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The dynamics of dominance: open questions, challenges, and solutions

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Abstract

Although social hierarchies are recognized as dynamic systems, they are typically treated as static entities for practical reasons. Here, we ask what we can learn from a dynamical view of dominance, and provide a research agenda for the next decades. We identify five broad questions at the individual, dyadic, and group levels, exploring the causes and consequences of individual changes in rank, the dynamics underlying dyadic dominance relationships, and the origins and impacts of social instability. Although challenges remain, we propose avenues for overcoming them. We suggest distinguishing between different types of social mobility to provide conceptual clarity about hierarchy dynamics at the individual level, and emphasize the need to explore how these dynamic processes produce dominance trajectories over individual lifespans and impact selection on status-seeking behavior. At the dyadic level, there is scope for deeper exploration of decision-making processes leading to observed interactions, and how stable but malleable relationships emerge from these interactions. Across scales, model systems where rank is manipulable will be extremely useful for testing hypotheses about dominance dynamics. Long-term individual-based studies will also be critical for understanding the impact of rare events, and for interrogating dynamics that unfold over lifetimes and generations.

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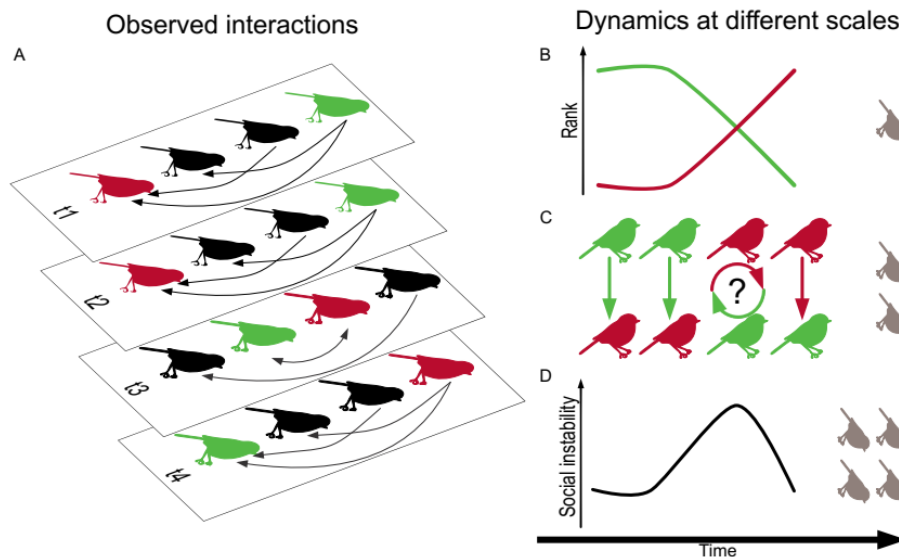
Table 1. A research agenda for the dynamics of dominance.

	Open questions	Challenges	Solutions
Individual Level	How and why do individuals change position in the dominance hierarchy?	Lack of conceptual clarity about rank dynamics at individual level	Conceptual distinction between <i>inter- and intragenerational mobility</i> and <i>active and passive mobility</i>
		Accurately measuring social mobility	Account for uncertainty in rank measurement when identifying changes
			Determine appropriate time-scale at which to assess social mobility
	How do dominance trajectories across life produce fitness trajectories and impact selection on status-seeking behaviour?	It is difficult to study processes occurring at lifetime scale	Long-term individual-based studies Theoretical models integrating behaviour and dominance trajectories
Dyadic level	When & why do dyads engage in contests?	Requires data that go beyond direct interactions — e.g., initiation, avoidance, long-distance signals, behavioural state, etc.	Develop methods for studying the lack of interactions
			Account for opportunity to interact
			Distinguish the roles of dominant and subordinate individuals in driving interaction rates
	How do dominance relationships form and dissolve?	Requires high-resolution interaction data	Captive systems with the capacity for high-resolution data collection (e.g., automated tracking)
Lack of theoretical framework to guide empirical studies		Development and testing of interaction-to-relationship models and cognitive models of dominance relationships	
Group level	What are the causes and consequences of social instability?	Lack of conceptual clarity about social instability	Conceptual distinction between <i>membership, rank, and aggression network instability</i>
		Accurately measuring instability	Research into appropriate time-scale at which to measure instability
			Account for uncertainty in rank measurement when identifying hierarchical instability
		Rare but extreme instability can have high impact but be difficult to study	Long-term studies that capture naturally occurring extreme instability
			Experimental manipulation of social instability

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52 **Introduction**

53 Dominance is one of the most widely studied social behaviours, but is typically studied using a
54 static approach in which agonistic interactions are tabulated and used to infer individual ‘rank’ in
55 the dominance hierarchy [1, Strauss et al. this issue]. These dominance ranks are then
56 compared with other covariates of interest to understand causes and consequences of position
57 in the dominance hierarchy in social systems [2]. Although the traditional static approach has
58 produced valuable insight into the role of dominance in social systems, it side-steps challenges
59 associated with the *dynamics* of dominance, i.e., changes in dominance hierarchies over time.
60 As a result, many gaps remain in our understanding of how and why dominance hierarchies
61 change over time and what impacts these changes have for of animal societies. Here we
62 highlight these gaps, discuss the challenges to addressing them, and suggest solutions to these
63 problems and promising avenues for future research (Table 1). Specifically, we examine
64 research questions about dynamics of dominance occurring at three scales — individuals,
65 dyads, and groups (Figure 1). Targeting these gaps in future research will provide an integrative
66 understanding of how dominance operates dynamically to structure societies at multiple scales.



67

68 **Figure 1.** (A) Dominance hierarchies are inferred from observed agonistic interactions, depicted
69 as a network sampled over four time periods (t1-t4; individual identity indicated for two
70 individuals by color). Arrows point from winners to losers, and the bidirectional arrow indicates
71 cases where two individuals are each observed defeating the other. Dynamics within hierarchies
72 occur at three scales (panels B-D, scale symbolized by pale birds on the right). (B) *Individuals*
73 change position in the hierarchy. Here the two shaded individuals show opposite changes in
74 rank over the study. (C) Dominance relationships within *dyads* change over time. Here, the two
75 shaded individuals have a stable dominance relationship that reverses over the course of the
76 study. In time-point t3, the birds have an uncertain dominance relationship. (D) Social instability
77 reflects dynamics at the *group* level.

78

79 **Individual level**

80 *How and why do individuals change position in the dominance hierarchy?*

81 Social rank has important consequences for individuals, impacting stress physiology, social
82 relationships, longevity, immune function, and reproductive success [3–6]. For most species, it
83 is unclear what causes individuals to change position in the dominance hierarchy, or conversely,
84 how dominants may preserve their status [7,8]. It is important to understand the causes and
85 consequences of rank changes, both to understand potential selection on status-seeking
86 behaviour [9–11], and because rank changes can shed light on the forces involved in
87 determining social rank in the first place [12]. However, progress in understanding the dynamics
88 of dominance hierarchies is hampered by lack of a clearly defined concept of ‘rank change’. The
89 literature is plagued with redundant and ambiguous terminology such as rank change [13,14],
90 rank reversal [15,16], revolutionary coalition [17], dominance turnover [18,19], social mobility
91 [20–22], and power trajectories [23]. The proliferation of related terms reflects the complexity of
92 the concept--i.e., that position in the dominance hierarchy can change in multiple ways. Thus,
93 there is a need for multiple rank-change concepts and clear distinctions between them.

94

95 We borrow concepts from the study of social mobility in humans to delineate categories of how
96 rank changes can occur. Social mobility can occur between generations — *intergenerational*
97 *mobility* — or within generations — *intragenerational mobility* [24]. Intergenerational mobility
98 measures the extent to which parental dominance rank predicts offspring dominance, whereas
99 intragenerational mobility describes movements of individuals in the hierarchy over their
100 lifetimes. There are two types of inter- and intragenerational mobility that arise via different
101 processes [25]: *active mobility*, which involves a reversal of a previously held rank relationship
102 and *passive mobility*, which is a change in rank that occurs without any reordering of the
103 hierarchy. Passive mobility results from demographic processes like births/deaths and
104 immigration/emigration — for example, if the highest-ranked individual dies and no active
105 intragenerational mobility occurs, all remaining individuals improve their ranks by one position
106 through passive intragenerational mobility [26,27]. Drivers of active mobility are less well-
107 understood, but this type of mobility could result from changes in covariates that influence rank
108 (e.g., increase in social support [9,12,28] or resource holding potential [18]), by stochastic
109 outcomes that are reinforced (e.g., by winner/loser effects [29]), or feedbacks between multiple
110 processes [30].

111 Recent work on hierarchy dynamics in spotted hyenas (*Crocuta crocuta*) illustrates the
112 various forms of social mobility. In this system, social rank is highly predictable based on the
113 rank of the mother, in a process termed ‘maternal-rank inheritance’, which is also observed in
114 many old world monkeys [31–34]. Such systems represent an extreme version of restricted
115 intergenerational mobility, because a female’s rank is strongly correlated with the rank of her
116 mother. Intragenerational mobility occurs through active and passive processes in this system.
117 Active intragenerational mobility occurs when lower-ranking females overtake their higher-
118 ranked group-mates through coalitionary support [12]. Passive intragenerational mobility due to
119 reproduction drives increasing differences among individuals and lineages over time [12]. This

120 example demonstrates how distinguishing among these different types of social mobility will
121 help to bring conceptual clarity to research into hierarchy dynamics and will reveal diverse
122 drivers and impacts of mobility.
123
124 Methodological groundwork exists for inferring patterns of social mobility, but more work in this
125 area is needed. Mobility can be measured in absolute units (e.g., increase/decrease in number
126 of individuals dominated) or relative to other members of society (e.g., increase/decrease in
127 rank standardized for group size) [35,36]. Contrasts in the causes and consequences of relative
128 and absolute mobility can reflect biological differences in competitive landscapes; absolute
129 mobility is expected to be more important when the resources over which animals compete are
130 density dependent, whereas relative mobility is expected to be more important when these
131 resources are density-independent [37]. Many methods exist for inferring a rank order from a
132 sample of animal contests [38,39], and numerous studies have evaluated the efficacy of these
133 methods at finding rank orders [39–41], but very little work has evaluated the efficacy of these
134 methods for inferring changes in rank over time. Consequently, applying these existing methods
135 to the study of social mobility will require some refinements. First, if social mobility is rare, then
136 noise in calculations of social rank will make it difficult to distinguish true mobility events from
137 false identification of rank changes [25]. Thus, the study of social mobility requires the
138 development of approaches that accurately estimate social mobility and account for uncertainty
139 (Box 1). Additionally, more work should focus on measuring intergenerational mobility. To
140 measure intergenerational mobility, researchers can use parent-offspring correlations between
141 rank, as is often done in economics. An alternative approach is to compare observed offspring
142 rank to a rank based on a reference model where offspring win and lose interactions with equal
143 probability as their parents [42]; this approach may be less biased by differences between
144 parents and offspring in observation time or interaction rate. Finally, more work needs to
145 address how to decompose mobility into active and passive components. Techniques have

146 been advanced for decomposing changes in ordinal rank (e.g., rank 1, 2...n) into passive and
147 active mobility [25], but this method does not work for cardinal ratings (e.g., David's scores, Elo-
148 rating), which are sometimes preferable (e.g., when measuring hierarchy steepness; [43–45]).
149 In sum, a fruitful path forward is to continue refining methods for inferring hierarchy dynamics at
150 the individual level.

151

152 Box 1 - Methodological challenges in inferring hierarchy dynamics

153 A few studies have made progress towards improving the efficacy of ranking methods for
154 identifying mobility, but considerable work remains. Approaches that determine ranks based on
155 discrete subsets of the data and infer changes by comparing these rank orders overestimate the
156 true amount of mobility [25]. This issue can be alleviated by using an “updating” process to rank
157 individuals in each study period based on prior ranks informed by newly collected data. This
158 updating approach is implemented by default in the Elo-rating and Glicko-rating methods
159 [44,46–49], but can also be incorporated into other commonly used types of ranking methods
160 such as David's Scores or matrix reordering [25]. An issue with approaches that update scores
161 after each encounter (e.g., Elo-rating and Glicko) is that they require some data to be allocated
162 to an initial “burn-in” period during which hierarchy position and dynamics are discarded as part
163 of a process of statistical convergence, leading to lost data. This problem can be exacerbated
164 when there is a high degree of demographic turnover and initial data for new individuals are
165 reserved for burn-in [50]. Solutions for this problem include using prior information to help place
166 new individuals [25,50] or using statistics to estimate starting scores of new individuals based
167 on the outcomes of early interactions [51,52].

168

169 A crucial methodological decision when identifying social mobility is to determine the time period
170 over which potential dynamics are assessed. The more frequently potential changes are
171 assessed, the more potential changes can be found. For instance, assessing an individual's

172 change monthly over a year can lead to the identification of 11 changes in position, whereas
173 measuring mobility daily over the same period could potentially identify 364. Accordingly,
174 sampling for dynamics more frequently leads to the identification of more changes [25]. There
175 are dangers to assessing potential changes both too frequently or too infrequently — if changes
176 are assessed too rarely, real changes can be missed or misinterpreted (i.e., false negatives)
177 [44], while assessing changes too frequently can lead to inference that is overly sensitive to
178 uncertainty in an animal's relationships (i.e., false positives). If only a few individuals or
179 interactions are sampled during the periods over which mobility is assessed, this will lead to an
180 overestimation of the number of changes and an underestimation of the rate of change (i.e.,
181 rank instability; see Group level section). Data-splitting approaches can be used to assess the
182 timescale over which a rank order is predictive of future interaction outcomes [53], providing a
183 guide for the appropriate time-scale over which to assess potential hierarchy dynamics. Finally,
184 we recommend a sanity check for a correspondence between the particulars of a given study
185 (e.g., question of interest, study organism) and the time-scale over which hierarchy dynamics
186 are assessed. For instance, assessing hierarchy dynamics over very short time-scales is
187 appropriate for studies focused on fine-scale patterns in the emergence of hierarchical social
188 structure in small groups of short-lived animals [54]. In contrast, assessing hierarchy dynamics
189 over longer time-scales is more appropriate for studies of the fitness consequences of
190 dominance trajectories in large groups of long-lived species, where some individuals may only
191 interact infrequently and the outcome of interest (e.g., reproductive success) operates over long
192 time-scales [12]. In this sense, we advise against a default paradigm of assessing dynamics
193 daily or after every interaction, as is currently typically done with the Elo-rating method.

194

195 The last challenge for measuring social mobility is identifying and accounting for uncertainty.

196 There is a pressing need to expand methods for detecting social mobility to account for

197 uncertainties in rank orders. Otherwise, measurement error can lead to the overestimation of

198 social mobility and lead the noise of spurious social mobility to swamp the signal of true social
199 mobility. This is particularly challenging because it is difficult to distinguish *measurement*
200 *uncertainty* in rank order — arising from sampling bias, observer error, and missing data — from
201 *biological uncertainty* in rank relationships among individuals (McCowan contribution to this
202 issue). In fact, because active intragenerational mobility by definition involves changing
203 dominance relationships, biological uncertainty in rank orders is expected to increase during
204 periods of active mobility. Therefore, a crucial step is to develop methods for measuring and
205 interpreting uncertainty in estimates of social mobility. The Glicko-rating, randomized Elo-rating,
206 and Percolation and Conductance (PERC) methods incorporate approaches for quantifying
207 uncertainty around inferred dominance ranks or scores [40,47,55], but no study has yet used
208 these uncertainty estimates when inferring hierarchy dynamics.

209

210 *How do dominance trajectories across life produce fitness trajectories and impact selection on*
211 *status-seeking behaviour?*

212 Dominance rank is often linked to fitness [6], but we know relatively little about the temporal
213 dynamics of these effects. Effects of rank could be ephemeral, with each instance of rank
214 change causing corresponding changes in rank-related outcomes ([27]; Tung this issue), or they
215 could be persistent and manifest even after individuals undergo social mobility [56]. Moreover,
216 the way in which individuals move through the hierarchy over the course of their lifetime can
217 moderate short-term influences between rank and fitness [6,8,57]. For instance, the costs of
218 dominance status acquisition can offset the benefits of high rank [58–60], making it necessary
219 for individuals to hold high status for sufficient time to gain a net benefit. Furthermore,
220 individuals could all show similar trajectories over life — in such a case, subordinates may
221 appear to be paying a fitness cost by being subordinate, when instead they will eventually enjoy
222 dominant status, and in fact all individuals may experience relatively equal lifetime fitness. The
223 dynamics of rank across development (e.g. being raised by humans is associated with reduce

224 dominance in juvenile greylag geese (*Anser anser*) [61]) and life-history stages (e.g., dispersal
225 in spotted hyenas [62]) add further complexity to the ways that dynamic rank links to fitness.

226

227 Critically, in addition to modulating short-term associations between rank and fitness,
228 dominance trajectories can reflect selection on status-seeking behaviour or influence the
229 stability of social systems. For instance, some have suggested that an on-average tendency to

230 improve in social status over the life course is critical for maintaining persistent groups [36].

231 Theoretical work suggests that if subordinates can achieve high status by queuing, this relaxes

232 selection on status-seeking behaviour and could lead subordinates to be more tolerant of

233 despotism by dominants [57]. Subordinate individuals with similar rank may vary in status-

234 seeking behaviours (e.g., information collecting, prospecting, challenging dominants) that later

235 influence their trajectory in social status [63–65]. In sum, to truly understand the influence of

236 rank on fitness and the evolution of status-seeking behaviour, it is necessary to examine

237 dominance trajectories over individuals' lifetime to understand how fitness outcomes vary as a

238 function of rank and mobility over the life course. Here, theoretical models of optimal strategies

239 under different dominance trajectory regimes [57] and long-term individual-based studies will be

240 particularly valuable.

241

242 This life-course approach of dominance trajectories also opens an opportunity to take a life-

243 history view of status-seeking behaviour. From this perspective, how individuals invest in status-

244 seeking behaviour across a lifetime will depend on a combination of the fitness consequences

245 of status, the longevity of such effects, and the probable mechanisms of rank change (i.e., intra-

246 vs. intergeneration mobility, active vs. passive mobility) [57,64]. For example, in systems where

247 rank and fitness are highly correlated, and upward social mobility is largely passive, selection

248 may favor life-history strategies that increase longevity to maximize the chances of attaining

249 high rank by persisting in the queue. Conversely, in systems where active mobility

250 predominates, selection may favor early investment in growth in order to maximize the
251 probability of displacing dominants. Such integration of social dynamics and life-history theory
252 will contribute to an emerging perspective on life history of social behaviour [66–68]. In total,
253 viewing dominance rank as a trajectory that unfolds over the life course will reveal typical
254 patterns of dominance trajectories, potential alternative strategies to maximizing fitness in
255 hierarchical societies, and the role of social mobility in the evolution of status-seeking behaviour.

256

257 **Dyadic level**

258 *How do dominance relationships form and dissolve?*

259 A century ago, Thorleif Schjelderup-Ebbe [1] presented a simplistic verbal model of how
260 dominance relationships form and change, stating of a contest between hens A and B: "If B
261 wins she will become the despot, possibly forever but in any case for the time being." Over a
262 century of research on dominance, considerable progress has been made in understanding how
263 the outcomes of interactions influence individual behavior and physiology, but the dynamics of
264 dyadic relationships are less well-understood. What processes lead some dominance
265 relationships to form and persist, whereas others change, and still others are never formed?

266

267 A major insight from the last century of dominance research is that dominance relationships are
268 influenced by the social context in which they operate — that is, dyadic dominance relationships
269 are not determined in a vacuum, but are instead influenced by other dyadic relationships [69–
270 71]. Dyads in newly formed groups tend to form dominance relationships producing transitive
271 triads, demonstrating how the formation of relationships plays a causal role in shaping the
272 formation of other relationships within the group [70,72,73]. A survey of dominance hierarchy
273 structure across broad taxonomic groups confirms that this tendency towards transitive triads is
274 a reliable feature of dominance hierarchies [74]. Most recently, work in chickens, cichlids, and
275 mice tracking all interactions among small newly formed groups provides an in-depth look into

276 how dominance hierarchies emerge and persist after formation, showing that even after
277 establishment, shifting dominance relationships still tend to change from one transitive network
278 to another [54]. These results suggest that dominance hierarchies are best thought of as
279 existing in a state of “dynamic stability,” where dyadic relationships and individual positions in
280 the hierarchy change but the overall transitive structural feature of the hierarchies remains
281 constant. This impressive literature reveals why some dominance relationships are more likely
282 to form than others, but we still don’t know what processes produce the dynamics in dyadic
283 relationships that give rise to this dynamic stability.

284

285 Individual and dyadic interaction history are processes that can contribute to the dynamics of
286 dyadic dominance relationships. Theoretical and empirical work has demonstrated that
287 dominance interactions lead to winner and loser effects, where the winners (losers) of
288 interactions perceive themselves as more (less) able to win contests, and thus increase
289 (decrease) their probability of winning subsequent interactions [29,75–77]. These winner- and
290 loser-effects operate in addition to intrinsic differences in individual competitive ability to affect
291 individual rank [78], but it is less clear how such effects impact dyadic relationships. Insofar as
292 dominance relationships result from the combination of interactions [79,80], these effects of
293 prior interaction experience are expected to influence dominance relationship formation [29].
294 However, in many species, individuals recognize group-mates, so dominance relationships
295 formed between pairs of individuals are impacted by their specific dyadic interaction history
296 [81,82]. When two individuals interact, the status of their dominance relationship is probed,
297 reinforced, or altered [79]. For unfamiliar individuals, repeated interactions quickly lead to the
298 establishment of a dominance relationship, which is characterized by an overall reduction in
299 aggression [83]. Repeated interactions can also lead to a change in how dominance
300 relationships are assessed. For instance, in golden-crowned sparrows (*Zonotrichia atricapilla*),
301 experimental enhancement of head plumage to signal higher dominance influenced dominance

302 relationships among strangers but not among familiar flockmates, suggesting a move from
303 reliance on status signals to recognition-based mechanisms of dominance relationship
304 assessment [84]. In established relationships, additional interactions typically reinforce the
305 existing dominance relationship, but can sometimes counter it and lead to its reversal.
306 Individual-level changes such as winner/loser effects or changes in competitive ability play a
307 role in the dynamics of these relationships, but are insufficient to fully explain these dyadic
308 phenomena. Future work can shed new light on the evolution of dominance by exploring how
309 individuals integrate information from prior interactions with specific opponents to form stable
310 yet dynamic dyadic relationships.

311

312 Specifically, a productive way to deepen understanding of how dominance relationships form
313 and dissolve requires the development of *interaction-to-relationship* models of how repeated
314 interactions with particular opponents are integrated to form relationships [85]. These models
315 should be able to reproduce typical patterns of dominance relationships, where established
316 relationships form, remain stable, but can also change to a new stable state after new
317 interactions — that is, relationships that once formed remain stable “possibly forever, but in any
318 case for the time being.” Feedback loops between interaction outcomes and their determinants
319 (e.g., body size, resource holding potential) suggest mechanisms by which stable dominance
320 relationships might be pushed over a tipping point [30,86]. Interaction-to-relationship models
321 need to consider a) potential time dependency in the influence of interactions on relationship
322 status [87], b) effects of social context on the dyadic dominance relationship [70,71], and c)
323 underlying cognitive models by which individuals understand their relation to their groupmates.

324

325 Empirical studies point to some alternative plausible cognitive models underlying dominance
326 relationships. Individuals may track group consensus about position in the dominance hierarchy
327 [88], track the aggression received by group members and use it to infer position in the

328 hierarchy [89], monitor aggression network structure using transitive inference [89], remember
329 their specific relationship with other members of the group [90], attend to signals reflecting
330 competitive ability [91], or some combination of these models. These models make predictions
331 about how dominance relationships might change under different perturbations, such as the
332 removal of the dominant individual, changes in physical condition, social mobility among other
333 group-members, or stochastic outcomes of interactions that don't align with the dominance
334 relationship. These cognitive models also imply differences in access to third-party information
335 and other social information about the ranks of groupmates [92,93]. Theoretical models and
336 agent-based simulations [94] present a promising venue to establish where models make
337 different predictions about the dynamics of dyadic relationships. Empirically testing many of
338 these models may require complete or nearly complete interaction data, so these tests are best
339 suited for captive systems that support high-resolution data collection [83], potentially aided by
340 automated data collection [95].

341

342 *When and why do dyads interact?*

343 Why do some dyads compete more than others? We know that in many species, attributes of
344 dyads — for instance, kinship, size similarity, or sex-homophily — influence the frequency of
345 agonistic interactions within dyads [96,97]. Rank differences between individuals also shape
346 interactions, for instance leading to increased likelihood of escalation of interactions among
347 closely-ranked individuals [98]. Recently, aggregated data on dominance interactions across a
348 broad array of species has examined the occurrence of multiple rank-difference-based patterns
349 of aggressive contests [92]. In the “downward heuristic” pattern, dyads interact at random with
350 respect to rank differences. In contrast, in the “bullying” pattern, dyads with increasing rank
351 differences are more likely to interact, and in the “close-competitors” pattern, dyads with
352 increasing rank differences are less likely to interact [92]. This work suggests potential
353 strategies determining when and why dyads choose to interact, inferred from these social

354 dominance patterns. More work is needed to understand the processes that give rise to these
355 patterns (Dehnen et al. this issue), how they change over time, and what they reveal about the
356 dynamics of dyadic dominance relationships.

357

358 Interaction-to-relationship models (see previous section) are likely to make different predictions
359 about the occurrence of these social dominance patterns. Newly formed groups of monk
360 parakeets (*Myiopsitta monachus*) show unstructured aggression early after group-formation but
361 quickly converge on the close-competitor pattern, indicating how these patterns may reflect the
362 process of dominance relationship formation [89]. A promising future direction is to inquire how
363 interaction strategies combine with different interaction-to-relationship models to influence the
364 stability of dyadic relationships and overall hierarchical stability (see next section). Are certain
365 strategies more effective at ensuring the stability of dyadic relationships? For instance, under
366 some interaction-to-relationship models, bullying the lowest-ranked group member is predicted
367 to reinforce dyadic dominance relationships broadly with other group members, whereas under
368 other models it is predicted to only influence the dyadic relationship of the bully and her target.
369 Addressing this question will reveal how dyadic interaction strategies influence dominance
370 hierarchy dynamics across scales [99].

371

372 A challenge for understanding when and why dyads interact is that aggregated interaction data
373 do not contain full information on the processes that influence dyadic interaction. These data
374 only reflect interactions that occurred, but avoidance, long-distance signals, and behavioural
375 state can influence how dyads interact by eliminating interactions [96,100]. Furthermore, dyadic
376 interactions could be driven by the behaviour of the dominant or the subordinate member of the
377 dyad (e.g., a subordinate approaching a dominant who is feeding), but agency over the
378 interaction is often assumed to belong to the dominant individual. A solution to these problems
379 is to incorporate data on these other covariates into analysis of dyadic interaction rate. For

380 instance, Dehnen et al (this issue) account for spatial subgrouping when calculating their
381 measures of the tendency for vulturine guineafowl (*Acryllium vulturinum*) dyads to interact,
382 reflecting interaction decisions after accounting for the opportunity to interact. Incorporating data
383 on the initiation of interactions (e.g., approaches) can reveal the extent to which dominant or
384 subordinate individuals are influencing dyadic interaction rates.

385

386 **Group level**

387 *What are the causes and consequences of social instability?*

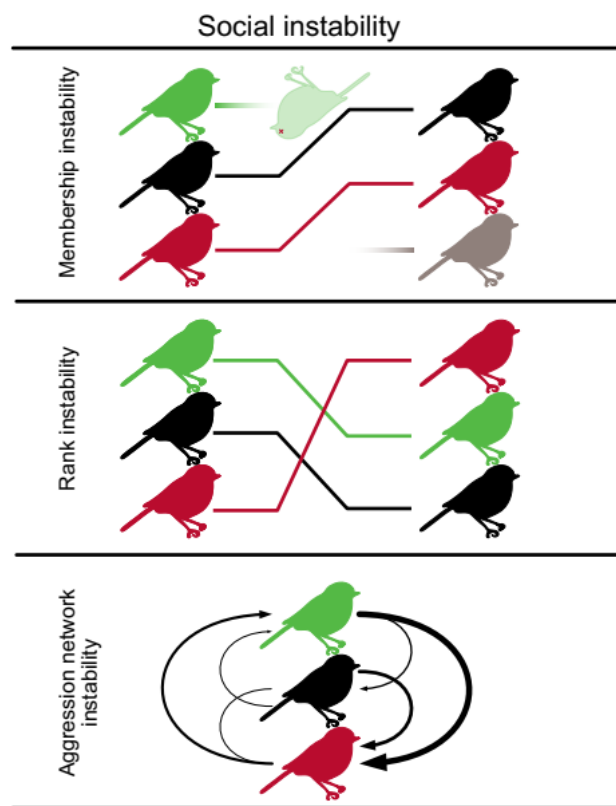
388 Schjelderup-Ebbe hypothesized that dominance hierarchies serve to regulate conflict among
389 group-members [1]. A corollary to this hypothesis is that social instability — i.e., changes to a
390 social group's dominance hierarchy — leads to increased conflict and its associated costs.
391 Thus, an ongoing area of research is aimed at identifying periods of instability and determining
392 the consequences of social instability for group members [101–103]. If instability is often not
393 costly, this would challenge the idea that stable hierarchies arise as conflict regulatory
394 adaptations [104]. Finally, there may be feedback between social instability and dominance-
395 related traits, where competitive strategies differ in species with stable hierarchies compared to
396 those with unstable hierarchies. For these reasons, to understand the role of dominance
397 dynamics in animal societies, it is critical to explain the causes and consequences of social
398 instability.

399

400 A major challenge to the study of social instability is to agree on what it is, how to talk about it,
401 and how to measure it. In some studies, social instability is defined as a measure of changes in
402 group composition [103,105,106], for instance due to the loss or gain of many individuals or the
403 occurrence of group fission. In other studies, instability is defined by rearrangements of the
404 dominance hierarchy or by changes in individual-level dominance rating over time [44,50,107].
405 Instability is also sometimes defined a third way, as a reduction in orderliness of the aggression

406 network. Here, instability is measured by an increase in intransitivity in dominance relationships
407 [102], or by an increase in the frequency and inconsistency of dominance interactions [108].
408 Although thematically linked, these different types of instability don't necessarily arise from the
409 same processes or have the same consequences. In order to properly understand sources of
410 social instability and its impacts on animals, it is crucial to refine the concept to distinguish
411 between these different patterns. We suggest distinguishing *membership instability* — caused
412 by demographic turnover [68] — from *rank instability*, caused by changes in the ordering of
413 individuals in the hierarchy. Finally, *aggression network instability* is defined by an increase in
414 uncertainty and intransitivity in aggression networks (Figure 2).

415



416

417 **Figure 2.** Three types of social instability. Membership instability results from demographic
418 turnover. Rank instability results from rearrangements of the order of individuals within the

419 social hierarchy. Aggression network instability results from a reduction in orderliness (e.g.,
420 transitivity, directional consistency) of the aggression network.

421
422 Distinguishing among these types of instability is especially important because they can interact
423 in important ways. Demographic turnover can have direct effects on dominance hierarchies by
424 removing or adding individuals and their relationships with others in the group, but can also
425 have indirect effects on other individuals [68]. Influx of new individuals can lead to rank
426 instability — this is especially common in species with multi-male groups where males compete
427 for dominance. For instance, during the mandrill (*Mandrillus sphinx*) mating season, an
428 increased influx of males leads to increased intra-sexual competition, more active mobility
429 among males and consequently higher rank instability, and higher levels of oxidative damage in
430 high ranking males [101]. The loss of certain key individuals can also lead to rank instability
431 [109,110] and aggression network instability [111], or even group collapse [112]. Membership
432 instability, rank instability, or aggression network instability may be more impactful if it occurs in
433 the upper portion of the hierarchy [44,110]. Despite these avenues for interaction between
434 types of social instability, it is also possible for each to occur independently of the others.
435 Finally, in natural populations, extreme instability of these different types may occur rarely but
436 have a large impact on animal societies, emphasizing the need to study these processes over
437 long time-scales.

438
439 Methods exist for quantifying these different types of social instability, but again this is an area
440 where there is room for improvement. To quantify membership instability, similarity metrics
441 [113–115] can be used to assess differences in group composition between two time periods,
442 even when group membership is not binary. Future work should aim to identify a metric that
443 optionally weights measures of demographic turnover by the attributes (e.g., sex, rank) of
444 individuals who join or leave the group. Multiple approaches exist for quantifying rank instability.

445 One approach is to calculate an index based on the amount of active mobility taking place from
446 one study period to the next. The S index [44] measures hierarchical instability in this way, but it
447 has some shortcomings — “study periods” have a fixed length of one day, mobility among
448 highly-ranked individuals is weighted more heavily than others, and there is no way to account
449 for measurement uncertainty. Future work should aim to extend this approach to assess
450 instability over more biologically relevant time frames (Box 1; [53]), incorporate measurement
451 uncertainty [40], and optionally weight instability among all individuals equally. Aggression
452 network instability can be measured from the aggression network itself, for instance as
453 frequency of the occurrence of intransitive triads [74] or the amount of uncertainty in the network
454 [55]. However, doing so relies on the assumption that intransitivity reflects instability rather than
455 a stable but intransitive state [102,104], an assumption which has received some support [85]
456 and some criticism [116] and will likely vary by species. It could be productive to break the
457 network into components and measure features of those components separately. For instance,
458 the Helmholtz-Hodge decomposition can be used to break an aggression network into the sum
459 of a unique perfectly transitive network and a unique perfectly cyclical network — aggression
460 network instability can then be measured as the cardinality of the cyclical graph [117]. This
461 approach could also allow for independent study of cyclical and transitive elements of the
462 aggression network.

463

464 **Conclusion**

465 Dominance hierarchies are enigmatically both stable and dynamic. As a repeated pattern of
466 asymmetry in agonistic outcomes between individuals, the concept of dominance is founded
467 upon some element of stability [80]. However, dominance relationships can also undergo rapid
468 reversals, leading sometimes to dramatic changes in individual rank and group-level social
469 instability. Nevertheless, even when relationships change, hierarchies gravitate towards the
470 same underlying structural state of transitivity [54].

471
472 After a century of research on dominance hierarchies, we are still left with many questions to
473 explore about how and why dominance hierarchies change over time, and what impact these
474 changes have on animal societies. Hierarchy dynamics occur at three scales — individual,
475 dyadic, and group (Figure 1) — and open questions remain about the dynamics of dominance
476 occurring at each of these scales (Table 1). We have known for some time that individual ranks
477 change over time (e.g., as individuals grow and age), but conceptual clarity about the different
478 forms of social mobility will aid us in making sense of how evolution has molded social traits and
479 optimal status-seeking behavior in the context of life history. One critical need is to extend
480 methods for inferring dynamics at the individual and group scales. These methods need to
481 account for measurement uncertainty, and guidelines are needed for determining the time-scale
482 at which to assess hierarchy dynamics. Fortunately, these are already active areas of research
483 [25,44,53,118]. At the dyadic level, more work is needed to understand when and with whom
484 individuals choose to interact [92], and how these interactions are integrated to form a
485 relationship [85]. Here, a combination of model development and studies in captive groups
486 provide a promising avenue for insight through an iterative process of model testing and
487 refinement. Captive groups where high-resolution interaction data can be collected are
488 promising systems in which to test different interaction-to-relationship models [54,83]. Across
489 scales, study systems where rank can be manipulated (e.g., Tung this issue) will be extremely
490 useful for conducting targeted experiments testing hypotheses about the causes and
491 consequences of the dynamics of dominance. Finally, long-term individual-based studies will be
492 essential for interrogating dynamics occurring at long time scales and for studying the impact of
493 rare events. We hope that this research agenda enables new insight into the dynamics of
494 dominance and further extends the last century of productive research into this fundamental
495 dimension of social organisms.

496

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505

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