisons. Ribbon shading shows posterior empirical quantiles (90th, 60th, 40th and 20th). Dark
403 lines show posterior medians. Points show observations.

404 **Figure S9:** Posterior distributions of vector autoregressive coefficients (matrix **A**). Off-diagonals
405 represent cross-dependencies. For example, the entry in **A**[1, 2] captures the effect of **DO**'s state at
406 time $t - 1$ on the current state estimate for **DM** (at time t). Diagonals (with grey shading) represent
407 autoregressive coefficients (the effect of a species' state at time $t - 1$ on its own state at time t).
408 Colours indicate the proportion of probability mass at or below zero (in blue) vs above zero (in red).
409 **DO**, *Dipodomys merriami*; **DO**, *Dipodomys ordii*; **OL**, *Onychomys leucogaster*; **OT**, *Onychomys*
410 *torridus*; **PB**, *Chaetodipus baileyi*; **PE**, *Peromyscus eremicus*; **PF**, *Perognathus flavus*; **PP**, *Chaetodipus*
411 *penicillatus*; **RM**, *Reithrodontomys megalotis*.

412 **Figure S10:** Posterior distributions for process error correlations (matrix **C**). Colours indicate the
413 proportion of probability mass at or below zero (in blue) vs above zero (in red). **DO**, *Dipodomys*
414 *merriami*; **DO**, *Dipodomys ordii*; **OL**, *Onychomys leucogaster*; **OT**, *Onychomys torridus*; **PB**,
415 *Chaetodipus baileyi*; **PE**, *Peromyscus eremicus*; **PF**, *Perognathus flavus*; **PP**, *Chaetodipus penicillatus*;
416 **RM**, *Reithrodontomys megalotis*.

417 **Figure S11:** Simulated rodent communities. Using the **GAM-VAR** model's posterior predictive
418 distribution, we simulated communities of 200 individuals at different timepoints to investigate how
419 well the model captured known community transitions. Colours represent different species

420 **Figure S12:** Posterior trend estimates from three competing models for Ord's kangaroo rat
421 (*Dipodomys ordii*; in red) and silky pocket mouse (*Perognathus flavus*; in blue). Trends were scaled to
422 unit variance for comparisons. Ribbon shading shows posterior empirical quantiles (90th, 60th, 40th
423 and 20th). Dark lines show posterior medians.

424 **Figure S13:** Posterior estimates of trend standard deviations from the three competing models.
425 Estimates are the square root of diagonal parameters from the trend covariance matrix (Σ_{VAR}) for
426 the **GAM-VAR** (black), **GAM-AR** (red) and **AR** (blue).

427 **Figure S14:** Expected responses to a pulse in captures of the desert pocket mouse (*Chaetodipus*
428 *penicillatus*). Ribbon plots show how mean captures (μ , on the log scale) are expected to change
429 over the next six months if three additional *C. penicillatus* individuals are captured. Ribbon shading
430 shows posterior empirical quantiles (90th, 60th, 40th and 20th). Dark red lines show posterior
431 medians.

432 **Figure S15:** Posterior NDVI contrasts from the independent slopes component of the **GAM-AR no**
433 **pooling** model. Histograms illustrate how much the expected number of captures, $exp(\mu)$, would
434 change if the z-scored NDVI 12-month moving average ($NDVI_{MA12}$) changed from a relatively low
435 value (-0.50) to a relatively high value (0.50). Numbers in each plot indicate the proportion of
436 probability mass at or below zero (in blue) vs above zero (in red).

437 **Figure S16:** Conditional distributed lag minimum temperature functions from the hierarchical
438 smooth component of the **GAM-VAR** model, using temperatures observed in 1997. All other effects
439 were ignored. Functions for *O. leucogaster*, *C. baileyi*, *P. eremicus*, *P. flavus* and *R. megalotis* were
440 drawn solely from the global function. Functions for other species were the sum of the global
441 function and a species-specific deviation function. Estimates were scaled to unit variance for
442 comparisons. Ribbons show posterior empirical quantiles (90th, 60th, 40th and 20th). Dark red lines
443 show posterior medians.

444 **Figure S17:** Conditional distributed lag minimum temperature functions from the independent
445 smooth component of the **GAM-AR no pooling** model, using temperatures observed in 1997. All
446 other effects were ignored. Functions for *O. leucogaster*, *C. baileyi*, *P. eremicus*, *P. flavus* and *R.*
447 *megalotis* were drawn solely from the global function. Functions for other species were the sum of
448 the global function and a species-specific deviation function. Estimates were scaled to unit variance

449 for comparisons. Ribbons show posterior empirical quantiles (90th, 60th, 40th and 20th). Dark red lines
450 show posterior medians.

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