

1 **CRITTERS: Climate, Resource, and Image Tracking in Tiny, Ecologically**
2 **Representative Systems**

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7

8 **Abstract**

- 9 1. Conservation and ecology research and practice is most effective when theory
10 and models that underly species management are well explored and
11 understood in experimental systems. Microcosm studies can provide
12 experimental evidence to support theory, test model performance in different
13 conditions, and suggest generality. However these benefits have been limited
14 to primarily extinction and population studies, while habitat models have
15 largely remained unexplored in newer systems.
- 16 2. There is presently lacking an experimental system that uses benchtop
17 temperature and food manipulation combined with automated, in situ non-
18 destructive sampling – necessary for conducting habitat and spatial structure
19 studies in microcosms.
- 20 3. We developed Climate, Resource, and Image Tracking in Tiny, Ecologically
21 Representative Systems (CRITTERS), an experimental microcosm system that
22 manipulates habitat through abiotic temperature and biotic components
23 (resources) in a benchtop design, and automates data collection through in
24 situ observations. We propose it as a system in which to test a variety of
25 models and theories in conservation and ecology.
- 26 4. We present the counting accuracy of CRITTERS and population responses of
27 *Paramecium caudatum* to the temperature and resource availability. Using a
28 modified version of the software *Wellcounter*, the correlation between
29 automated and manual counts was $r = 0.98$. In logistic models, *P. caudatum*
30 growth rate r responded to temperature quadratically, and carrying capacity K
31 responded to resources (concentration of carbon in media) log-linearly,
32 allowing independent control of r and K .
- 33 5. This system can be used to test a variety of habitat models in which climate
34 and/or resources require manipulation when in situ sampling and high
35 replication is important. We describe potential uses for testing adaptive
36 management strategies, occupancy and N-mixture models, and Species
37 Distribution Models.

38 **Introduction**

39 Microcosms are miniature experimental systems that are a powerful tool in ecology
40 and conservation, with potential to test and improve a wide variety of models.

41 Microcosms have been used for over 100 years to provide experimental evidence for
42 ecological theories, and the use of ciliate microcosms in particular as surrogates for
43 larger, complex ecosystems is well established (Woodruff, 1908, 1911; Bonsall &
44 Hassell, 2005; Holyoak & Lawler, 2005; Altermatt et al., 2015). In conservation
45 biology, microcosm experiments are versatile, have management implications, and
46 may be used for both ecosystem- or assemblage-specific hypotheses as well as
47 broadly applied theories and models (Stern et al 2025). Furthermore, microcosms
48 allow researchers to explore questions in critical topics such as biodiversity loss,
49 extinction, climate change, and anthropogenic disturbance in a relatively low-risk and
50 ethical manner compared to field experiments, which typically conduct experiments
51 directly on focal ecosystems which may include rare or endangered species (Benton
52 et al., 2007; Stern et al., 2025). Microcosm experiments can provide experimental
53 backing for models, demonstrate their generalisability to many ecosystems or
54 species, and provide insights into model strengths and limitations (Stern et al., 2025).

55 Microcosms are perhaps most usefully employed to complement both field and
56 simulation studies rather than as substitutes. Microcosms provide answers from
57 simplified systems absent of ecosystem-specific noise, allowing findings to potentially
58 be widely used or applied, but they are limited in how complex and realistic they can
59 be (Drake et al., 1996; Fraser & Keddy, 1997; Holyoak & Lawler, 2005; Benton et al.,
60 2007; Altermatt et al., 2015; Stern et al., 2025). Mesocosms and field experiments,
61 which are larger and more realistic can capture ecosystem-specific traits and
62 dynamics in a controlled environment, but their findings may be difficult to generalise
63 outside a given study system (Beyers & Odum, 1993; Diamond, 1983; Sagarin et al.,
64 2016; Stewart et al., 2013). Finally, simulated studies are highly customisable and
65 controllable and can test things impossible to explore in real systems, but they lack
66 true natural responses and are inherently more deterministic (Peck, 2004; Petrovskii
67 & Petrovskaya, 2012). These experiment types provide distinct, independent insights
68 while complementing each other, and ideally should all be used to explore theories
69 and test models. . However, the advantages of experimental manipulability, high
70 replication and the natural variability of biological systems make microcosms very
71 beneficial for model testing (Stern et al. 2025).

72 In ecology and conservation, statistical models which use data on population
73 responses and habitat drivers are frequently used to support conservation efforts,
74 plan protected areas, manage harvesting, and protect endangered species (Hayes et
75 al., 1996; Guisan & Zimmermann, 2000; McCarthy & Possingham, 2007; McCarthy et
76 al., 2011; Kéry et al., 2013; Guisan, 2017; Tucker & Runge, 2021; Ovaskainen, 2002).
77 However, when models are inappropriate for the situation, poorly constructed, or ill-
78 informed, conservation outcomes can be poor (Addison et al., 2013), emphasising
79 the need to understand models and their best applications thoroughly. Many models
80 (e.g. species distribution, occupancy models, etc.) have been tested in simulated or
81 observational studies (Elith et al., 2006; Elith & Leathwick, 2009; Valavi et al., 2020)
82 but lack experimental exploration, validation, and testing (Drew, 1994; J. A. Miller,

83 2014). Calls for increased experimental testing of conservation theory dates back at
84 least to the 1990s (Drew, 1994).

85 Ecological and conservation microcosm experiments have been limited in scope and
86 replicability by labour and the logistics of habitat manipulations. Past ciliate
87 microcosm studies (e.g. Naeem & Li, 1997; Donahue et al., 2003; Fox et al., 2017)
88 relied on manual counting where populations are grown in incubators (which
89 characterises temperature habitat) and destructively sampled to estimate population
90 densities rather than absolute population counts. The lack of benchtop habitat
91 manipulation has prohibited experiments from easily exploring different temperature
92 levels at the same time during the same experiment, instead repeating experiments
93 in multiple parallel experiment systems. Some recent progress has included
94 automation (Altermatt et al., 2015; Besson et al., 2022a; Stelzer & Groffman, 2025)
95 and benchtop observational sampling, in which microcosms are kept on laboratory
96 benches and populations counts are achieved by non-destructive, in-situ sampling
97 through imaging (Besson et al., 2022a; Stelzer & Groffman, 2025), but differential
98 benchtop temperature control has not been achieved. As such, many of these
99 improvements have been restricted to population studies that focus on extinctions
100 driven solely by food availability (Cerini et al., 2023) and ecotoxicology studies
101 (Stelzer & Groffman, 2025), while distribution and habitat studies have remained
102 limited (Table 1).

103 Benchtop habitat control would allow one to test more complex models and theories
104 which rely on more than one facet of habitat (e.g. combining abiotic and biotic
105 drivers). Benchtop temperature control can allow this variable to be integrated into a
106 single experimental platform (unlike incubators which may require a split plot
107 experimental design), increase habitat realism, reduce labour, and allow connectivity
108 and spatial complexity to be more easily explored. Here, we present the new
109 microcosm system Climate, Resource, and Image Tracking in Tiny Ecologically
110 Representative Systems (CRITTERS), designed to test ecology and conservation
111 models and theories through benchtop, automated direct observation of
112 experimental microcosms that can simultaneously control temperature and food to
113 impose habitat quality differences on microorganisms.

114

115 Table 1. Comparison of automated microcosm systems and their current uses.

Automated System, Location, and Citation	Automated Sampling	Automated Counting	Benchtop Sampling	Benchtop Temperature Manipulation	Current Uses
Unnamed System, University of Bristol, (Besson et al., 2022a)	✓	✓	✓		Extinction models, Population models
Wellcounter, Innsbruck	✓	✓	✓		Ecotoxicology

University, (Stelzer & Groffman, 2025)					
Unnamed System, Swiss Federal Institute of Aquatic Science and Technology, (Fronhofer et al., 2015)	✓	✓			Population models, Density dependence, range expansions (food gradient)
CRITTERS, University of Melbourne, <i>preprint link</i>	✓	✓	✓	✓	Habitat models

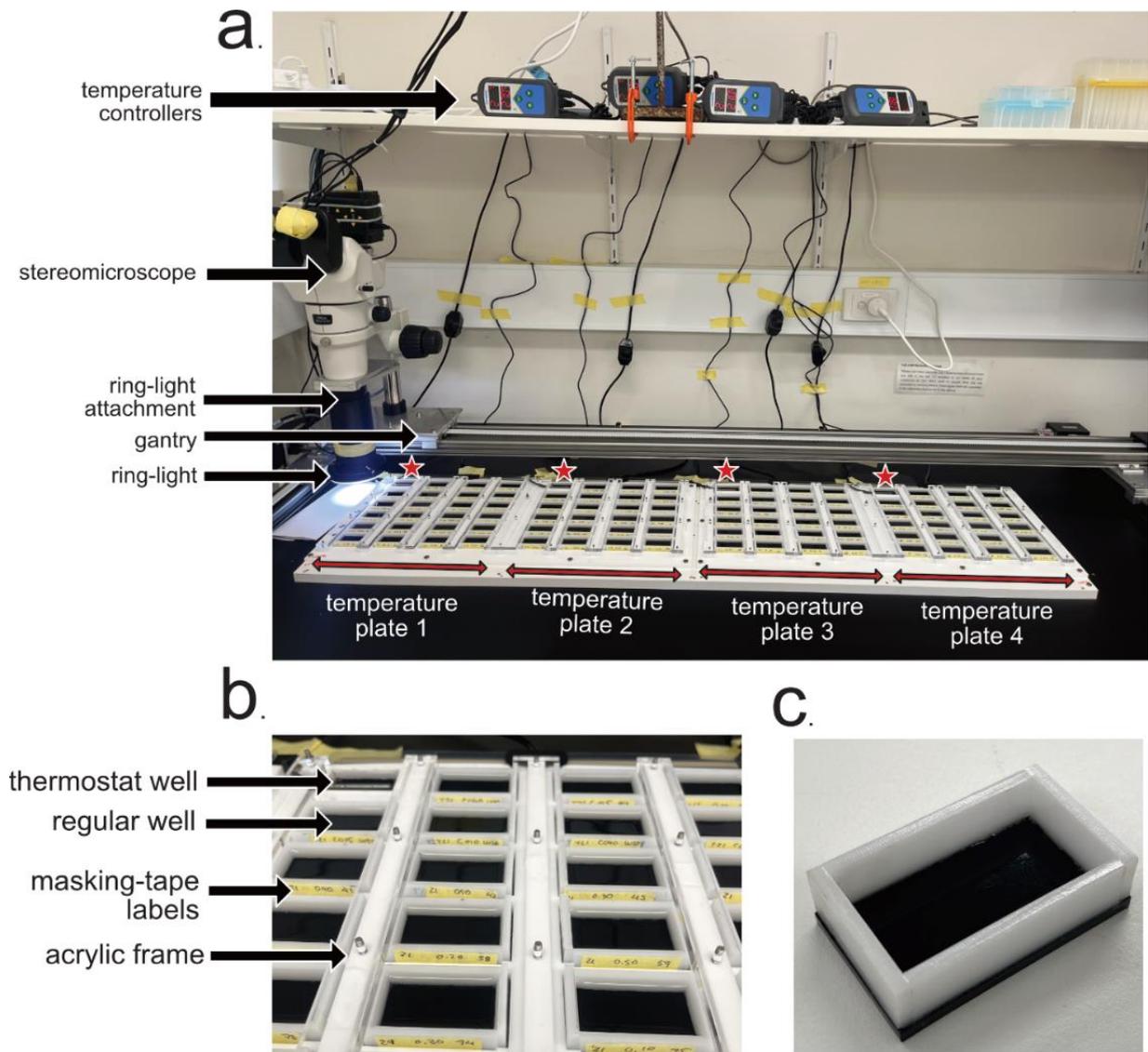
117 **Methods**

118 Overview and Rationale

119 This experimental system is designed to replicate closed habitat patches that are
120 large relative to species body size, where both temperature and resources (abiotic
121 and biotic habitat, respectively) are controlled. We factorially cross temperature and
122 food levels during experiments to produce a variety of habitat qualities. Microcosm
123 wells (hereafter “wells”) are constructed from acrylic and held in a frame on top of
124 heat mats (Figure 1). *Paramecium caudatum* are grown in liquid media made up of
125 Chalkey’s solution (filtered water with a standardized amount of salts added, the salts
126 being necessary for osmoregulation of *P. caudatum*), ground alfalfa, and bacteria.

127 Our system uses top-down imaging of microcosms, conducted using a video camera
128 atop a stereomicroscope that is mounted on a robot moving on a 2-dimensional
129 frame (hereafter referred to as the “gantry”). Videos are then processed in a modified
130 version of Wellcounter (Stelzer & Groffman, 2025) to count *P. caudatum* in each
131 video.

132



133

134

135 Figure 1. A) overview of the experimental system depicting the microcosms,
 136 temperature plates (red arrows), temperature controllers, thermostat wells (red stars),
 137 robotic gantry, ring light configuration, and stereomicroscope; B) microcosms in
 138 acrylic frame with media, *Paramecium* stock, and mineral oil inside, as in an
 139 experiment, C) top view of a microcosm;

140

141 Study Species

142 Although other similar organisms could also be used, the experimental system as
 143 described here uses *Paramecium caudatum*, a globally occurring freshwater ciliate
 144 protozoan, as its model species. *P. caudatum* measure between 170-290 μm , and are
 145 elongated and ovoid in shape, and typically reproduce asexually with a generation
 146 time of around 1 day (Wichterman, 1986). *P. caudatum* are covered in hairlike cilia
 147 that allow them to be highly active and motile (Wichterman, 1986). *Paramecium* have

148 a long history of use in ecological microcosms and are well established as proxies for
149 larger species (Woodruff, 1908, 1909, 1911; Woodruff & Baitsell, 1911; Gause, 1933,
150 1934; Gause et al., 1936; Gill, 1972; Luckinbill, 1973; Maly, 1978). *Paramecium* are a
151 bacterial grazer (Wichterman, 1986), which allows them to take the functional role of
152 a non-predatory animal in microcosms. Their population growth primarily depends on
153 environmental conditions such as food, temperature, pH, waste products, oxygen and
154 aeration, and light, and the relationship between these factors and population growth
155 is relatively well described and understood (Wichterman, 1986).

156

157 Microcosm Configuration and Construction

158 During experiments, *P. caudatum* populations inhabit custom-built microcosms
159 designed to be waterproof while optimising detection in top-down imaging.
160 Microcosms are rectangular open boxes made of 3 mm acrylic sheet, with sides laser
161 cut and joined with acrylic adhesive. Bases are shiny black acrylic and walls are
162 translucent white acrylic. Note that translucent white is necessary to reduce the glare
163 issues that occur in transparent acrylic or plastic when imaged from above. For
164 complete construction instructions, see Appendix. Our microcosms have an internal
165 floor area of 26 x 44 mm, 24 wells are on each temperature plate, and the acrylic
166 frame holds 4 temperature plates (Figure 1A, 1B).

167

168 Climate manipulation through temperature

169 The climate is controlled through the temperature of media within which *P. caudatum*
170 are grown during experiments. Temperature is known to drive population growth rate
171 of *P. caudatum* (Krenek et al., 2011). *P. caudatum* tend to have a thermal preference
172 of around 24 C , a lower critical limit of around 3-5 C and an upper critical limit of
173 around 32 - 35 C, depending on the strain of *P. caudatum* (Krenek et al., 2011).

174 We control temperature using flat heat mats (Lerway reptile heat mats, 20 W) placed
175 underneath the acrylic frame. This allows manipulation of the temperature of liquid
176 medium in wells. Each heat mat has separate temperature control (Inkbird ITC-306T-
177 WIFI) with a thermostat probe placed in a dedicated well on each mat (top leftmost
178 well on each mat). Heating of the mats, and thus the microcosms, is regulated by this
179 thermostat well.

180 To describe the variability of temperature in the CRITTERS system, we recorded in-
181 well variability of the thermostat well (recordings automatically taken every 5 minutes
182 by the probe) and additionally recorded the oil surface temperature of each well
183 multiple times across 4 experiments using a hand-held infrared thermometer.

184

185 Resource manipulation through food source

186 Resources are controlled through the bacterial food source for *P. caudatum*. While
187 bacterial concentrations are difficult to directly manipulate, they may be indirectly
188 controlled through organic matter in media, which drives bacterial populations. We
189 control this through the concentration of alfalfa brewed in media. Our experiments
190 have test food levels between 0.1 and 0.5 g alfalfa / L Chalkey's solution, which
191 presents a range of food concentrations from very poor food resources to abundant
192 food resources. For detailed instructions on preparing media, see Appendix.

193

194 Experiment Duration and Protocol

195 During experiments, *P. caudatum* are grown in alfalfa broth (described above) inside
196 the microcosms. In our system, a combined total of 5 mL media made up of alfalfa
197 broth and *Paramecium* inoculation stock is added to microcosms. Then 3 mL of
198 mineral oil is gently dispersed on top of the medium to prevent evaporation during
199 the experiments, while not impairing visibility during imaging (Figure 1B). The ratio of
200 media and stock may be determined by desired inoculation density; we generally
201 inoculate wells with around 20 individuals which is approximately 0.2 – 0.4 mL of
202 stock into 4.6 – 4.8 mL of media. Experimental durations were restricted to less than
203 3 weeks (~ 30 generations for *P. caudatum*) because mineral oil restricts oxygen
204 diffusing into the medium, which will eventually lead to extinction in the microcosms.
205 We typically conduct experiments for up to 14 days (~ 14 generations for
206 *Paramecium*). We have not found that the mineral oil poses a complication for
207 *Paramecium* populations up to this duration. The population density of *Paramecium*
208 in wells covered by mineral oil is about 20% lower than when grown in bottles in
209 incubators. Otherwise, populations in wells under the oil follow expected trajectories
210 of growth and then stability at carrying capacity. Note, due to heating of the aquatic
211 medium, it is not possible to cover the wells with lids because condensation would
212 impair imaging.

213

214 In-Situ Sampling using Automated Video Recording

215 Our sampling process is similar to other automated high-throughput microcosm
216 designs developed recently (Besson et al., 2022a; Stelzer & Groffman, 2025). We
217 also perform non-destructive, in-situ counting of the abundance of *Paramecium* in
218 microcosms using an automated recording system (Figure 1A).

219 We use a stereomicroscope mounted on the gantry, set to 1x magnification, atop a c-
220 mount set to 0.55x (a sufficient magnification to clearly see *P. caudatum* when
221 projected to a computer monitor), with video pixel resolution of 5440 x 3060. This is
222 approximately 1 million pixels per square centimetre, or about 20 pixels over the
223 length of an individual *P. caudatum*. This microscope has a video camera attached,
224 with a ring light attached to the microscope lens. A custom, 3D printed, attachment
225 holds the ring light approximately 0.5 cm above the surface level of the microcosms
226 using a 3D printed extension piece (Figure 1A). Reducing the distance between the

227 microcosm surface and the ring light minimises glare effects on the mineral oil. For
 228 details on the gantry, its construction, and its operation, see Appendix.

229 Sampling is done by recording 15 second videos at 4-hour intervals (6 recordings
 230 per day, roughly equivalent to 6 observations per generation).

231

232 Automated Abundance Estimates

233 To process videos recorded by the CRITTERS system we adapted the ‘*Wellcounter*’
 234 software for automated detection of microinvertebrates developed by Stelzer &
 235 Groffman (2025) (Stelzer & Groffman, 2025). The original open-source software is
 236 written in Python and uses a deterministic image-processing approach, which
 237 identifies organisms by isolating areas of movement in videos and applying geometric
 238 thresholds to determine if a shape is comparable to a microorganism.

239 Our CRITTERS system differs from the system in which the *Wellcounter* software was
 240 developed, in that we use rectangular rather than circular wells and are more prone
 241 to contamination by dust particles and bacterial clumps due to the open tops (rather
 242 than closed petri dishes as in *Wellcounter*), resulting in a high false-positive detection
 243 rate from *Wellcounter* even after optimisation. To mitigate these challenges, we made
 244 substantial modifications throughout the *Wellcounter* analysis pipeline, resulting in
 245 our *Wellcounter-Modified* software summarised in Table 2. For expanded
 246 explanations of *Wellcounter-Modified*, see Appendix. Our changes significantly
 247 improve detection accuracy in open-top wells.

248 Table 2: *Wellcounter-Modified* workflow compared against the original *Wellcounter*.

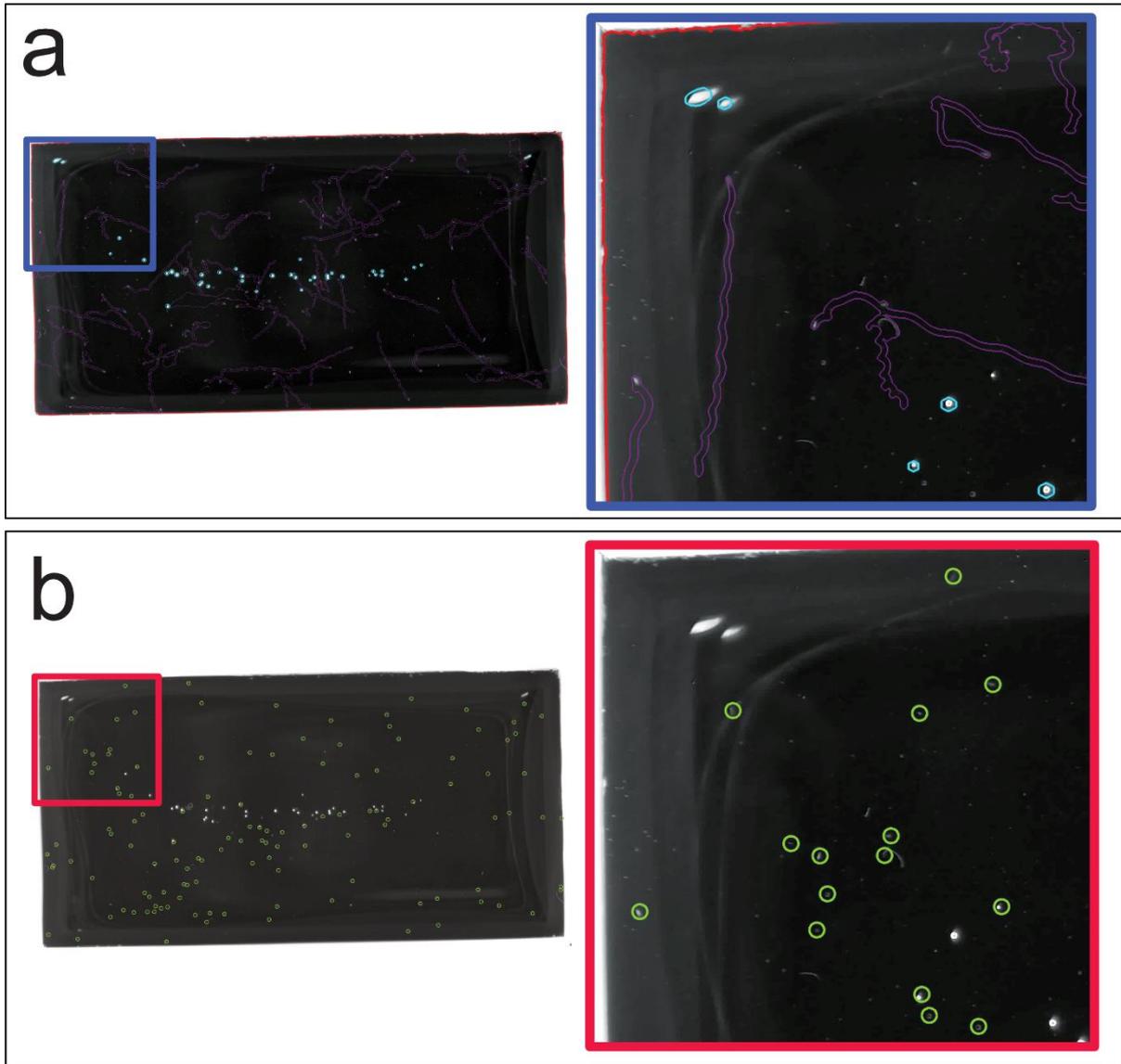
Step	<i>Wellcounter</i>	<i>Wellcounter-Modified</i>	Reason for change
Convert to greyscale (all frames)	Convert to grayscale	Same as <i>Wellcounter</i> .	No difference.
Detect and mask non-well areas (all frames)	Apply a circular mask based on known well dimensions to isolate the regular well area.	Detect the largest contiguous area of high-brightness pixels (the well walls) and apply as a mask to isolate the irregular well area.	<i>Wellcounter</i> used circular wells, CRITTERS custom wells are rectangular but may have rough edges.
Identify movement channels (all frames)	Not included.	For each frame of the video, calculate difference between pixel brightness and minimum value to identify areas of potential movement, then detect contours of these areas and filter to large contiguous areas that correspond with ‘tracks’ of moving <i>Paramecium</i> . (Figure 2A)	Isolating areas of continuous movements helps to distinguish slow-moving dust particles from active <i>Paramecia</i> .
Detect and mask bubbles	Not included.	Detect bright circular areas in the image and mask as	Air bubbles were a frequent source of

(all frames)		likely air-bubbles.(Figure 2A)	false positive detections.
Apply background subtraction (repeat for 3 frames)	For each of three frames in the video, find the difference in pixel values from the other two to identify areas of potential movement.	For each of three frames in the video, find the difference in pixel values from the median value to identify areas of potential movement. These areas are then masked by the movement channel mask.	Applying the movement channel mask reduces false positives, and using the median value rather than values from the other frames reduces stochasticity.
Convert greyscale to binary image (repeat for 3 frames)	Apply a fixed brightness threshold to the background-subtracted image.	Apply a dynamic threshold to the background-subtracted image, where the threshold is automatically determined by Otsu's binarization,	Different lighting conditions make a fixed threshold inconsistent.
Detect <i>Paramecium</i> (repeat for 3 frames)	Used automated contour detection to identify contiguous areas of positive pixels as possible <i>Paramecium</i> . (Figure 2B)	Same as <i>Wellcounter</i> . (Figure 2B)	No change.
Filter contours (repeat for 3 frames)	Filter contours of possible <i>Paramecium</i> by an area threshold.	Filter contours of possible <i>Paramecium</i> by area, eccentricity, solidity, aspect ratio, perimeter, ferret radius, and axis ratio.	Additional shape parameters help reduce false positives.
Compare counts	The three counts, the maximum count, and the mean count are returned.	Same as <i>Wellcounter</i>	No change.

249

250 The primary output from both *Wellcounter* and *Wellcounter-Modified* has three
251 estimates of *Paramecium* abundance from each video. We take the mean of these
252 estimates as the population estimate for a video. This process is automated and
253 performed in batches over large quantities of videos. Because our experiments
254 record over 6000 videos per experiment, we use the High Performance Computing
255 system Spartan at the University of Melbourne to run these modified *Wellcounter*
256 scripts.

257



258
 259 Figure 2. A) Additional masks added which identify *P. caudatum* movement channels
 260 (purple polygons), bubbles or lighting aberrations (blue circles), and microcosm walls
 261 (red polygons). All of these masks are unique to *Wellcounter-Modified*, with
 262 *Paramecium* detection limited to the purple polygons. B) *P. caudatum* identified in the
 263 same well (green circles, also present in the original *Wellcounter* code) within
 264 movement channels, which are unique to *Wellcounter-Modified*.

265

266 Validation

267 We optimised *Wellcounter-Modified* detection settings (e.g. particle size, obliqueness,
 268 blur, etc.) using a sample set of videos from trial-runs of experiments. After
 269 optimisation, accuracy of *Wellcounter-Modified* was validated on 5 independent sets
 270 of data (Experiments 0-4) to assess performance:

- 271 i. 16 videos taken of 16 microcosm wells (1 video per well) in the laboratory
 272 for the purpose of validation only, run for less than 1 day (Experiment 0),

- 273 ii. 24 videos from two experiments with 12 wells in each run for 14 days:
274 Experiment 1 & Experiment 2 (one video was removed from Experiment 2
275 because it was recorded during a software malfunction). Videos from
276 Experiment 1 & Experiment 2 were selected randomly, stratified by time in
277 experiment (0-4 days, 5-9 days, 10-14 days) and the predicted count (< 10,
278 10 – 50, 50 - 200, and >200), sampling 1 video from of these crossed
279 groups.
- 280 iii. 24 videos from two experiments with 12 wells in each run for 14 days:
281 Experiment 3 & Experiment 4. This validation aimed to assess if error was
282 biased in time. 4 sequential videos starting at Day 10, when populations
283 were at equilibrium, were chosen from 3 wells sampled randomly for each
284 experiment. The 3 wells were sampled from groups stratified by predicted
285 count (< 10, 10 – 50, 50 – 200).

286 Each of these 63 videos was validated manually by a single observer. Videos had
287 grids imposed and observed *Paramecium* were counted in each grid cell (112 cells
288 per video, which will fit a maximum of about 10 *Paramecium* in a very dense well).
289 For detailed counting protocol, see Appendix. Counts were summed to produce a
290 manual population count per video. This was compared with the *Wellcounter-*
291 *Modified* estimate for the same video. The 16 videos in Experiment 0 were
292 independently validated by two observers to determine consistency between
293 observers ($R^2 = 0.9996$, mean difference = -0.44 paramecia per well), indicating that
294 one observer was sufficient for the remaining videos in Experiments 1-4.

295

296 Population modelling

297 We used all available data in Experiment 1 (87 total wells for 14 days) to model the
298 population response to the temperature and resource manipulations. Analyses were
299 conducted in R version 4.4.3 (R Core Team, 2022) and visualised using the package
300 ggplot (Wickham, 2016). Population responses in individual wells were modelled
301 using a logistic growth model:

302
$$N(t) = \frac{K}{1 + \left(\frac{K - N_0}{N_0}\right) e^{-rt}}$$

303 Where $N(t)$ is the population at a given timestep t in the experiment (in our
304 experiments, a timestep = 4 hour intervals), K is carrying capacity (number of
305 individuals), N_0 is the starting population (number of individuals when $t = 0$, i.e. the
306 inoculation population), and r is the per capita growth rate.

307 Parameters r and K were estimated for each well in experiment SDM1 ($n = 87$
308 microcosms) by fitting the population growth function for $N(t)$ versus time using
309 Bayesian non-linear regressions in the BRMS package in R (Bürkner, 2017). The prior
310 distribution for r was uniform between 0 and 10, the prior distribution for K was
311 uniform between 0 and 1000, and the prior distribution for N_0 was normal with a

312 mean of 20 and standard distribution of 1 (wells were inoculated with an estimated 20
313 individuals). Some populations did not grow, especially those in unfavourable
314 conditions. In these cases, estimates of r were very uncertain because the low initial
315 population sizes were very close to the carrying capacity K (r controls that rate of
316 population growth toward K). When the posterior distribution of r had a standard
317 deviation greater than 0.3, the data point was excluded from further analysis. For the
318 remaining parameter estimates, weighted linear regressions were then performed to
319 determine how temperature and alfalfa concentration influenced the estimated values
320 of r and K . The weights were equal to the inverse of the variance. Thus, regressions
321 for r were weighted by:

$$322 \quad \frac{1}{sd^2}$$

323
324 where sd is the standard deviation of the posterior distribution of r .

325 The regression model for K was based on $\ln(K)$, so to estimate the the appropriate
326 weight, we assumed that uncertainty in K had a log-normal distribution, in which case
327 $\ln(K)$ would have a normal distribution with variance equal to $\ln(cv^2+1)$, where cv is
328 the coefficient of variation of the posterior distribution of K . Thus, regressions for
329 $\ln(K)$ were weighted by:

$$330 \quad \frac{1}{\ln(cv^2 + 1)}$$

331 We explored models to explain patterns in r and K as a function of concentration
332 and/or temperature, including additive and interactive models, as well as linear and
333 quadratic relationships. The full set of tested models to explain variation in r & K ,
334 separately includes:

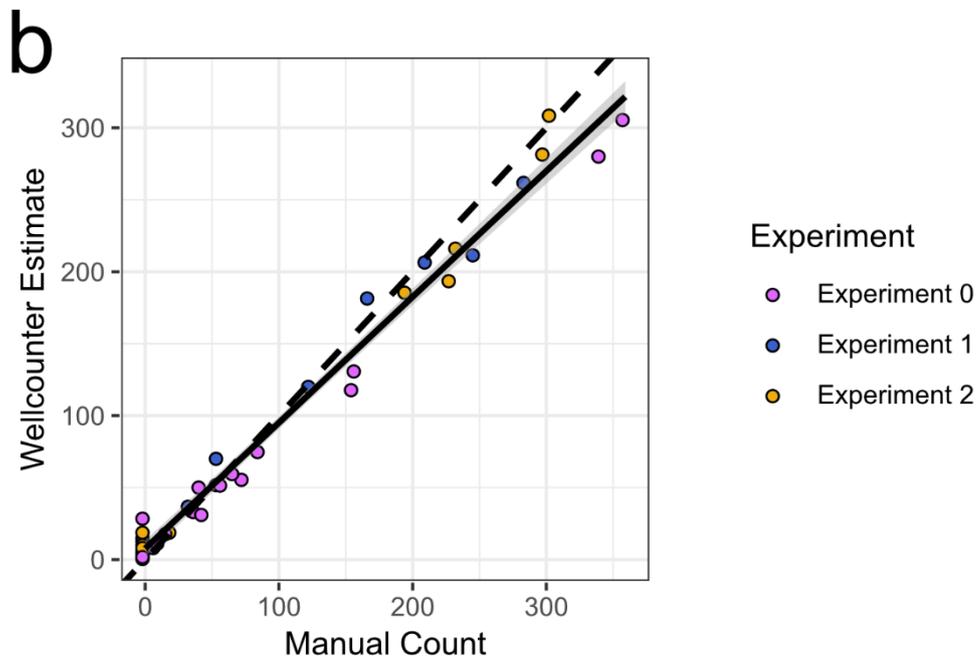
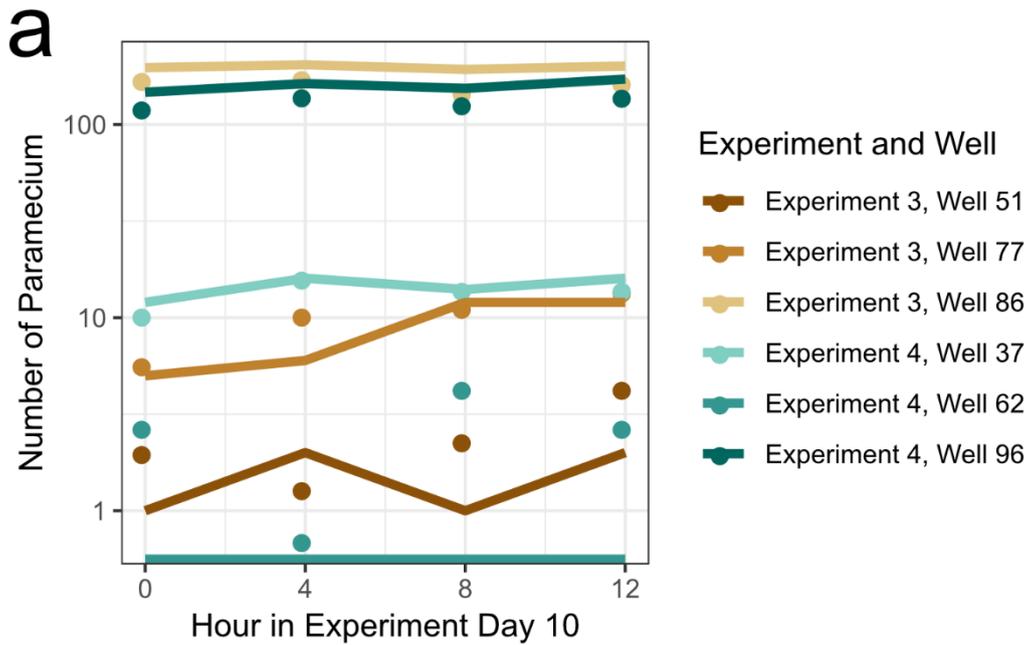
- 335 1. r OR $\ln(K) \sim$ concentration
- 336 2. r OR $\ln(K) \sim$ temperature + temperature²
- 337 3. r OR $\ln(K) \sim$ temperature + temperature² + concentration
- 338 4. r OR $\ln(K) \sim$ (temperature + temperature²) * concentration

339

340 **Results**

341 Validation

342



343

344 Figure 3. a) Wellcounter-Modified estimates (points) compared to manual counts
 345 (lines) over 4 sequential recording intervals for 6 wells (3 each from Experiment 3 &
 346 Experiment 4, stratified by *Paramecium* abundance) to assess autocorrelation of
 347 errors (log_e scaled counts); b) comparison of manual counts and Wellcounter-
 348 Modified estimate across all validation sets (points) with linear model (solid black line)
 349 and a 1:1 line (dashed black line) for comparison, where a 1:1 relationship would
 350 indicate perfect correspondence between manual counts and Wellcounter-Modified
 351 estimates.

352

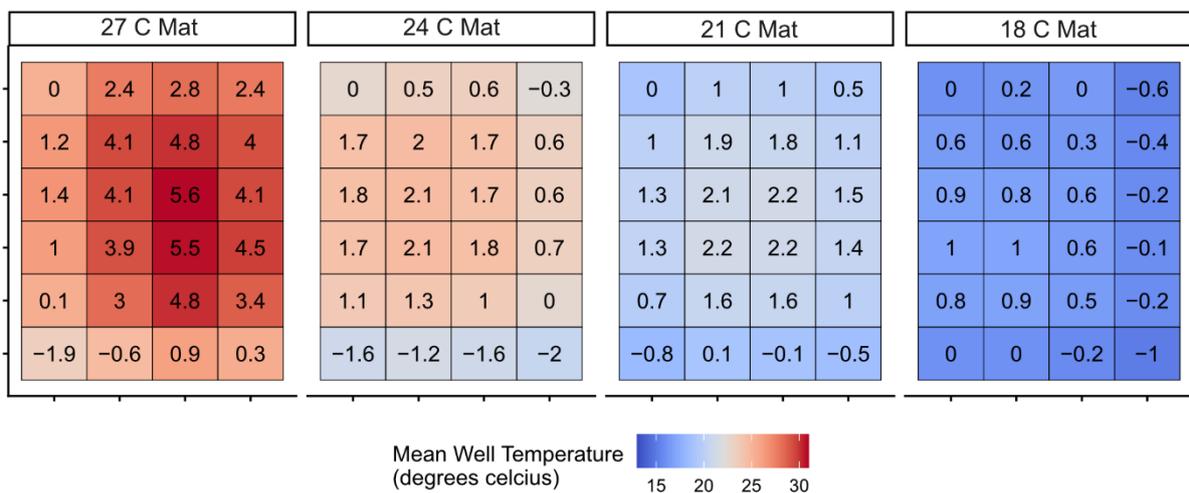
353 *Paramecium* were highly detectable using the CRITTERS workflow. Wellcounter-
 354 Modified estimates were strongly correlated with manual counts (adjusted $R^2 = 0.98$,
 355 $n = 63$ across 5 experiments, linear regression slope = 0.87, intercept = 7.6) (Figure
 356 3B). Wellcounter-Modified occasionally predicted a small number of *Paramecium*
 357 when none were present, and it tended to slightly undercount when *Paramecium*
 358 were abundant (Figure 3A).

359

360 Temperature variation

361 Temperatures within wells are very consistent ($\pm 1^\circ\text{C}$). Across a single heat mat,
 362 temperature may deviate by up to 5°C from the thermostat well, especially on mats
 363 kept at warmer temperatures (e.g. 24°C and above) (Figure 4). Colder mats closer to
 364 the temperature of the room or walk-in incubator (eg. 18°C and 21°C) had less
 365 variation across mats. When there was significant variation within a mat, heat
 366 generally decreased in a radial pattern from the centre of the mat. Experiments
 367 including connectivity could use this variation to generate a habitat gradient within a
 368 single mat, allowing organisms to disperse or distribute according to habitat
 369 preference. For studies not considering spatial complexity, because well
 370 temperatures are autocorrelated based on location, other treatments (e.g. broth
 371 concentration) should be distributed randomly using Latin squares or similar
 372 randomisation method.

373



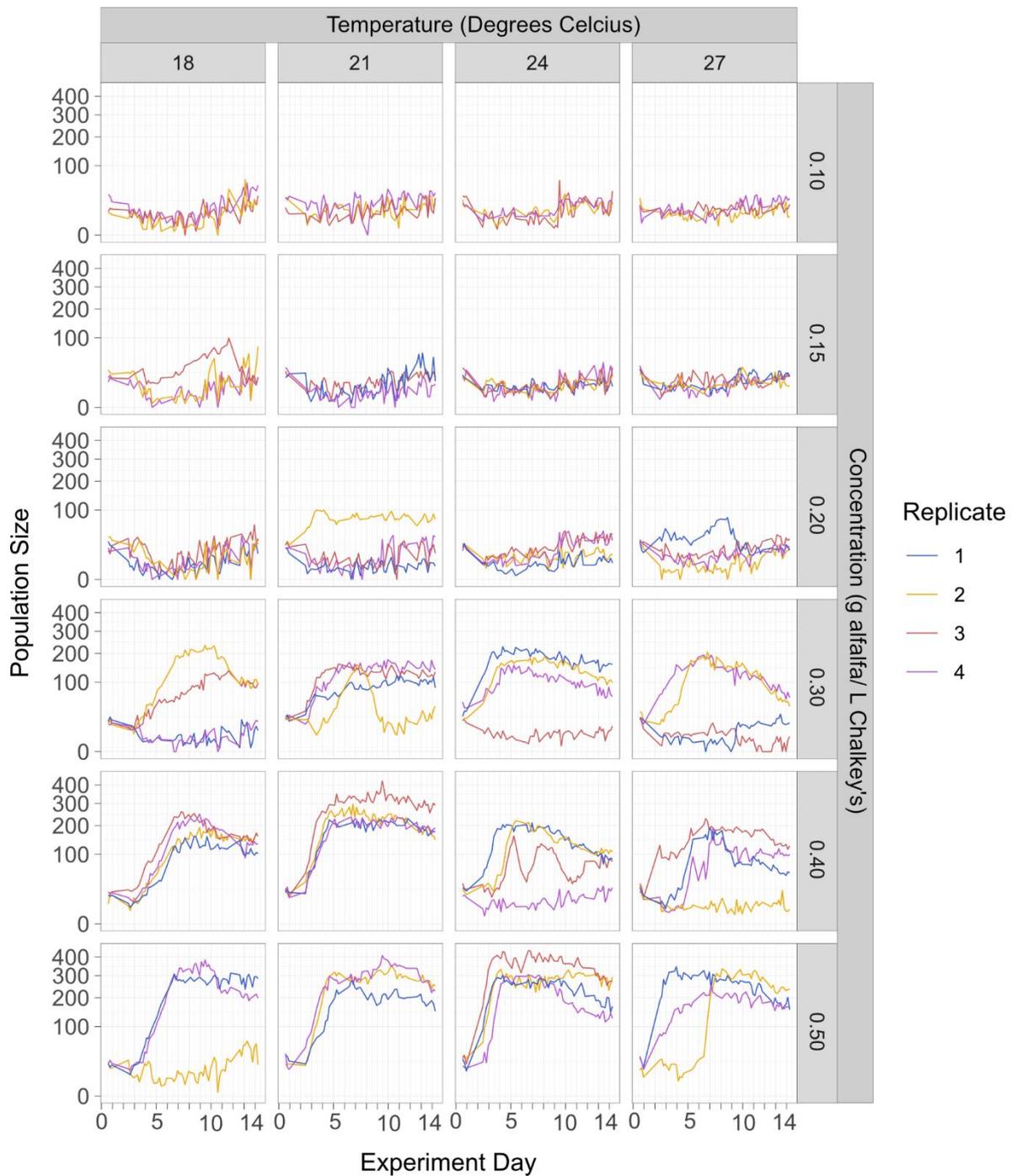
374

375 Fig. 4. Mean temperature of median inside wells (colour of tiles) and deviation from
 376 the temperature of a dedicated thermostat well (black labels) over the duration of 4
 377 experiments.

378

379 Population responses to temperature and resources

380



381

382 Figure 5. Population trajectories for each well in Experiment 1, grouped by
 383 temperature plate (columns) and broth concentration (rows)

384

385 Temperature and food concentration influenced the population trajectories. There
 386 was some variation among replicates and stochastically through time, with
 387 differences in trajectories being occasionally quite large (Figure 5).

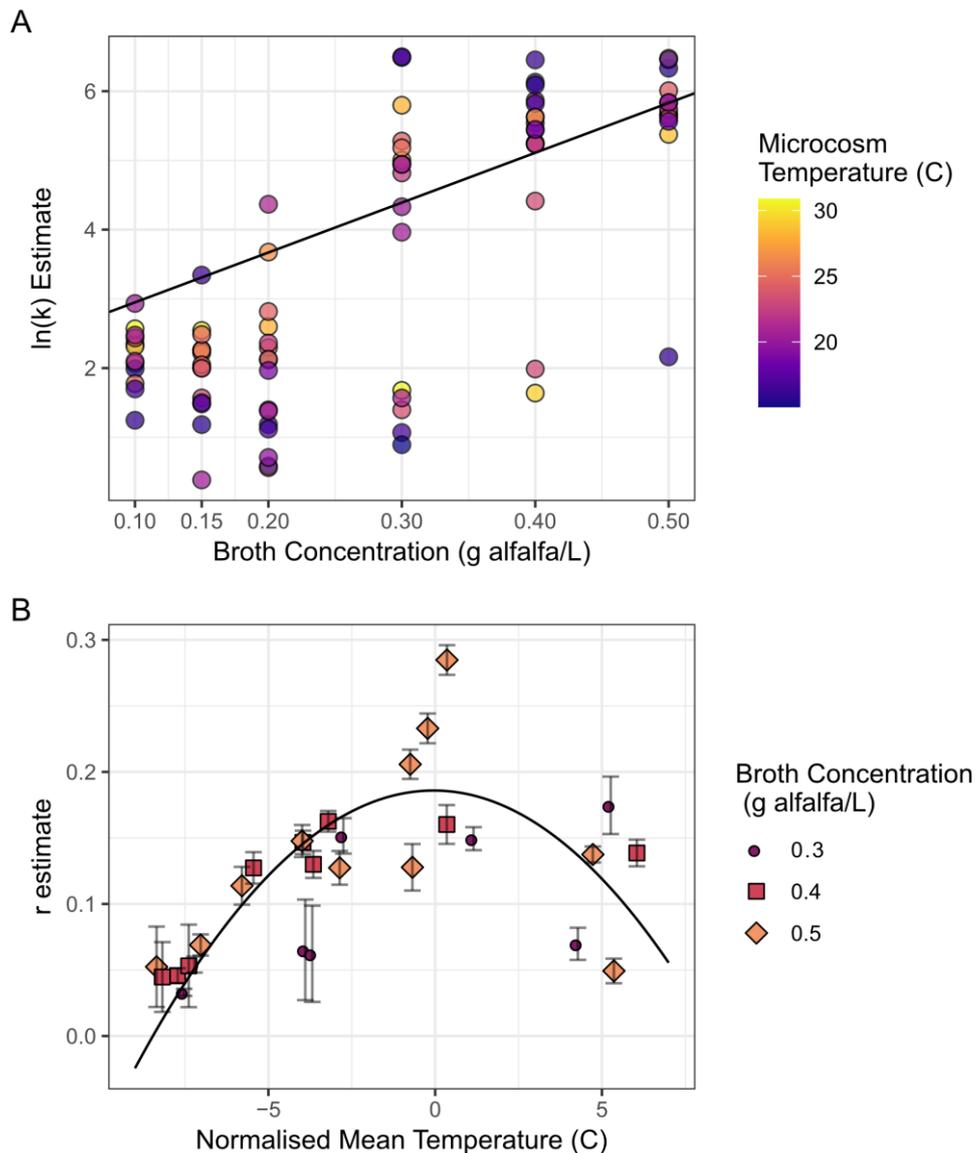
388 Resources (broth concentration) primarily drove the carrying capacity K in
 389 microcosms (Figure 6A). It had little effect on the growth rate r in microcosms. K had
 390 a positive linear relationship with the concentration of media (Table 3). The

391 relationship between K and broth concentration can be described by the equation
392 produced from a GLM (Table 1, Figure 6A):

393
$$\ln(K) = 2.23 + 7.2C$$

394 where K is carrying capacity and C is the concentration of alfalfa broth in g alfalfa per
395 L Chalkey's solution.

396



397

398

399 Figure 6. A) Estimate of the natural logarithm of carrying capacity $\ln(K)$ as a function
400 of broth concentration B) estimate of growth rate r as a function of normalised mean
401 temperature of a microcosm.

402 The mean temperature in a microcosm over the course of experiments drove the
403 growth rate r (Figure 5B), while having little effect on the carrying capacity K of

404 microcosms. Growth rate r had a quadratic response to temperature. The relationship
 405 between r and microcosm temperature can be described by the equation produced
 406 from the GLM (Table 3, Figure 5B):

407
$$r = 0186 + 2.54 * 10^{-4}(T - O) - 2.63 * 10^{-3}(T - O)^2$$

408 where r is growth rate and T is the average temperature of a microcosm,
 409 standardised by subtracting O , the approximate optimal temperature (24C for our
 410 populations).

411

412 Table 3. Response of growth rate r ($n = 30$ microcosms) to temperature (where
 413 temperature is normalised by subtracting the approximate optimum) and carrying
 414 capacity K ($n = 87$ microcosms) to broth concentration (resources) in *Paramecium*
 415 *caudatum* microcosms, derived from weighted linear regressions.

416

Model	Term	Estimate	Std. Error	p value
ln(K) ~ broth concentration	Intercept	2.23	0.24	<0.001
	Broth Concentration	7.21	0.57	<0.001
r ~ (temp - O) + (temp - O)²	Intercept	0.186	1.11 x 10 ⁻²	<0.001
	Temperature	-2.54x 10 ⁻⁴	1.66 x 10 ⁻³	0.879
	Temperature ²	-2.63 x 10 ⁻³	43.49 x 10 ⁻⁴	<0.001

417

418 **Discussion**

419 The CRITTERS system presented here represents an advance in replicable, realistic,
 420 and efficient benchtop experiments for developing and testing ecological models. By
 421 leveraging existing robotics and computer vision tools while introducing benchtop
 422 temperature manipulation CRITTERS allows direct and confident counts of
 423 populations to be achieved in ecologically realistic microcosm systems with relative
 424 ease. A key improvement of CRITTERS is our benchtop temperature and resource
 425 manipulations which improve realism relative to previous incubator-based
 426 experimental designs, permitting an expanded variety of models and theories to be
 427 tested. With the exception of experiment setup and validation, the system is entirely
 428 automated, increasing the potential for replication compared to the historically labour-
 429 intensive data collection of non-automated and/or non-benchtop systems. Similar
 430 experiments may be repeated many times, potentially in different locations by
 431 different research groups, to increase confidence in results and facilitate model
 432 testing over short time-scales at minimal cost relative to field surveys. It has been
 433 noted that more experimentation is necessary to complement the plethora of
 434 observational research in conservation (Drew, 1994), and CRITTERS is well situated

435 to support experiments developing or testing models or theories relating to species
436 occurrence and environmental factors.

437 While the simplification in microcosms means that they cannot fully replace field
438 studies, the advantage of microcosm experiments is their simplicity and
439 generalisability. Much as statistical models themselves simplify complex, real-world
440 systems for the purpose of inference and prediction, “generalised microcosms”
441 (Stern et al 2025) such as CRITTERS simplify natural systems for the same purposes.
442 By eliminating ecosystem-specific complexities and confounders, focal phenomena
443 can be isolated to improve mechanistic understandings of systems (Drake et al.,
444 1996; Fraser & Keddy, 1997; Benton et al., 2007; Altermatt et al., 2015). CRITTERS
445 can test models in simplified, generalised systems, while improving on realism from
446 some other microcosm experiments through benchtop temperature control.
447 Environmental drivers can act as a continuous variable (Figure 4) rather than discrete
448 - as in homogenous incubators -and more complex manipulations are also possible
449 such as connectivity across temperature gradients, cycling, stochastic disturbances
450 or changes in environmental conditions (e.g. temperature) over time. Our
451 populations showed some variation in responses that would not be present in
452 deterministic simulations and would be difficult to foreshadow and parameterise in
453 stochastic simulations (Figure 4A). *Paramecium* populations have natural
454 stochasticity that provides randomness that mimics larger organisms – some
455 populations fail even in good conditions, and populations in poor conditions may
456 persist.

457 While significant work has gone towards counting micro-organisms automatically
458 using computer vision (Stelzer & Groffman, 2025) or machine learning (Besson et al.,
459 2022a), previous deterministic computer-vision based methods operate on largely
460 sterile microcosms with no competing particles (e.g. Wellcounter (Stelzer &
461 Groffman, 2025)). Other alternatives for open-top wells require computationally-
462 taxing machine learning and classification to eliminate false positives (e.g.
463 CommTrack (Besson et al., 2022a)), requiring additional training to adapt to new
464 conditions and datasets. Our modifications to Wellcounter allow for automated
465 counting of micro-organisms in non-sterile, open-top microcosms, necessary in
466 lidded heated systems due to condensation and an inability to image from below if
467 heating the wells. These modifications use deterministic image manipulation
468 techniques rather than machine-learning based classification methods, avoiding an
469 onerous increase in required computing power. Automated detection of *P. caudatum*
470 with *Wellcounter-Modified* proved functionally equivalent to the accuracy of manual
471 counting (Figure 3B).

472

473 *Potential Uses of CRITTERS*

474 The advances of CRITTERS create opportunities to test a wide array of models in
475 ecology and conservation with microcosm experiments. Here, we discuss how
476 adaptive management strategies, N-mixture and occupancy models, and species

477 distribution models (SDMs) may be studied using CRITTERS. Many of these models
478 are difficult to evaluate with field studies or field experiments, because
479 comprehensive field evaluation is precluded by the required levels of experimental
480 control, replication, and monitoring accuracy. .

481 A compelling example of these opportunities is adaptive management (Holling,
482 1978), which is specifically designed for cases where experimental manipulation is
483 limited and the ability to manipulate habitat drivers independently may be necessary.
484 Adaptive management aims to “learn by doing” while explicitly acknowledging limited
485 options for in-field experimentation, meaning that full knowledge of the managed
486 system is unattainable. Attempts to optimise adaptive management account for this
487 uncertainty (e.g. McCarthy & Possingham, 2007)) but the limitation on
488 experimentation in adaptive management systems precludes experimental evaluation
489 of such optimisation with field studies (Holden & Ellner, 2016). Our pilot experiments
490 with CRITTERS found that the carrying capacity of the microcosms (K) is largely
491 driven by food availability, while the rate of population change (r) is largely driven by
492 temperature (Fig. 6). These fundamental properties can be independently
493 manipulated in CRITTERS to permit evaluation of adaptive management – with
494 separate control of both r and K , high replication, and accurate monitoring of
495 abundance, optimisation of adaptive management in biological systems can be
496 feasibly tested beyond simulation studies. Wells may act as discrete units in which
497 nominally optimal management actions can be tested, with population outcomes
498 easily and accurately assessed. Testable ‘management’ interventions in CRITTERS
499 could include patch size (i.e., volume of media), inoculation density relative to
500 carrying capacity, habitat quality via temperature and food, culling of individuals from
501 the population, management of r versus K , survey effort, genetic strain of inoculated
502 populations, etc. Management scenarios that can be evaluated include re-
503 introduction and captive management, eradication and population management more
504 generally, optimal monitoring, and reserve design.

505 Interest in models for species occurrence or abundance that account for imperfect
506 detection has increased recently. Examples of such hierarchical models like
507 occupancy-detection or N-mixture models are difficult to test in natural experimental
508 systems because the true underlying state (abundance or occupancy) is generally
509 not directly observed. As the modifications to *Wellcounter* enable high-accuracy
510 counts of organisms in open-top wells, CRITTERS can accurately observe these
511 ‘latent’ states to provide a source of truth and enable evaluation. Because the
512 locations of individuals within wells is recorded, subsampling of the populations
513 within the wells is straight-forward, facilitating the incorporation of imperfect (and
514 potentially biased) detection, which is fundamental to occupancy and N-mixture
515 models. While occupancy models have been tested through observational or field
516 data (D. A. W. Miller et al., 2015; Briscoe et al., 2021; Valente et al., 2024), these tests
517 have limited precision of detection and monitoring, levels of replication, and
518 experimental control. As such, it has been difficult to experimentally assess
519 performance across a range of conditions or with violations of particular

520 assumptions. Given the increasingly popularity of these models and a proliferation of
521 extensions (Kelleher et al., 2024), the rapid and efficient testing of these assumptions
522 with CRITTERS can improve confidence in novel methods.

523 A third example of CRITTERS' potential relates to testing Species Distribution Models
524 (SDMs). This class of models is widely used in ecology and conservation to both
525 predict species abundances and infer habitat relationships to support management
526 and conservation efforts (Elith & Leathwick, 2009; Guisan, 2017). While these models
527 are well tested in simulated studies and have been assessed observationally (Briscoe
528 et al., 2021, 2021; Elith et al., 2006), the performance of SDMs have not yet been
529 tested in natural experimental systems such as microcosms. To test the predictive
530 performance of SDMs experimentally, one needs accurate population response data
531 to multiple environmental drivers that may be controlled independently to produce a
532 variety of habitat conditions. Prior to benchtop temperature manipulation, testing
533 these was prohibitively difficult to achieve in incubators. CRITTERS makes it easy to
534 explore habitat gradients through temperature and food in benchtop systems.
535 Potential experiments to address knowledge gaps may include testing effects of
536 imperfect detection, and assessing predictive performance in real-world experimental
537 systems based on data quantity and quality, whether populations are at equilibrium or
538 are establishing during data collection, and how model performance changes when
539 conditions are not at equilibrium (e.g. climate change).

540

541 **Conclusions**

542 Stern et al. (2025) distinguished between specialised microcosms that aimed to
543 replicate specific communities or ecosystems, and generalised microcosms that
544 were designed to be simplified analogues of many different systems. CRITTERS, a
545 generalised microcosm system, is best used on models with broad applicability,
546 where fundamental validity or performance needs to be assessed. Importantly,
547 CRITTERS in its simplicity has potential to be widely deployed to test models in
548 separate experimental systems at different researching institutions in collaborative
549 efforts. This opens up potential for “between study replication”, which is uncommon
550 in ecology and conservation (Filazzola & Cahill, 2021). For researchers interested in
551 testing models or theories in CRITTERS or setting up their own version, instructions
552 on lab setup and protocol notes are available through the Appendix. We also
553 encourage reaching out to the CRITTERS team directly.

554

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564

565 Appendix

566 1) response data

567 2) experiment protocol notes

568 3) construction and setup information

569

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