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6	Estimating (non)linear selection on reaction norms:
7	A general framework for labile traits
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Abstract

- Individual reaction norms describe how labile phenotypes vary as a function of organisms' expected trait values (intercepts) and plasticity across environments (slopes), as well as their degree of stochastic phenotypic variability or predictability (residuals). These reaction norms can be estimated empirically using multilevel, mixed-effects models and play a key role in ecological research on a variety of behavioral, physiological, and morphological traits. Many evolutionary models have also emphasized the importance of understanding reaction norms as a target of selection in heterogeneous and dynamic environments.
- However, it remains difficult to empirically estimate nonlinear selection on reaction norms,
 inhibiting robust tests of adaptive theory and accurate predictions of phenotypic evolution.
 To address this challenge, we propose generalized multilevel models for estimating
 stabilizing, disruptive, and correlational selection on the reaction norms of labile traits,
 which can be applied to any repeatedly measured phenotype using a flexible Bayesian
 framework.
- 39 3. Our modelling approach avoids inferential bias by simultaneously accounting for
 40 uncertainty in reaction norm parameters and their potentially nonlinear fitness effects. We
 41 formally introduce these nonlinear selection models and provide detailed discussion on
 42 their interpretation and potential extensions. We then validate their application in a
 43 Bayesian framework using simulation-based calibration and power analyses.
- 4. We find that our models facilitate unbiased Bayesian inference across a broad range of
 effect sizes and desirable power for hypothesis tests with large sample sizes. Coding
 tutorials are further provided to aid empiricists in applying these models to any phenotype
 of interest using the Stan statistical programming language in R. The proposed modeling
 framework should, therefore, readily enhance tests of adaptive theory for a variety of labile
 traits in the wild.

50 Keywords:

51 phenotypic evolution, complex trait, multivariate, adaptation, personality, flexibility

Introduction

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53 A population will evolve by natural selection whenever heritable variation occurs in fitness-54 relevant phenotypes (Darwin 1859). Measuring the fitness consequences of individual differences 55 in highly labile behavioral, physiological, and morphological traits is, therefore, fundamental for 56 explaining their adaptive evolution. Across a variety of phenotypes and taxa, repeatable individual 57 differences have been observed in organisms' average trait values (Bell, Hankison, & Laskowski 58 2009; Fanson & Biro 2015; Cauchoix et al. 2018) and in their plasticity across environments 59 (Dingemanse et al. 2010; Stamps 2016; Arnold, Nicotra, & Kruuk 2019), with some individuals 60 consistently being more or less responsive to environmental change than others. In addition, it is 61 increasingly appreciated that individuals may repeatably differ in their degree of stochastic 62 phenotypic variability within a given environment (see **Box 1** below for a conceptual overview; 63 Biro & Adriaenssens 2013; Westneat, Schofield, & Wright 2013; Mitchell, Beckmann, & Biro 64 2021), a phenomenon which has often been ignored in ecological research (Hansen, Carter & 65 Pélabon 2006). These individual-specific patterns reflect distinct but potentially integrated parameters (intercepts, slopes, and within-individual residuals) of the reaction norms (RNs, i.e. 66 state-dependent functions relating phenotype to environment, **Table 1**) evolving in a population 67 68 (Figure 1). RN models provide a highly generalizable, guantitative framework for investigating the 69 evolution and development of labile traits, with broad applications ranging from social behaviors 70 (Dingemanse & Araya-Ajoy 2015; McNamara & Leimar 2020; Martin, Jaeggi, & Koski, 2023) and 71 learning processes (Wright, Haaland, Dingemanse, & Westneat 2022) to thermal performance 72 curves (Svensson, Gomez-Llano, & Waller 2020) and extended phenotypes (Munar-Delgado, 73 Araya-Ajoy, & Edelaar, 2023), such as gall size in insect-host plant interactions (Weis & Gorman 74 1990). Interest in the evolutionary ecology of RNs has grown steadily across a diverse range of 75 fields in recent decades (e.g. Brommer, Kontiainen, & Pietiäinen 2012; Strickland et al. 2021; 76 Newediuk, Prokopenko, & Wal 2022), generating methodological innovations for estimating RNs 77 subject to measurement error (e.g. Nussey, Wilson, & Brommer 2007; Dingemanse & 78 Dochtermann 2013; Gomulkiewicz et al. 2018; O'Dea, Noble, & Nakagawa 2021; Martin & Jaeggi 79 2022), as well as theoretical models for explaining the selection pressures shaping and 80 maintaining individual variation in RNs within populations (e.g. Wolf & Weissing 2010; Dall & 81 Griffith 2014; Sih et al. 2015; Wright et al. 2019). Attention to RNs has also increased in related fields of inquiry such as personality psychology (Denissen & Penke 2008; Nettle & Penke 2010) 82 83 and evolutionary anthropology (Jaeggi et al. 2016).

84 RN models are not only useful statistical tools for describing phenotypic variation. Classic 85 theoretical models often assumed that selection acted independently on phenotypes expressed 86 in discrete states of the environment (so-called character states), where the evolution of RN 87 parameters and thus phenotypic plasticity across environments was interpreted as a byproduct 88 of state-specific selection (Via & Lande 1985; Gomulkiewicz & Kirkpatrick 1992). Many biologists 89 disagreed with this perspective on empirical and theoretical grounds, resulting in historical 90 debates about whether RN parameters should be conceptualized as direct or indirect targets of 91 natural selection (Gavrilets & Sheiner 1993; Scheiner 1993a; Via et al. 1995; Nicoglou 2015). 92 Fortunately, this disagreement is now largely resolved (Futuyma 2021), with evolutionary 93 quantitative genetic theory demonstrating the mathematical equivalence and thus conceptually 94 complementarity of models emphasizing selection on expressed character states or the RNs 95 producing them (de Jong 1995). As such, many contemporary evolutionary frameworks 96 emphasize RNs parameters (intercepts, slopes, and residuals) and their underlying mechanisms 97 as putative targets of selection, leading to differential patterns of adaptation and extinction in 98 changing environments (Schlichting & Piglucci 1998; Ghalambor, McKay, Carroll, & Reznick 99 2007; Fox et al. 2019). For instance, evolutionary ecologists have long investigated the unique 100 role of both cue-induced and stochastic phenotypic plasticity in the colonization of novel habitats 101 (Caño et al. 2008; Volis, Ormanbekova, & Yermekbayev 2015; Hendry 2016; Wang & Althoff 102 2019). In addition, evolutionary geneticists have shown how plasticity in social environments can 103 magnify heritable variation in mean trait values, accelerating or inhibiting phenotypic evolution in 104 comparison to unresponsive phenotypes (Moore et al. 1997; Bijma & Wade 2008; McGlothlin et 105 al. 2010; Kazancioğlu, Klug, & Alonzo 2012). Game theorists and behavioral ecologists have 106 further emphasized the importance of understanding selection on RNs due to the prevalence of 107 fluctuating density- and frequency-dependent selection in social environments (Araya-Ajoy, 108 Westneat, & Wright 2020; McNamara & Leimar 2020; Martin, Jaeggi, & Koski 2023), as well as 109 the role of dynamic environments more generally in selecting for learning mechanisms and 110 emotional states rather than specific behaviors per se (Skinner, 1966; Henrich & McElreath 2003; 111 McNamara & Houston 2009; Fawcett, Hamblin, & Giraldeau 2013; Nakahashi & Ohtsuki 2015; 112 Wright et al. 2022). Distinct genetic control of phenotypic stability and change has also been 113 experimentally demonstrated for diverse phenomena from cold tolerance (Ørsted, Rohde, 114 Hoffmann, Sørensen, & Kristensen 2018) to body size (Scheiner & Lyman, 1991) and various 115 forms of developmental polyphenism (Suzuki & Nijhout 2006; Projecto-Garcia, Biddle, Ragsdale 116 2017), suggesting that differential selection on heritable variation in RN intercepts, slopes, and 117 residuals, as well as differential patterns of genetic integration between RN parameters (Wagner,

118 Booth, & Bagheri-Chaichian, 1997; Tonsor, Elnaccash, & Scheiner, 2013), can in turn have 119 distinct consequences for the evolutionary response to selection (de Jong 1995: Martin et al. 120 2024). Accordingly, divergence has been observed in the RNs of many naturally occurring 121 populations, such as differential plasticity in the growth rates of phytoplankton (Thalassiosira 122 pseudonana; Schaum, Buckling, Smirnoff, & Yvon-Durocher 2022), ponderosa pine (Pinus 123 ponderosa; de la Mata et al. 2022) and single-leaf pinyon (Pinus monophylla; Vasey, Weisberg, 124 & Urza 2022) populations in response to temperature fluctuations and microhabitat heterogeneity. 125 Despite this strong theoretical emphasis and empirical basis, robust statistical methods have not 126 yet been developed for detecting complex patterns of selection on the RNs of labile traits.

127 Many of the phenotypes commonly studied by evolutionary ecologists are highly labile (i.e. 128 exhibit high degrees of reversible plasticity; Scheiner, 1993b) in response to the local 129 environment. This means that repeatable individual differences in the RN underlying these traits 130 tend to account for only a modest proportion of the total variation observed in measurements 131 across space and time (Bell, Hankison, & Laskowski 2009; Fanson & Biro 2015; Cauchoix et al. 132 2018). This is expected, given that labile traits are often adapted to facilitate flexible responses 133 toward fitness-relevant variation in the environment (Scheiner 1993b), such as by up-regulating 134 circulating testosterone in response to social challenges (Wingfield et al. 1990; Eisenegger, 135 Haushofer, & Fehr 2011), temporarily inducing a fear state in response to odor cues of predation 136 (Mathuru et al. 2012), or regulating alloparental care in response to the quality of the local 137 environment (Guindre-Parker & Rubenstein, 2018; Martin et al. 2020). Conversely, labile traits 138 may also be prone to maladaptive plasticity in response to novel or extreme environmental 139 stressors (e.g. Ghalambor et al. 2015). As such, single measures of labile phenotypes tend to 140 reflect within- rather than among-individual variation, potentially biasing empirical estimates of 141 trait (co)variances and selection gradients estimated across heterogeneous environments 142 (Brommer 2013; Dingemanse & Dochtermann 2013; Niemelä & Dingemanse 2018; Royauté et 143 al. 2018), leading to inaccurate inferences about adaptive evolution (Dingemanse, Araya-Ajoy, & 144 Westneat 2021; Martin & Jaeggi 2022). Classical approaches such as the Lande and Arnold 145 (1983) regression framework do not partition repeatable and non-repeatable differences across 146 phenotypic measurements and, as a consequence, may lead to downwardly biased estimates of 147 selection gradients for labile traits in field research (Dingemanse et al. 2021). Classical methods 148 can also be biased by unmeasured, within-individual environmental effects on fitness and 149 phenotype that generate spurious signals of selection (Scheiner et al. 2002; Stinchcombe et al. 150 2002). Using these methods to estimate selection on labile traits with single measures, averages

of raw data, or point estimates in multi-stage analyses can, therefore, increase the risk of biased
 evolutionary inference (Hadfield et al. 2010), particularly when attempting to understand the
 adaptation of RNs underlying observed phenotypes across environments.

154 Fortunately, generalized linear mixed-effects models (GLMMs) provide a flexible toolkit for 155 estimating RNs from empirical data, as well as for modelling the effects of RNs on fitness and 156 other biological outcomes of interest. Current variance-partitioning methods rely on the use of 157 multi-response/multivariate GLMMs with covarying random effects to model selection, which 158 effectively account for uncertainty in individuals' RNs and their estimated effects (Hadfield et al. 159 2010). This approach has been repeatedly introduced to selection studies of RNs in variety of 160 contexts, demonstrating its broad applicability (e.g. Brommer, Kontiainen, & Pietiäinen 2012; 161 Houslay & Wilson 2017; Arnold, Nicotra, & Kruuk 2019), and can be further extended to provide 162 a veritable treasure chest of biological insights (Blows 2007). For example, such models can be 163 used to identify trajectories of phenotypic conservation and divergence among closely related 164 populations (Royauté, Hedrick, & Dochtermann 2020), discover latent behavioral characters 165 among multiple traits (Araya-Ajoy & Dingemanse 2014; Martin et al. 2019), or calculate genetic 166 responses to directional selection (Stinchcombe, Simonsen, & Blows 2014). Therefore, multi-167 response GLMMs with covarying random effects can be used to accomplish many empirical goals 168 with relative ease, while also avoiding statistical bias due to uncertainty in RNs.

169 Despite their benefits, these commonly used GLMMs cannot detect nonlinear selection on 170 RNs (i.e. disruptive, stabilizing, and correlational selection) because the random effect covariance 171 is defined as an average measure of linear dependency among fitness and phenotype. By failing 172 to describe the curvature of the adaptive landscape, and thus the ecological phenomena 173 generating fitness saddles, ridges, domes, and cliffs (Lande & Arnold, 1983; Blows & Brooks, 174 2003; Blows 2007; Vercken et al., 2012), random effect models can provide an incomplete and 175 potentially misleading perspective on the biological processes driving and constraining 176 multivariate evolution. In non-randomized experiments or field settings, ignoring nonlinear 177 selection can further generate biased estimates of directional selection gradients, in addition to 178 biased predictions of the evolutionary response to selection on the expectations and 179 (co)variances of RN parameters (Arnold et al., 2001; Morrissey et al., 2012; Pick et al., 2022). Therefore, despite their clear utility, current covarying random effects models can also limit robust 180 181 tests of adaptive theory, which often predicts that stabilizing, disruptive, and/or correlational 182 selection will shape RN evolution (e.g. Wagner et al., 1997; Gavrilets & Hastings, 1994). This

inhibits accurate predictions of phenotypic evolution more generally (Bulmer 1971; Lande &
Arnold 1983; Arnold, Pfrender, & Jones, 2001; Villemereuil et al., 2020).

185 Here we address this challenge by introducing multi-response/multivariate GLMMs for 186 unbiased estimation of nonlinear selection on RNs, building on well-established approaches to 187 estimating linear selection (e.g. Brommer, Kontiainen, & Pietiäinen 2012; Houslay & Wilson 2017; 188 Arnold, Nicotra, & Kruuk 2019; Araya-Ajoy, Dingemanse, Westneat, & Wright 2023). The 189 proposed GLMMs are applicable to any labile and repeatedly measured phenotype. We begin by 190 reviewing so-called double hierarchical GLMMs for estimating RNs from longitudinal, repeated 191 measures data (Westneat, Schofield, & Wright, 2013; O'Dea et al. 2021) and formally introduce 192 multi-response/multivariate models estimating linear and nonlinear selection on RNs, applicable 193 to both Gaussian and non-Gaussian measurements. We then consider their implementation in a 194 Bayesian framework, using a simulation-based calibration procedure to validate that the proposed 195 models are unbiased for statistical inference. We also explore statistical power for Bayesian 196 hypothesis tests across a range of sampling designs and selection effect sizes. Guided tutorials 197 are further provided (see data availability) to aid researchers in implementing and interpreting 198 these models for their own data using the Stan statistical programming language (Carpenter et 199 al. 2017).

200 **Figure 1.** Empirical estimation of reaction norms. Repeatable among-individual differences $var(\eta)$ (top 201 *left*) in the expected value μ and dispersion σ of observed phenotype z can be predicted with a RN model 202 (top right) using link functions g and three (or more) distinct parameters: RN intercept parameters μ_0 203 describing each individual's average phenotype across a mean-centered environment or in the absence of 204 the environment (i.e. when the environmental state x = 0); RN slope parameters β_x describing each 205 individual's systematic change in phenotype across environmental states x; and RN residual parameters 206 σ_0 reflecting each individual's degree of stochastic variability (or, conversely, their predictability/precision) 207 in phenotype within a given environment. See Eq. 1 for index rather than matrix notation. These parameters 208 will be unknown in empirical research and must be estimated using raw measurements (teal circles) across 209 environmental states (bottom left). An example is shown for a simple linear RN with a log-link on the 210 dispersion of a normal distribution, so that an individual's residual parameter, expressed as a variance on the squared log scale sqrt $(\exp(\sigma_0 + \sigma_{0j}))$, is proportional to (\propto) the spread of observed residuals on the 211 212 original data scale, as shown here by a 95% credible interval. Failure to account for uncertainty around 213 point estimates of individual is RN parameters (bottom right) leads to anti-conservative inference and 214 increased risk of false positives (Hadfield et al. 2010).

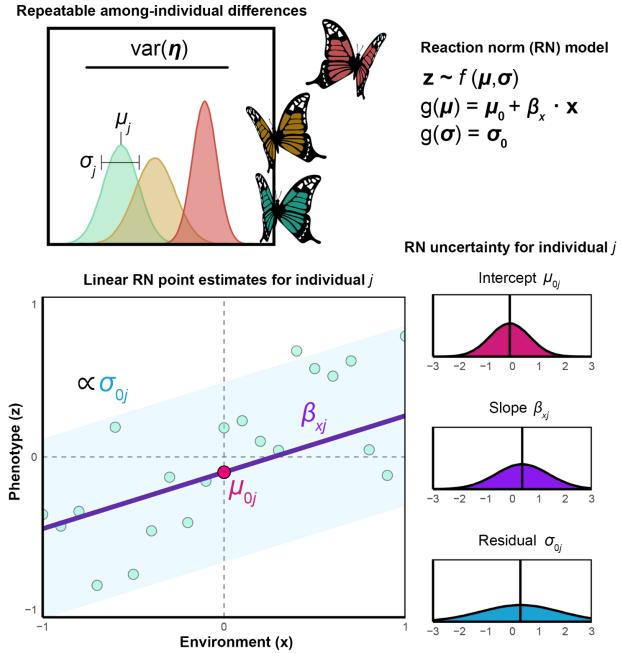


Table 1. Notation and terminology.

Term	Symbol	Description
Individual reaction norm (RN)	f(μ,σ)	A probabilistic function f with parameters predicting the expectation μ and dispersion σ of an individual's phenotype in response to a measurable aspect of the environment.
RN intercept	μ_0, μ_{0j}	The expected phenotype in the average environment or in the absence of an environmental factor. Individual RN intercept μ_{0j} is expressed as a deviation from population RN intercept μ_0 .
RN slope	β_x , β_{x_j}	The expected change in phenotype in response to a measured environment <i>x</i> . Individual RN slope β_{xj} is expressed as a deviation from the population average slope β_x .
RN residual	σ_0, σ_{0j}	The magnitude of stochastic variability in phenotype within a given environment, i.e. the inverse of predictability (O'Dea et al., 2021) and precision (Hansen et al., 2006). Individual RN residual parameter σ_{0j} is expressed as a deviation from population average residual parameter σ_0 , which together determine the magnitude of variation in observed residuals.
RN trait value/ character state	η_{jt}	The repeatable trait value predicted by individual <i>j</i> 's reaction norm being expressed within the environmental state at time <i>t</i> . This context-specific trait value is also referred to as a character state in quantitative genetics.
Repeatable among-individual differences	$\operatorname{var}(\boldsymbol{\eta})$	The total amount of among-individual variation in the phenotype available to natural selection over the sampling period, which reflects consistent individual differences in RN expression across environments (i.e. the variance of character states).
Link functions	$g_{\mu}, g_{\sigma}, g_{ heta}$	Transformations that facilitate modelling of non-Gaussian phenotypes and fitness measures on a linear scale.
Fitness	$W, f(\theta, \delta)$	A measure of an individual's observed survival, reproduction, and/or performance <i>W</i> , as predicted by the expectation θ and dispersion δ parameters of distribution <i>f</i> . These quantifiable 'fitness components' are used to approximate the repeatable, differential rate of zygote production across individuals.
Directional selection	b, β	Selection gradients β quantify the magnitude of direct selection on the population means of reaction norm parameters. Regression coefficients b approximate these effects on the transformed scale of a GLMM.
Quadratic selection	q , γ	Selection gradients γ quantify the magnitude of direct selection on the (co)variances of reaction norm parameters. Regression coefficients q approximate these effects on the transformed scale of a GLMM.
Fluctuating selection	\Deltaoldsymbol{eta} , $\Delta\gamma$	Environmental change that shifts the magnitude of selection on RNs $\Delta\beta$, $\Delta\gamma$ across space and/or time

Modelling nonlinear selection on labile traits

218 The models we propose in this section are straightforward extensions of the multi-219 response/multivariate random effects GLMMs discussed above. Our trait-based approach shifts 220 estimation of fitness effects from random effect covariances to flexibly parameterized linear and 221 nonlinear selection coefficients. This approach builds on a long tradition of measurement error 222 models in biostatistics (Loken & Gelman 2017; Ponzi et al. 2018; Martin & Jaeggi 2022), also 223 known as structural equation (Bollen & Noble 2011; Araya-Ajoy & Dingemanse 2014; Martin et 224 al. 2019) or errors-in-variables models (Dingemanse et al. 2021), which allow for latent trait values 225 such as RN intercept, slope, and residual parameters to simultaneously affect multiple response 226 models. The basic structure of these models has been previously introduced in the broader 227 context of phenotypic selection analysis by Ponzi et al. (2018), Dingemanse et al. (2021), and 228 Araya-Ajoy et al. (2023), who considered Gaussian models of selection on repeatable trait values. 229 Here, we generalize and extend these models to allow for estimating (non)linear selection on RN 230 intercepts, slopes, and residuals (and any other distributional parameters of interest), as well as 231 to estimate directional and quadratic selection gradients on RN parameters with non-Gaussian 232 phenotype and fitness measures.

233 **Reaction norm model**

234 The first step in any selection analysis is to define the trait of interest. For repeatedly 235 expressed traits that exhibit plasticity, the 'traits' of interest may be latent properties of a RN, 236 which researchers can estimate as functional parameters. As shown in Figure 1, individual 237 variation in a linear RN can be decomposed into underlying repeatable differences in individuals' 238 RN intercept μ_0 , slope β_x , and residual parameters σ_0 . Note that we use β_x here to reference 239 any slope defined over a non-social environmental state (see Martin & Jaeggi, 2022 for a 240 treatment of social effects). Table 1 provides a glossary of formal notation and terminology used 241 throughout the paper. GLMMs effectively describe the RNs of non-Gaussian phenotypes using 242 additive linear functions on a transformed latent scale (Bolker et al., 2009; Villemereuil et al., 243 2016). Extensive prior work has been done on appropriate study design and GLMM 244 implementation for RN research in evolutionary ecology (e.g. see Nussey, Wilson, & Brommer 245 2007; Martin, Nussey, Wilson, & Réale, 2010; Dingemanse & Dochtermann 2013; O'Dea et al. 246 2021 among others). Therefore, we avoid reviewing this material in detail here, instead focusing 247 on the introduction of a general form and notation for RN models of any labile trait.

248 Consider a GLMM for repeated measure t of individual j, who expressed labile phenotype 249 z_{it} in environmental state x_{it} . The distribution of measurements can be predicted using a probability function $f(\mu, \sigma)$ with mean, location, or rate parameter μ and dispersion, shape, or 250 251 scale parameter σ (e.g. as with normal, gamma, and beta distributions). Link functions g_{μ} and g_{σ} are used for modelling the vectors μ and σ across observations so that the RN parameters $\mu_0,$ 252 253 β_x , and σ_0 can be expressed as additive linear effects on a transformed scale, irrespective of the assumed distribution of the raw data. For instance, $g_{\mu} = identity(\mu)$ and $g_{\sigma} = \log(\sigma^2)$ are 254 255 sensible choices for a Gaussian measure. The generalized form of the model is given by

$$z_{jt} \sim f(\mu_{jt}, \sigma_j) \tag{1}$$

257
$$g_{\mu}(\mu_{jt}) = \mu_0 + \mu_{0j} + (\beta_x + \beta_{xj})x_t$$

258
$$g_{\sigma}(\sigma_j) = \sigma_0 + \sigma_{0_j}$$

259
$$[\boldsymbol{\mu}_0^{\mathsf{T}}, \boldsymbol{\beta}_x^{\mathsf{T}}, \boldsymbol{\sigma}_0^{\mathsf{T}}]^{\mathsf{T}} \sim \mathsf{MVN}(\boldsymbol{0}, \mathbf{P}): \mathbf{P} = \begin{bmatrix} \operatorname{var}(\boldsymbol{\mu}_0) & \dots & \dots \\ \operatorname{cov}(\boldsymbol{\beta}_x, \boldsymbol{\mu}_0) & \operatorname{var}(\boldsymbol{\beta}_x) & \vdots \\ \operatorname{cov}(\boldsymbol{\sigma}_0, \boldsymbol{\mu}_0) & \operatorname{cov}(\boldsymbol{\sigma}_0, \boldsymbol{\beta}_x) & \operatorname{var}(\boldsymbol{\sigma}_0) \end{bmatrix}$$

260 where \top indicates the transpose operator. Here μ_0 , β_{χ} , σ_0 are the average values for the RN 261 intercept, slope, and residual parameters in the population, expressed on the scale of the link 262 functions. Repeatable individual differences in RN parameters are in turn estimated as deviations 263 from these averages using random effects μ_{0i} , β_{xi} , and σ_{0i} . For simplicity, the model assumes 264 environmental exposures x are randomized across individuals, but it may be necessary in non-265 experimental contexts to center covariates within individuals for appropriate scaling of RN slopes 266 (Schaeffer, 2004; van de Pol & Wright 2009; Araya-Ajoy, Mathot, & Dingemanse, 2015; Westneat 267 et al., 2020; Fay, Martin, & Plard 2022). The magnitude of among-individual (co)variance in these 268 RN parameters is described by the P matrix. See Box 1 for further discussion of the RN residual 269 parameter.

270 **Box 1.** Interpreting among-individual differences in RN residuals.

271 The functional role of the RN residual parameters σ_0 can be ambiguous because these individual 272 effects are modelled on the dispersion σ of the phenotypic distribution, rather than the expectation 273 μ (Eq. 1). Phenotypic variance due to dispersion is generally interpreted as noise or measurement 274 error around individuals' repeatable mean trait values (Brommer 2013), which are determined by 275 the expression of RN intercepts μ_0 and slopes β_x across measured environments. However, the 276 residuals of labile traits may also contain repeatable and fitness-relevant variation in how 277 organisms intrinsically regulate their phenotype (Westneat, Wright, & Dingemanse 2015), such 278 as in their assessment and response toward developmental noise within a given environment 279 (Gavrilets & Hastings, 1994; Hansen et al., 2006; Mitchell et al. 2021). Such repeatable among-280 individual differences in *within*-individual variation, described by σ_0 , may arise from a variety of 281 mechanisms regulating patterns of stochastic expression in behavior or other labile traits 282 (Prentice, Houslay, Martin & Wilson, 2020). For instance, stochasticity can be generated through 283 the repeatable activities of the organism, such as by random sampling of the environment, which 284 can be shaped via reinforcement and punishment to facilitate adaptive learning in novel or 285 uncertain environments (Niv et al. 2002; Barrett 2011; Wright et al., 2022). Consequently, intrinsic 286 variability may evolve in conjunction with learning mechanisms to track unpredictable shifts in 287 fitness optima during development (Borenstein, Feldman, & Aoki 2008). Predation may also select 288 for greater variability in movement, so as to reduce predators' capacity to predict prey escape 289 trajectories (Hugie, 2003; Moore et al. 2017), while reduced variability may instead be adaptive 290 for reputation formation and trust in repeated social interactions (McNamara & Leimar, 2010). 291 Stochasticity may also result from exogenous factors, such that individual differences in σ_0 reflect 292 how organisms regulate in response to the environment. For example, when environmental states 293 fluctuate rapidly in an unpredictable and uncontrollable manner, negative selection may act on 294 the RN residual parameter to promote phenotypic canalization, decreasing susceptibility of the 295 phenotype to developmental perturbation (Flatt 2005; Siegal & Leu 2014; Westneat et al., 2015).

In empirical research, it will often be challenging to distinguish variance in residuals due to intrinsically stochastic variability or unmeasured processes of cue-induced plasticity and individual-by-environment interaction (Westneat et al. 2015; Prentice et al., 2020). Estimates of var(σ_0) in the field may, for example, reflect repeatable functional interactions between unmodelled RN slopes and stochastic environmental exposures. Therefore, caution is warranted when inferring the mechanistic underpinnings of σ_0 outside of well-controlled experiments. Poorly specified statistical models, in which predicted residual processes do not accurately describe

303 observed phenotypic variance, will also inhibit accurate biological inference of RNs (Mitchell, 304 Dujon, Beckmann, & Biro, 2020; Ramakers, Visser, & Gienapp, 2020). Nonetheless, to the degree 305 that individual differences in residuals are repeatable across time and not due to unbalanced 306 sampling or pseudo-repeatability (Dingemanse & Dochtermann 2013), selection can still shape 307 RN residuals, irrespective of whether within-individual deviations arise from mechanisms of 308 intrinsically stochastic or cue-induced trait expression. Therefore, we suggest that researchers in 309 both observational and experimental systems focus their attention on functionally interpreting and 310 operationally defining RN residual parameters with respect to theoretically motivated RN slopes, 311 defined over measured dimensions of environmental change (Figure 1).

312

313 **Box 2.** *Repeatable among-individual differences due to RNs.*

314 Selection on the RNs of labile traits can only occur if individuals differ in their intercepts, slopes, 315 and residual parameters across time. The covariance matrix P in Eq. 1 describes these 316 repeatable among-individual differences and, therefore, ultimately determines the total amount of 317 trait (co)variation available to natural selection on phenotype z over the sampling period of 318 interest, given that RN parameters μ_0 , β_x , and σ_0 predict how organisms will repeatedly express 319 their phenotype within and across environments. We denote the total magnitude of repeatable 320 among-individual differences in z due to RNs as $var(\eta)$, which in the general case sets an upper 321 limit on the heritability of a phenotype due to direct genetic effects (see Bijma, 2011 for social 322 traits) and thus provides a useful phenotypic proxy of the evolvability of a trait (Martin et al., 2023). 323 The trait values η represent the repeatable character states that organisms are expected to 324 express within and across sampled environments, as predicted by their individual RNs (Fig. 1 top 325 left). Conversely, any variance in observed trait values z due to non-repeatable effects $var(\xi) =$ 326 $var(z) - var(\eta)$ introduces noise into the estimation of selection gradients defined across 327 sampled environments. Failure to distinguish non-repeatable $var(\xi)$ and repeatable $var(\eta)$ 328 variance in measured phenotypes $var(z) = var(\eta) + var(\xi)$ can thus lead to biased estimates of 329 directional β^* and quadratic γ^* selection gradients (Figure 2). For evolutionary ecologists, 330 correlations between fitness and phenotype that are repeatable over time and potentially heritable 331 across generations will generally be of primary interest, motivating partitioning of var(η) from 332 var(z) with a GLMM (Martin & Jaeggi 2022).

333 O'Dea et al. (2022) and de Villemereuil et al. (2016), among others, provide exact analytic 334 solutions and numeric methods for calculating $var(\eta)$ with many commonly used GLMMs. For the

339
$$\operatorname{var}(\boldsymbol{\eta}) \approx \operatorname{var}(\boldsymbol{z}_{\operatorname{pred}})_{\boldsymbol{\eta}} - \operatorname{var}(\boldsymbol{z}_{\operatorname{pred}})_{-\boldsymbol{\eta}}$$
 (2)

340 Model predictions can also be used to approximate the total repeatability of among-individual341 differences in the phenotype on the original data scale for any GLMM

342
$$R_{\eta} \approx \frac{\operatorname{var}(\boldsymbol{\eta})}{\operatorname{var}(\boldsymbol{z}_{\operatorname{pred}})_{\boldsymbol{\eta}}}$$
(3)

The bias of estimated selection gradients will increase as the R_{η} of a phenotype decreases and var(ξ) in turn increases (Spearman, 1904; Searle, 1961). Therefore, failure to remove nonrepeatable causes of variation from observed phenotypic measures is a particularly serious issue when estimating selection on labile traits across heterogeneous environments (**Figure 2**; Dingemanse et al. 2021).

(4)

348 (Non)linear selection model

To model selection on the individual-specific RN parameters μ_{0j} , β_{xj} , and σ_{0j} , the RN GLMM in **Eq. 1** can be expanded to include an additional response model predicting measure *t* of fitness component or proxy *W*. Linear *b* and quadratic *q* selection coefficients, as well as other more complex forms of nonlinear selection, can then be estimated directly for the RN parameters.

 $z_{it} \sim f(\mu_{it}, \sigma_i)$

354
$$g_{\mu}(\mu_{jt}) = \mu_0 + \mu_{0j} + (\beta_x + \beta_{xj})x_t$$

355
$$g_{\sigma}(\sigma_j) = \sigma_0 + \sigma_{0j}$$

357
$$[\boldsymbol{\mu}_{\boldsymbol{0}}^{\mathsf{T}}, \boldsymbol{\beta}_{\boldsymbol{x}}^{\mathsf{T}}, \boldsymbol{\sigma}_{\boldsymbol{0}}^{\mathsf{T}}]^{\mathsf{T}} \sim \mathsf{MVN}(\boldsymbol{0}, \mathbf{P})$$

356

 $W_{jt} \sim f(\theta_{jt}, \delta)$

359
$$g_{\theta}(\theta_{jt}) = W_0 + W_{0j} + b_1 \mu_{0j} + b_2 \beta_{xj} + b_3 \sigma_{0j}$$

$$360 \qquad \qquad +q_1\mu_{0j}^2 + q_2\beta_{xj}^2 + q_3\sigma_{0j}^2 + q_4\mu_{0j}\beta_{xj} + q_5\mu_{0j}\sigma_{0j} + q_6\beta_{xj}\sigma_{0j}$$

361
$$W_0 \sim N(0, sd(W_0))$$

362 Fitness W for individual *i* at measurement *t* is described by a GLMM with expectation parameter 363 θ and dispersion parameter δ . The full model thus estimates the RN parameters and their 364 accompanying selection coefficients in the fitness model simultaneously using a multivariate 365 analysis. Figure 2 visualizes this model structure and explains how it avoids bias by partitioning 366 repeatable sources of (non)linear association between phenotype and fitness. Parameter W_0 is 367 the average fitness on the transformed scale given by link function g_{θ} . When repeated fitness measures t are available, an individual random effect W_{0j} should be estimated to capture 368 369 repeatable among-individual differences in fitness that are not due to the modelled phenotypes 370 (i.e. unexplained selection). If only a single fitness measure is available, $sd(W_0)$ cannot be 371 identified separately from fitness residual dispersion δ , so these effects should instead be 372 excluded from the analysis.

The polynomial regression in **Eq. 4** can be used to infer short-term population trajectories on the adaptive landscape, under the assumption that a quadratic function effectively approximates the local shape of the individual selection surface on the latent transformed scale (Lande & Arnold 1983; Phillips & Arnold 1989). However, the values of the **b** and **q** regression 377 coefficients should only be interpreted as measures of directional and quadratic selection 378 gradients when fitness is a mean-scaled Gaussian response, after appropriately scaling the 379 coefficients (see Stinchcombe et al. 2008; Dingemanse et al. 2021 for details). Analytic 380 expressions can also be used for direct interpretation of coefficients in a log-normal fitness model 381 (Bollen, Morrissey, & Kruuk 2019). However, in the general case, it will be necessary to further 382 process regression coefficients from the fitness model before making quantitative inferences 383 about directional and quadratic selection on the scale of the original data, which is generally of 384 greater biological interest.

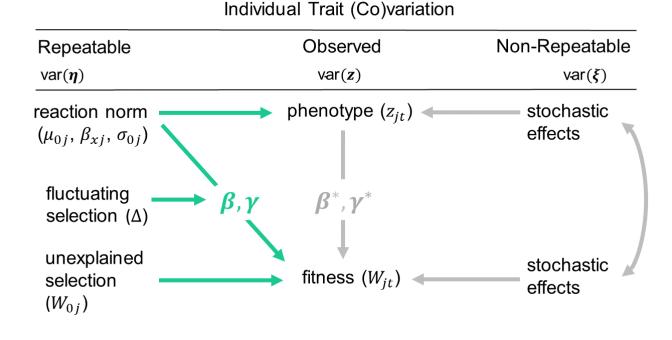
Following Lande and Arnold (1983) and Morrissey and Sakrejda (2013), directional β and quadratic γ selection gradients can be numerically calculated for any GLMM by taking the first ∂ and second ∂^2 partial derivatives of the estimated fitness function with respect to the expected population-level RN parameters $\bar{\mu}_0$, $\bar{\beta}_x$, and $\bar{\sigma}_0$.

389
$$\beta_{\mu_0} = \frac{\partial \operatorname{E}(\overline{W}, \overline{\mu}_0)}{\partial \overline{\mu}_0} \,\overline{W}^{-1} \dots \,\gamma_{\mu_0} = \frac{\partial^2 \operatorname{E}(\overline{W}, \overline{\mu}_0)}{\partial \overline{\mu}_0 \,\delta \overline{\mu}_0} \overline{W}^{-1} \dots \,\gamma_{\beta_x \sigma_0} = \frac{\partial^2 \operatorname{E}(\overline{W}, \overline{\beta}_x)}{\partial \overline{\beta}_x \,\delta \overline{\sigma}_0} \overline{W}^{-1} \tag{5.1}$$

where \overline{W} is the expected population fitness on the original data scale, as predicted by the fitness 390 function defined with **b** and **q** coefficients on the link scale in Eq. 4. The directional gradients β_{μ_0} , 391 β_{β_x} , and β_{σ_0} indicate the direction and magnitude of selection on the expected values of 392 population RN parameters, with respect to the original untransformed scale of the data. Quadratic 393 selection gradients γ_{μ_0} , γ_{β_x} and γ_{σ_0} in turn indicate convex or concave curvature in the selection 394 surface shaping the variance of RN parameters (Stinchcombe et al. 2008); and $\gamma_{\mu_0\beta_x}$, $\gamma_{\mu_0\sigma_0}$, and 395 $\gamma_{\beta_x \sigma_0}$ indicate further curvature due to the presence of correlational selection between RN 396 397 parameters (Blows & Brooks 2003). These gradients can be expressed in standardized units for 398 effect size comparison between traits and parameters using the appropriate variances and 399 standard deviations (Lande & Arnold 1983)

400
$$\beta_{\mu_0}^{sd} = \beta_{\mu_0} \operatorname{sd}(\boldsymbol{\mu_0}) \dots \gamma_{\mu_0}^{sd} = \gamma_{\mu_0} \operatorname{var}(\boldsymbol{\mu_0}) \dots \gamma_{\beta_x \sigma_0}^{sd} = \gamma_{\beta_x \sigma_0} \operatorname{sd}(\boldsymbol{\beta_x}) \operatorname{sd}(\boldsymbol{\sigma_0})$$
(5.2)

Standardized gradients are particularly useful for GLMMs because the magnitude of variances
 may differ appreciably between the distinct transformed link scales used for estimating RNs and
 selection, which makes it challenging to meaningfully distinguish between small and large effect
 sizes across models.



40L

406 Figure 2. Removing non-repeatable effects from selection gradients. The diagram shows causal 407 pathways (directional arrows) by which repeatable (green) and non-repeatable (grey) effects can 408 influence selection gradients of fitness (W) on phenotype (z). Non-repeatable, stochastic effects 409 influence both fitness and phenotype (directional arrows) and may be correlated (double-headed 410 arrow), introducing statistical noise into the selection analysis. This leads to biased directional β^* and 411 quadratic gradients γ^* when observed variance in the phenotype var(z) is used to estimate selection 412 across environments. However, if the (non)linear relationships between phenotype and fitness are 413 modelled independently of stochastic effects on the phenotype var(ξ), using RN parameters μ_0, β_x , and σ_0 (Eq. 1-4), unbiased selection gradients β and γ can be estimated (Eq. 5) directly for 414 415 repeatable among-individual differences in the phenotype var(η) (see **Box 2**). Spatiotemporal 416 fluctuations Δ in these selection gradients can also be described by additional coefficients (Eq. 6), and 417 any repeatable among-individual differences in fitness unexplained by RN parameters can be 418 estimated with random effects W_0 when repeated fitness measures are available (Eq. 4).

Model extensions

Simplified models are presented above (Eq. 1, Eq. 4) to aid interpretation, but it will often be necessary to specify more complex models for explaining empirically observed variation in fitness and phenotype. Various model extensions can be straightforwardly accomplished using the basic toolkit of GLMMs and related regression frameworks, along with appropriate study design and sufficient repeated sampling for reliable estimation. Below we briefly consider three key areas for model extension and provide references for further consideration. Implementation for social traits and interactions is discussed by Martin and Jaeggi (2022).

427 Fluctuating selection

428 Fluctuating selection on RNs may occur due to variation in the density of mates and 429 competitors, resource availability and seasonality, bodily condition and age, the availability of local 430 niches, or any other state that modulate the fitness costs and benefits of labile traits (Houston & 431 McNamara, 1999; Sih et al., 2015). Fluctuating selection is also expected to be a key mechanism 432 for explaining patterns of macroevolutionary stasis (Estes & Arnold, 2007), the adaptive evolution 433 of phenotypic plasticity (de Jong, 1995; King & Hadfield, 2019; Martin et al., 2024), and the 434 evolutionary maintenance of individual and genetic variation within populations more generally 435 (e.g. Sasaki & Ellner, 1997; Dingemanse & Wolf, 2010; Wolf & Weissing, 2010; Wright et al., 436 2019; Abdul-Rahman, Tranchina, & Gresham, 2021; Martin et al., 2023). As previously noted, 437 quantitative genetic theory has demonstrated the mathematical equivalence of models for 438 selection on character states and RNs. A key finding from this theoretical work is that fluctuating 439 selection on character states expressed within environments generates directional and quadratic 440 selection on RN parameters across environments (Gavrilets & Scheiner, 1993; de Jong, 1995). 441 Therefore, estimating non-zero directional and quadratic selection on a RN parameter via Eq. 4-442 5 implies that selection on the phenotype is fluctuating with respect to the environment over which 443 the RN parameter is defined (Martin et al., 2024). For example, the degree to which density-444 dependent selection on character states fluctuates across the environments encountered by a 445 population will be proportional the average directional and quadratic selection on the RN slope β_r defining how the phenotype changes with respect to density x. In general, this means that the RN 446 447 selection model can be used to infer the presence of fluctuating phenotypic selection with much 448 fewer parameters than an equivalent character state model (de Jong, 1995).

449 These considerations suggest that RN selection analyses will often not require estimating 450 additional parameters beyond the main linear **b** and nonlinear **q** effects on RN parameters to 451 accurately describe patterns of fluctuating selection on the expressed phenotype. However, in the 452 presence of environmental change, the magnitude and pattern of fluctuating character state 453 selection experienced by a population may also vary across space and time, which is expected 454 to result in fluctuating selection on RN parameters (Figure 2). In some systems, the putative 455 environmental causes of fluctuating selection will be directly measured, while in others, it may be 456 informative to estimate spatiotemporal heterogeneity in RN selection even if the underlying 457 causes are not directly measured (Reynolds, de Los Campos, Egan, & Ott 2016). For example, 458 long-term field studies can be used to investigate the adaptive maintenance of RN variation by 459 yearly fluctuations in selection, even if the mechanisms underpinning these fluctuations remain 460 unclear (de Villemereuil et al., 2020; Mouchet et al., 2021). To incorporate such effects, the basic 461 fitness model (Eq. 4) can be extended by including fixed or random interaction effects on the 462 selection coefficients, which will estimate continuous or discrete fluctuations $\Delta\beta$ and $\Delta\gamma$ (Figure 463 2) across space and time. For example,

$$g_{\theta}(\theta_{jt}) = W_0 + W_{0j} + (b_1 + b_{1x}x_t + u_{tb_1})\mu_{0j} + \dots (q_1 + q_{1x}x_t + u_{tq_1})\mu_{0j}^2 + \dots$$
(6)

465 where b_{1x} and q_{1x} describe how the (non)linear selection coefficients change as a function of x_t , 466 and u_{tb_1} and u_{ta_1} describe changes due to a random factor at time *t*.

467 Adjusted and nonlinear effects

468 As with any regression analysis, additional fixed and random effects may need to be 469 adjusted for to facilitate appropriate biological inference. Predation may, for instance, cause 470 differential mortality as a function of repeatable differences in behavior across sex and age 471 classes, but this selection will not generate an evolutionary response on behavioral variation 472 within sexes or age classes. This motivates estimating repeatable individual variation adjusted for 473 the effects of sex and age, among other commonly studied factors such as size and morphology 474 (Bolnick et al., 2003). Unadjusted environmental effects on fitness and phenotype can also bias 475 estimates of selection and among-individual variation in both field and laboratory settings 476 (Scheiner et al. 2002; Stinchcombe et al., 2022; Kinsler et al., 2023; Munar-Delgado et al., 2023). 477 It is, therefore, often useful to include additional environmental covariates (e.g. average 478 temperature and rainfall, date within season, resource availability), including potential interaction 479 effects, and random factors (e.g. nesting site, spatial position, batch, observer identity) to adjust fitness variation during the selection analysis. As discussed in Box 2, model predictions can
always be used to quantify and better understand how adjusting for these effects changes the
repeatable variation available to selection in any multivariate GLMM.

483 Relationships between fitness, phenotype, and the local environment may also be best 484 described by additional terms beyond quadratic regression coefficients. For example, RN slopes 485 of thermoregulatory and life history traits such as growth rate are often highly nonlinear in 486 response to temperature (Oomen & Hutchings, 2022), violating the assumption of Eq. 4 that 487 individuals' phenotypic deviations from the linear RN slope β_x are multivariate normally 488 distributed. Polynomials (Henderson, 1982; Yamahira, Kawajiri, Takeshi, & Irie, 2007) or 489 generalized additive effects such as splines or Gaussian processes (Schluter & Nychka, 1994; 490 Sigourney, Munch, & Letcher, 2012; Pederson, Miller, Simpson, & Ross, 2019; Catalina, Bürkner, 491 & Vehtari, 2020) can be used to account for nonlinearity in the population RN and ensure the 492 statistical model more accurately predicts observable phenotypic and fitness variation. In the 493 general case, the basic model (Eq. 4) can be expanded to include any generalized additive 494 function s() describing how expected phenotypic μ_{it} or fitness values θ_{it} change in response to 495 the environment

$$g_{\mu}(\mu_{jt}) = \mu_0 + \mu_{0j} + s(x_t) + \beta_{xj} x_t$$
⁽⁷⁾

$$g_{\theta}(\theta_{jt}) = W_0 + W_{0j} + s(x_t) + b_1 \mu_{0j} + b_2 \beta_{x_j} + b_3 \sigma_{0j} \dots$$

498 Extensive tutorials for incorporating such nonlinear effects into Bayesian regression 499 models in Stan are freely available online (see https://mc-stan.org/documentation/case-studies 500 for worked examples of fitting splines and Gaussian processes). Code from Stan models 501 constructed using familiar R syntax in the brms package (Bürkner, 2019) also provides a helpful 502 reference point for getting started. By allowing for arbitrarily complex average RN shapes across 503 subjects, individual deviations from the average slope for phenotype as well as for fitness are 504 much more likely to exhibit multivariate normality. This general approach allows researchers to 505 accurately describe trait change across complex and dynamic environments, while still using 506 standard theory from quantitative genetics to quantify selection gradients and predict short-term 507 evolutionary responses.

508 Additional individual effects

509 The RN model presented in the main text (**Eq. 1**) does not account the fact that phenotypic 510 dispersion σ may also be plastic across environments, a phenomenon broadly referred to as 511 'malleability' (see O'Dea, Noble, & Nakagawa 2021 for discussion). Malleability in residuals can 512 be estimated by including population- and individual-level slopes in the linear predictor of the 513 dispersion parameter (Westneat et al., 2013). For example,

$$g_{\sigma}(\sigma_{jt}) = \sigma_0 + \sigma_{0j} + (\rho + \rho_j)x_t$$
(8)

515 if observation-level variation in environmental measure **x** is expected to have effect ρ on average 516 differences in phenotypic residuals. Malleability can then be treated as a further RN parameter 517 that is also potentially under selection. Some statistical distributions such as the Poisson lack an 518 explicit dispersion parameter, due to deterministic mean-variance relationships, and thus at first 519 glance only provide scope for selection on the RN intercepts and slopes of expected values. 520 However, in many empirical datasets, there is more variance observed in the phenotype than 521 predicted by these distributions (overdispersion), which can be accounted for through the 522 inclusion of further random effects capturing stochastic, observation-level deviations from model 523 expectations (i.e. residuals; Harrison, 2014). The dispersion of these observation-level random 524 effects can then be modelled as a function of individual-level intercepts and slopes, similar to a 525 standard Gaussian model, providing scope for estimating selection on phenotypic variability using 526 a broad range of RN GLMMs.

527 More generally, any theoretically relevant component of a statistical distribution may be 528 modelled as a function of further individual-level effects and conceptualized as a RN parameter 529 regulating the expression of phenotypes within and across environments. Hurdle models, for 530 example, combine multiple distributions together to distinguish effects on the presence/absence 531 of trait expression from effects on the subsequent magnitude or intensity of trait expression 532 (Mullahy 1986; Heilbron 1994). This is particularly useful for phenotypes such as allogrooming 533 behavior in primates, which can vary repeatably among individuals both in its probability of 534 occurring as well as its intensity and duration once expressed (Silk et al., 2017). These processes 535 are interdependent but may nonetheless be subject to distinct selection pressures (e.g. whom 536 should be groomed and how much), which can be investigated by estimating separate RN 537 intercepts and/or slopes on both model components.

Statistical inference

539 Bayesian estimation

540 The proposed models cannot currently be estimated using popular GLMM software 541 packages, due to the need for latent RN parameters to be simultaneously estimated with random 542 and fixed effects across different response models. Fortunately, the Stan statistical programming 543 language (Carpenter et al. 2017), which relies on cutting-edge and computationally efficient 544 Markov Chain Monte Carlo (MCMC) sampling algorithms, provides the flexibility needed for 545 estimating these novel GLMMs within a Bayesian framework. Researchers unfamiliar with the 546 deneral motivations of Bayesian inference are encouraged to see McElreath (2020) and Gelman 547 et al. (2020) for helpful tips on developing an effective workflow for data analysis. The brms 548 package (Bürkner, 2018) is also a very helpful bridge for writing complex (non)linear Bayesian 549 GLMMs in Stan using familiar R formula syntax. We provide guided tutorials (see data 550 availability) for various implementations of the models presented here in Stan.

551 Prior distributions need to be specified for all the population-level parameters in a 552 Bayesian model. While flat or highly diffuse priors are often recommended in the literature (e.g. 553 Ellison 2004; Villemereuil et al. 2016; Houslay and Wilson 2017), weakly informative or 554 regularizing priors, which place relatively low probability on extreme effect sizes, facilitate more 555 robust inferences with limited sample sizes and should generally be preferred over flat priors 556 (Gelman & Tuerlinckx 2000; Lemoine 2019; McElreath 2020). This does not necessarily require 557 strong a priori assumptions; general-purpose priors can be used to increase the generalizability 558 and robustness of parameter estimates, even in a state of relative ignorance about the true effect 559 size. See Lemoine (2019) for more detailed discussion and recommendations.

560 Model validation

561 Previous work has validated the performance of our general approach in Stan for modest 562 effect sizes, showing robust estimates of directional selection on RN intercepts and slopes with 563 many repeated measures and sample sizes of N = 100 - 300 (Martin & Jaeggi, 2022). To provide 564 more general validation, we further conducted a simulation-based calibration (SBC; Talts et al. 565 2018; Säilynoja, Bürkner, & Vehtari, 2022) procedure to assess whether the proposed models are 566 unbiased estimators of nonlinear selection under a broader range of scenarios. SBC is a

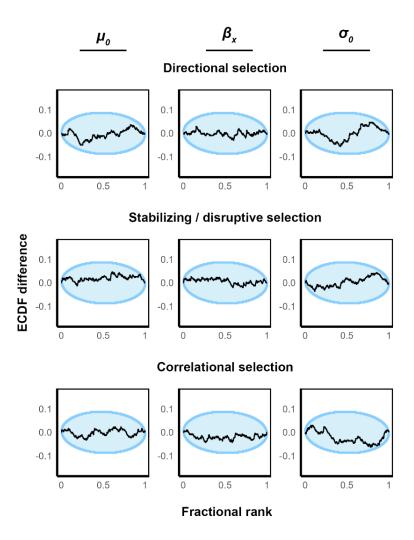
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567 procedure for validating the performance of any Bayesian algorithm across many possible 568 parameter values, as defined by the prior distributions of a generative model. This approach 569 removes the arbitrariness of setting a limited range of fixed parameter values for assessing 570 performance, which can lead to unexpected sources of bias being overlooked in uninvestigated 571 regions of parameter space (e.g. rare but possible combinations of phenotypic variances and 572 selection coefficients). Instead, random parameter values are repeatedly sampled across many 573 simulated datasets. Visual inspection of the correspondence between the generative distributions 574 used to simulate datasets and the subsequent posterior distributions inferred from these datasets 575 allows for detecting sources of bias such as overdispersion, overestimation, or inconsistent model 576 performance for extreme values. A GLMM validated through SBC is thus an unbiased Bayesian 577 estimator with respect to the range of effect sizes described by the prior generative model.

578 Particular attention was given to the estimation of directional and quadratic selection 579 coefficients during SBC, using 300 simulated datasets assuming conditions of very minimal 580 sampling effort (N = 100 subjects with 3 repeated phenotypic measurements and 2 repeated 581 fitness measures). Parameters were simulated such that 582 $\mu_0, \beta_x, \sigma_0, \boldsymbol{b}, \boldsymbol{q} \sim N(0, 1), \operatorname{sd}([\mu_0, \beta_x, \sigma_0, W_0]), \delta \sim \operatorname{exponential}(2), \operatorname{and} \operatorname{cor}([\mu_0, \beta_x, \sigma_0]) \sim \operatorname{LKJ}(2).$ Note 583 that LKJ refers to the Lewandowski-Kurowicka-Joe distribution, which is useful for generating 584 positive-definite correlation matrices (Gelman et al., 2013). These priors led to a broad range of 585 very small to large selection effect sizes, as well as very small to large effects for the standard 586 deviations and correlations of RNs and the residual fitness standard deviation (δ). Phenotype and 587 fitness were assumed to be Gaussian for computational efficiency, with mean fitness fixed to 1. 588 Following the recommendations of Säilynoja et al. (2022), we computed and visualized the 589 difference in expected cumulative distribution functions between the generative and inferred 590 parameters to perform a quantitative graphical test of the model's performance. As shown in 591 **Figure 3**, our results demonstrated with probability ≥ 0.95 that the posterior distributions of 592 inferred selection coefficients were not systematically higher or lower than the prior distributions 593 used to generate expected selection coefficients. The proposed model thus provides unbiased 594 inference of nonlinear selection on RNs across a broad range of effect sizes, even under 595 conditions of minimal sampling effort.

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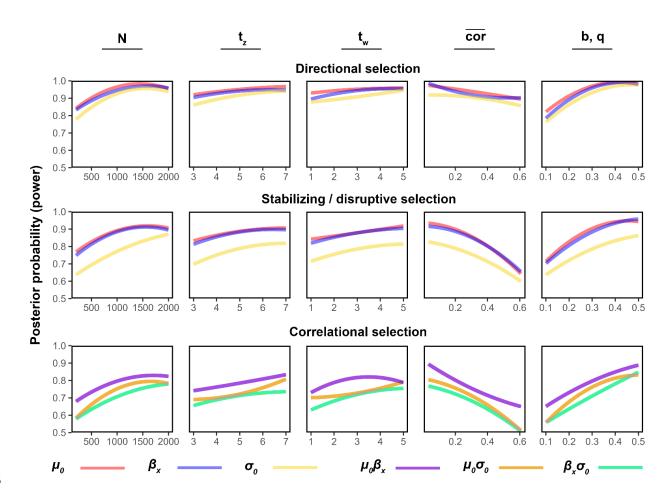
599 Figure 3. Simulation-based calibration of the nonlinear selection model. Results are shown for 600 analyses of 300 simulated datasets (N = 100 subjects, 3 repeated phenotype measures and 2 repeated 601 fitness measures) generated from prior distributions defined over the parameters of a Gaussian nonlinear 602 selection model for RNs (Eq. 4). Plots show the difference between the expected cumulative density 603 functions (y-axis) for directional and quadratic selection gradients, based on their generative prior 604 distributions N(0,1), and the estimated cumulative density functions based on inferred posterior 605 distributions. The x-axis indicates the ordered fractional ranks across posterior samples used for computing 606 these comparisons. Blue circles show 90% Bayesian credible intervals for regions of concordance between 607 the estimated and expected parameter distributions, and the black line reflects the observed difference 608 between the expected and inferred distribution (a perfectly horizontal line would thus indicate perfect 609 concordance with the simulated parameters in every dataset). Consistent deviations of the black line 610 beyond the blue region would provide evidence of systematic inferential bias during model estimation. Note 611 that due to stochasticity, fluctuations of the black line within the blue circle are expected at computationally 612 efficient sample sizes.

613 **Power analysis**

614 The SBC procedure demonstrated that our model facilitates unbiased Bayesian estimation 615 across a broad range of parameter values (Figure 3). We also conducted an additional simulation 616 study to provide concrete guidelines for empiricists designing studies to assess nonlinear 617 selection on RNs, investigating how the power to detect the direction of selection gradients is 618 influenced by the number of subjects and repeated measures per subject for phenotypes and 619 fitness proxies. For simplicity and ease of effect size comparison, we modelled Gaussian 620 phenotype and fitness measures. Fitness effects for the nonlinear selection model were simulated 621 such that **b**, $q \sim U(0.1, 0.5)$, resulting in selection effects ranging from statistically weak to strong in strength, with a mean effect size of |0.3| across datasets. For simplicity, we assumed $W_0 = \delta =$ 622 623 1 and $\mu_0 = \beta_0 = 0$. Continuous environmental variation (**x**) for quantifying reaction norm slopes 624 was treated as a standardized variable drawn from $x \sim N(0,1)$. Repeatable among-individual $sd([\mu_0, \beta, \sigma_0]) = 0.55$ with correlations drawn from 625 differences in RNs were fixed to $cor([\mu_0, \beta, \sigma_0]) \sim LKJ(5)$, and the residual standard deviation of the phenotype was fixed to 626 627 $sqrt(exp(\sigma_0)) = 0.77$, so that repeatable and residual random effect variances were 0.3 and 0.6 628 respectively. This resulted in each RN parameter exhibiting modest repeatability, R = 0.2 =629 $\frac{0.3}{3(0.3)+0.6}$ in the absence of phenotypic correlations. Unexplained selection was also fixed to 630 $sd(W_0) = 0.55$ for the fitness model.

631 Power to detect the appropriate direction of selection coefficients was explored with 1000 632 datasets of varying size drawn from $N \sim U(200, 1000)$ subjects with $t_z \sim U(3,7)$ repeated 633 phenotype and $t_w \sim U(1,5)$ repeated fitness measures per subject. Classical frequentist methods 634 define power with respect to a binary decision rule based on the desired significance level of a 635 null hypothesis test. In Bayesian analysis, 'power' is not precisely defined but may instead refer 636 to the continuous level of support provided for a direct (rather than null) hypothesis test, such as 637 the posterior probability of positive selection occurring on a trait. The power of a Bayesian analysis 638 thus reflects how confident a model is likely to be in the existence and direction of a true selection 639 effect, with p = 0.5 indicating no confidence (+ and - values are equally likely) and p = 1.0640 indicating complete confidence in the effect. We herein use 'power' in this sense to refer to the 641 expected posterior probability supporting positive directional and quadratic selection effects on 642 RN parameters.

643 Power for detecting selection across simulated scenarios is visualized in **Figure 4**, with 644 second-order polynomial lines plotted across datasets to infer general patterns expected in 645 empirical research. As expected, we find that Bayesian power for inferring directional and 646 quadratic selection increases with a greater number of subjects (N) and repeated phenotype (t_z) 647 and fitness measures (t_w) , as well as with greater selection effect sizes (b, q), while larger 648 absolute phenotypic correlations among RN parameters (cor) reduce power, particularly for 649 detecting guadratic selection. Power to detect guadratic selection is lower than for directional 650 selection across small to moderate sample and effect sizes, with power for correlational selection 651 also being relatively lower than stabilizing/disruptive selection except under ideal conditions. This 652 implies that research particularly focused on detecting correlational selection of RNs will require 653 larger samples to attain confident inferences. Power is also consistently lower for detecting all 654 types of selection on RN residual parameters in comparison to RN intercepts and slopes, 655 indicating a need for greater sampling effort in selection studies on phenotypic variability. As with 656 any multivariate selection model, these results show that large sample sizes and sufficient 657 repeated measurements are crucial for robust hypothesis testing, particularly in the presence of 658 weak selection. As a rule of thumb, sample sizes of at least N = 500-1000 will be desirable to 659 appropriately reduce the risk of false negatives, particularly in the absence of many repeated 660 phenotype and/or fitness measures. The negative effect of RN parameter correlations on power 661 also shows that (non)linear selection will be much easier to detect when RN parameters vary 662 quasi-independently among individuals within a population.



663

664 Figure 4. Bayesian power analysis of the nonlinear selection model. Results are shown for 665 directional hypothesis tests of selection effects across 1000 simulated datasets used to estimate the nonlinear selection model for RNs (Eq. 4) with Gaussian phenotype and fitness measures. 666 667 Plots show the expected posterior probability ('power', y-axis) supporting selection effects as a 668 function of variation in sampling conditions across simulated datasets (x-axis): the number of 669 subjects/sample size (N), the number of phenotypic measures per subject (tz), the number of 670 fitness measures per subject (t_w), the mean absolute correlation among RN parameters (\overline{cor}), and 671 the size of linear (b) and nonlinear (q) selection effects. General patterns were inferred using 672 second-order polynomials across conditions, which are color-coded by RN parameter (red = 673 intercepts, blue = slopes, yellow = residuals, purple = intercepts x slopes, orange = intercepts x 674 residuals, and green = slopes x residuals).

Conclusion

676 Studying selection on highly labile traits is essential for explaining how and why organisms 677 adapt to environmental change. RN models are a crucial tool for characterizing such phenotypes, 678 but their application to selection analysis remains hampered by the limitations of current methods. 679 A major challenge is to avoid inferential bias caused by non-repeatable, stochastic effects and 680 other sources of measurement error in RNs and their fitness effects (Hadfield et al. 2010; FIGURE 681 1-2). A common solution is to use multi-response/multivariate random effect GLMMs to account 682 for uncertainty in selection on RNs. However, this approach restricts analyses to focus on linear 683 effects and directional selection. Ignoring quadratic selection caused by nonlinear effects 684 fundamentally inhibits researchers' capacity to study the adaptive landscape of labile traits 685 (Bulmer 1971; Arnold et al., 2001; Blows & Brooks, 2003).

686 To overcome this limitation, we proposed a novel Bayesian GLMM framework for studying 687 complex patterns of nonlinear selection on RNs, which we validated over a broad range of 688 possible parameter values using a simulation-based calibration approach (Figure 3). We also 689 found that these models exhibited desirable statistical power under reasonable sampling 690 conditions for many long-term field research projects (Figure 4). This modeling framework 691 synthesizes the well-established Lande and Arnold (1983) approach to error-free selection 692 analysis with measurement error or error-in-variables models (Ponzi et al. 2018; Dingemanse et 693 al. 2021; Martin & Jaeggi 2022) and double hierarchical (Westneat et al. 2013; O'Dea et al. 2021), 694 multi-response GLMMs (Brommer et al. 2012; Houslay & Wilson 2017; Arnold et al. 2019). These 695 models can be applied to estimate directional and quadratic selection irrespective of the 696 distribution of the data and the potential nonlinearity of the RN or fitness function, allowing 697 researchers to construct more realistic models of the processes underlying their measurements. 698 This focuses attention on accurate description of observed data rather than the restrictive 699 assumptions of linear regression. With the analytic toolkit of quantitative genetics (Lande & Arnold 700 1983; Morrissey & Sakrejda 2013), estimates from these models can also be transformed to 701 quantify selection gradients, visualize multivariate selection, and predict ongoing adaptation. The 702 proposed modeling framework should, therefore, readily enhance tests of adaptive theory for 703 labile traits in the wild.

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704 Data availability statement

R and Stan code with detailed tutorials for implementing the models presented in this paper are
 available online through a GitHub public repository HTTPS://GITHUB.COM/JORDAN-SCOTT MARTIN/SELECTION-ON-RNS.

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