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3 **A plain language review and guidance for modeling animal habitat-selection**

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37 **ABSTRACT** Animal habitat selection is the process of how individual organisms
38 disproportionately use habitat compared to what is available to them. Understanding habitat
39 selection is important for the study of ecology and conservation. However, learning the
40 foundations of making inference or prediction on animal habitat selection can be quite
41 challenging. Foremost, the literature is large and highly technical. We summarize important
42 considerations in getting the basics right, pointing to key papers in the modern literature. We also
43 demonstrate many of these considerations in an online vignette and associated code. We hope
44 this work will help jumpstart student and practitioner learning about habitat selection modeling,
45 provide guidance when reviewing analyses, and lead to rigorous ecological studies that help
46 guide the management and conservation of animal populations.

47 **KEYWORDS: habitat selection, logistic regression, random effect, resource selection**
48 **function, statistical model, step selection function.**

49

50 Habitat selection is a central tenet of ecology and a major focus in studies of animal ecology and
51 evolution. The results of these studies provide inference to the behavioral process of how
52 animals choose locations to maximize fitness when confronted with variation in habitat quality
53 (McLoughlin et al. 2010). The corresponding spatial predictions (Morris et al. 2016a; Winter et
54 al. 2024) are equally important as they are often used in managing animal populations (Morris et
55 al. 2016b, Buderman et al. 2023, Colorado Parks and Wildlife, 2024) and making land
56 conservation decisions to protect habitat (Guisan et al. 2013; Dellinger et al. 2020). How
57 individual animals interact with their environment leads to population-level patterns of
58 distribution and abundance (Boyce and McDonald 1999, Matthiopoulos et al. 2015, Boyce et al.
59 2016), which are often the scales at which management policy and decisions are targeted

60 (Williams et al. 2002). As such, the study of habitat selection is fundamental to understanding
61 wild animals and to their conservation and management.

62 The process by which habitat selection is studied varies but is commonly done using a
63 use-availability design, where features at animal locations are contrasted with features at
64 locations deemed available to the animal for selection (Manly et al. 2002, Johnson et al. 2006,
65 Lele et al. 2013). Animal location observations can be collected many ways (e.g., aerial or
66 ground surveys) but are commonly obtained from radio/GPS/cellular/satellite telemetry
67 technologies. These technologies have advanced considerably in the last several decades (Kays
68 et al. 2015) and similarly, so have the conceptual and statistical frameworks to make inference
69 on and prediction about animal habitat selection (Matthiopoulos et al. 2023). Positive outcomes
70 of these combined advances are finer-scale animal location data, multiple sources of data on the
71 same individual or population, and more flexibility in fitting diverse statistical models when
72 studying animal-habitat relationships (Tucker et al. 2018, Northrup et al. 2022). However, a less
73 desirable outcome is confusion by practitioners and students learning about or implementing
74 habitat selection modeling because more data, while helpful in many respects, can create
75 modeling challenges that were absent from these approaches in the past; thus, highly complex
76 statistical approaches have been introduced to address these issues and they are described in
77 often highly technical literature.

78 The result of the many advances described above is that there is a growing divide
79 between those developing methods for understanding habitat selection and those that most need
80 to use these methods. Our aim is to provide a relatively simple plain language introduction to and
81 review of the literature on the study of animal habitat selection and guidance on important
82 considerations when fitting statistical models to make inference on animal-habitat selection using

83 a use-availability design. We do this by reviewing the modern literature, stating concepts and
84 guidance plainly, and pointing readers to more technical publications on specific topics. **We**
85 **highlight notable points by bold font.** Our motivation stems from working with students and
86 practitioners learning and applying these methods and finding it difficult to provide material for a
87 simple introduction to the topic that focuses on getting the basics right. Further, getting the
88 basics right is important for all studies because habitat selection results can have consequences
89 for habitat conservation and management, as well as government policy decisions.

90 Our challenge is twofold. The first is that this review cannot be exhaustive because of the
91 breadth of the material. We have chosen topics that we see as important to highlight or often
92 confusing when learning. Throughout, we provide references for readers to dive deeper into
93 topics not covered or not covered exhaustively. We have also chosen to focus more on recent
94 literature, after the underlying statistical foundations relevant to habitat selection modeling with
95 presence-only data have been reconciled (Warton and and Sheperd 2010; Aarts et al. 2012;
96 Fithian and Hastie 2013; Johnson et al. 2013), and generally preferencing articles with a
97 statistical focus over applications. The focal cited literature is thorough on the topics, aimed to
98 guide learners, but not exhaustive, given the long history of the topic. For more extensive
99 reviews and establishment of the history of habitat selection analyses, please see Northrup et al.
100 (2022) and Matthiopoulos et al. (2023). Second, there is an inherent risk when writing without
101 technical detail (i.e., statistical notation) that the lack of specificity will lead to misinterpretation.
102 Conversely, there is also a risk that highly technical material will lose early learners or
103 practitioners and keep them from following recommended practices. We hope by writing plainly,
104 without technical detail, that we will reach practitioners and students near the beginning of their
105 learning about habitat selection modeling. However, this document may also be a good review

106 for practitioners implementing these models and reviewing manuscripts. Our intention is to
107 communicate fundamental aspects of habitat selection and habitat selection modeling that will
108 encourage the uptake in following recommended guidance from the modern literature.

109 With the goal of providing a straightforward and digestible introduction to this topic, we
110 include quotes from publications that explain fundamental concepts to draw attention to the
111 publications readers can reference for further reading. We define fundamental terminology in
112 sections 1 through 5, provide guidance in sections 6 through 15, each with one or more
113 highlighted points in bold (summarized in Box 1), and provide recommended literature for
114 further learning in Table 1. We also offer a more detailed checklist with relevant questions for
115 thinking through a habitat selection analysis in Box S1, available in the Supporting Information.
116 In addition, we provide code in the R programming language (v4.4.2; R Core Team, 2024;
117 available on GitHub: <https://github.com/bgerber123/Habitat-Selection-Guidance/> and GitLab
118 <https://code.usgs.gov/cooperativeresearchunits/colorado/habitat-selection>, archived on Zenodo:
119 <https://doi.org/10.5281/zenodo.14847204>, and viewable online at:
120 <https://bgerber123.github.io/hsfguide/>) that follows the outline of the manuscript sections and
121 implements much of the points we discuss. We hope readers will use this work as a beginning
122 step and ultimately go beyond to discover the wealth of information written on modeling animal-
123 habitat relationships.

124

125 *1. What is habitat?*

126 The term habitat has been defined variably throughout its history in the ecological literature.

127 Some authors define it simply as the conditions and resources leading to the occupancy of a

128 species (Hall et al. 1997), while others define it in relation to variation in density of individuals

129 (Morris 2023). We define habitat below to maximize flexibility and interpretability while staying
130 true to aspects of the foundational literature on the topic. As such, we do not take a hardline
131 stance on any one strict definition but allow for users to apply their own definition within this
132 flexible framework and encourage explicitly including that definition in one’s own work.

133 We define habitat as “a set of conditions, resources and risks for the species of interest.”
134 (Northrup et al. 2022; see also Matthiopoulos et al. 2023 section 1.2; Krausman and Morrison,
135 2016). While colloquially habitat is often equated with land cover type, e.g., “forest habitat”,
136 animal habitat encompasses much more than just cover (Krausman and Morrison, 2016), and in
137 the above definition, includes any biotic or abiotic environmental factors that influence the
138 fitness of the animal. Conditions are environmental variables influencing the functioning of the
139 species (e.g., salinity, temperature, diel period, social context). Resources are a substance, object
140 or place required by the species to carry out its life history and positively impact fitness;
141 importantly, resources are limited and can be reduced by the species (e.g., forage or prey). Risks
142 are those environmental variables that are negatively related to a species’ fitness (e.g., predator
143 abundance or proximity to anthropogenic features). See Matthiopoulos et al. (2023; section 1.2)
144 and Northrup et al. (2022; Table 1) for additional details.

145

146 *2. What is habitat selection?*

147 From Matthiopoulos et al. (2023), habitat selection is “the process whereby an organism uses a
148 habitat disproportionately more (or less) than that habitat’s availability.”

149

150 From Northrup et al. (2022), “The process through which individual animals differentially use
151 habitat relative to their availability at a given population density”.

152

153 The word “selection” is important to note here because it emphasizes the behavioral and
154 availability processes resulting in use or disuse. Habitat use is conceptually not the same as
155 habitat selection. From Beyer et al. 2010, “Habitat use is the proportion of their time that animals
156 spend in a particular habitat”. Habitat selection is differentiated from habitat use by considering
157 what is available to the animal. While conceptually different, in practice it is common to assume
158 constant availability within a large geographic area (see section 8. *Traditional habitat selection*
159 *function (HSF) or step-selection function (SSF)?*), such that habitat selection is proportional to
160 habitat use and directly equivalent to relative habitat use.

161

162 3. *What is a habitat-selection function?*

163 From Fieberg et al. 2021, “Habitat-selection functions (HSFs; also referred to as
164 ‘resource-selection functions’; Boyce and McDonald, 1999) provide a framework for linking
165 locations of individual animals to important features of their environment (i.e., resources, risks
166 and environmental conditions).” Conceptually, the HSF is a quantitative description of how the
167 animal selects habitat relative to its availability (i.e., which components of the habitat and how
168 strong that selection is relative to other components). It is conceived as the mathematical
169 function that translates available habitat into used habitat. **A HSF does not refer to a statistical**
170 **model but is one component of an underlying statistical model** (see Hooten et al. 2017
171 Chapter 4 and Michelot et al. 2024, paragraph 1 notes discrepancies in language). Further, while
172 not consistent in the literature, a HSF is also not equivalent to a habitat selection analysis, which
173 generally refers to the whole process of analyzing data (e.g., structuring the response variable
174 and covariates, fitting and evaluating the model, making inference or prediction from the model).

175 One of the most common approaches focuses on comparing *used* animal locations (along with
176 associated environment covariates at those locations) to a set of locations and their associated
177 environmental covariates that are considered *available* within a defined area (e.g., species' range,
178 home range, the next "step" in a movement path); the used locations are part of the larger
179 available sample. The specific types of statistical models used to estimate HSFs are discussed in
180 section 9. *The data generating model and the model being fit.*

181

182 4. 'Habitat selection function' or 'resource selection function'?

183 The literature interchangeably uses habitat (Northrup et al. 2022; Matthiopoulos et al.
184 2023) and resource selection function (RSF; Manly et al. 2002) to describe the same functional
185 analysis. Throughout, we choose to use habitat selection function for the reasons articulated by
186 Matthiopoulos et al. (2011): "Although widely used, the term "resource selection" is perhaps
187 inappropriate since the dimensions of environmental space can be nondepletable conditions (e.g.,
188 temperature) as well as resources (e.g., forage) and because organisms select combinations of
189 values of environmental variables rather than single resources or conditions (e.g., it makes little
190 sense to say that a particular species selects temperature. It is more likely that it selects a
191 particular range of temperatures combined with types of vegetation, and ranges of moisture,
192 slope, etc.)." Essentially, the joint combination we consider within this framework of resources,
193 risks, and conditions leads to a combined inference on what is habitat, which is more than
194 depletable resources. The shift in language also helps differentiate the potential confusion
195 between a resource unit (now as a habitat unit; e.g., grid cell of a raster) and a resource type (e.g.,
196 soil type; Lele et al. 2013). Ultimately, the choice of name is a semantic argument. We find it
197 convenient to think about what comes out of these selection functions as learning about habitat

198 and what goes into the selection function as more than resources, thus our use of HSF rather than
199 RSF. **In writing and presentations, consider how you are defining terminology and using**
200 **terms (e.g., HSF/RSF, analysis, function, model, selection, resource, etc.), aiming for**
201 **consistency and clarity.**

202

203 *5. What about scale?*

204 The scale at which practitioners examine habitat selection and the terminology
205 surrounding it are often points of confusion. When we discuss spatial scale, we are typically
206 referring to the spatial extent and grain of a study, defined as “the overall area encompassed by a
207 study” and “the size of the individual units of observation,” respectively (Wiens, 1989; see also
208 McGarigal et al. 2016). Resolution, the cell size at which environmental covariates are quantified
209 in a raster, is also an aspect of scale, but typically is under less control by the user so not
210 discussed further here. The extent and grain of the study fundamentally determine the extent and
211 grain of the resulting inference. This is discussed through the orders of selection defined in
212 Johnson’s (1980) seminal paper; these orders are used frequently throughout the literature to
213 denote the scale at which selection is occurring. In summary, selection can refer to habitat a
214 species or population selects from a large landscape (first order), selection of home ranges from
215 within a population or species’ range (second order), selection of habitat from within an
216 individual’s home range (third order, most common in the literature), or selection of “food items
217 from those available at the site” that has been generalized to “micro-movement and behavior
218 (e.g., acquisition of food, mating, nest building)” (Hooten et al. 2017) within portions of a home
219 range (fourth order). Notably, individual animals within a study may or may not have the same
220 set of available locations, depending on the scale of interest. For example, the nest locations of

221 mallards (*Anas platyrhynchos*) might be considered used locations and available locations might
222 be sampled from the area typically considered the size of a breeding mallard's home range (e.g.
223 Dyson et al. 2019, Setash et al. 2024; third order selection). In this case, each individual would
224 have different sets of available locations. Alternatively, GPS locations from several mule deer
225 (*Odocoileus hemionus*) might be considered used while available locations are sampled from the
226 national forest they inhabit to evaluate home range characteristics (e.g., Peterson et al. 2022). In
227 this case, the available locations would be the same across individuals. This example does not
228 fall exactly into the orders of selection described above (between 2nd and 3rd order), as it does not
229 consider selection of the whole home range within the landscape (2nd order) nor selection of
230 locations within just the home range (3rd order), but selection of locations from the landscape and
231 not the home range. This serves as an important reminder that Johnson's (1980) orders are a
232 good conceptual framework, but not exhaustive ("it is no doubt possible to divide these selection
233 orders more finely", Johnson 1980).

234 The temporal scale of habitat selection is equally important to consider (Bischof et al
235 2024; Dejeante et al. 2024). Individuals may change selection through time, across diel, seasonal,
236 or annual periods (Borowik et al. 2024; Forrest et al. 2025; Ganoe et al. 2025). It can be
237 important to consider whether the environment is changing through time and to capture these
238 changes by including dynamic spatial layers (e.g., anthropogenic activity that varies by season or
239 diel time) or discretizing the analysis into different temporal periods. However, a temporally
240 dynamic habitat selection analysis will depend on the temporal extent of sampling and whether
241 there are observed animal locations across different time periods. Ultimately, choosing the
242 spatial and temporal scale of inference should be based on the research goal.

243

244 *6. Considering objectives and data collection*

245 In the process of studying habitat, it is important to remember that we will never have all
246 the spatial quantities that make up habitat, and, in reality, the set of conditions, resources and
247 risks that maximizes fitness for an individual animal is dynamic. Thus, our goal is one of
248 approximation, as in any modeling exercise. How we go about approximating ecological and
249 behavioral processes depends on what we know of the species, how the species was sampled,
250 and the intended objective of the study. We can consider ‘what we know of the species’ by
251 making sure to include fundamentally important variables that have clear support from studies of
252 the same species in the same or different populations. We can consider ‘how the species was
253 sampled’ by recognizing the individual as our main sampling unit and our locations as sub-
254 samples that are potentially correlated. We can consider the ‘intended objective of the study’ by
255 deciding if the goal is inference, prediction, description, or some mixture (Tredennick et al.
256 2021). For example, if our goal was strictly prediction, we may consider a high number of
257 correlated covariates that improves predictive performance but may jeopardize inference (Gerber
258 and Northrup, 2020). We can also focus on deriving spatial layers relevant for specific objectives
259 that motivated the study, such as creating maps of selection or avoidance relative to development
260 when we are interested in anthropogenic impacts. **It is each practitioner’s responsibility to**
261 **think deeply about the species, system, sampling design, and objectives ahead of data**
262 **collection and acknowledge the limitations of the study in terms of its habitat selection**
263 **related objectives.** Some specific examples of questions to consider before collecting data
264 include: How many individuals of each group of interest (e.g., age/sex class) is it necessary to
265 sample to adequately assess habitat selection at a given degree of landscape heterogeneity? At
266 what scale(s) should available habitat be measured for a given species or question and can those

267 data be collected via remotely-sensed imagery or do they need to be collected in the field? What
268 GPS fix rate is necessary to evaluate habitat selection (e.g., every minute, once a day)? Are the
269 spatial variables at the spatio-temporal scale that is hypothesized to affect habitat selection?
270 What spatial variables are recognized as important but are not being considered because they are
271 highly correlated with other variables? All these choices have implications for how we sample
272 individuals and model the data and emphasize the importance of understanding the anticipated
273 model structure being used before collecting data.

274

275 *7. What is the scientific goal of implementing a habitat-selection function?*

276 The goal of using most statistical models is either inference (“to evaluate the strength of
277 evidence in a data set for some statement about nature”; Tredennick et al. 2021) or prediction
278 (estimating new response variable values for new observations of the covariates; Tredennick et
279 al. 2021). The inferential goal of a habitat selection analysis is likely to evaluate the different
280 magnitudes of effects (i.e., estimated coefficients, often denoted as β ; see Fierberg et al. 2021 for
281 further discussion of how to interpret and compare coefficients) from hypothesized spatial
282 variables of risks, resources, and conditions. In other words, a statistical model is fit and
283 estimates of coefficients/effects for each spatial variable are evaluated in terms of whether they
284 are large, small, or near zero and whether they lead to selection less than available (negative
285 coefficients) or selection more than available (positive coefficients). Subsequently, this
286 information is used to make inference about the habitat selection process itself, or some other,
287 related ecological or evolutionary process. The prediction goal of a habitat selection analysis is
288 likely to apply the fitted model to a raster of variables across a landscape of interest to produce a
289 spatial map depicting where selection or avoidance is expected to occur across that landscape

290 (Morris et al. 2016b; Gerber and Northrup, 2020) or, depending on the approach and
291 assumptions, an approximation of the utilization distribution (Potts and Schlägel, 2020; Signer et
292 al. 2017; Signer et al. 2024). It is important to recognize that there are tradeoffs when using
293 models for inference versus prediction (Shmueli 2010; Fieberg and Johnson 2015; Tredennick et
294 al. 2021); this decision can impact how complex a model is, which variables are included, and
295 how many models are considered.

296 In addition to the above, HSFs can also be used to make inference to broader population-
297 level processes. Specifically, habitat selection is a mechanism that drives species distribution and
298 population abundance. But, can we use habitat selection analyses to predict abundance? From
299 Street et al. 2017, predicting density “relies on the notion that high-quality habitats will contain
300 more individuals than low-quality habitats (Fretwell and Lucas 1970), and that the resulting
301 distribution is predictable.” Namely, that animals will follow an ideal free distribution (see
302 Northrup et al. 2022, section ‘How do selection functions provide inference to habitat
303 selection?’) and we have an appropriate approximating model that includes variables that can
304 differentiate areas of low and high abundance. There is reasonable evidence suggesting that
305 predicting population density is possible using habitat selection analyses (Boyce, 2006; Boyce
306 and McDonald, 1999; VanDerWal et al. 2009; Boyce et al. 2016; Weber et al. 2017;
307 Matthiopoulos et al 2019). Some consideration from Boyce et al. 2016 is “Scale and domain of
308 the sampling frame, both in time and space, are crucial considerations limiting application of
309 these models. Ultimately, identifying reliable models for predicting abundance from habitat data
310 requires an understanding of the mechanisms underlying population regulation and limitation.”
311 **In other words, it is important to consider the regulating and/or limiting mechanisms of**
312 **abundance in the population of interest, and the relationship between the sampling scale**

313 **and the scale of the underlying mechanisms.** Lastly, beyond methodological challenges in
314 predicting abundance, a species' behavioral plasticity may dampen or even eliminate
315 demographic effects (e.g. on survival, reproduction), such that there is no impact on population
316 density, despite high variation in habitat selection (Northrup et al. 2021). **As such, leaping from**
317 **habitat selection to inferring variation in population density will be most supported with**
318 **validation.** For example, comparing independent estimates of population density to habitat
319 selection predictions.

320

321 *8. Traditional habitat selection function (HSF) or step-selection function (SSF)?*

322 A traditional HSF involves fitting a model to a collection of animal location data, usually
323 at a broad scale (e.g., first through third order), without explicit consideration of the times at
324 which the location data were collected. Availability data are sampled from within the entire
325 spatial extent of interest. A step-selection function (SSF or step selection analysis (SSA))
326 involves fitting a model to location data in such a way as to evaluate selection relative to what is
327 available at each step along a movement path (Forester et al. 2009); the temporal order of the
328 location guides the data setup. Availability data are sampled only from within an area deemed to
329 be available to an animal over the interval between consecutive locations (e.g., where did the
330 animal choose to go next given where they were and the habitat available for them to select for
331 the next step, which is constrained by their movements; Avgar et al. 2016). Michelot et al. (2019)
332 reconciles the connection between traditional HSFs and SSFs, such that multi-scale inference
333 from a single modeling framework is possible. However, until implementation across scales is
334 more widely available for practitioners, the decision of traditional HSF vs. SSF is an important

335 question and one that should be based on the goals of the study and meeting modeling
336 assumptions.

337 Fitting a model to estimate parameters of a traditional HSF or SSF will likely depend on
338 two main considerations, 1) the scale of inference that is being sought, and the 2) temporal
339 dependence between consecutive relocations of the same individual being tracked. Traditional
340 HSFs typically provide inference to an animal's selection at a broad extent (Johnson 1980). The
341 researcher decides the scale by assigning the geographic extent across which they sample
342 available locations. From there, the researcher fits a statistical model to estimate parameters of
343 the HSF under two critical assumptions.

344

345 *8.1. Critical Assumption 1: Accessibility of habitat*

346 It is assumed that all available locations within the selected geographic extent are equally
347 available to the animal (i.e., uniform distribution within the defined geographical extent). This
348 implies that there are no constraints on the animal in accessing all available locations from any
349 given animal location. This may not be true if a dataset consists of relocations with a short time
350 period between consecutive locations. For example, if the interval between locations is 15-
351 minutes and the species' max speed is 1.5 m/s (typical of a 10 kg animal; Cloyed et al. 2021),
352 they can maximally cover 1350 m in this time. Thus, locations that are more than this distance
353 from an animal location are not realistically available to the animal. If this movement constraint
354 is ignored in an HSF, it will lead to incorrect inference on selection. From Northrup et al. (2013):
355 “These coefficients likely represent some mix of a behavioral response to the environmental
356 factors, and noise induced by the distribution of the covariates on the landscape and the
357 movement of the animal (Beyer et al. 2010)”.

358

359 *8.2. Critical Assumption 2: Independence of location data*

360 Apart from the issues of equal availability within a defined geographic area (e.g., a home
361 range), short intervals between consecutive locations also induce the issue of temporal
362 dependence (i.e., autocorrelation) between consecutive animal locations. Ignoring this
363 dependence will lead to an overly inflated sample size and estimated uncertainty (i.e., variance)
364 of effects (e.g., coefficients) will be too precise. The consequence of this will often lead to
365 finding that many or even most estimated effects have very low p-values, which may lead to
366 incorrect interpretation (Alston et al. 2022). From Alston et al. (2022), “Estimates of resource
367 selection are therefore overconfident and often biased when autocorrelated data are modeled as
368 independent and identically distributed (IID). This is one form of pseudoreplication, which has
369 long been acknowledged as a problem in ecology (Hurlbert, 1984)”. Note that the IID
370 assumption is a common one in statistical modeling and can be understood as observations that
371 are not dependent on each other and follow a similar process, often defined by a probability
372 distribution (e.g., the Normal/Gaussian distribution). **In summary, ignoring temporal
373 dependence in the data and assuming there are no movement constraints when there are
374 may lead to poor inference with misleading statistical conclusions.** With that said, if it is
375 reasonable to assume there are no movement constraints and accessible habitat is captured well,
376 traditional HSFs are a powerful framework to learn about animal-habitat relationships.

377 Step-selection functions were developed to deal with serial dependence (i.e.,
378 autocorrelation, like described above) as well as temporally varying availability distributions
379 resulting from movement constraints (Fortin et al., 2005; Thurfjell et al., 2014). Rather than treat
380 locations as independent (with availability that is static through time), SSFs model transitions, or

381 ‘steps’, connecting sequential locations (Fortin et al. 2005; Thurfjell et al. 2014; Fieberg et al.
382 2021) in geographical space. By design, each used animal location is compared against only
383 those resources, conditions, and risks that are reasonably available to the individual within the
384 interval during which the next location will be observed.

385 If a researcher prefers broadscale inference with a traditional HSF, but violates one or
386 both critical assumptions above, they have the choice of thinning high frequency data with a
387 short interval to reduce autocorrelation and movement constraints to fit a broadscale HSF
388 (Swihart and Slade, 1997; Northrup et al. 2013). There are however downsides to thinning data
389 (Alston et al. 2022). Alternatively, there are approaches that retain use of the full, auto-correlated
390 dataset, but which “weight each observed location in an animal's movement track according to its
391 level of non-independence, expanding confidence intervals and reducing bias that can arise when
392 there are missing data in the movement track” (Alston et al. 2022).” For additional guidance, see
393 Box 1 and 2 of Florko et al. (2025) for a decision tree and a comparison chart of methods.

394

395 *9. The data generating model and the model being fit*

396 In any modeling analysis, the analyst must make an assumption about the model that
397 generated the data. As above, this is always an approximation of the true process that produced
398 the data. For traditional HSFs, the accepted data generating model is an Inhomogeneous Poisson
399 Point process model (also understood via the weighted distribution theory; Warton and Shepherd
400 2010, Aarts et al. 2012, Fithian and Hastie 2013, Johnson et al. 2013). Most people do not fit this
401 model directly to their data but use statistical models with other names that approximate the
402 Inhomogeneous Poisson Point process model. This can create confusion and lead to decisions
403 that seem appropriate for a given model (e.g., logistic regression model), but are in fact, not

404 appropriate because they are not actually fitting this model. Below, we introduce some statistical
405 model names, connections among them, and relevant details; this section may be overwhelming
406 and skipped to be later revisited. For now, take away that the same HSF or SSF can be
407 approximated by different modeling approaches, much the same way different software
408 programs can be used to fit the same model.

409 In brief, for a Inhomogeneous Poisson Point process model, spatial locations of
410 individuals are considered points, and the average density of those points in space is dictated by
411 the intensity parameter of the Poisson statistical distribution (often denoted with the Greek letter
412 λ) and its variation across that space (Aarts et al. 2012). Each used point is a realization from a
413 weighted probability distribution, whereby a HSF dictates how animals are selecting resources,
414 and that is weighted by what is available to them to produce the distribution of used locations
415 (Gerber and Northrup 2020, see paragraphs 2-4 or Hooten et al. 2017, Chapter 4.2). The SSF is
416 an extension of the point process model (i.e., spatio-temporal point process model), in which the
417 available samples are conditional on the previous time step (Hooten et al. 2017, Chapter 4.7). For
418 a more general overview of point process models and species distribution modeling, see Hefley
419 and Hooten, 2016.

420 For common implementations of traditional HSFs and SSFs, one of the major areas of
421 confusion is that the model being fit (by way of coding and name of statistical model being
422 implemented) is often an approximation of the model that is intended to be fit (i.e., the point
423 process model). It is common practice to use convenient and widely available statistical models
424 and software to approximate the true underlying statistical model. Traditional HSF models are
425 often indirectly fit using a generalized linear modeling (GLM) framework; specifically, as a
426 logistic or Poisson regression (Fieberg et al. 2021; see affiliated code). This is not the only way

427 though, as equivalent models can be made using maximum entropy modeling, boosted regression
428 trees, generalized additive models, and more (Fithian and Hastie 2013). For SSFs, it is common
429 practice to approximate the spatio-temporal point process model using conditional logistic
430 regression (specific type of discrete choice model; see affiliated code) or Poisson regression with
431 stratum-specific (related to differentiating each step) fixed intercepts (Muff et al. 2020, Michelot
432 et al. 2024). These approaches are only done out of convenience because the point process
433 models are difficult to fit directly as they contain a large, often intractable integral (Hooten et al.
434 2017 Eqn. 4.6 and 4.30, Michelot et al. 2024 Eqn. 1). This raises significant confusion, however,
435 because the model being fit (via coding) and the model that we actually desire is not the same. **In**
436 **summary, the habitat selection model being fit is approximating the underlying assumed**
437 **generating model (i.e., point process model, which includes a large integral) for the sake of**
438 **simplicity and accessibility.** Practitioners format used and available data to meet the
439 specifications of the approximating model (e.g., logistic or Poisson regression) rather than the
440 underlying point process model. Therefore, appropriate steps need to be taken to ensure the
441 approximation process is done with minimal approximation error (see next section, *10. The*
442 *model being approximated*). Somewhat contrastingly, and adding to the confusion on this point,
443 it is advisable to use best practices associated with the underlying habitat selection model (i.e.,
444 the point process model) rather than those associated with the analysis being coded, such as
445 logistic regression, when conducting model diagnostics or goodness of fit tests. As an example,
446 using the area under the receiver operating characteristic curve is inappropriate for HSFs because
447 this is a diagnostic for logistic regression models, which are only used out of convenience, but
448 are not the true underlying model.

449

450 *10. The model being approximated*

451 Fitting traditional HSFs using a logistic or Poisson regression framework and SSFs using
452 conditional logistic regression or Poisson regression with stratum-specific fixed intercepts
453 assumes the habitat selection process follows an exponential form (see “Interpreting Coefficients
454 and Predictions” section below; Hooten et al. 2017, Gerber and Northrup 2020; Michelot et al.
455 2024). The practical implication of this assumption is that inference is on relative selection,
456 rather than absolute selection (which would be the probability of selection; Lele and Keim 2006).
457 In other words, our inference about selection at habitat units with their unique
458 environmental/spatial values is relative to other such units; this is equivalent to how a measure of
459 relative population abundance indicates where there are likely more or less individuals across
460 different areas, but the true number of individuals (absolute population abundance) in different
461 areas is unknown. While it is theoretically possible to estimate absolute selection, it often
462 requires strict assumptions that are unlikely to be met (Hastie and Fithian, 2013). Relative
463 selection is usually perfectly sufficient for most studies given that we are often interested in
464 comparing habitat units and the relative selection of one habitat unit over another.

465 To make sure we are approximating the model we intend (i.e., point process model) with
466 the model we fit (e.g., Poisson or logistic regression), care needs to be taken when setting up the
467 data for analysis. Most importantly, the number of locations in the available sample (the zeros)
468 of the logistic regression needs to be very large (Northrup et al. 2013; Hooten et al. 2017).
469 Similarly, the number of grid cells being sampled when using Poisson regression needs to be
470 very large. This has a statistical justification that is beyond the scope of this paper but see Gerber
471 and Northrup (2020) for further detail. The natural next question is, what is large? It is common
472 to see in the literature a pre-set ratio of used to available (e.g., 1 used: X available), but this does

473 not guarantee an appropriate approximation. The answer ‘to what is large’ depends on the
474 species and study and can only be determined by conducting a sensitivity analysis. In other
475 words, large should be determined by increasing the ratio of available to used locations (i.e.,
476 sample many more available locations than used) until the estimated effects or coefficients and
477 their uncertainty no longer change, or change little (Northrup et al. 2013; Figure 1). To start,
478 create random or systematic locations within the geographic area of interest (e.g., home range).
479 These available locations are used to characterize the spatial variation from the hypothesized
480 covariates. Fit the model, examine the estimated selection coefficients with their measure of
481 uncertainty, and then do the whole exercise again with a larger number of sampled available
482 points. If the selection coefficients and their uncertainty do not change, the original number of
483 available points sampled was sufficient (see affiliated code). If they do change, keep repeating
484 the exercise until they do not.

485 The greater the spatial complexity of the landscape, the more available locations will be
486 needed. One recommendation from Street et al. 2021 is that the “availability sampling should be
487 conducted in a regular (non-random) fashion at a spatial interval equal to the resolution of the
488 underlying landscape data such that every possible location within the availability boundary is
489 considered (Benson, 2013; Fieberg et al., 2021). This would produce an availability observation
490 for every raster pixel and thus overlap between used and available locations.” If using logistic
491 regression, the available samples are best weighted (Fithian and Hastie 2013) to help ensure the
492 approximation is accurate. If using the ‘glm’ or similar function (e.g., glmmTMB: Brooks et al.
493 2017) in the R programming language (R Core Team, 2024), this would mean specifying a
494 vector in the argument ‘weights’ (see affiliated code); this vector would be a series of 1s

495 corresponding to the used locations (the ones; indicating no weighting) and a series of large
496 numbers repeated (e.g., 1000) corresponding to the available locations (the zeros).

497 This same issue for SSFs and fitting a conditional logistic or Poisson model with stratum-
498 specific fixed intercepts has not been discussed in the literature, but the same idea applies. The
499 available locations are used to approximate the spatial surface in selection driven by the
500 environmental covariates being used in the model. Since the scale of SSFs is much smaller, there
501 is likely less landscape heterogeneity within each sampled area. While this likely means less
502 overall area sampled as available per used location, the total number of sampled available points
503 might be much larger than when using a traditional HSF. A sensitivity analysis will still help
504 evaluate when enough available samples matched to each used location leads to converged
505 parameter estimates. **Ultimately, whether fitting a traditional HSF or SSF, the number of**
506 **available samples needed depends on context, and it is the responsibility of the researcher**
507 **to investigate parameter sensitivity to the size of the availability sample and demonstrate**
508 **that estimates have converged (i.e., are no longer changing) in any manuscript.** For either
509 HSF or SSF, a starting consideration could be 10 available locations to each used location,
510 increasing by 10 up until at least 100.

511

512 *11. Individuals*

513 For many habitat selection studies, multiple individuals are tracked simultaneously. This
514 provides an important opportunity to evaluate how individuals vary in their habitat selection.
515 Generally, across species and populations, individual variation in habitat selection is the norm
516 (Pape and Löffler, 2015; Montgomery, et al. 2018; Muff et al. 2020; Ganoë et al. 2025). This is
517 because individuals vary in their age, experience, reproductive status, dominance, morphology

518 and more. Furthermore, there is considerable evidence that animal personality can be an
519 important driver of individual specialization regarding resource use (Leclerc et al. 2016; Brehm
520 and Mortelliti, 2021). Lastly, from Bastille-Rousseau and Wittemyer (2019), “Understanding
521 heterogeneity in individual responses to ecological properties is critical to investigate the
522 mechanisms underpinning population level spatial processes (Westneat et al. 2019).”

523 What does this mean for habitat-selection studies? *A priori*, it is safe to assume there is
524 **individual variation in habitat selection, this variation is important to making inference on,**
525 **and thus it is important that the individual is our main sampling unit.** Specific to SSFs, it
526 may also be important to account for individual variation in the movement process, as well as the
527 habitat-selection model (Chatterjee et al. 2024). Of course, when individuals are not sampled
528 directly, such as observing animal locations via snow tracking, we cannot directly account for
529 individual variation. However, considerations can be made as to the spatial scale and how
530 individual behavior (e.g., foraging vs seeking cover) differs across space (Hebblewhite et al.
531 2014).

532 **When individuals are tracked, pooling data across individuals and ignoring**
533 **individual variation without additional statistical treatment can lead to poor statistical**
534 **conclusions** (Figure 2). Pooling data across individuals leads to a situation where we are
535 obtaining multiple samples from the same sampling unit (i.e., the individual) to estimate effects.
536 From Muff et al. 2020, “treating all observations as though they are independent would result in
537 optimistic standard errors and confidence intervals, leading to what Hurlbert (1984) referred to as
538 pseudoreplication” (Figure 2). Pooled data will likely lead to finding inappropriate statistical
539 support (i.e., have p-values that are too small) for effects only because the appropriate sampling
540 unit (i.e., the individual) is being ignored. Note that, using a random effect on the intercept only,

541 but not the slope(s), pools the data to estimate the slope (more details in section 12. *Population*
542 *Inference*). This creates a lack of independence on yet another level, separate from what was
543 described earlier when locations were collected at short fix intervals (sections 8.1 and 8.2).
544 Pooling data also can lead to issues with certain individuals contributing more data to the model
545 if, as is common in telemetry studies, individuals are tracked for different durations, which can
546 further induce inappropriate inference at the population level.

547 Pooling individual data may be required when each individual has few used locations and
548 thus estimating effects can be challenging. If data are pooled across individuals with large
549 variation in the sample size of used locations, the manuscript should explain that inference is
550 heavily weighted to certain individuals. From Gillies et al. 2006, “pooling will lead to bias
551 towards the individuals with the most data”. Further, when individual characteristics are known,
552 it is important to consider these in our habitat selection analysis. To do so, we have to recognize
553 that individual characteristics are not spatial variables and as such are dealt with differently (e.g.,
554 interactions with spatial variables or separate models for each group; see Northrup et al. (2022),
555 Box 2). Third, if we are sampling individuals from a larger population we are likely interested in
556 a population-level inference, which we should consider along with our individual-level
557 inference. **The population-level inference (see section 12. Population Inference for details)**
558 **provides information on the average or typical response, which is useful, but is most**
559 **accurately expressed within the context of individual-level responses rather than ignoring**
560 **them (Winter et al. 2024).** The variability in responses across individuals is important, for
561 example, on the magnitude of the variation for each variable of interest. But also, only focusing
562 on the population-level response can be misleading in some circumstances. For example, if half
563 the individuals respond negatively to an environmental feature and the other half respond equally

564 positively, the population-level inference will be that they do not select for or against this feature
565 (effect would be zero). By ignoring the individual-level estimates, the population-level inference
566 that there is no selection or avoidance by individuals would be very misleading.

567 When modeling habitat selection, we want to have the statistical power to estimate
568 selection and have statistical clarity (Dushoff et al. 2019) of when an effect is different than zero
569 (i.e., no support for an effect). Two considerations in determining the number of used animal
570 locations are required: 1) the magnitude of the selection strength (effect size) and 2) the
571 complexity of landscape (Street et al. 2021). Street et al. (2021; Figure 1) demonstrate the
572 relationship between the magnitude of selection strength and the number of used locations
573 required to have a 50% and 95% chance of rejecting the null hypothesis (i.e., no effect) at a
574 significance level of $p = 0.05$. This is done for a reasonably complex, and thus realistic, resource
575 layer; for evaluation of specific landscape layers, see the code available by Street et al (2021) or
576 that associated with this manuscript. The take home is that for a given time period (e.g., season)
577 and a single selection behavior (e.g., foraging), only a moderate number of used locations (e.g.,
578 100) are needed to achieve statistical clarity when there are moderate to large selection effects (\leq
579 -0.2 or ≥ 0.2). Recognizing this provides hope to those studies with modest sample sizes in
580 considering an individual-based analysis and not pooling data from multiple individuals. In many
581 instances of low sample size, it is still worthwhile to fit models with full random effects
582 (intercepts and slopes) structures. However, as more complexity is considered in the model (e.g.,
583 different behaviors or time periods), the number of required used locations will increase. The
584 lack of clear and generalizable guidance on sample sizes necessary to fit full models is a
585 considerable gap in the literature. We encourage future research to focus on eliminating that gap,

586 but for now, we encourage collaborating with a statistician to get parameter estimates to
587 converge.

588

589 *12. Population Inference*

590 Commonly, species are not managed at the individual-level, but at the population-level,
591 and we are interested in how a population generally behaves and interacts with their
592 environment. For habitat selection studies, this means we are often interested in scaling up our
593 inference from an individual's selection to an average individual's selection. One way to do this
594 is to first fit separate models to each individual and estimate parameters. Then, for each shared
595 parameter between individual models, estimate a population-level mean and measure of
596 uncertainty using defined equations (see Sawyer et al. 2006) or bootstrap methods (Prokopenko
597 et al. 2017; see affiliated code). The benefit of this approach is that the statistical distribution
598 from which individual-level effects are realized does not need to be assumed (Fieberg et al.
599 2010). However, it is necessary that effects for each individual can be estimated, such that
600 sample sizes are adequate for each individual; this concern is relaxed in the next approach.
601 Importantly, each individual's model structure needs to be set up similarly, such that the
602 estimated effects for each individual mean the same thing. For example, if using a land cover
603 classification variable, each individual needs to have the same reference level (i.e., which land
604 cover variable is considered the baseline or model intercept), so the estimate of differences from
605 the reference to the other levels mean the same thing.

606 An alternative to separate individual models is to jointly estimate individual and
607 population selection parameters in a single model. This can be done using a random effect
608 (Gillies et al. 2006; Duchesne et al. 2010), which is when a statistical model allows parameters to

609 be random variables. The whole model is also known as a hierarchical or multilevel model. It is
610 common to have fixed (i.e., not random) and random parameters together in a single model. In
611 this context, we can think about how some effects on habitat selection might be the same across
612 all individuals (fixed effect) or vary by individual in such a way that they come from a shared
613 distribution of possible values (random effect). This shared distribution is often assumed to be a
614 Normal distribution, which can be fully described by two model parameters, the 1) mean and 2)
615 standard deviation. The mean of the random effect represents the population-level parameter
616 effect and the standard deviation a measure of the variability across the sampled individuals.
617 Fortunately, this modeling approach also retains estimates of individual-level selection
618 parameters and their uncertainty. Depending on how the model is fit (i.e., means
619 parameterization vs. effects parameterization), the individual selection parameters may represent
620 the individual difference from the population-level mean.

621 Before implementing random effects, we should understand some background about
622 them and implications when using them. Thinking of two extremes of using data, we could pool
623 all used locations from all individuals (which we do not suggest), ignore the individual as a
624 factor in a model and estimate a single effect for a habitat selection variable of interest (referred
625 to as complete pooling). Or, we could treat all individuals as different and unrelated and estimate
626 an effect for each individual separately (no pooling; e.g., separate models for each individual;
627 Gelman and Hill 2007, Chapter 12). Random effects represent the middle ground and are
628 referred to as partial-pooling where an estimated population-level distribution (i.e., the random
629 effect) provides a “soft constraint” (Gelman and Hill, 2007 Chapter 12, pg 257) on the individual
630 parameter estimates. While each individual-level effect is estimated from the data for that
631 individual, the soft constraint has the effect of pulling or shrinking the individual effect towards

632 the population-level mean (across all individuals). The effect of this shrinkage is that the
633 estimate of the population-level parameters from across the individuals is helping inform the
634 estimates of the individual, i.e., there is sharing of information across individuals.

635 Why is sharing information good? The primary reason is that the amount of sharing will
636 be mediated by the sample size for each individual. Therefore, the shrinkage can help estimate
637 individual coefficients that otherwise would be difficult to estimate if data were modeled
638 completely separately (no pooling). For example, if an individual rarely interacts with a land
639 cover category, it might be impossible to estimate a coefficient for that category in an individual
640 model. When sharing information, the coefficient for this individual would be estimated close to
641 the population level mean, allowing inclusion of this animal in the analysis. Furthermore, for
642 individuals with small sample sizes, coefficients may be estimated at the extremes (highly
643 negative or positive) due to low replication of used locations (referred to as ‘Type M’ errors;
644 Lemoine et al. 2016). A nice feature of the random effect is that if there is little to no individual
645 variation, the estimated population standard deviation will be near zero and will represent a
646 model that has pooled data. “Conversely, when group-level coefficients vary greatly multilevel
647 modeling reduces to classical regression with group indicators” (Gelman and Hill 2007, Chapter
648 11, page 247). As such, from Gelman and Hill (2007, Chapter 11, pg 247), “there is little risk
649 from applying a multilevel model, assuming we are willing to put in the effort to set up the
650 model and interpret the resulting inferences.” Lastly, taking a random effect approach leads to
651 allowing a joint inference to individual- and population-level effects with proper measures of
652 uncertainty (Gilbert et al. 2023). This makes using a random effect a convenient statistical
653 option, but one that can certainly lead to computational challenges (see text at the end of this
654 section).

655 Several considerations are needed when implementing random effects in a habitat
656 selection analysis. The foremost is whether to include a random effect for the intercept only, or
657 the intercept and slope parameters (Muff et al. 2020). For HSFs, the intercept is largely the ratio
658 of used to available, which is partly controlled by the analyst (Warton and Shepherd, 2010,
659 Theorem 3.2). As such, individuals will likely have different intercepts simply because each
660 individual is unlikely to have the same number of used locations (i.e., an unbalanced design).
661 Random intercepts account for this unbalanced design. From Gillies et al. 2006, “Without a
662 random intercept for individuals with unbalanced data, sample size differences may influence
663 model coefficients.” Furthermore, the intercept is also influenced by the variable values within
664 the model, which may not be the same for all individuals. Thus, when jointly modeling
665 individuals in a habit selection model, allowing the intercept to be different by individual is a
666 must. One way of doing this is using a random intercept. **However, we do not want the**
667 **intercepts to be shrunk towards the population-mean because it would induce bias in the**
668 **selection function (Muff et al. 2020). Therefore, the best practice is to not estimate the**
669 **variance or standard deviation of the random intercept, but to fix it to a large value (e.g.,**
670 **variance of 10^6 ; Muff et al. 2020).** While this is important for traditional HSFs, it is even more
671 important for SSFs being approximated via the Poisson model with stratum-specific fixed
672 intercepts (Muff et al. 2020).

673 Muff et al. (2020) noted in their literature review that most habitat selection studies that
674 use random effects only use random intercepts and not random slopes. Therefore, most studies
675 are assuming there is no variation in an individual's response (i.e., fixed effect parameter) to their
676 hypothesized variables about habitat selection. From Schielzeth and Forstmeier (2009),
677 “Problematically, random intercept models wrongly treat repeated measurements within

678 individuals as independent data points with respect to the population slope.” The outcome of this
679 is described by Muff et al. (2020) as, “Random intercept-only models tend to underestimate
680 standard errors of (potentially biased) fixed effect parameters.” For studies with many used
681 locations and several to many individuals, this will lead to too many rejections of the null
682 hypothesis (i.e., effect of no difference) for the population-wide mean slope. **Therefore, the**
683 **recommended approach is to always use random slopes/effects along with random**
684 **intercepts (with a fixed, large variance on the intercept; Muff et a. 2020).** Doing so will
685 account for unbalanced sampling across individuals, reduce pseudoreplication, recognize that
686 individuals are the main sampling unit, capture the *a priori* assumption that individuals are
687 expected to show variability, estimate appropriate standard errors, and guard against overly
688 optimistic interpretations of statistical clarity (i.e., rejecting the null hypothesis of no difference
689 for habitat selection effects).

690 The intention of making inference from across a set of sampled individuals is that this
691 inference reflects the larger population, including unsampled individuals. But, how many
692 individuals are required to safely make inference to the larger population? Street et al. (2021)
693 demonstrated that when population-level effects are greater than 1 (assuming covariates have
694 been standardized to a mean 0 and standard deviation of 1), it is possible that fewer than 10
695 individuals are needed (Street et al. Figure 5). **It is not warranted to assume studies with few**
696 **individuals sampled are unable to make population-level inference.** Rather, the reliability of
697 making such an inference is best evaluated based on effect sizes, variation among individuals,
698 landscape complexity (i.e., Street et al. 2020, Eqn. 8; see also the affiliated code with this
699 manuscript), and some assessment (even qualitative) of the representativeness of the individuals

700 in the small sample. Generally, the “more variation amongst individuals is likely to mean one has
701 to sample a higher number of animals” (Street et al. 2020).

702 A common reason for forgoing random intercepts and slopes is they create computational
703 issues when fitting models (Bolker, 2009). These issues can happen for many reasons. The
704 model may be over parameterized for the sample size (i.e., too many variables in the model; see
705 recommendations by Fieberg and Johnson 2015) or there is redundancy among intercepts (can
706 happen when factor levels are included as binary covariates and one level is not dropped).

707 Another common estimation issue is when too many land cover variables are used, such that
708 some types are rarely available and rarely used. In these cases, aggregating land cover types may
709 be necessary. Estimation should generally be feasible when land cover types are highly available
710 but rarely used, but initial computational issues are likely. Generic solutions relating to the
711 optimization process (iterative numerical evaluations happening when fitting a model) is to try
712 changing the optimization function, the maximum number of iterations, and providing starting
713 values for the optimization function (e.g., estimates from models fit separately to individuals). If
714 implementing random effects, a good way to diagnose which individuals are causing the issues is
715 to first fit the same model to each individual separately (i.e., no random effects) and evaluate
716 whether each model converges and provides reasonable estimates. From here, leave out the
717 individuals with suspect model fits and fit the full random effect model. If this model fits, add in
718 individuals until it is clear which individual’s data are causing issues. Once the problem data are
719 identified, it might be necessary to discuss options with statistically minded colleagues.

720

721 *13. Considering context in habitat selection analyses*

722 Habitat-selection is about behavior, and “animals are likely to select disparate resources
723 for different behaviors” (Northrup et al. 2022). For example, if an animal is actively seeking or
724 guarding a mate, their risk tolerance is likely to be different to when they are not, such that their
725 selection of habitat can be quite different. Considering all animal locations simultaneously
726 without regard to behavior or contextual environments (e.g., diel period) can “mask strong diel
727 period- and behavior-specific differences in habitat selection” (Suraci et al. 2019). **Generally,**
728 **ignoring behavioral dependence can strongly impact inference on habitat selection (Roever**
729 **et al 2014; Abrahms et al. 2016).** From Beyer et al. (2010), “We argue that analysing location
730 data outside its behavioural context limits our ability to establish the link between habitat use,
731 preference, selection and, ultimately, fitness. Further, “Collecting behavioural data to
732 complement fine-scale location data is prerequisite to developing a better mechanistic
733 understanding of habitat use.” (Beyer et al. 2010)

734 Incorporating behavior into habitat selection analyses requires identifying when
735 behaviors are occurring and assigning a behavior type to each animal location (e.g., resting,
736 foraging, hunting). For some species, certain behaviors may be obvious, such as a bird roosting
737 at nighttime versus feeding or loafing during the daytime. When behaviors are not obvious, one
738 can classify locations by movement trajectory types that consider speed and turning angle to
739 sequence locations into ‘behavior states’ (Michelot et al. 2017). Habitat selection analyses can
740 then be done separately for the animal locations in each of the different states (Suraci et al.
741 2019). This approach is the most straightforward for practitioners, however, it is important to
742 recognize that it ignores uncertainty about the state classifications. Several newer approaches are
743 being developed to jointly model habitat selection and behavioral states (Nicosia et al. 2017;
744 Klappstein et al. 2023; Pohle et al. 2024; McClintock and Lander, 2024). However, “Caution is

745 warranted when interpreting behavioral insights rendered from statistical models applied to
746 location data, particularly when there is no form of validation data.” (Buderman et al. 2021).
747 Ideally, additional field data (e.g., direct observations or accelerometers) could be used to
748 validate the meaning of these behavioral states. Ultimately, we will rarely capture detailed
749 behaviors such that we can expect that our habitat selection inferences are in fact averaging
750 across multitudes of unknown behaviors.

751 Not only is habitat selection a behavioral process, but the behaviors and resulting
752 selection have fitness consequences (Matthiopoulos et al. 2015; see Matthiopoulos et al. 2022
753 Figure 1.2). What is available to an individual is not only a function of their current position on
754 the landscape and their ability to move to other habitats, but also the competitive forces incurred
755 by other individuals. By definition, habitat selection is dependent on the population density of
756 the species and is expected to change based on intraspecific competition (Avgar et al. 2020).
757 Specifically, increasing population density will on average lead to more general selection of
758 habitats, i.e., the selection intensity of certain habitats will be reduced (Fortin et al. 2008; van
759 Beest et al. 2014) because their fitness payoff relative to other available habitats has been
760 reduced from intraspecific competition. When estimates of population density are available it is
761 important to consider them in habitat selection analyses (McLoughlin et al. 2010) and when
762 comparing habitat selection results of the same species across regions or years. Differences in
763 habitat selection may be a result of different population density.

764 Another consideration for habitat selection modeling is to recognize that for many
765 species, selection is highly context dependent (Northrup et al. 2022, section ‘Context dependence
766 in habitat selection; Suraci et al. 2019). When considering spatial variables of resources, risks,
767 and conditions we need to consider how selection regarding one variable may depend on another

768 variable (Ganoe et al. 2025). For example, an animal may have strong selection for areas near a
769 road with low traffic volumes at nighttime to forage within, but differently select for the same
770 areas (i.e., a stronger or weaker magnitude of selection) during the daytime or twilight, and also
771 differently select for areas near roads with higher traffic volumes at nighttime, daytime, or
772 twilight (e.g., Scrafford et al. 2018). To consider this spatial context dependency, we need to
773 consider interactions among the variables of distance to road, traffic volume, and diel time. **The**
774 **general point being that complex landscapes with spatially varying risks, resources, and**
775 **conditions require hypothesizing interactions among spatial variables.**

776

777 *14. Interpreting coefficients and predicting*

778 Interpreting estimated effects requires a clear understanding of linear models, design
779 matrices, and statistical notation. We suggest starting with Edwards and Auger-Méthé (2019) to
780 learn notation, then progress to a regression or linear model textbook to learn about design
781 matrices and estimation (e.g., Fieberg, 2024; Chapter 3), and finally apply this knowledge when
782 reading Fieberg et al. (2021).

783 When predicting from a HSF, we need to remember that we (probably) have assumed an
784 exponential form for our habitat selection model and that we are approximating the point process
785 model (e.g., by logistic regression). Understanding the implication of this will require some
786 general modeling knowledge; specifically, that parameters are often transformed to another scale
787 (via a ‘link’ function; e.g., logit, log) for estimation but can be back-transformed (via a ‘inverse-
788 link’ function; e.g., logit-inverse, exp) to the original scale of the data. In fitting a HSF via
789 logistic regression, the presumed inverse function is the logit-inverse, but since we are
790 approximating an exponential function the parameters are estimated on the log-scale, thus the

791 correct inverse-function is the exponential function. Therefore, simply back-transforming (e.g.,
792 logit-inverse) the combinations of our estimated effects and variable values using common
793 coding functions (e.g., predict.glm, plogis) is inappropriate to predict the relative intensity of
794 selection for a given set of covariates. This holds for any prediction being carried out, including
795 providing a series of new data values to interpret interactions or simply plotting the selection or
796 avoidance behavior across a range of values for a continuous covariate. **To compute predicted**
797 **values, we need to remove the intercept from the selection model (often denoted as β_0 ; it is**
798 **largely a measure of the ratio of used to available locations, which is controlled by the**
799 **analyst) and exponentiate the summed combinations of effects (β_1 to β_n) and variable**
800 **values ($e^{(\beta_1 \times X_1 + \beta_2 \times X_2 \dots + \beta_n \times X_n)}$) where e can be implemented in R using the exp() function**
801 **and the X_1, X_2, \dots, X_n values are the values of the variables of resources, risks and**
802 **environmental conditions.** The resulting values of these predictions will be between 0 and
803 positive infinity. It is common in the literature to see spatial prediction maps of the relative
804 intensity of selection scaled between zero and one. This is not necessarily inappropriate, as long
805 the predictions are calculated as described above first, but there is a concern that readers may
806 unintentionally interpret zero to one values as absolute probabilities, which they are not. In
807 addition, without explicit language/notation on how the predictions are calculated, readers will
808 not know whether the predictions are being calculated correctly.

809 Following above in calculating predicted values, we can interpret avoidance as
810 predictions less than one and selection as greater than one. Mapping these predictions is most
811 effective when they highlight the spatial differences in selection and avoidance and is a common
812 goal of habitat selection studies. The predicted values described above are used to map habitat
813 selection. Rasters of predictor variables are sampled across the landscape of interest (likely the

814 same rasters used to sample predictor variables for used and available locations) and, using the
815 above transformation, predicted selection values are assigned to each raster cell. Importantly,
816 predictions are most robust when they focus on the study system where the observed data were
817 collected. Predicting outside of this region (model transferability) can be done but with great
818 caution (Wiens et al. 2008; McLoughlin et al. 2010; Olson et al. 2020; Matthiopoulos et al. 2011;
819 Matthiopoulos et al 2023) and it is important to consider the sampling design to ensure the
820 sampled area is representative of the area to which selection is being predicted. Lastly, predicting
821 from a SSF needs additional care because selection is conditional on each step and thus needs to
822 be considered when interested in scaling up predictions to a larger landscape. These processes
823 can be computationally intensive but are an area of active research (Potts and Börger, 2023;
824 Signer et al. 2024).

825

826 *15. Model Selection*

827 For some, learning habitat selection modeling will coincide with learning about the role
828 of ‘model selection’. The first question one needs to ask is what is the goal of the model(s)?
829 Tredennick et al. 2019 starts from this point of view and helps frame different ways to think
830 about model selection depending on the goal. We also suggest Bolker (2024) and Fieberg, 2024
831 (Chapter 8) who separate model selection by goals of inference or prediction.

832 There are a few points about model selection specific for habitat selection models that are
833 worth considering here. It is not unusual in GPS telemetry studies to have many thousands of
834 animal locations per individual. Given such a sample size, inference is straightforward because
835 you can include all variables of interest in a single model (which also forces you to think *a priori*
836 about which variables are of interest). Model selection may be irrelevant because there is no need

837 for trading off bias for variance in parameter estimates by considering simpler models, which is,
838 in technical terms, what model selection accomplishes. **It is thus reasonable to focus on fitting**
839 **one model that captures all the variables that represent the complete hypotheses of interest.**
840 **Do not assume model selection is a requirement.** More generally, considering a single model
841 makes for clearly interpretable inference; from Bolker 2024, “If researchers want to use limited
842 data sets to accurately estimate the strength of multiple competing ecological processes along
843 with reliable confidence intervals, the current best approach is to use full (maximal) statistical
844 models (possibly with Bayesian priors) after making principled, *a priori* decisions about model
845 complexity.” This is particularly salient in habitat selection models where there are often
846 extremely large numbers of potential covariates that could be included in models and typically
847 little logical reason for excluding potential habitat covariates (doing so amounts to testing
848 whether a habitat feature has no effect on a species which can more easily be assessed by looking
849 at coefficient magnitudes).

850

851 CONCLUSION

852 The literature landscape pertaining to habitat selection is vast, full of jargon, often
853 technical, confusing, and unfortunately includes numerous examples of poor implementation
854 practices. While important, the technical notation of the statistical processes underlying HSFs
855 can intimidate ecologists and field-hardened practitioners, alike. This review was intended to
856 identify, in no uncertain terms, some important guidelines to conduct rigorous, statistically sound
857 habitat selection studies, and to help readers better understand the reasons behind these
858 guidelines in plain terms. This guide is a first step to gaining the foundation needed to conduct
859 and review habitat selection studies, but extensive resources abound to continue learning. We

860 have referenced many of those resources throughout this paper, but also provide a more
861 consolidated list of recommendations in Table 1. We also offer Box S1 (Supporting Information)
862 to provide support in thinking through a habitat selection analysis.

863 Learning the principles of any ecological field takes time and effort, and those new to the
864 field of habitat selection have their work cut out for them as the methodology has rapidly
865 advanced and studies have quickly proliferated over the past several decades. We urge anyone
866 conducting habitat selection studies to take their time and focus on getting the basics right (i.e.,
867 sampling design, model fitting, and interpretation). Ecological studies are difficult, and
868 researchers often cannot accomplish everything they set out to do. This is entirely okay. They
869 can, however, make an effort to understand the justification for why they are doing what they
870 are, acknowledge the components that cannot be accommodated in sampling or analysis, and
871 ensure their sampling and analysis methodology are appropriate for the questions of interest. The
872 statistical underpinnings of habitat selection analyses are of paramount importance to ensuring
873 proper applied inference for wildlife management decisions. We urge practitioners to note that
874 there is no better way to learn than to simply try these methods on a study system of interest and
875 to seek help when needed.

876

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883

884 **CONFLICT OF INTEREST STATEMENT**

885 The authors declare no conflicts of interest.

886

887 **ETHICS STATEMENT**

888 Not applicable.

889

890 **DATA AVAILABILITY**

891 Data and code supporting this manuscript is available at GitHub at

892 <https://github.com/bgerber123/Habitat-Selection-Guidance/> and Gitlab at

893 <https://code.usgs.gov/cooperativeresearchunits/colorado/habitat-selection>, archived at Zenodo

894 <https://doi.org/10.5281/zenodo.14847204>, and viewable online at

895 <https://bgerber123.github.io/hsfguide/>.

896

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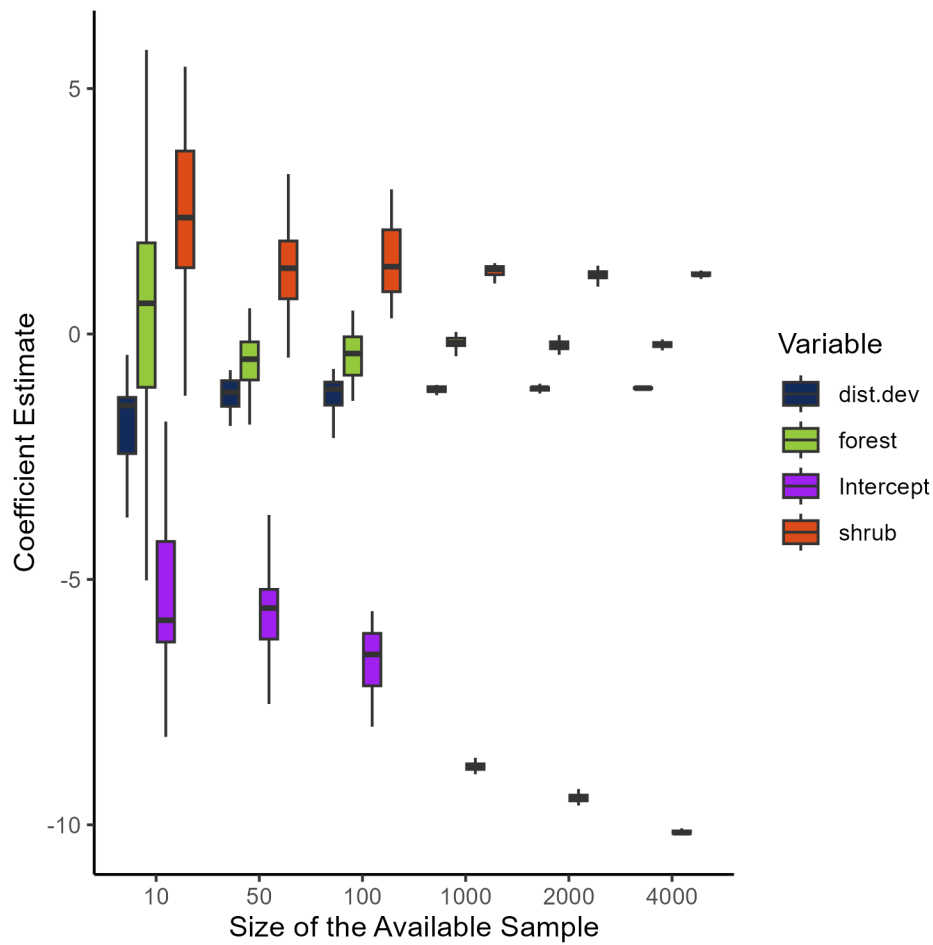
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1226 Figure 1. Variation of estimated slope coefficients of individual habitat selection for three
1227 variables when approximating the point process model with different sizes of the available
1228 sample. Note that as the available sample gets larger, the estimates stabilize and reduce in
1229 variation; this is specifically a traditional habitat selection, but the concept also applies to SSFs.

1230 The intercept does not stabilize but will decrease as the available sample size increases.

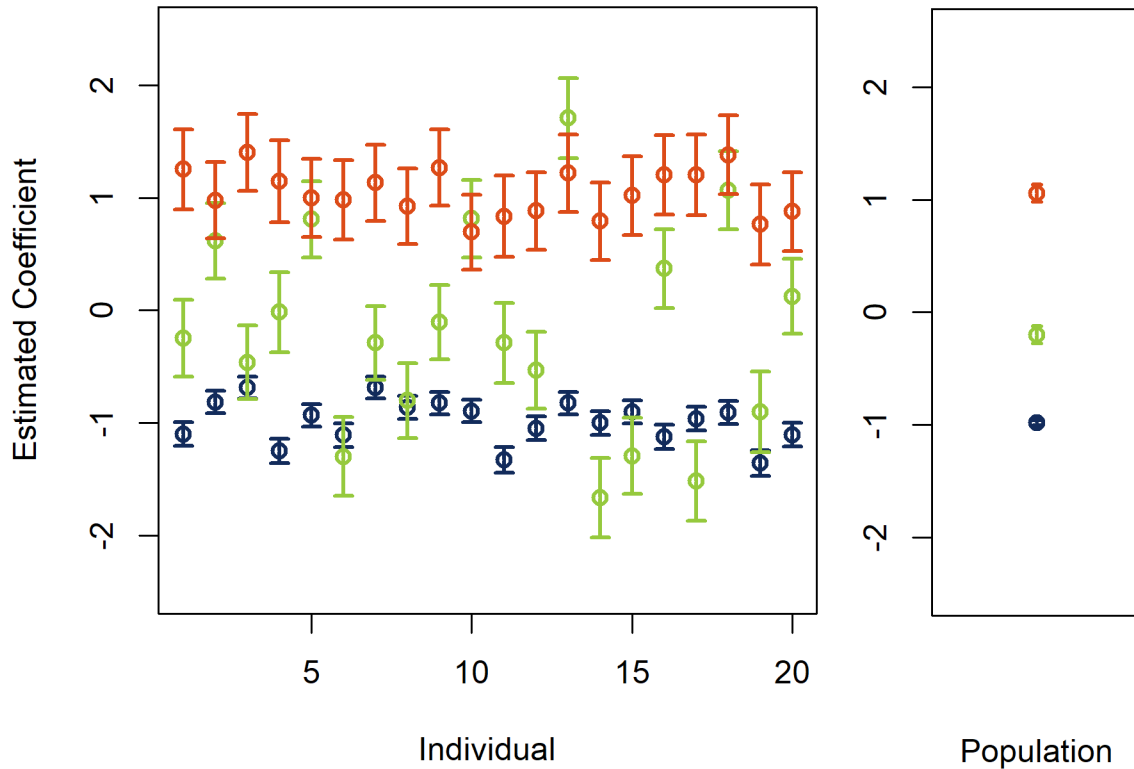
1231 Associated code replicates this figure.

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1237 Figure 2. Individual estimates of slope coefficients and 95% confidence intervals for three spatial
1238 variables across 20 individuals from simulated data (left panel) compared with population-level
1239 estimates and 95% confidence intervals when pooling all individual data and ignoring individual
1240 variation in responses. Associated code replicates this figure.

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1248 Box 1: Guidelines for getting the basics right in habitat selection analyses

- 1249 1. Think thoroughly about the question(s) of interest and the appropriate geographic and
1250 temporal scales in the specific study system before data collection begins.
- 1251 a. Which groups or classes are of interest in your system? Are you planning to break
1252 up the dataset by age/sex class/study area? How many individuals of each group
1253 must be sampled?
- 1254 2. Define availability and determine whether you want to fit a HSF or SSF
- 1255 a. Are you interested in identifying where individuals select home ranges (second
1256 order HSF) or locations within that home range (third order HSF) or along a
1257 movement path (SSF)?
- 1258 3. Decide whether you are interested in inference or prediction and how that impacts model
1259 building
- 1260 a. Inference is most straightforward when a single model is used with all relevant
1261 variables that capture the hypotheses of interest; it is important that the
1262 mechanisms motivating variables are given great thought. Prediction will often be
1263 improved by considering many models and does not necessarily require clear
1264 mechanisms behind including variables.
- 1265 4. Understand and acknowledge the assumptions underlying your specific analysis
- 1266 a. Assumption of an exponential selection function that forces inference to the
1267 relative intensity of selection or relative probability of selection.
- 1268 b. Logistic regression and conditional logistic regression are used to approximate
1269 the underlying spatial or spatio-temporal point process model, respectively.
- 1270 5. Conduct a sensitivity analysis for availability sample size.

1271 a. Fit the model, examine the estimated selection coefficients, and then do the whole
1272 exercise again with a larger number of sampled available points. If the selection
1273 coefficients do not change, the original number of available points sampled was
1274 sufficient. If they do change, keep repeating the exercise until they do not.

1275 6. Account for animal behavior and heterogeneity in your analysis

1276 a. How quickly can the animal of interest move? Available locations from an animal
1277 location that are more than this distance within the considered time frame are not
1278 realistically available to the animal.

1279 b. Is it reasonable to consider consecutive points on an individual's track
1280 independent or are they temporally autocorrelated? It is important to account for
1281 this autocorrelation either by using a SSF, weighting techniques (Alston et al.
1282 2022), or data thinning.

1283 c. Ecological literature leads us to *a priori* consider individual variation, which is an
1284 important source of variation, and thus our main sampling unit is the individual.
1285 When individuals are tracked, pooling data across individuals and ignoring
1286 individual variation leads to poor statistical conclusions. Accounting for
1287 individual level differences can be accounted for using a full random effects
1288 (intercept and slopes) structure.

1289 d. Consider all animal locations with regard to behavior and contextual
1290 environments (e.g., diel period, life stage, reproductive behaviors, etc.), which
1291 may require interactions among variables.

1292 7. Correctly interpret your model parameters and inference

1293 a. To compute predicted values, we need to remove the intercept from the selection
1294 model (β_0) and exponentiate the summed combinations of effects and variable
1295 values ($e^{(\beta_1 \times X_1 + \beta_2 \times X_2 + \dots + \beta_n \times X_n)}$) where e can be implemented in R using the exp()
1296 function and the X_1, X_2, \dots, X_n values are the new values of predictor variables (i.e.,
1297 not the original data input into the model).

1298 b. Inferring population density from habitat selection is most robust when there is
1299 auxiliary or additional validation of population density.

1300 8. Decide whether model selection is necessary. It is reasonable to focus on fitting one
1301 model that captures all the variables that represent the complete hypotheses of interest.
1302 Do not assume model selection is a requirement.

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1316 Table 1: Resources organized by topic for further learning about habitat selection studies.

Topic	Subtopics or Areas of Common Misconceptions	Resources
Commonly-used terminology definitions	Glossary of terms	Northrup et al. (2022)
	Resource selection function	Manly et al. (2007)
	1st-4th order selection	Johnson (1980)
Utilization distributions	Estimating UD from SSF	Signer et al. (2017) Signer et al. (2024) Potts and Schlägel (2020). Potts and Börger (2023)
Predicting population abundance from habitat selection		Matthiopoulos et al. (2015), Boyce et al. (2016)
		McGarigal et al. (2016), Paton and Matthiopoulos (2016) Johnson (1980)
Defining availability in HSFs	Sample size of available points	Northrup et al. (2013)
	Movement ability of the	Beyer et al. (2010)

	animal	
	Temporal autocorrelation of consecutive locations	Alston et al. (2022), Noonan et al. (2019)
	Spatial heterogeneity/complexity	Fieberg et al. (2021), Fithian and Hastie (2013), Street et al. (2021)

Random effects and population-level inference	Random effects	Gelman and Hill (2007)
	Examples of hierarchical habitat selection models	Muff et al. (2020), Winter et al. (2024)

Sample size considerations	Number of used locations required per individual and number of individuals required/power analyses	Street et al. (2021)
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Model selection		Fieberg, 2024 (Chapter 8), Fieberg and Johnson (2015), Gerber and Northrup (2020)
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Interpretation of parameters		Fieberg et al. (2021)
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