

1 **Title:** Individual identity information persists in learned calls of introduced parrot populations

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25 **Abstract**

26 Animals can actively encode different types of identity information in learned communication

27 signals, such as group membership or individual identity. The social environments in which

28 animals interact may favor different types of information, but whether identity information

29 conveyed in learned signals is resilient or responsive to social disruption over short

30 evolutionary timescales is not well understood. We inferred the type of identity information

31 that was most salient in vocal signals by combining computational tools, including supervised

32 machine learning, with a conceptual framework of “hierarchical mapping”, or patterns of

33 relative acoustic convergence across social scales. We used populations of a vocal learning

34 species as a natural experiment to test whether the type of identity information emphasized in

35 learned vocalizations changed in populations that experienced the social disruption of
36 introduction into new parts of the world. We compared the social scales with the most salient
37 identity information among native and introduced range monk parakeet (*Myiopsitta*
38 *monachus*) calls recorded in Uruguay and the United States, respectively. We also evaluated
39 whether the identity information emphasized in introduced range calls changed over time. To
40 place our findings in an evolutionary context, we compared our results with another parrot
41 species that exhibits well-established and distinctive regional vocal dialects that are
42 consistent with signaling group identity. We found that native and introduced range monk
43 parakeet calls both displayed the strongest convergence at the individual scale and minimal
44 convergence within sites. We did not identify changes in the strength of acoustic convergence
45 within sites over time in the introduced range calls. These results indicate that the individual
46 identity information in learned vocalizations did not change over short evolutionary timescales
47 in populations that experienced the social disruption of introduction. Our findings point to
48 exciting new research directions about the resilience or responsiveness of communication
49 systems over different evolutionary timescales.

50

51 **1. Introduction**

52 Animals can use communication signals to transmit social information, including group
53 membership, individual identity, social status, sex, or other social characteristics (Bradbury &
54 Vehrencamp, 1998; Seyfarth, Cheney, Bergman, Fischer, Zuberbühler, et al., 2010). The
55 types of identity information that animals encode in signals may be an outcome of differences
56 in the social environment within or among species. Different types of information may be more
57 or less important for animals to communicate in social environments that can change over
58 ecological or evolutionary timescales (Bergman, 2010; Hobson, 2020; Hobson, Mønster, &
59 DeDeo, 2021; Ramos-Fernandez, King, Beehner, Bergman, Crofoot, et al., 2018).

60 Vocalizations are well-studied communication signals that can contain identity
61 information. For example, voice cues arising from vocal tract filtering can provide receivers
62 with information about individual identity (Furuyama, Kobayasi, & Riquimaroux, 2016; Prior,
63 Smith, Lawson, Ball, & Dooling, 2018; Rendall, Owren, & Rodman, 1998). However,
64 individuals can also use social learning to modify identity information, such as vocal learning
65 species that can encode both group-level and individual identity information in learned
66 vocalizations in a stable manner. When individuals imitate vocalizations of their social
67 companions, the resulting group-level acoustic convergence can be used to recognize group
68 members (Boughman & Wilkinson, 1998; Nowicki & Searcy, 2014; Sewall, Young, & Wright,
69 2016). Learned vocalizations with group identity information, such as vocal dialects, have
70 been reported in several vocal learning taxa, including cetaceans (Janik & Slater, 1998;
71 Jones, Daniels, Tufano, & Ridgway, 2020; Nousek, Slater, Wang, & Miller, 2006; Rendell &
72 Whitehead, 2003; Watwood, Tyack, & Wells, 2004), bats (Boughman, 1998), songbirds
73 (Mammen & Nowicki, 1981; Sewall, 2009;2011), and parrots (Martinez & Logue, 2020; Wright,
74 1996). Individuals can also communicate individual identity information by developing
75 distinctive vocalizations that differentiate them from other individuals. For instance, bottlenose
76 dolphins (*Tursiops truncatus*) and green-rumped parrotlets (*Forpus passerinus*) can use vocal
77 learning to produce distinctive individual signatures used for individual vocal recognition
78 (Berg, Delgado, Okawa, Beissinger, & Bradbury, 2011; Berg, Delgado, Cortopassi, Beissinger,
79 & Bradbury, 2012; Janik, Sayigh, & Wells, 2006; Kershenbaum, Sayigh, & Janik, 2013).

80 These findings from the same or closely related taxa suggest that changes in the social
81 environment could influence the identity information that animals encode in learned
82 vocalizations. For instance, living in large social groups or interacting repeatedly with different
83 individuals may favor signaling individual identity information, due to either the pressure of
84 providing sufficient information for receivers to discriminate among unique individuals (Pollard

85 & Blumstein, 2011), or the relative benefits and costs associated with maintaining many
86 different social relationships (Tibbetts & Dale, 2007). However, the degree to which identity
87 information encoded in learned communication signals dynamically responds to changes in
88 social conditions over short evolutionary timescales is not well understood. Short-term
89 changes in the social environment can influence identity information in learned vocalizations.
90 For instance, captive and wild Puerto Rican Amazon parrots (*Amazona vittata*) exhibit distinct
91 vocal dialects that have arisen over only a few decades, and translocated individuals will
92 switch to calling in the dialect of the local population (Martinez et al., 2020). In a field
93 experiment with yellow-naped amazons (*Amazona auropalliata*), a juvenile translocated
94 between regional populations also switched to calling in the local vocal dialect (Salinas-
95 Melgoza & Wright, 2012). However, regional dialect boundaries in this species remained
96 stable over 11 years (Wright, Dahlin, & Salinas-Melgoza, 2008), despite natural dispersal of
97 individuals across dialect boundaries (Wright, Rodriguez, & Fleischer, 2005). In elephant
98 seals (*Mirounga angustirostris*), increasing population size appears associated with a change
99 in the type of identity information encoded in learned vocalizations over short evolutionary
100 timescales. As recovering populations grew in size over 50 years, vocal dialects were
101 replaced by more structurally complex calls that displayed greater individual distinctiveness
102 (Casey, Reichmuth, Costa, & Le Boeuf, 2018).

103 To test whether identity information in vocalizations is resilient or responsive to short-
104 term changes in the social environment, we need two critical components: a way to quantify
105 the relative salience of different types of identity information in learned signals and the
106 potential to compare identity information across groups with different social characteristics.

107 First, new tools are needed to better quantify the salient types of information in
108 vocalizations. Computational approaches like machine learning can be applied within a
109 conceptual framework that links patterns of vocal convergence to identity signaling.

110 Individuals should use vocal learning to converge on vocalizations across different scales of
111 social organization (Smith-Vidaurre, Araya-Salas, & Wright, 2020), and such vocal
112 convergence should yield “hierarchical mapping” patterns, which are patterns of relative
113 acoustic convergence that vary in a stable manner across social scales (Bradbury et al.,
114 1998). To evaluate hierarchical mapping patterns, we can use machine learning tools to
115 quantify relative acoustic convergence over different social scales, for example, from
116 individuals to flocks or regional populations. From hierarchical mapping patterns, we can use
117 the social scale with the strongest relative acoustic convergence to infer the most salient type
118 of identity information encoded in vocalizations. This conceptual framework assumes that
119 patterns of acoustic convergence reflect identity information encoding that is stable across
120 social contexts, in contrast to the rapid vocal matching exhibited by some vocal learners that
121 should yield varying patterns of acoustic convergence and divergence in real time (Balsby &
122 Bradbury, 2009; King & Janik, 2013; Scarl & Bradbury, 2009; Vehrencamp, Ritter, Keever, &
123 Bradbury, 2003).

124 Second, we can compare hierarchical mapping patterns among groups with historical
125 variation in population stability to test whether identity information in learned vocalizations is
126 resilient or responsive to disruption of the social environment. We can leverage different types
127 of natural experiments for this comparison, including the introduction of species to new parts
128 of the world, which can cause founder effects that influence traits transmitted by genetic
129 inheritance and by social learning in introduced populations (Aplin, 2019; Dlugosch & Parker,
130 2008). Introduction events that expand a species’ range can be thought of as an extreme form
131 of social disruption. In particular, when this process occurs through the pet trade, individuals
132 are removed from their natural social environments, placed in captivity for transport, and then
133 can remain in captivity throughout the remainder of their lives, such as in breeding colonies
134 that sustain the pet trade. These original individuals or their captive-bred descendants can

135 found new populations after escaping or being released from captivity (Blackburn, Pysek,
136 Bacher, Carlton, Duncan, et al., 2011; Carrete, Edelaar, Blas, Serrano, Potti, et al., 2012;
137 Chapple, Simmonds, & Wong, 2012). New populations established outside of the native
138 range after this form of social disruption should be small shortly after establishment. However,
139 if boom and bust population growth leads to increased population size after establishment
140 (Blackburn et al., 2011), then social environments that are similar to native range populations
141 could gradually re-establish in the introduced range. Alternatively, the effects of social
142 disruption could persist over generations and influence learned vocal outcomes, since vocal
143 learning is a social process. For example, there could be fewer overall numbers of individuals
144 available for social interactions in introduced populations, which could alter the cognitive costs
145 of social recognition for receivers (Sewall et al., 2016; Tibbetts et al., 2007), and in turn, alter
146 the type of identity information that signalers convey in learned vocalizations compared to the
147 native range.

148 In this study, we focused on native and introduced range populations of monk
149 parakeets (*Myiopsitta monachus*) to test how social disruption that occurred generations ago,
150 over the course of the past 50 years, could cause changes in the type of identity information
151 encoded in contact calls. Parrots are suitable for this research because they can use social
152 learning to both acquire and modify “contact” calls, which individuals are thought to use to
153 maintain contact with their social companions while flying and foraging (Bradbury & Balsby,
154 2016). Monk parakeets in particular are also suitable because they have established new
155 populations worldwide through the pet trade since the late 1960s, enabling comparisons
156 between native range populations and introduced range populations. The independently
157 established introduced range populations share a common origin, with the majority of these
158 populations stemming from native range populations in Uruguay and the surrounding region
159 of northern Argentina (Edelaar, Roques, Hobson, Goncalves Da Silva, Avery, et al., 2015;

160 Hobson, Smith-Vidaurre, & Salinas-Melgoza, 2017; Russello, Avery, & Wright, 2008; Smith-
161 Vidaurre, 2020). In addition, we know more about monk parakeets' social system than most
162 parrot species. While social relationships among pairs are important, experiments with captive
163 social groups indicate that this species is capable of hierarchical social organization, which
164 could extend to wild populations (Hobson, Avery, & Wright, 2013;2014; Hobson, John,
165 McIntosh, Avery, & Wright, 2015; van der Marel, Francis, O'Connell, Estien, Carminito, et al.,
166 2022). Finally, recent work has contributed to growing knowledge of this species' vocal
167 communication system (Smeele, Tyndel, Aplin, & McElreath, 2022; Smeele, Senar, Aplin, &
168 McElreath, 2023; Smith-Vidaurre et al., 2020; Smith-Vidaurre, Perez-Marrufo, & Wright,
169 2021).

170 We used introduced range monk parakeet populations in the United States (U.S.) as
171 independent replicates of populations established following social disruption. Recent work
172 with monk parakeets supports the idea that the introduction process, including transport out of
173 the native range and housing in long-term captivity, represents a form of extreme social
174 disruption. Under naturalistic conditions, removing even a single individual from an
175 established social group consistently disrupts monk parakeets' dominance ranks (van der
176 Marel et al., 2022). In the U.S. introduced range, social disruption through the pet trade has
177 occurred over short evolutionary timescales, beginning about 50 years ago. The earliest
178 sightings of monk parakeets in the U.S. were reported in 1969, although populations in some
179 states may have been established in the 1980's or later (Edelaar et al., 2015; Russello et al.,
180 2008). In our previous work, we used the term "invasive" to refer to monk parakeet
181 populations outside of the native range (Smith-Vidaurre et al., 2020;2021). We now use the
182 term "introduced" to refer to these populations, as "invasive" and "invasions" were recently
183 identified as terms that should be changed to use more inclusive terminology in ecology and
184 evolutionary biology (Cheng, Gaynor, Moore, Darragh, Estien, et al., 2023).

185 We used contact call recordings to infer which type of identity information was most
186 salient in learned monk parakeet vocal signals. We used this approach on both native and
187 introduced range contact calls to test whether the type of identity information was the same or
188 differed between the native and introduced ranges. Previous work with native range
189 populations in Uruguay demonstrated that the strongest acoustic convergence in contact calls
190 occurs at the individual scale (Smith-Vidaurre et al., 2020). We expected that if introduced
191 populations had recovered following social disruption, then the type of identity information in
192 introduced range contact calls would not change, such that both native and introduced
193 populations would exhibit the strongest acoustic convergence at the individual scale.
194 However, if the introduction process was sufficiently disruptive, then we expected that
195 introduced range parakeets would diverge from the type of identity information used in the
196 native range, and would instead display stronger acoustic convergence at a higher social
197 scale. We placed our results in the context of longer timescales by comparing against another
198 parrot species with strong contact call convergence at higher social scales and distinctive
199 vocal dialects. Our integration of quantitative approaches with a conceptual framework of
200 hierarchical mapping patterns can be used to evaluate stable identity information encoding in
201 learned communication signals more broadly across taxa. Together, our rigorous
202 computational and comparative approaches provide new insight into how identity information
203 in learned vocal signals is resilient to social disruption over ecological timescales, but differs
204 between species representing longer evolutionary timescales.

205

206 **2. Methods**

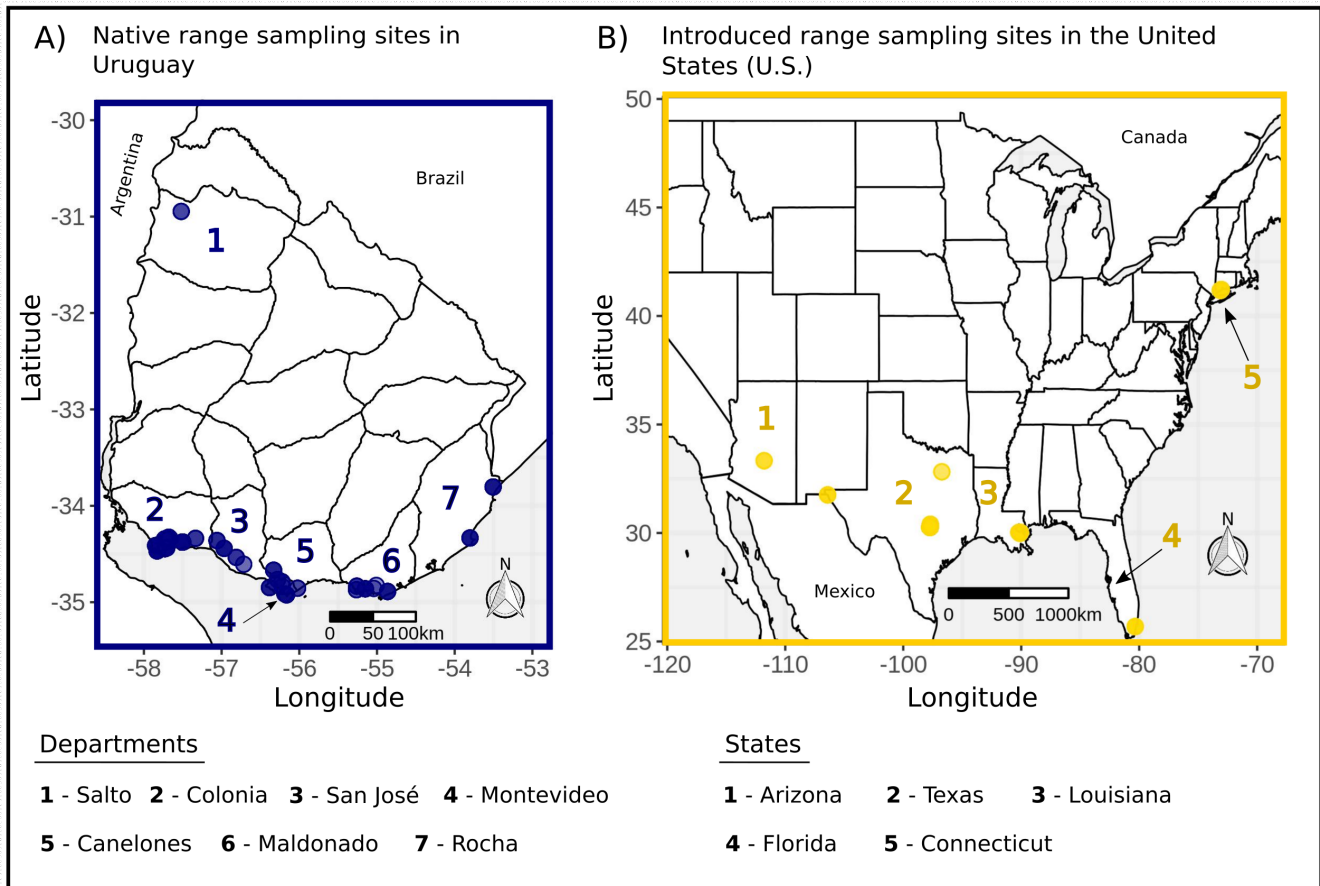
207 *2.1 Recording contact calls*

208 We recorded contact calls from native range monk parakeets in 2017 at 37 sites across 7
209 departments in Uruguay in our previous work (Smith-Vidaurre et al., 2020). Our introduced

210 range dataset included contact calls recorded at 26 sites across 5 states in the U.S. in 4
211 different sampling years: 2004, 2011, 2018, and 2019. In 2004, introduced range contact calls
212 were recorded in Connecticut, Florida, Louisiana, and Texas (calls were provided by
213 Buhrman-Deever, Rappaport, & Bradbury, 2007). We recorded parakeets in Texas and
214 Louisiana in 2011, Arizona in 2018, and Texas again in 2019. For our temporal analyses
215 below, we relied on contact calls that we recorded in Texas in 2004, 2011, and 2019 (3
216 sampling years), and contact calls recorded in Louisiana in 2004 and 2011 (2 sampling years,
217 see supplementary section 1).

218 Recording sessions in 2004 used Marantz PMD670 or PMD690 recorders with
219 Sennheiser ME67K6 shotgun microphones, and these recordings were digitized at 48000 Hz
220 and 16 bit depth (Buhrman-Deever et al., 2007). In all other recording sessions we used
221 Marantz PMD661 MKII and PMD660 solid state recorders, Sennheiser ME67 long shotgun
222 microphones and foam windscreens, and we digitized our recordings at 44100 Hz sampling
223 rate and 16 bit depth (Smith-Vidaurre et al., 2020;2021). All recorded individuals were
224 unmarked, with the exception of a few marked individuals in the native range (Smith-Vidaurre
225 et al., 2020).

226



229 **Figure 1:** Map of contact call recording sites for (a) native range populations in Uruguay and
 230 (b) introduced range populations in the United States (U.S.). We recorded parakeets across 7
 231 departments in Uruguay and 5 states in the U.S. Our geographic sampling was more
 232 contiguous in the native range, which reflected the natural contiguity of populations across the
 233 southeastern coast of Uruguay, compared to the more geographically isolated populations in
 234 the U.S. introduced range.
 235

236 *2.2 Pre-processing contact calls*

237 We manually selected contact calls from our field recordings. For our introduced range
238 recording sessions in later years, we selected contact calls using Raven version 1.4 (The
239 Cornell Lab of Ornithology Bioacoustics Research Program, 2014), consistent with native
240 range contact call selection in Smith-Vidaurre et al. (2020). The previously published
241 introduced range contact calls from 2004 were provided as clips of original recordings
242 (Buhrman-Deever et al., 2007). We performed pre-processing for all introduced range contact
243 calls, including the 2004 clips, with the warbleR package (Araya-Salas & Smith-Vidaurre,
244 2017) to implement the same quality control pipeline we had previously used for native range
245 contact calls (supplementary section 1, Smith-Vidaurre et al., 2020;2021). Our quality control
246 criteria included contact calls with signal to noise ratios of 7 or higher (e.g. calls that were at
247 least 7 times louder than background noise) that also did not display loud signals or other
248 background noise that overlapped with contact call structure. We performed the majority of
249 our pre-processing and downstream analyses in the R software environment (R Core Team,
250 2022), including the tidyverse (Wickham, Averick, Bryan, Chang, McGowan, et al., 2019).

251

252 *2.3 Social scales represented in our contact call datasets*

253 We obtained contact calls at two different social scales for the purposes of this study: the
254 individual scale, and a group scale that represented a higher level of social organization. To
255 assess contact call convergence at the individual scale, we repeatedly sampled known
256 individuals to obtain multiple exemplar contact calls produced by the same individual. This
257 individual-level dataset included 229 total contact calls from 8 native range birds (3 marked, 5
258 unmarked) recorded at 3 different sites in 2017, and 9 introduced range birds (all unmarked)
259 recorded at 7 different sites in either 2004, 2011, or 2019 (see Table A5 in Smith-Vidaurre et
260 al. (2021)). Each individual was recorded at one site only, and because the birds we recorded

261 were generally unmarked, we recorded repeat contact calls from particular individuals while
262 the calling bird was producing multiple contact calls within a short period of time (e.g. a few
263 minutes (Smith-Vidaurre et al., 2020)). After pre-processing contact calls, our individual scale
264 dataset included a median of 10 (range: 4 - 25) contact calls for the native range individuals
265 and a median of 12 (range: 5 - 28) contact calls for the introduced range individuals. Our
266 individual scale dataset provided us with sufficient sampling depth per individual to assess
267 acoustic convergence at the individual scale. We used this contact call dataset to represent
268 individual vocal signatures over a short sampling period for each repeatedly sampled
269 individual. In previous work with this same dataset, we identified individual vocal signatures
270 encoded in frequency modulation patterns (Smith-Vidaurre et al., 2021), which are widely
271 considered to be acoustic structures that animals modify by learning to create individually
272 distinctive signals (Berg et al., 2011; Fripp, Owen, Quintana-Rizzo, Shapiro, Buckstaff, et al.,
273 2005; Janik & Slater, 2000; Janik et al., 2006). While individuals' physiological states could
274 influence subtle patterns of variation in learned vocalizations (Janik & Knörnschild, 2021),
275 studies with other vocal learning taxa, such as bottlenose dolphins, have also identified
276 individual vocal signatures encoded in the frequency contours of learned vocalizations
277 recorded over short timescales (Kershenbaum et al., 2013; King et al., 2013).

278 To address contact call convergence at a group scale, we recorded and compared
279 contact calls across nesting sites. We used nesting sites as groups because parakeets likely
280 interact frequently with other individuals at the same nesting site. Monk parakeet nesting sites
281 include clusters of single or multi-chambered stick nests that are often built in close proximity
282 (Eberhard, 1998), and parakeets from nearby clusters of nests engage in social interactions
283 (Hobson et al., 2014), making it difficult to determine the boundaries of independent nesting
284 colonies. In this study, we recorded at groups of nests that were geographically separate (the
285 shortest distance among these nesting sites was 0.15 km), which we refer to hereafter as

286 “sites”. For our site scale dataset, we obtained a single contact call per bird at each site.
287 Because the parakeets usually produced a single contact call when leaving or returning to
288 their nests, we sampled a single contact call per unmarked individual at this higher social
289 scale.

290 After pre-processing, our site scale dataset included 1353 total contact calls recorded
291 at 63 sites across 37 native and 26 introduced range sites (some introduced range sites were
292 repeatedly sampled in different sampling years, see Tables A3 and A4 in Smith-Vidaurre et al.
293 (2021)). This dataset contained a median of 15 (range: 5 - 53) and 15.5 (range: 5 - 91)
294 contact calls across the native and introduced range sites, respectively. Since we recorded a
295 single contact call per unique individual at each site, our site scale dataset did not provide
296 sufficient resolution of individual vocal signatures. However, this dataset allowed us to
297 compare patterns of acoustic variation at a higher scale of social organization over broader
298 geographic areas in each range (Figure 1).

299 To compare hierarchical mapping patterns between the native and introduced ranges,
300 we used 37 native range sites separated by 0.15 – 513.59 km across 7 departments in
301 Uruguay, and 18 introduced range sites across 5 U.S. states that were separated by 0.74 –
302 3502.98 km (Smith-Vidaurre et al., 2020;2021). In our analyses below, we randomly selected
303 a subsample of sites and contact calls per site for calculations of acoustic convergence, and
304 we repeated this process over many resampling iterations, which allowed us to control for
305 non-independence among sites (e.g. sites separated by short geographic distances that may
306 be easily traversed by volant animals). To compare hierarchical mapping patterns over time in
307 the introduced range, we used a subsample of sites in Texas and Louisiana that were
308 recorded in more than one sampling year (see the respective number of sites and geographic
309 distances in supplementary section 1). For our analyses at the site scale, we also generated 3
310 versions of the site scale dataset to account for the possibility that some contact calls could

311 represent repeated sampling of the same unmarked individual(s) (supplementary section 2).
312 These 3 datasets included the full dataset of contact calls, as well as the full dataset filtered
313 by either clustering with Gaussian mixture models in the mclust R package (Scrucca, Fop,
314 Murphy, & Raftery, 2016) or visual classification methods with a custom-designed RShiny app
315 (Chang, Cheng, Allaire, Xie, & McPherson, 2018) to remove contact calls that were likely to
316 represent such repeated individual sampling (supplementary sections 3 - 7). Following
317 contact call similarity measurements, we performed all subsequent analyses with these 3 site
318 scale datasets to compare the degree of repeated individual sampling in each of the native
319 and introduced ranges, as well as to assess the robustness of our overall results at this higher
320 social scale. We used separate contact call datasets at the individual and site scales under
321 the assumption that our sampling approach captured stable patterns of acoustic convergence,
322 rather than the rapid vocal matching that some parrots exhibit in real time (Balsby et al., 2009;
323 Scarl et al., 2009; Vehrencamp et al., 2003). In other words, if individuals were using learning
324 to stably converge on vocalizations at a given social scale, then we expected to find relatively
325 higher convergence at one social scale compared to the other, regardless of the individuals
326 that we sampled at each social scale.

327 328 *2.4 Measuring contact call similarity with spectrographic cross-correlation*

329 We used contact call similarity measurements to quantify hierarchical mapping patterns.
330 Contact call similarity measurements formed the basis for our comparisons of calls within and
331 among individuals or social groups to assess hierarchical mapping patterns, or the relative
332 strength of acoustic convergence across different social scales. For instance, if individuals
333 were converging on shared contact calls within sites, then we expected that contact calls
334 compared within the same site would exhibit high similarity measurements, and lower
335 similarity measurements when compared to contact calls from different sites. We measured

336 contact call similarity with spectrographic cross-correlation (SPCC) (Clark, Marler, & Beeman,
337 1987), which has traditionally been used in studies reporting patterns of acoustic variation
338 consistent with social learning of vocalizations in parrots (Balsby et al., 2009; Berg et al.,
339 2011; Bradbury, Cortopassi, & Clemmons, 2001; Buhrman-Deever et al., 2007; Eberhard,
340 Zager, Ferrer-Paris, & Rodríguez-Clark, 2022; Guerra, Cruz-Nieto, Ortiz-Maciel, & Wright,
341 2008; Salinas-Melgoza et al., 2012; Salinas-Melgoza & Renton, 2021; Scarl et al., 2009;
342 Smith-Vidaurre et al., 2020; Wright, 1996; Wright et al., 2008). We performed SPCC with a
343 Hanning window, a window length of 378 samples, and a window overlap of 90 samples for
344 Fourier transformations, as well as Pearson's correlation method and a bandpass filter of 0.5
345 to 9kHz (Araya-Salas et al., 2017). Unless otherwise specified, we used these same
346 parameters for subsequent spectrum-based analyses. We conducted SPCC with all contact
347 calls across the native and introduced ranges, which allowed us to use this similarity
348 measurement in subsequent quantitative assessments of hierarchical mapping patterns.

349

350 *2.5 Measuring contact call similarity with supervised machine learning*

351 We also measured similarity among monk parakeet contact calls using a supervised machine
352 learning approach that identifies biologically relevant patterns of variation in avian acoustic
353 signals (Humphries, Buxton, & Jones, 2018; Keen, Ross, Griffiths, Lanzone, & Farnsworth,
354 2014; Smith-Vidaurre et al., 2020). As in our previous work (Smith-Vidaurre et al., 2020),
355 measuring similarity with a traditional method (SPCC) and a newer method (supervised
356 random forests), allowed us to verify that the hierarchical mapping patterns we identified were
357 not an artifact of using a single similarity method. We built supervised random forests models
358 with 1844 acoustic and image features, including features derived from spectrographic cross-
359 correlation (SPCC) and dynamic time warping similarity measurements, standard spectral
360 acoustic measurements, descriptive statistics of Mel-frequency cepstral coefficients, and

361 spectrogram image measurements (supplementary sections 8 – 9). We used the warbleR and
362 dtw R packages for acoustic measurements (Araya-Salas et al., 2017; Giorgino, 2009), the
363 software WNDCHRM for image measurements (Shamir, Orlov, Eckley, Macura, Johnston, et
364 al., 2008), and the MASS and base R packages to extract features (R Core Team, 2022;
365 Venables & Ripley, 2002). We trained random forests models to classify contact calls back to
366 4 repeatedly sampled individuals in each of the native and introduced ranges (156 contact
367 calls and 8 individuals total, supplementary sections 10 - 11) (Breiman, 2001). We built and
368 trained models on known repeatedly sampled individuals because monk parakeet contact
369 calls group visibly by individual in a low dimensional trait space (e.g. two-dimensional acoustic
370 space, Figure S1) (Smith-Vidaurre et al., 2020). It is important to train classification models on
371 discrete categories or classes (Kuhn & Johnson, 2013), as a means of ensuring that
372 classification outcomes reflect biologically relevant variation, rather than issues with how the
373 models were built.

374 We built our first model with the full set of 1844 acoustic and image features. We built a
375 second model by performing automated feature selection and using the most important
376 features from that analysis (supplementary section 11). Then, we used our second model with
377 114 features for final analyses, as this model outperformed the first. To predict the similarity of
378 the individual scale contact calls that we used for validation, as well as the site scale contact
379 calls, we ran the remaining individual scale contact calls (73 total contact calls, 4 and 5
380 repeatedly sampled native and introduced range individuals, respectively) and the 1353 site
381 scale contact calls down the final model. We extracted the resulting proximity matrix as the
382 random forests similarity measurements (Humphries et al., 2018; Keen et al., 2014; Keen,
383 Odom, Webster, Kohn, Wright, et al., 2021; Odom, Araya-Salas, Morano, Ligon, Leighton, et
384 al., 2021; Smith-Vidaurre et al., 2020). We performed our random forests analyses with the
385 caret, ranger, Boruta, and edarf R packages (Jones & Linder, 2016; Kuhn, 2008; Kursu &

386 Rudnicki, 2010; Wright & Ziegler, 2017). To validate model performance, we used these
387 similarity measurements to cluster the validation contact calls with Gaussian mixture modeling
388 in the R package mclust (Scrucca et al., 2016), which allowed us to determine whether the
389 random forests model identified biologically relevant patterns of acoustic variation within and
390 among contact calls of new individuals (e.g. individuals that were not present in the training
391 dataset).

392 After confirming that the final model captured relevant patterns of variation among the
393 individuals that we used to validate model performance, we used random forests similarity
394 measurements to generate low-dimensional acoustic space for the individual scale validation
395 contact calls and the site scale contact calls. Since we had used the individual scale contact
396 calls to train and validate the random forests model that we used to predict contact call
397 similarity, we did not use random forests similarity measurements to perform quantitative
398 analyses of acoustic convergence at the individual scale. Instead, we used the training
399 classification performance of our final random forests model, and the clustering performance
400 during validation with random forests similarity, to support our individual scale analyses with
401 SPCC similarity. Using two similarity methods to quantify acoustic convergence at the site
402 scale allowed us to validate that our results at this social scale reflected biologically relevant
403 variation, and were not artifacts associated with using a single similarity method.

404

405 *2.6 Comparing native and introduced range hierarchical mapping patterns in acoustic space*

406 To assess hierarchical mapping patterns in each of the native and introduced ranges, we
407 compared patterns of acoustic convergence in low-dimensional acoustic space at the
408 individual and site social scales. To generate acoustic space for each similarity method, we
409 optimized non-metric multidimensional scaling (MDS) to reduce the dimensionality of the
410 SPCC and random forests similarity matrices, respectively, with the MASS R package

411 (Venables et al., 2002) (supplementary section 12). For acoustic space at the individual scale,
412 we used random forests similarity obtained during model validation for 4 native range
413 parakeets recorded at 3 sites in the department of Colonia, Uruguay in 2017, and 4
414 introduced range birds recorded at 3 sites in Austin, United States in 2019. For the site scale,
415 we used both random forests and SPCC similarity measurements for 5 native range sites in
416 the department of Colonia, Uruguay in 2017, and 5 introduced range sites in Austin, United
417 States in 2019. We also filtered the acoustic space MDS coordinates by contact calls in each
418 of the 3 site scale datasets that we used to address repeated sampling of individuals (see
419 section 2.3). Acoustic space can be interpreted on the same axes for each similarity method
420 but not compared between similarity methods (e.g. acoustic space is different between SPCC
421 and random forests analyses). We interpreted contact calls that grouped together in acoustic
422 space by individual or site as structurally similar calls (e.g. high convergence), while calls
423 dispersed in acoustic space were structurally different (e.g. low convergence). We compared
424 hierarchical mapping patterns between the native and introduced ranges by comparing the
425 relative patterns of overlap in acoustic space among individuals or sites.

426

427 *2.7 Using Earth Mover's Distance to compare hierarchical mapping patterns between ranges*

428 Due to recent criticism of using Mantel tests to quantify acoustic convergence (Smeele et al.,
429 2022), we propose using Earth Mover's Distance (Rubner, Tomasi, & Guibas, 2000) to
430 estimate the strength of acoustic convergence across social scales. Mantel tests have been
431 used to correlate matrices of acoustic similarity with matrices of binary categorical identity
432 (e.g. individual or group identity) over many permutations, in order to address whether
433 vocalizations compared within categories are more similar than vocalizations among
434 categories (supplementary sections 15 – 16), while controlling for non-independent data in
435 pairwise symmetric matrices (Smith-Vidaurre et al., 2020; Wright, 1996). Earth Mover's

436 Distance provides a conceptually similar approach that can be used to quantify and compare
437 acoustic convergence. We compared hierarchical mapping patterns between the native and
438 introduced range populations by comparing the relative magnitude of Earth Mover's Distance
439 values at each social scale between ranges.

440 For this analysis, we obtained similarity values representing comparisons of contact
441 calls within and among categories at each social scale (e.g. comparisons of the same or
442 different individuals at the individual scale). We used the emdist R package (Urbanek &
443 Rubner, 2022) to calculate Earth Mover's Distance, or the minimum amount of work needed
444 to convert distributions of the same-category contact call comparisons into distributions of
445 different-category contact call comparisons. We performed these calculations in a single
446 dimension bounded between 0 and 1 (e.g. the minimum and maximum possible similarity
447 values). In these calculations, larger values of Earth Mover's Distance are equivalent to
448 stronger acoustic convergence. For instance, if stronger convergence occurred at the
449 individual scale, then similarity values for contact calls compared for the same individual
450 should be distributed closer to 1, while similarity values for contact calls compared among
451 individuals should be distributed closer to 0, and it should take more work, or greater Earth
452 Mover's Distance, to convert one distribution into the other. We calculated Earth Mover's
453 Distance in a histogram-based approach with a customized resampling routine to generate
454 even sample sizes for calculations across social scales. Our resampling routine also allowed
455 us to control for variation in same-site membership at the individual scale (some introduced
456 range individuals were sampled at the same or different sites), as well as possible non-
457 independence among sites at the site scale (supplementary section 13).

458

459 *2.8 Evaluating hierarchical mapping patterns over time in the introduced range*

460 We compared the relative magnitudes of Earth Mover's Distance calculations over time in two
461 U.S. cities to determine whether the strength of acoustic convergence at the site scale
462 changed over time in the introduced range. For these analyses, we used introduced range
463 populations that we had repeatedly recorded in Austin, Texas and New Orleans, Louisiana.
464 We calculated Earth Mover's Distance with the emdist package (Urbanek et al., 2022) with
465 our customized resampling routine for each year that we had sampled contact calls in each
466 city, because we did not always sample the same sites in each year. For Austin, we obtained
467 Earth Mover's Distance using different sites recorded in each of 3 sampling years: 3 sites in
468 2004, 5 sites in 2011, and 6 sites in 2019. For New Orleans, we calculated Earth Mover's
469 Distance using different sites sampled in 2 years: 3 sites in 2004 and 2 sites in 2011. We
470 obtained Earth Mover's Distance with random forests and SPCC similarity measurements, as
471 well as each of the 3 site scale datasets. These analyses were similar to those that we
472 performed above to compare hierarchical mapping patterns between ranges (section 2.7,
473 supplementary section 13). We also performed Mantel test results over time in these
474 introduced range cities (supplementary section 17). Finally, we addressed the possibility of
475 population recovery since introduction by using the auk R package (Strimas-Mackey, Miller, &
476 Hochachka, 2018) to evaluate population trends from eBird checklists in each city over our
477 sampling years (supplementary section 14) (Sullivan, Wood, Iliff, Bonney, Fink, et al., 2009).

478

479 *2.9 Comparing hierarchical mapping patterns with another parrot species*

480 We placed our results in context by quantifying and directly comparing hierarchical mapping
481 patterns of native and introduced range monk parakeets with the yellow-naped amazon, a
482 species well-known for having regional group identity information in their contact calls. These
483 amazon parrots imitate the contact calls of conspecifics and exhibit distinctive regional vocal
484 dialects that are audibly perceptible to humans (Wright, 1996). Such vocal sharing may

485 facilitate recognizing familiar group members (Sewall et al., 2016; Wright, 1996). Regional
486 dialects in yellow-naped amazon contact calls have provided a baseline for identifying strong
487 acoustic convergence within social groups for other vocal learning species (Bradbury et al.,
488 2001; Buhrman-Deever et al., 2007; Guerra et al., 2008), including monk parakeets (Smith-
489 Vidaurre et al., 2020). Here we used yellow-naped amazon contact calls as a point of
490 reference for strong acoustic convergence that could occur at a higher social scale in
491 introduced range monk parakeet contact calls if group membership information became more
492 important to signal after introduction than individual identity.

493 For our comparative analyses, we quantified hierarchical mapping patterns over the
494 individual and site social scales for native and introduced range monk parakeets (separately),
495 and over the individual, site, and regional dialect social scales for yellow-naped amazons.
496 For yellow-naped amazons, we used previously published contact calls recorded in Costa
497 Rica in 1994 (Wright, 1996). We measured contact call similarity for each species using
498 SPCC (Araya-Salas et al., 2017), and selected similarity values for a subsample of individuals
499 or groups at each social scale that represented similar sampling depth and geographic
500 breadth for each range and species (supplementary sections 19 – 20). We compared
501 hierarchical mapping patterns by assessing patterns of relative overlap among distributions of
502 the subsampled SPCC similarity values within and among categories (e.g. individuals or
503 groups).

504 We also designed a customized bootstrapping approach to quantify the strength of
505 acoustic convergence at each social scale for native range monk parakeets, invasive range
506 monk parakeets, and yellow-naped amazons that complemented and validated our analyses
507 with Earth Mover's Distance. We used the same SPCC values selected above in a
508 bootstrapping analysis in which we randomly selected 5 similarity values within the given
509 category and 5 similarity values among the given category in each bootstrapping iteration

510 (supplementary section 21). This random sampling was performed with replacement, such
511 that SPCC values within or among categories could be randomly selected more than once in
512 the same iteration. We calculated bootstrapped similarity ratios by dividing similarity values
513 within the given category by similarity values among the given category. We performed
514 bootstrapping over 200 iterations and calculated 1000 total similarity ratios for exemplars of
515 each category (individual or group) at each social scale for native range parakeets, introduced
516 range parakeets, and yellow-naped amazons. Similarity ratios close to 1 pointed to weaker
517 convergence. We used similarity ratios increasingly greater than 1 as evidence of stronger
518 convergence (e.g. contact calls were more similar within categories than among categories).

519

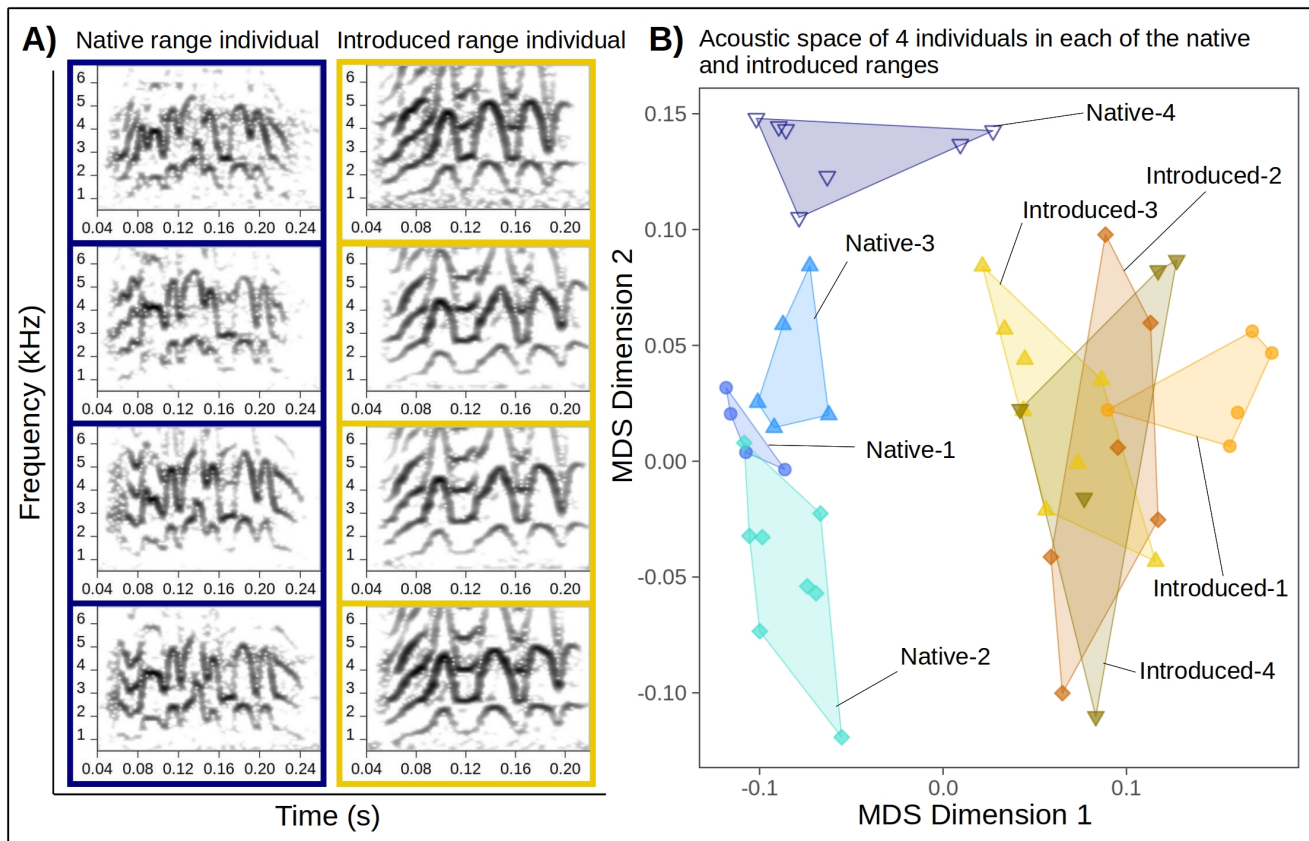
520 **3. Results**

521 *3.1 Strong individual signatures in native and introduced range contact calls*

522 We identified strong acoustic convergence at the individual scale in contact calls recorded in
523 both ranges. Contact call lexicons (or collections of spectrograms) for known repeatedly
524 sampled individuals indicated that parakeets in each of the native and introduced ranges
525 consistently produced contact calls that were distinctive from those of other birds (Figure 2A).
526 This result was further supported by the general patterns of low overlap among individuals
527 that we identified in random forests and SPCC acoustic space, although there was higher
528 overlap among introduced range individuals (Figure 2B, Figure S1).

529 Our supervised machine learning results also pointed to strong acoustic convergence
530 at the individual scale. The final random forests model that we used to predict similarity of the
531 site scale contact calls displayed high classification accuracy during training. The model
532 classified contact calls back to the individuals that we used for training with 97.44% accuracy
533 (95% CI: 93.57 - 99.30). The mean \pm SE balanced accuracy of our model's classification
534 performance per individual (representing the averaged sensitivity and specificity) was similarly

535 high for the 4 native range ($99.00\% \pm 0.010$) and 4 introduced range training individuals
536 ($98.75\% \pm 0.008$). Finally, our analyses of the strength of acoustic convergence at the
537 individual scale with Earth Mover's Distance also supported strong individual signatures in
538 native and introduced range contact calls (Figure 4). The Earth Mover's Distance values that
539 we calculated at the individual scale in each of the native and introduced ranges were of
540 similar magnitude (Figure 4, Native range mean and 95% CI: 0.159 (0.153, 0.164); Introduced
541 range mean and 95% CI: 0.131 (0.125, 0.138), Table S2). We obtained qualitatively similar
542 results using Mantel tests (supplementary section 16, Tables S4 and S5).

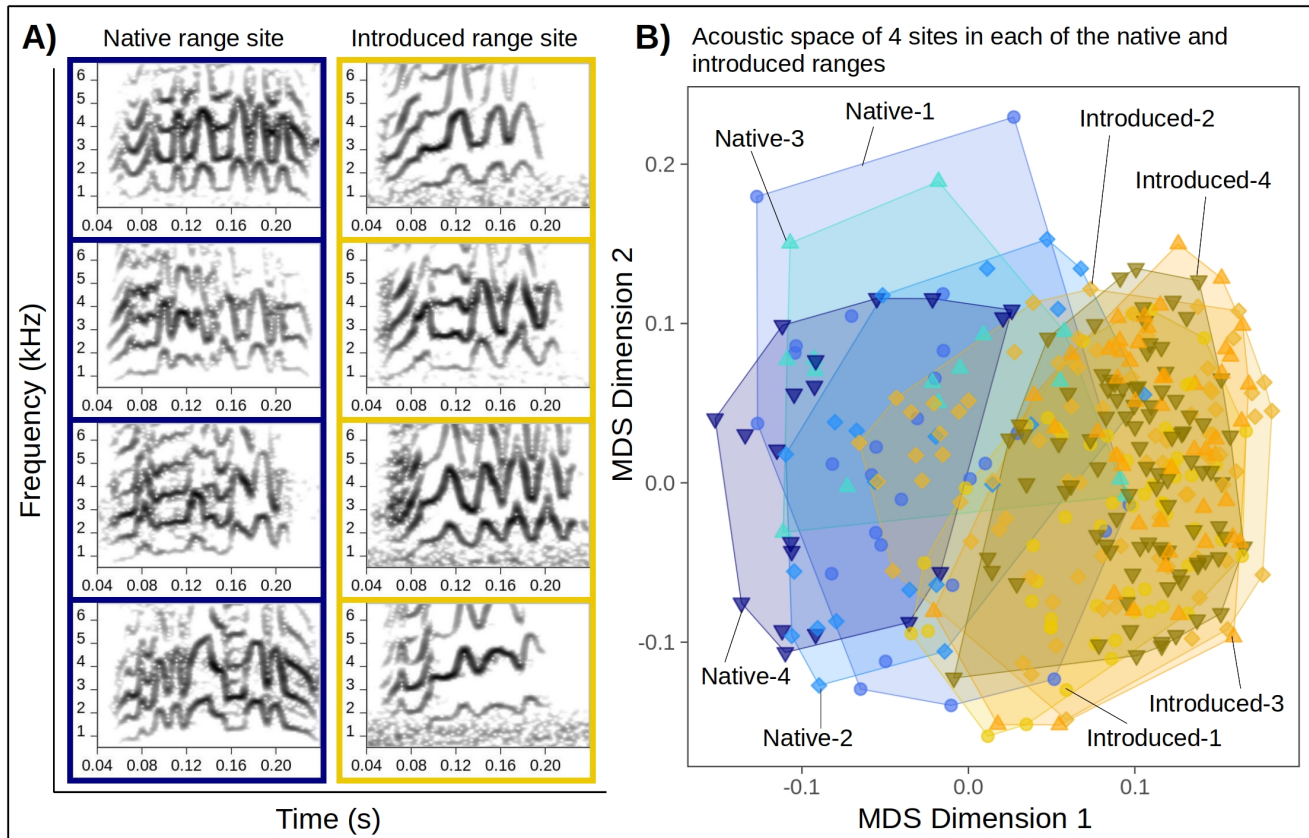


545 **Figure 2 Legend:** Native and introduced range monk parakeets displayed strong individual
 546 vocal signatures. Panel A shows a lexicon with 4 contact calls for one repeatedly sampled bird
 547 in each of the native and introduced ranges. In panel B, random forests acoustic space is
 548 shown for 4 native range and 4 introduced range individuals. Each point represents a different
 549 contact call per individual, and individual identities are encoded by shapes and hues. The
 550 convex hull polygons demonstrate the area per individual in acoustic space. The blue palette
 551 corresponds to the native range and gold-brown to the introduced range. See Table S1 for
 552 decoded individual identities. Individuals generally produced visibly consistent contact calls
 553 (Panel A) that were also distinctive from other individuals (Panel B).
 554

555 *3.2 Contact call convergence within sites was low*

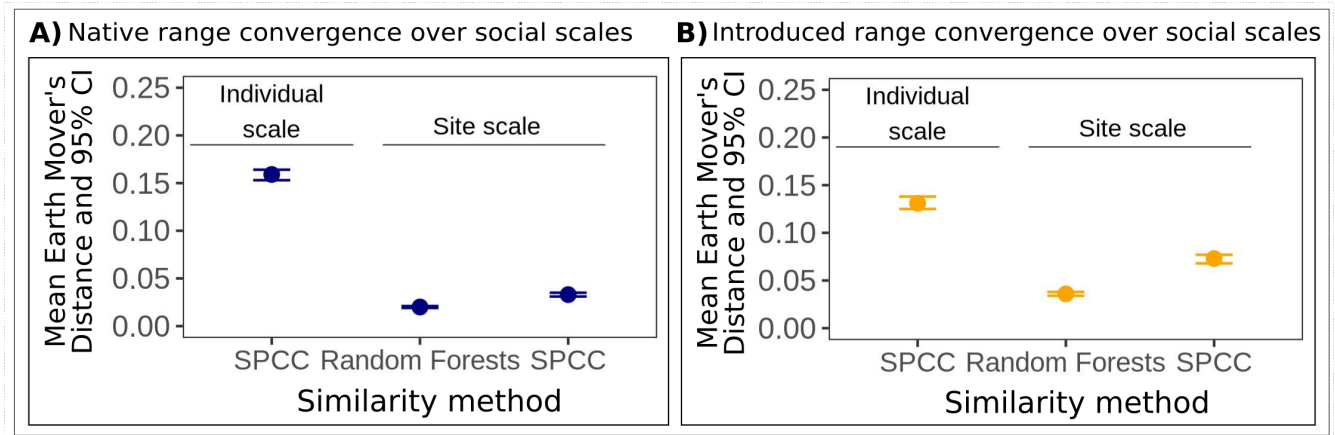
556 We found that individuals at the same site did not produce similar contact calls (Figure 3A).
557 When we assessed hierarchical mapping patterns in acoustic space, we found that contact
558 calls did not group by site identity. Instead, contact calls from the same site were
559 overdispersed, resulting in substantial overlap among different sites in acoustic space
560 generated using random forests similarity (Figure 3B), as well as SPCC similarity (Figure S2).
561 The low degree of acoustic convergence that we identified at the site scale was supported by
562 Earth Mover's Distance values that were an order magnitude lower for the site scale
563 compared to the individual scale in each of the native and introduced ranges (Figure 4, Table
564 S2). This result held across the complementary SPCC and random forests similarity methods
565 that we used for Earth Mover's Distance calculations at the site scale (Figure 4).

566 We compared our Earth Mover's Distance results across the 3 site scale datasets to
567 determine how keeping or filtering out contact calls of potentially repeatedly sampled
568 individuals affected our results at this social scale. While the Earth Mover's Distance statistics
569 for the 3 native range site scale datasets were consistently low, values for the introduced
570 range varied more across the site scale datasets. The introduced range Earth Mover's
571 Distance values for each site scale dataset were uniformly greater than those we obtained for
572 the native range datasets using each similarity method (Table S2). However, despite this
573 variation that we observed between ranges, and across site scale datasets for the introduced
574 range, all Earth Mover's Distance values at the site scale remained an order of magnitude
575 lower than the values we calculated at the individual scale in each of the native and
576 introduced ranges (Figure 4, Table S2). The highest Earth Mover's Distance values that we
577 observed at the site scale for the native and introduced ranges occurred with the full dataset
578 of contact calls, in which we did not filter out contact calls attributed to repeatedly sampled
579 unmarked individuals at this social scale (Figure 4, Table S2).



581 **Figure 3 Legend:** We identified minimal acoustic convergence at the site scale in the native
 582 and introduced ranges. Panel A shows a lexicon of 4 contact calls each for one native range
 583 site and one introduced range site, in which each contact call represents a unique individual.
 584 Panel B shows random forests acoustic space for 4 native range and 4 introduced range
 585 sites. The full dataset of contact calls was used per site (see Figure S2 for the other site scale
 586 datasets). Across panels, the color palettes, aesthetics, and polygons used are similar to
 587 Figure 2, but here encode site identities. See Table S1 for decoded site identities. Contact
 588 calls within sites were visibly different (Panel A), and there was low differentiation among sites
 589 in acoustic space (Panel B) compared to the individual scale (Figure 2B).
 590

591 **Figure 4:**

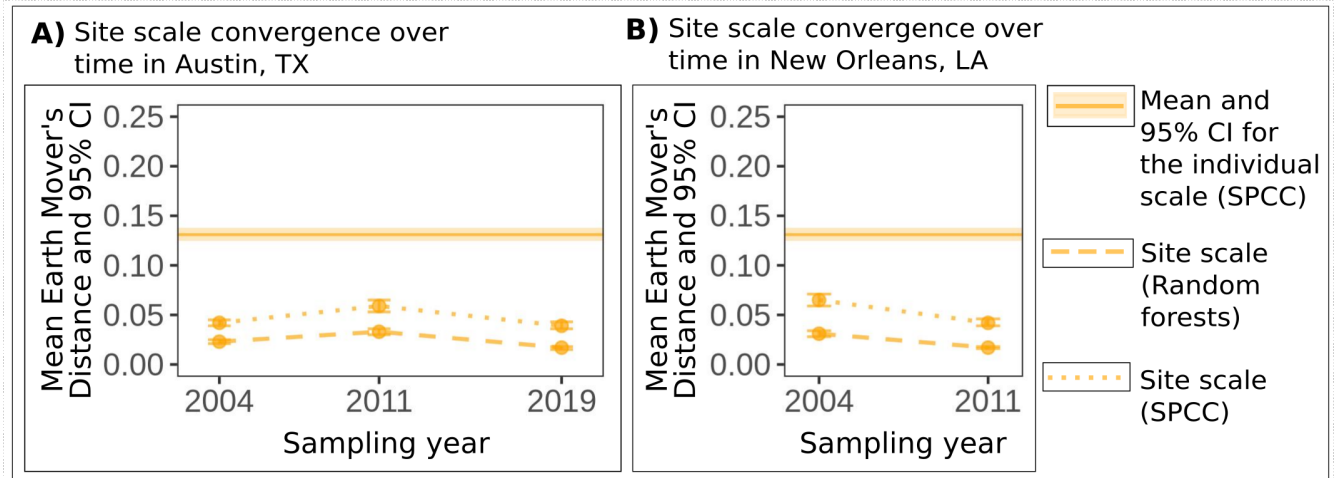


592 **Figure 4 Legend:** Acoustic convergence was stronger at the individual scale for A) native
593 range and B) introduced range monk parakeets. In each panel, the symbols and error bars
594 show the mean individual and site scale Earth Mover's Distance values and 95% confidence
595 intervals calculated with spectrographic cross-correlation (SPCC) or random forests similarity.
596 Higher Earth Mover's Distance values indicate higher convergence, and we identified higher
597 convergence at the individual scale in each of the native and introduced ranges. The site
598 scale values were calculated with the full contact call dataset at this social scale.
599

600 *3.3 Patterns of site scale convergence in the introduced range were consistent over time*

601 We did not identify clear evidence of temporal change in the strength of site scale acoustic
602 convergence in the introduced range (Figure 5, Table S3). In the city of Austin, we identified
603 higher Earth Mover's Distance values (indicating higher convergence) in 2011 using the all 3
604 site scale datasets for both SPCC and random forests similarity (Table S3). For the city of
605 New Orleans, we found the highest Earth Mover's Distance values in 2004 using the full and
606 visual classification datasets and both similarity methods (Table S3). Despite this variation,
607 the Earth Mover's Distance values never reached the same magnitude as convergence at the
608 individual scale (Figure 5), but rather remained at the same order of magnitude over time in
609 each city (Table S3). These Earth Mover's Distance values that we calculated over time in
610 each city were similar to the site-level calculations we obtained in our comparison between
611 ranges (Tables S2 and S3). We used eBird checklists from these cities in a complementary
612 analysis of population trends over time, to address the possibility that population size could
613 have increased since establishment. However, we found that the mean annual frequency of
614 monk parakeets reported in complete checklists in Austin and New Orleans remained low
615 (less than 5% of all species sightings) and was also generally consistent from 2004 to 2020
616 (supplementary section 14, Figure S7).

617



619 **Figure 5 Legend:** Introduced range acoustic convergence at the site scale remained low over
 620 A) 3 sampling years in Austin, TX and B) 2 sampling years in New Orleans, LA. The mean
 621 Earth Mover's Distance value calculated for the individual scale with SPCC similarity is shown
 622 as a point of reference (a solid horizontal line in each panel). The shading around the
 623 individual scale line represents the 95% confidence interval. Lower Earth Mover's Distance
 624 values indicate weaker convergence, and site scale convergence over time in each city
 625 remained weaker than individual scale convergence for the introduced range. In each panel,
 626 the symbols and error bars show the mean site scale Earth Mover's Distance values and 95%
 627 confidence intervals calculated with random forests (dashed lines) or spectrographic cross-
 628 correlation (SPCC) similarity (dotted lines). The site scale values were calculated with the full
 629 contact call dataset at this social scale.
 630

631 *3.4 More repeated sampling of individuals in our introduced range site scale dataset*

632 Using clustering with Gaussian mixture models, and visual classification across multiple
633 observers, we attributed more contact calls in our introduced range site scale datasets to the
634 inadvertent repeated sampling of unmarked individuals compared to our native range site
635 scale datasets. The mean number of repeated individuals that we identified by our clustering
636 and visual classification filtering approaches were only slightly higher for the introduced range
637 than the native range (Table 1). However, we found that the mean number of contact calls
638 attributed to repeated individuals was about twofold greater for introduced range sites by each
639 of the clustering and visual classification approaches that we had used to identify repeated
640 sampling of individuals in our site scale datasets (Table 1).

641

642 Table 1. Assessing the degree of repeated sampling of individuals at the site scale for both
643 the introduced and native ranges.
644

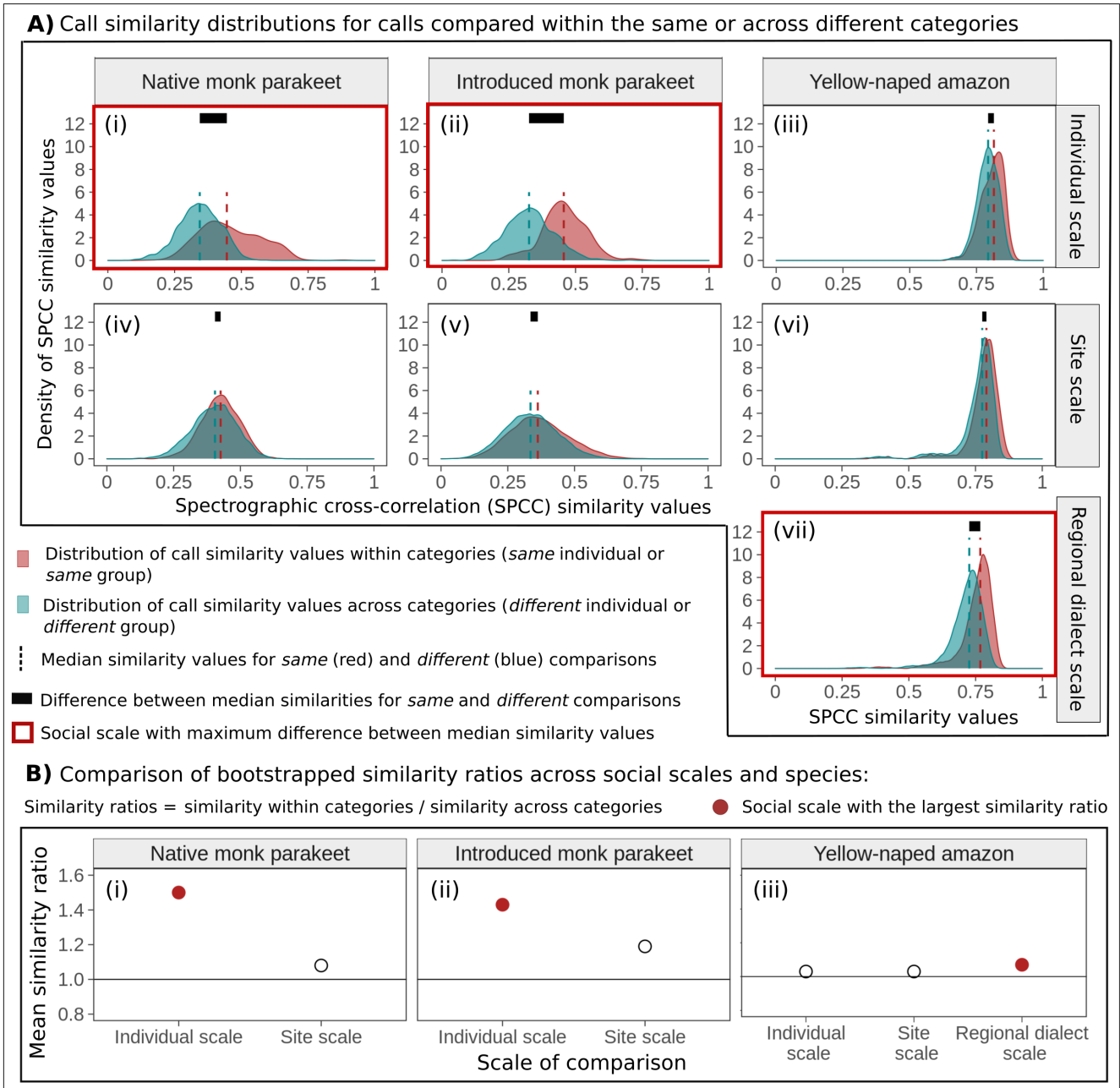
Filtering approach	Range	Repeated individuals (mean \pm SE)	Contact calls per repeated individual (mean \pm SE)
Clustering	Native	3.24 \pm 0.38	10.4 \pm 1.61
	Introduced	3.40 \pm 0.47	23.6 \pm 5.53
Visual classification	Native	3.48 \pm 0.39	2.83 \pm 0.15
	Introduced	3.57 \pm 0.54	5.31 \pm 0.64

645

646 *3.5 Distinct hierarchical mapping patterns between monk parakeets and yellow-naped*
647 *amazons*

648 The hierarchical mapping patterns that we identified for both native and introduced range
649 monk parakeet contact calls differed from the hierarchical mapping patterns that we
650 recapitulated in yellow-naped amazon contact calls. Our results from this comparative
651 analysis showed that the individual scale was the social scale with the strongest acoustic
652 convergence in native and introduced range monk parakeet contact calls, while the regional
653 dialect scale displayed the strongest convergence in yellow-naped amazon contact calls. We
654 found that the greatest separation between the median similarity values of the two categories
655 of comparison per social scale (e.g. same or different individual or group) occurred at the
656 individual scale for native and introduced range monk parakeets (Figure 6A, panels i and ii).
657 For yellow-naped amazons, we detected the greatest separation between categories at the
658 regional dialect scale (Figure 6A, panel vii). In addition, the bootstrapped similarity ratios that
659 we used to assess the strength of acoustic convergence were greatest at the individual scale
660 for monk parakeets in each of the native and introduced ranges (Figure 6B, panels i and ii). In
661 contrast, the largest similarity ratio for yellow-naped amazons occurred at the regional dialect
662 scale (Figure 6B, panel iii).

663



666 **Figure 6 Legend:** We compared hierarchical mapping patterns in native and introduced range
 667 monk parakeet contact calls against yellow-naped amazon contact calls. Panel A shows
 668 density curves for the distributions of spectrographic cross-correlation (SPCC) similarity
 669 values that represent comparisons of contact calls within or among categories in red and blue
 670 shading, respectively. The dashed lines represent the median similarity values per
 671 distribution. In Panel B, we show the mean similarity ratios calculated from bootstrapped
 672 SPCC values. The solid line at 1 represents no convergence within a given category. For both
 673 native and introduced range monk parakeets, we show site scale results obtained from the full
 674 dataset of contact calls. Across both panels, the social scale at which the strongest
 675 convergence occurred is shown in red.
 676

677 **4. Discussion**

678 We asked whether the type of identity information that is important to communicate in learned
679 acoustic signals changed in introduced populations established after social disruption that
680 occurred over ecological timescales. We inferred that individual identity remained the most
681 important type of identity information to communicate in learned monk parakeet vocalizations,
682 even in populations established after repeated introductions to new parts of the world. We
683 discuss this new insight into the resilience of identity information encoded in learned
684 communication signals, and point to possible directions for future work over ecological and
685 evolutionary timescales.

686

687 *4.1 Hierarchical mapping patterns were similar between native and introduced range monk*
688 *parakeet populations*

689 Monk parakeets in native range populations in Uruguay and introduced range populations in
690 the U.S. emphasized individual identity information in learned vocalizations. In each range,
691 the hierarchical mapping patterns that we quantified in contact calls showed the strongest
692 convergence at the individual scale and weaker convergence within sites. These results were
693 robust to the greater degree of repeated individual sampling that we identified in our
694 introduced range site scale dataset (supplementary section 18). In addition, the low
695 convergence that we identified at the site scale in two cities sampled over time, which
696 represented independent introduction events, suggested that these hierarchical mapping
697 patterns were unlikely to have changed in the broader U.S. introduced range over the
698 timespan of this study. We also recapitulated the structural differences between native and
699 introduced range contact calls that reflected the simplification of individual vocal signatures
700 associated with smaller local populations in the U.S. (see the separation in acoustic space
701 among native and introduced range contact calls in Figures 2B and 3B) (Smith-Vidaurre et al.,

2021). This simplification of individual vocal signatures post-introduction may explain the patterns of greater overlap that we identified among introduced individuals in acoustic space (Figure 2), as well as lower acoustic convergence at the individual scale for the introduced range compared to the native range using Earth Mover's Distance (Figure 4, Table S2). However, despite these differences at the individual scale between ranges, we found that acoustic convergence at the individual scale was consistently an order of magnitude greater than convergence at the site scale in each of the native and introduced ranges. This overall result of stronger convergence at the individual scale in monk parakeet contact calls was supported by the two independent analytical approaches that we used to quantify acoustic convergence: Earth Mover's Distance and a customized bootstrapping routine (see below). Using two methods to measure contact call similarity at the site scale also allowed us to validate the weaker convergence that we identified at this higher social scale in each of the native and introduced ranges.

Our analyses indicate that individual identity remained the most important type of identity information to communicate to receivers, even in introduced populations. In other words, we inferred that the type of identity information emphasized in learned contact calls was resilient to social disruption that occurred over short evolutionary timescales (less than 50 years ago when monk parakeets were introduced to the U.S. (Edelaar et al., 2015; Russello et al., 2008)). Although some features of the social environment changed after introduction, such as the smaller local population sizes that we identified in previous work (Smith-Vidaurre et al., 2021), monk parakeets' social environments may have been generally resilient to introduction or were re-established after initial perturbations. If the individually distinctive contact calls that we identified in the native and introduced ranges are used for individual vocal recognition, then parakeets in each range should be engaging in social interactions that favor signaling individual identity in learned communication signals, which is

727 an idea that can be tested in future work. Our quantitative approaches with vocal signals
728 allowed us to reach this inference without depending on the time- and resource-intensive
729 collection of social data. These findings do not preclude the possibility that social interactions
730 at higher scales of social organization are important in this species. While relationships at the
731 pair level are important for monk parakeets, this species consistently forms social groups with
732 multiple levels of social organization in captive settings (Hobson et al., 2013;2014;2015; van
733 der Marel, Prasher, Carminito, O'Connell, Phillips, et al., 2021; van der Marel et al., 2022).

734 Signaling individual identity information in learned vocalizations could instead reflect a
735 more fixed aspect of vocal communication systems, such as developmental constraints or
736 genetic encoding of receivers' perceptual abilities. Future work could also address the stability
737 of individual identity information in learned contact calls across different social contexts, given
738 that some vocal learning species exhibit rapid convergence or divergence that appears
739 conditional on the social context (Balsby et al., 2009; King et al., 2013; Scarl et al., 2009;
740 Vehrencamp et al., 2003), and in others, individual vocal signatures appear to change over
741 time (Zdenek, Heinsohn, & Langmore, 2018).

742

743 *4.2 Comparing our results against a parrot species that exhibits regional vocal dialects*

744 We performed a comparative analysis with yellow-naped amazon contact calls to place our
745 ecological comparison of native and introduced range monk parakeet contact calls in an
746 evolutionary context. If introduced range monk parakeets switched to emphasizing group
747 membership information in contact calls, then hierarchical mapping patterns in introduced
748 range monk parakeet contact calls should have exhibited stronger convergence at a higher
749 social scale. We used yellow-naped amazons as a baseline for comparison because this
750 species exhibits strong acoustic convergence at a higher social scale (regional populations),
751 and regional vocal dialects that are audibly and visibly distinctive to humans (Salinas-Melgoza

752 et al., 2012; Sewall et al., 2016; Wright, 1996; Wright & Dahlin, 2018). We found that
753 hierarchical mapping patterns were similar between native and introduced range monk
754 parakeets, supporting our conclusion that identity information in monk parakeet contact
755 contact calls did not change after social disruption that occurred over ecological timescales. In
756 this comparative analysis, we used a customizing bootstrapping approach that yielded similar
757 results for native range and introduced range monk parakeets as our analysis with Earth
758 Mover's Distance.

759 Our comparative analysis also highlighted the importance of using quantitative tools to
760 complement human perception of audible and visible variation in avian vocalizations. When
761 relying on the human ear and eye, the variation among regional dialects in yellow-naped
762 amazon contact calls is far more perceptible than individually distinctive monk parakeet
763 contact calls. For example, the regional dialects that we recapitulated in the amazon contact
764 calls are distinctive to the human ear (Wright, 1996), including North dialect contact calls that
765 sound like "wah-wah", and variants of the South dialect that sound like "weeup". In contrast,
766 patterns of individual variation in monk parakeet contact calls are difficult to distinguish by the
767 human ear, and contact calls of different individuals all sound like "chees". However, when we
768 used quantitative methods to compare hierarchical mapping patterns between species, we
769 found that individual scale convergence in native and introduced range monk parakeet
770 contact calls was stronger than regional dialect convergence for yellow-naped amazons
771 (Figure 6A: panels i, ii, and vii).

772 Amazon vocal dialects may be more perceptible to humans than monk parakeet
773 individual vocal signatures because of humans' limited abilities to perceive fine-scale temporal
774 variation at higher frequencies (Dooling, Leek, Gleich, & Dent, 2002; Lohr, Dooling, &
775 Bartone, 2006). Parrots' auditory perception abilities appear tuned for higher frequencies,
776 such as orange-fronted conures (*Eupsittula canicularis*), which display the greatest auditory

777 sensitivity in a frequency band that overlaps with the greatest spectral energies in contact
778 calls (Wright, Cortopassi, Bradbury, & Dooling, 2003). In addition, yellow-naped amazon
779 contact calls exhibit slower frequency modulation patterns that are more perceptible to
780 humans, and can also be arranged into fewer categories (e.g. a few regional dialects), a task
781 that should pose reduced cognitive challenges compared to categorizing monk parakeet
782 contact calls by many different individuals (Bradbury et al., 1998; Wiley, 2013). Overall, our
783 results from this comparative analysis point to the importance of using computational
784 approaches to identify information in animal signals that is difficult for humans to perceive but
785 may be critical in animal communication systems.

786

787 *4.3 Future research considerations with hierarchical mapping patterns*

788 We combined computational tools with a conceptual framework of how hierarchical mapping
789 patterns are connected to identity signaling in animal vocal signals. This combined approach
790 allowed us to quantify hierarchical mapping patterns and then infer the most salient identity
791 information encoded in vocal signals. Similar computational approaches could be applied to
792 quantify hierarchical mapping patterns with existing datasets of animal signals to learn more
793 about the social environments in which individuals communicate across a broader range of
794 taxa, without depending on the time-intensive collection of social data from marked
795 individuals. When communication signals are learned, hierarchical mapping patterns should
796 capture overall patterns of acoustic variation that represent both active convergence or
797 divergence within social groups, as well as the side-effects of learning from others in a given
798 social group (e.g. vocalizations can be similar when individuals learned from templates that
799 happened to be similar). Here, we used the social scale with the strongest acoustic
800 convergence to infer which type of identity information animals are actively encoding in
801 learned vocalizations (e.g. the type of identity information that is most important to

802 communicate). In our conceptual framework, we considered stronger acoustic convergence
803 as active convergence, and weaker patterns of acoustic convergence as stochastic outcomes
804 associated with learning. For instance, monk parakeet contact calls recorded at the same site
805 did display a degree of convergence (Table S2), albeit minimal, which should be expected
806 when animals are learning to sound different from others and are learning from the same
807 social group or set of templates.

808 Whether and how animals perceive and use stronger or weaker patterns of acoustic
809 convergence in learned vocalizations can be assessed experimentally using playbacks of
810 contact call variants. Indeed, the hierarchical mapping patterns identified for a particular
811 population or species can be used as an important foundation for designing biologically
812 relevant playback experiments, which can be more time-consuming than recording
813 communication signals, and are fundamental to understand how receivers use the information
814 that signalers communicate. Playback experiments are important because mismatches can
815 occur between the social information encoded in signals and the information that receivers
816 use for social recognition, especially when it is cognitively costly to track certain types of
817 information (Bergman, 2010; Bergman & Beehner, 2015). Addressing how different types of
818 identity information are used by receivers will be important, since distantly related avian taxa,
819 including vulturine guineafowl (*Acryllium vulturinum*) and superb fairy-wrens (*Malurus*
820 *cyaneus*), exhibit multilevel social structures in the wild, suggesting that hierarchical social
821 structures may be more taxonomically widespread than traditionally thought (Camerlenghi,
822 McQueen, Delhey, Cook, Kingma, et al., 2022; Papageorgiou, Christensen, Gall, Klarevas-
823 Irby, Nyaguthii, et al., 2019).

824 While quantifying hierarchical mapping patterns can yield exciting insights into the
825 identity information that may be important to communicate, researchers should be careful
826 when using these patterns to inform new research directions about identity signaling and

827 social systems. Recording unmarked individuals in natural populations provides only a
828 snapshot of dynamic social interactions, as well as the social information conveyed in signals
829 that is important in a given social environment. For instance, sampling a few vocalizations per
830 individual over a short time frame makes it difficult to assess how identity information
831 encoding may change during dynamic social interactions, such as the rapid vocal matching
832 exhibited by wild orange-fronted conures and rose-breasted cockatoos (*Eolophus*
833 *roseicapillus*) (Balsby et al., 2009; Scarl et al., 2009; Vehrencamp et al., 2003). In addition,
834 while the literature has focused on social recognition in more complex social environments
835 with frequent and repeated interactions among many individuals (Bergman et al., 2015;
836 Pollard et al., 2011; Ramos-Fernandez et al., 2018; Sewall et al., 2016; Tibbetts et al., 2007),
837 future work could also address how learned identity signals should change in social
838 environments characterized by fewer individuals and differentiated relationships overall.

839

840 **5. Conclusions**

841 We used native and introduced range monk parakeet contact calls to test whether the type of
842 identity information encoded in learned vocalizations changed in populations that were
843 established after social disruption that occurred over the last 50 years. We used
844 computational tools, including supervised machine learning, to quantify and compare
845 hierarchical mapping patterns in contact calls between the native and introduced ranges. We
846 inferred that identity information encoding was resilient to social disruption over short
847 ecological timescales. By comparing hierarchical mapping patterns between monk parakeet
848 and yellow-naped amazon contact calls, we found that identity information encoding in
849 learned parrot vocalizations changed over longer evolutionary timescales. Our results suggest
850 that identity signaling systems facilitated by socially learned vocalizations are resilient to
851 changes in social conditions over short evolutionary timescales, despite the flexibility

852 generally attributed to socially learned behaviors. Taken together, our findings point to exciting
853 new research directions on how the flexibility of socially learned communication signals may
854 be constrained over short, cultural timescales.

855

856 **Data Accessibility:** Annotated code supporting this article is available on GitHub (gsvidaurre/
857 identity-information-post-introduction). Data that can be used to reproduce results will be
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859

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871 G.S.V. took the lead on analyses with support from V.P.M., E.A.H., A.S.M., and T.F.W.
872 Manuscript writing was led by G.S.V. and T.F.W, and all authors contributed to reviewing and
873 editing the manuscript.

874

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891

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